

# Benchmarking Spike-Based Visual Recognition:

#### a Dataset, Evaluation and Algorithms

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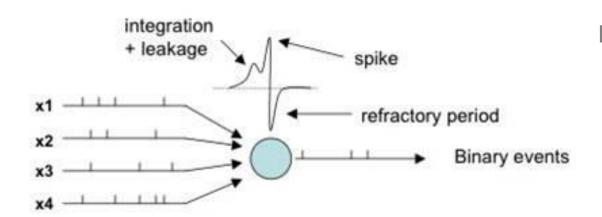
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# **Background**

- Spikes
- Spiking Neural Networks (SNNs)
- Special visual input for SNNs
  - e.g. DVS(Dynamic Vision Sensor)





DAVIS240: £3,346



#### **Aims and Motivations**

- Unified spiking data
- Meaningful comparisons
- Promoting future research

Authors	Data	Accuracy		
Matsugu et al. (2002)	Face plain images	98.3%		
Fu et al. (2012)	JAFFE plain images	97.35%		
O'Connor et al. (2013)	Poissonian Spiking MNIST	95.0%		
Bichler et al. (2012)	DVS recorded Car trajectories	98%		
Zhao et al. (2015)	DVS recorded Three postures	99.48%		

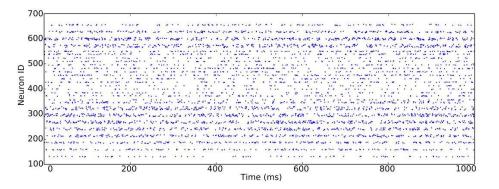


#### A Dataset: NE15-MNIST

- Unified spiking data
  - Poissonian generator
  - Rank order coding generator
  - DVS recorded flashing image
  - DVS recorded moving image









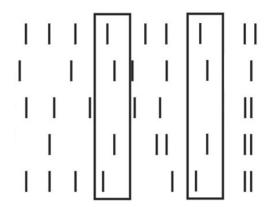
#### A Dataset: NE15-MNIST

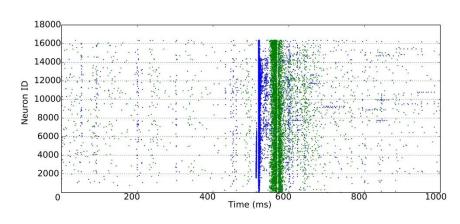
- Meaningful comparisons
  - On the same data
  - Among SNNs
  - vs. conventional algorithms



#### A Dataset: NE15-MNIST

- Promoting future research
  - Poissonian: easier accessible
  - ROC: spatio-temporal pattern recognition
  - Flashing image: fast recognition
  - Moving image: invariant recognition

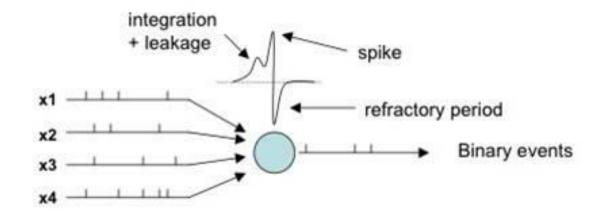






# **Evaluation on Spiking Vision Recognition**

- Metrics on SNN models
  - Biological training time
  - Biological testing time
  - Response latency



	Preprocessing	Network Training		Recognition	
Brader et al. (2007)	None	Two layer, LIF neurons	Semi-supervised, STDP, calcium LTP/LTD	96.5%	
Beyeler et al. (2013)	None	V1 (edge), V4 (orientation), and competitive decision, Izhikevich neurons	Semi-supervised, STDP, calcium LTP/LTD	91.6% 300 ms per test	
Neftci et al. (2013)	Thresholding	Two layer RBM, LIF neurons	Event-driven contrastive divergence, supervised	91.9% 1 s per test	
Diehl and Cook (2015)	None	Two layers, LIF neurons, inhibitory feedback	Unsupervised, exp. STDP, 3,000,000 s of training 200,000 s per iteration	95%	
Diehl et al. (2015)	None	ConvNet or Fully connected, LIF neurons	Off-line trained with ReLU, weight normalization	99.1% (ConvNet), 98.6% (Fully connected); 0.5 s per test	
Zhao et al. (2015)	Thresholding or DVS	Simple (Gabor), Complex (MAX) and Tempotron	Tempotron, supervised	Thresholding 91.3%, 11 s per test DVS 88.1%, 2 s per test	



# **Evaluation on Spiking Vision Recognition**

- Metrics on H/W platforms
  - Feasibility due to H/W limits
  - Simulation time
  - Energy use

