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C Programming Basic – week 14

Mapping and Hashing

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Topics of this week

- Dictionary ADT
- Hash Table
- Hash functions
- Compression maps
- Collision handling
- Exercises

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Dictionary ADT

- The dictionary ADT models a searchable collection of key-element items
- The main operations of a dictionary are searching, inserting, and deleting items
- Multiple items with the same key are allowed
- Applications:
 - address book
 - credit card authorization
 - mapping host names (e.g., csci260.net) to internet addresses (e.g., 128.148.34.101)

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Dictionary ADT methods

- **findElement(k)**: if the dictionary has an item with key k, returns its element, else, returns the special element NO_SUCH_KEY
- **insertItem(k, o)**: inserts item (k, o) into the dictionary
- **removeElement(k)**: if the dictionary has an item with key k, removes it from the dictionary and returns its element, else returns the special element NO_SUCH_KEY
- **size()**, **isEmpty()**
- **keys()**, **elements()**

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Key-Indexed Dictionaries

Key	Value
1	Intro to CS 1
2	Intro to CS 2
5	Theory of Computation
7	Data Structures
9	Digital Logic

→

0
Intro to CS 1
Intro to CS 2
Theory of Computation
Data Structures
Digital Logic

Space-efficient only if the cardinality of the set is close to N

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Searching without Comparisons

- How could a search algorithm proceed without comparing data elements?
- What if we had some sort of "oracle" that could take the key for a data value and compute, in constant-bounded time, the location at which that key would occur within the data collection?

data key K → **O(1) Oracle** → L_i → location of matching record within the collection

If the container storing the collection supports random access with $\Theta(1)$ cost, as an array does, then we would have a total search cost of $\Theta(1)$.

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Hash Functions and Hash Tables

- An efficient way of implementing a dictionary is a hash table.
- Use an array (or list) of size N (table)
 - Need to spread keys over range $[0, N-1]$
 - Collisions occur when elements have same key
- Keys are not always integers, nor in range $[0, N-1]$
- A **hash table** for a given key type consists of
 - Hash function h
 - Array (called table) of size N
- When implementing a dictionary with a hash table, the goal is to store item (k, o) at index $i = h(k)$

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Example

- We design a hash table for a dictionary storing items (SIN, Name), where SIN (social insurance number) is a nine-digit positive integer
- Our hash table uses an array of size $N = 10,000$ and the hash function
- $h(x) = \text{last four digits of } x$

0	→ 025-612-0001
1	→ 981-101-0002
2	→ 451-229-0004
3	
4	
...	
9997	
9998	→ 200-751-9998
9999	

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Hash functions

- A hash function h maps keys of a given type to integers in a fixed interval $[0, N - 1]$
- Example:
 - $h(x) = x \bmod N$ is a hash function for integer keys
 - The integer $h(x)$ is called the hash value of key x
- A hash function is usually specified as the composition of two functions:
- Hash code map:
 - $h1: \text{keys} \rightarrow \text{integers}$
- Compression map:
 - $h2: \text{integers} \rightarrow [0, N - 1]$

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Hash Code Maps

- **Integer cast**
 - Bits of the key are interpreted as integer
 - Suitable for keys of length shorter than the number of bits of an integer type
 - Example:
 - 'A' $\rightarrow 65$
 - 'N' $\rightarrow 78$
- **Component Sum**
 - We partition the bits of the key into components of fixed length (e.g., 16 or 32 bits) and we sum the components
 - Suitable for numeric keys of fixed length greater than or equal to the number of bits of the integer type

$$X = \left(\underbrace{x_1}_{12 \text{ bits}}, \underbrace{x_2}_{12 \text{ bits}}, \dots, \underbrace{x_{n-1}}_{12 \text{ bits}} \right) \Rightarrow h_1(x) = \sum_{i=0}^{n-1} x_i$$

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Hash code Maps

- **Polynomial accumulation**
 - We partition the bits of the key into a sequence of components of fixed length (e.g., 8, 16 or 32 bits)
 - $a_0 \ a_1 \ \dots \ a_{n-1}$
 - We evaluate the polynomial

$$p(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_{n-1} z^{n-1}$$
 at a fixed value z , ignoring overflows
 - Especially suitable for strings (e.g., the choice $z = 33$ gives at most 6 collisions on a set of 50,000 English words)

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Exercise 14.1

- Write three function which implements three type of hash code maps above.
- The input key for integer cast and polynomial is a string
- The input key for component sum method is a number of type long.

