.45 The x coordinate of the center of mass is

$$x_{\text{CM}} = \frac{\sum m_i x_i}{\sum m_i} = \frac{0 + 0 + 0 + 0}{2.00 \text{ kg} + 3.00 \text{ kg} + 2.50 \text{ kg} + 4.00 \text{ kg}} = 0$$

and the y coordinate of the center of mass is

$$\begin{split} y_{\text{CM}} &= \frac{\sum m_i y_i}{\sum m_i} \\ &= \left(\frac{1}{2.00 \text{ kg} + 3.00 \text{ kg} + 2.50 \text{ kg} + 4.00 \text{ kg}}\right) \\ &\times [(2.00 \text{ kg})(3.00 \text{ m}) + (3.00 \text{ kg})(2.50 \text{ m}) \\ &+ (2.50 \text{ kg})(0) + (4.00 \text{ kg})(-0.500 \text{ m})] \end{split}$$

$$y_{\rm CM} = 1.00 \text{ m}$$

Then

$$\vec{\mathbf{r}}_{CM} = (0\hat{\mathbf{i}} + 1.00\hat{\mathbf{j}}) \text{ m}$$

.49 This object can be made by wrapping tape around a light, stiff, uniform rod.

(a)
$$M = \int_{0}^{0.300 \text{ m}} \lambda dx = \int_{0}^{0.300 \text{ m}} [50.0 + 20.0x] dx$$

 $M = [50.0x + 10.0x^2]_{0}^{0.300 \text{ m}} = [15.9 \text{ g}]$

(b)
$$x_{\text{CM}} = \frac{\int_{\text{all mass}} x \, dm}{M} = \frac{1}{M} \int_{0}^{0.300 \, \text{m}} \lambda \, x \, dx = \frac{1}{M} \int_{0}^{0.300 \, \text{m}} \left[50.0x + 20.0x^2 \right] dx$$

$$x_{\text{CM}} = \frac{1}{15.9 \, \text{g}} \left[25.0x^2 + \frac{20x^3}{3} \right]_{0}^{0.300 \, \text{m}} = \left[0.153 \, \text{m} \right]$$

- 52 (a) ANS. FIG. P9.52 shows the position vectors and velocities of the particles.
 - (b) Using the definition of the position vector at the center of mass,

$$\vec{\mathbf{r}}_{\text{CM}} = \frac{m_1 \vec{\mathbf{r}}_1 + m_2 \vec{\mathbf{r}}_2}{m_1 + m_2}$$

$$\vec{\mathbf{r}}_{\text{CM}} = \left(\frac{1}{2.00 \text{ kg} + 3.00 \text{ kg}}\right)$$

$$= \left[(2.00 \text{ kg})(1.00 \text{ m}, 2.00 \text{ m}) + (3.00 \text{ kg})(-4.00 \text{ m}, -3.00 \text{ m})\right]$$

$$\vec{\mathbf{r}}_{\text{CM}} = \left[(-2.00\hat{\mathbf{i}} - 1.00\hat{\mathbf{j}}) \text{ m}\right]$$

(c) The velocity of the center of mass is

$$\begin{split} \vec{\mathbf{v}}_{\text{CM}} &= \frac{\vec{\mathbf{P}}}{M} = \frac{m_1 \vec{\mathbf{v}}_1 + m_2 \vec{\mathbf{v}}_2}{m_1 + m_2} \\ &= \left(\frac{1}{2.00 \text{ kg} + 3.00 \text{ kg}}\right) \\ & [(2.00 \text{ kg})(3.00 \text{ m/s}, 0.50 \text{ m/s}) \\ & + (3.00 \text{ kg})(3.00 \text{ m/s}, -2.00 \text{ m/s})] \\ \vec{\mathbf{v}}_{\text{CM}} &= \boxed{\left(3.00\hat{\mathbf{i}} - 1.00\hat{\mathbf{j}}\right) \text{ m/s}} \end{split}$$

(d) The total linear momentum of the system can be calculated as $\vec{\mathbf{P}} = M\vec{\mathbf{v}}_{\text{CM}}$ or as $\vec{\mathbf{P}} = m_1\vec{\mathbf{v}}_1 + m_2\vec{\mathbf{v}}_2$. Either gives

$$\vec{\mathbf{P}} = (15.0\hat{\mathbf{i}} - 5.00\hat{\mathbf{j}}) \text{ kg} \cdot \text{m/s}$$

.53 No outside forces act on the boat-pluslovers system, so its momentum is conserved at zero and the center of mass of the boat-passengers system stays fixed:

$$x_{\text{CM},i} = x_{\text{CM},i}$$

Define K to be the point where they kiss, and Δx_1 and Δx_b as shown in the figure. Since Romeo moves with the boat (and

 Δx_b Δx_J K Δx_b Δx_J Δx_J

thus $\Delta x_{\text{Romeo}} = \Delta x_b$), let m_b be the combined mass of Romeo and the boat. The front of the boat and the shore are to the right in this picture,

and we take the positive x direction to the right. Then,

$$m_1 \Delta x_1 + m_b \Delta x_b = 0$$

Choosing the *x* axis to point toward the shore,

$$(55.0 \text{ kg})\Delta x_1 + (77.0 \text{ kg} + 80.0 \text{ kg})\Delta x_b = 0$$

and
$$\Delta x_1 = -2.85 \Delta x_b$$

As Juliet moves away from shore, the boat and Romeo glide toward the shore until the original 2.70-m gap between them is closed. We describe the relative motion with the equation

$$|\Delta x_1| + \Delta x_b = 2.70 \text{ m}$$

Here the first term needs absolute value signs because Juliet's change in position is toward the left. An equivalent equation is then

$$-\Delta x_1 + \Delta x_h = 2.70 \text{ m}$$

Substituting, we find

$$+2.85\Delta x_b + \Delta x_b = 2.70 \text{ m}$$

so
$$\Delta x_b = \frac{2.70 \text{ m}}{3.85} = \boxed{0.700 \text{ m}}$$
 towards the shore

.60 (a) The fuel burns at a rate given by

$$\frac{dM}{dt} = \frac{12.7 \text{ g}}{1.90 \text{ s}} = 6.68 \times 10^{-3} \text{ kg/s}$$

From the rocket thrust equation,

Thrust =
$$v_e \frac{dM}{dt}$$
: 5.26 N = $v_e \left(6.68 \times 10^{-3} \text{ kg/s} \right)$
 $v_e = \boxed{787 \text{ m/s}}$

(b)
$$v_f - v_i = v_e \ln\left(\frac{M_i}{M_f}\right)$$
:
 $v_f - 0 = (787 \text{ m/s}) \ln\left(\frac{53.5 \text{ g} + 25.5 \text{ g}}{53.5 \text{ g} + 25.5 \text{ g} - 12.7 \text{ g}}\right)$

$$v_f = \boxed{138 \text{ m/s}}$$

.61 The force exerted on the water by the hose is

$$F = \frac{\Delta p_{\text{water}}}{\Delta t} = \frac{mv_f - mv_i}{\Delta t} = \frac{(0.600 \text{ kg})(25.0 \text{ m/s}) - 0}{1.00 \text{ s}}$$
$$= \boxed{15.0 \text{ N}}$$

According to Newton's third law, the water exerts a force of equal magnitude back on the hose. Thus, the gardener must apply a 15.0-N force (in the direction of the velocity of the exiting water stream) to hold the hose stationary.

Or (dm/dt)v