	System	Neuron Model	Synaptic Plasticity	Precision	Simulation Time	Energy/Power Usage
SpiNNaker (Stromatias et al., 2013)	Digital, Scalable	Programmable Neuron/Synap Axonal delay		11- to 14-bit synapses	Real-time Flexible time resolution	8 nJ/SE 54.27 MSops/W
TrueNorth (Merolla et al., 2014)	Digital, Scalable	Fixed models, Config params, Axonal delay	No plasticity	122 bits params & states, 4-bit synapse <sup>a</sup>	Real-time	46 GSops/W
Neurogrid (Benjamin et al., 2014)	Mixed- mode, Scalable	Fixed models, Config params	Fixed rule	13-bit shared synapses	Real-time	941 pJ/SE
HI-CANN (Schem- mel et al., 2010)	Mixed- mode, Scalable	Fixed models, Config params	Fixed rule	4-bit synapses	Faster than real-time <sup>b</sup>	198 pJ/SE 13.5 MSops/W (network only)
HiAER- IFAT (Yu et al., 2012)	Mixed- mode, Scalable	Fixed models, Config params	No plasticity	Analogue neu- ron/synapse	Real-time	22-pJ/SE (Park et al., 2014) 20GSops/W



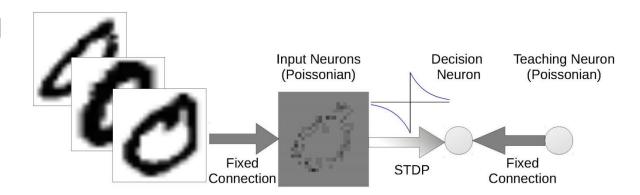
## **Benchmarking SNNs Algorithms**

- state-of-the-art
  - 2-Layer STDP (Synaptic-timing dependent plasticity)
  - Spiking Deep Network (off-line training)
  - Spiking Convolutional Network(ConvNet) (off-line training)
- Case studies on H/W (SpiNNaker)
  - STDP online training
  - Spiking Deep Belief Network (SDBN) (Evangelos Stromatias)
  - Spiking ConvNet (1st year, and future work)

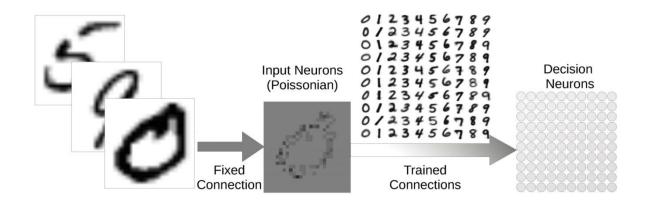


## Case Study I: 2-layer STDP

Training



Testing





#### Case Study I: 2-layer STDP

Metrics on SNN models

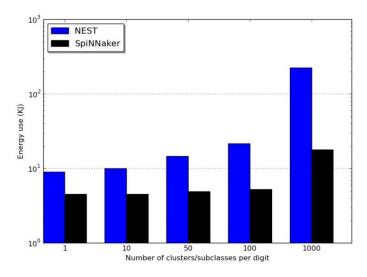
- biological training time: 18,000s, 0.3s / image

- biological testing time: 1s / image

- response latency: 10.7ms

Metrics on H/W platforms

- feasibility due to H/W limits
- simulation time
- energy use



N: Nest	Subclasses	Accuracy (%)		Simulation (s)		Power Use (W)	
S: SpiNNaker	per digit	N	S	N	S	N	S
_	1	79.62	79.50	446.52		$\sim 20$	0.38
	10	91.29	91.43	503.91		$\sim 20$	0.38
	50	92.98	92.92	772.70	12,000	$\sim 20$	0.41
	100	87.27	86.83	1,142.39		$\sim 19$	0.44
	1000	89.65	89.74	12,585.28		$\sim 17$	1.50

This work has been submitted to Frontiers in Neuromphic Engineering and is under interactive review.



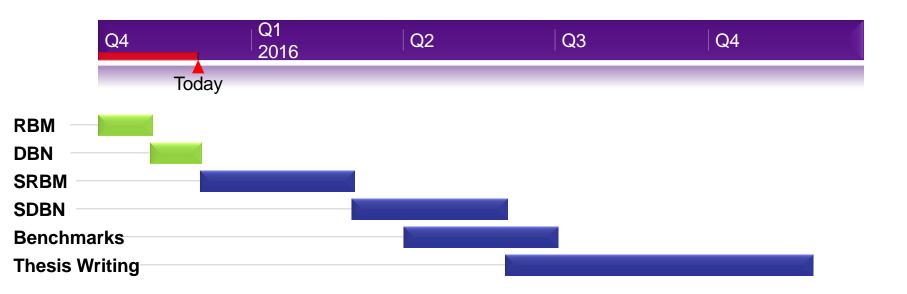
# Future Work: Towards the Robust Object Recognition

- state-of-the-art
  - 2-Layer STDP learned 1 case study
  - Spiking DBN (off-line training) online formalised training
  - Spiking ConvNet (off-line training) future case study
- My exploration on Spiking DBN
  - Restricted Boltzmann Machine (RBM)
  - Deep Belief Net
  - Future work: spiking RBM & DBN

Current work has been written down in a study report.



# Potential Research Tasks Contrastive Divergence RBM Validation Maths of DBN Practical Training Methods Future Tasks Mean-Field Theory SRBM Structure STDP Learning for CD Layered STDP Learning





#### **Questions?**