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Compression Map

- The result of the HCM needs to be reduced to a value in $[0, N-1]$
- Division Method:**
 - $h_2(y) = |y| \bmod N$
 - The size N of the hash table is usually chosen to be a prime
- Multiply, Add and Divide (MAD):**
 - $h_2(y) = |ay + b| \bmod N$
 - a and b are nonnegative integers such that $a \bmod N \neq 0$
 - Otherwise, every integer would map to the same value b

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Simple implementation of Hash Table

```
#define MAX_CHAR 10
#define TABLE_SIZE 13
typedef struct {
    char key[MAX_CHAR];
    /* other fields */
} element;
element hash_table[TABLE_SIZE];
```

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Hash Algorithm via Division

```
void init_table(element ht[])
{
    int i;
    for (i=0; i<TABLE_SIZE; i++)
        ht[i].key[0]=NULL;
}

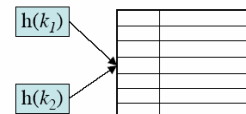
int transform(char *key)
{
    int number=0;
    while (*key) number += *key++;
    return number;
}

int hash(char *key)
{
    return (transform(key) % TABLE_SIZE);
}
```

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Conflict Resolution

- Collisions - occur when $k_1 \neq k_2$ but $h(k_1) = h(k_2)$
- Results in more complex *insertItem()* and *findElement()* operations
- Conflict Resolution Strategies
 - Closed Addressing (Open Hash Table) - i.e. slots other than $h(k)$ are "closed" and can not be used
 - Open Addressing (Closed Hash Table) - look for another open position in the table



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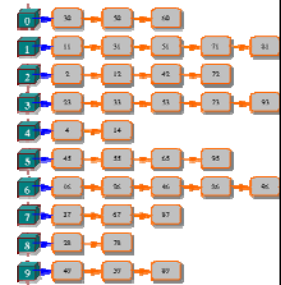
Data structure for Hash Table

- Open Hash Table:
 - Chaining Method
- Closed Hash Table
 - Linear Probing
 - Quadratic Probing
 - Rehashing

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Data structure for chaining

- Array of pointers
- Each pointer manage a linked list corresponding to a bucket (address).
- This example shows a chaining hash table with hash function $N \bmod 10$



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Exercise 14.1

- Implement an ADT for chaining hash table providing the following operations:
 - Init
 - Hash function
 - Insert (given key and element)
 - Search, Delete (given key)
 - IsEmpty
 - Clear
 - Traverse

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Solution

Data structure declaration

```
#define B ... // size of hash table
typedef ... KeyType; // int
typedef struct Node
{
    KeyType Key;
    // Add new fields if it is necessary
    Node* Next;
};
typedef Node* Position;
typedef Position Dictionary[B];
Dictionary D;
```

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Initiate a Hash Table

```
void MakeNullSet()
{
    int i;
    for(i=0; i<B; i++)
        D[i]=NULL;
}
```

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Search an element in the hash table

```
int Search(KeyType X) {
    Position P;
    int Found=0;
    //Go to bucket at H(X)
    P=D[H(X)];
    //Traverse through the list at bucket H(X)
    while((P!=NULL) && (!Found))
        if (P->Key==X) Found=1;
        else P=P->Next;
    return Found;
}
```

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Insert an element

```
void InsertSet(KeyType X)
{
    int Bucket;
    Position P;
    if (!Member(X, D)) {
        Bucket=H(X);
        P=D[Bucket];
        //allocate a new node at D[Bucket]
        D[Bucket] = (Node*)malloc(sizeof(Node));
        D[Bucket] ->Key=X;
        D[Bucket] ->Next=P;
    }
}
```

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Delete an element

```
void DeleteSet(ElementType X){
    int Bucket, Done;
    Position P,Q;
    Bucket=H(X);
    // If list has already existed
    if (D[Bucket]!=NULL) {
        // if X at the head of the list
        if (D[Bucket]->Key==X)
        {
            Q=D[Bucket];
            D[Bucket]=D[Bucket]->Next;
            free(Q);
        }
        else { // Search for X
            Done=0;
            P=D[Bucket];
            while ((P->Next!=NULL) && (!Done))
                if (P->Next->Key==X)
                    Done=1;
            else P=P->Next;
            if (Done) { // If found
                // Delete P->Next
                Q=P->Next;
                P->Next=Q->Next;
                free(Q);
            }
        }
    }
}
```

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Emptiness

Verify if a bucket is empty

```
int emptybucket (int b){  
    return(D[b] ==NULL ? 1:0);  
}
```

Verify if the table is empty

```
int empty( ){  
    int b;  
    for (b = 0; b<B;b++)  
        if(D[b] !=NULL) return 0;  
    return 1;  
}
```

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Clear a bucket

```
void clearbucket (int b){  
    Position p,q;  
    q = NULL;  
    p = D[b];  
    while(p !=NULL){  
        q = p;  
        p=p->next;  
        free (q);  
    }  
    D[b] = NULL;  
}
```

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Clear the hash table

```
void clear( )  
{  
    int b;  
    for (b = 0; b<B ; b++)  
        clearbucket(b);  
}
```

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Traverse a bucket

```
void traversebucket (int b)  
{  
    Position p;  
    p= D[b];  
    while (p !=NULL)  
    {  
        // Assume that the key is of int type  
        printf("%3d", p->key);  
        p= p->next;  
    }  
}
```

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Traverse the table

```
void traverse()  
{  
    int b;  
    for (b = 0;n<B; b++)  
    {  
        printf("\nBucket %d:",b);  
        traversebucket(b);  
    }  
}
```

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Exercise 14-2 Make a hash list

- You assume to make an address book of mobile phone.
- You declare a structure which can hold at least "name," "telephone number," and "e-mail address", and make a program which can manage about 100 these data.
- (1) Read about 10 from an input file, and store them in a hash table which has an "e-mail address" as a key. Then confirm that the hash table is made. In this exercise, the hash function may always return the same value.
- (2) Define the hash function properly, and make the congestion occur as rare as possible

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Linear Probing (linear open addressing)

- Compute $f(x)$ for identifier x
- Examine the buckets
 - $ht[(f(x)+j)\%TABLE_SIZE]$
 - $0 \leq j \leq TABLE_SIZE$
- The bucket contains x .
- The bucket contains the empty string
- The bucket contains a nonempty string other than x
- Return to $ht[f(x)]$

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Linear Probing - example

0	49**	
1	58**	
2	69**	
3		
4		
5		
6		
7		
8	18	
9	89	

With linear probing $ff(i) = i$.

Here is a hash table of size $T = 10$, where the entries 89, 18, 49, 58, and 69 have been inserted. The hash function is $h(key) = key \% 10$.

Throughout this talk we use a table size $T = 10$, although in practice it should be prime.

Exercise 14.3

- Implement an ADT Hash Table with linear probing method.

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Quadratic Probing

- Linear probing tends to cluster
 - Slows searches
- designed to eliminate the primary clustering problem of linear (but some secondary clustering)
- uses a quadratic collision function i.e. $f(i) = i^2$
- no guarantee of finding an empty cell if table is $>$ half full unless table size is prime

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Exercise 14.4

- Implement an ADT Hash Table with quadratic probing method.

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Double Hashing

- Double hashing uses a secondary hash function $h_2(k)$ and handles collisions by placing an item in the first available cell of the series $(i + h_2(k)) \bmod N$
- The secondary hash function $h_2(k)$ cannot have zero values
- The table size N must be a prime to allow probing of all the cells
- Common choice of compression map for the secondary hash
- function: $h_2(k) = q - k \bmod q$
- where
 - $q < N$
 - q is a prime

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Exercise 14.5

- Implement an ADT Hash Table with rehashing method, using two following hash functions:

- $f_1(\text{key}) = \text{key} \% M$
- $f_2(\text{key}) = (M-2) - \text{key} \% (M-2)$

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Hash functions

```
int hashfunc(int key)
{
    return(key%M);
}
//Secondary function
int hashfunc2(int key)
{
    return(M-2 - key%(M-2));
}
```

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