

unicorn模拟执行学习

前言

unicorn 是一个模拟执行软件，用于模拟执行各种平台的二进制文件，前几天在 [twitter](#) 上看到一篇文章，这里做个记录。

正文

记录系统调用

首先是一个简单的示例

```
e8fffffc05d6a055b29dd83c54e89e96a02030c245b31d266ba12008b39c1e710clef1081e9feffff8b4500c1e010c1e81089c309fb21f8f7d021d86689450083c5024a85d20f85cfffffec37755d7a0528ed24ed2
```

这是一段 x86_32 的 shellcode，可以用 radare2 反汇编它

```
rasm2 -a x86 -b 32 -d e8fffffc05d6a055b29dd83c54e89e96a02030c245b31d266ba12008b39c1e710clef1081e9feffff8b4500c1e010c1e81089c309fb21f8f7d021d86689450083c5024a85d20f85cfffffec37755d7a0528ed24ed2

hac1h@ubuntu:~$ rasm2 -a x86 -b 32 -d e8fffffc05d6a055b29dd83c54e89e96a02030c245b31d266ba12008b39c1e710clef1081e9feffff8b4500c1e010c1e81089c309fb21f8f7d021d86689450083c5024a85d20f85cfffffec37755d7a0528ed24ed2
0528ed24ed24ed0b887feb509838f95c962b9670fec6fffc6ff9f321f581e00d380
call 4
rcr byte [ebp + 0x6a], 5
pop ebx
sub ebp, ebx
add ebp, 0x4e
mov ecx, ebp
push 2
add ecx, dword [esp]
pop ebx
xor edx, edx
mov dx, 0x12
mov edi, dword [ecx]
shl edi, 0x10
shr edi, 0x10
sub ecx, 0xfffffe
mov eax, dword [ebp]
shl eax, 0x10
shr eax, 0x10
mov ebx, eax
or ebx, edi
and eax, edi
not eax
and eax, ebx
mov word [ebp], ax
add ebp, 2
dec edx
test edx, edx
jne 0x1d
in al, dx
aaa
jne 0xaf
jp 0x59
sub ch, ch
and al, 0xed
and al, 0xed
or ecx, dword [eax - 0x67af1481]
cmp cl, bh
pop esp
xchg eax, esi
sub edx, dword [esi - 0x390190]
invalid
lcall [edi + 0x1e581f32]
add bl, dl
invalid
```

这里的目標是记录他的系统调用，在 32 中使用 int 80 来执行系统调用，所以我们在执行 int 80 前记录它的寄存器信息，就可以记录系统调用了。

```
from unicorn import *
from unicorn.x86_const import *

shellcode = "e8fffffc05d6a055b29dd83c54e89e96a02030c245b31d266ba12008b39c1e710clef1081e9feffff8b4500c1e010c1e81089c309fb21f8f7d021d86689450083c5024a85d20f85cfffffec37755d7a0528ed24ed2

BASE = 0x400000
STACK_ADDR = 0x0
STACK_SIZE = 1024*1024

mu = Uc(UC_ARCH_X86, UC_MODE_32)
```

```

mu.mem_map(BASE, 1024*1024)
mu.mem_map(STACK_ADDR, STACK_SIZE)

mu.mem_write(BASE, shellcode)
mu.reg_write(UC_X86_REG_ESP, STACK_ADDR + STACK_SIZE/2)

def syscall_num_to_name(num):
    syscalls = {1: "sys_exit", 15: "sys_chmod"}
    return syscalls[num]

def hook_code(mu, address, size, user_data):
    #print('">>>> Tracing instruction at 0x%x, instruction size = 0x%x' %(address, size))

    machine_code = mu.mem_read(address, size)
    if machine_code == "\xcd\x80":

        r_eax = mu.reg_read(UC_X86_REG_EAX)
        r_ebx = mu.reg_read(UC_X86_REG_EBX)
        r_ecx = mu.reg_read(UC_X86_REG_ECX)
        r_edx = mu.reg_read(UC_X86_REG_EDX)
        syscall_name = syscall_num_to_name(r_eax)

        print "-----"
        print "We intercepted system call: "+syscall_name

        if syscall_name == "sys_chmod":
            s = mu.mem_read(r_ebx, 20).split("\x00")[0]
            print "arg0 = 0x%x -> %s" % (r_ebx, s)
            print "arg1 = " + oct(r_ecx)
        elif syscall_name == "sys_exit":
            print "arg0 = " + hex(r_ebx)
            exit()

        mu.reg_write(UC_X86_REG_EIP, address + size)

mu.hook_add(UC_HOOK_CODE, hook_code)

mu.emu_start(BASE, BASE-1)

```

关键就是使用 `mu.hook_add`, 使得在 `unicorn` 执行一条指令之前会先执行 `hook_code` 并且传入了与程序运行状态相关的参数, 便于我们对程序状态进行操纵。在这里就是获取了寄存器的值, 然后根据系统调用号解析参数。

ARM代码模拟执行

测试程序位于

<http://t.cn/RQ6viS6>

其实就是一个递归函数, 最后打印返回值

```

int __fastcall ccc(unsigned int a1, int a2, int a3)
{
    int v4; // r5
    int v5; // r1
    int v6; // r2
    int v7; // r4
    int v8; // r1
    int v9; // r2
    unsigned int v11; // [sp+4h] [bp-10h]

    v11 = a1;
    switch ( a1 )
    {
        case 0u:
            return 5;
        case 1u:
            return 8;
        case 2u:
            return 3;
        case 3u:
            return 1;
    }
    v4 = ccc(a1 >> 1, a2, a3);
    v7 = ccc(v11 - 1, v5, v6) * v4;
    return v7 + ccc(v11 - 3, v8, v9);
}

```

我们的目标是加速程序的执行，可以加速的原理在于，这里是递归

调用，对于的参数，返回值确定，所以我们可以对已经执行过的参数，直接设置返回值，进而加速程序的运行。

```

from unicorn import *
from unicorn.arm_const import *
import struct

def read(name):
    with open(name) as f:
        return f.read()

def u32(data):
    return struct.unpack("I", data)[0]

def p32(num):
    return struct.pack("I", num)

mu = Uc(UC_ARCH_ARM, UC_MODE_LITTLE_ENDIAN)

BASE = 0x10000
STACK_ADDR =
STACK_SIZE = 1024*10240x300000

mu.mem_map(BASE, 1024*1024)
mu.mem_map(STACK_ADDR, STACK_SIZE)

mu.mem_write(BASE, read("./task4"))
mu.reg_write(UC_ARM_REG_SP, STACK_ADDR + STACK_SIZE/2)

instructions_skip_list = []

CCC_ENTRY = 0x000104D0
CCC_END = 0x00010580

stack = []                                # Stack for storing the arguments
d = {}                                     # Dictionary that holds return values for given function arguments

def hook_code(mu, address, size, user_data):
    #print('>>> Tracing instruction at 0x%x, instruction size = 0x%x' %(address, size))
    if address == CCC_ENTRY:                 # Are we at the beginning of ccc function?
        arg0 = mu.reg_read(UC_ARM_REG_R0)      # Read the first argument. it is passed by R0

```

```

if arg0 in d:                                # Check whether return value for this function is already saved.
    ret = d[arg0]
    mu.reg_write(UC_ARM_REG_R0, ret)          # Set return value in R0
    mu.reg_write(UC_ARM_REG_PC, 0x105BC)       # Set PC to point at "BX LR" instruction. We want to return from fibonacci function

else:
    stack.append(arg0)                      # If return value is not saved for this argument, add it to stack.

elif address == CCC_END:
    arg0 = stack.pop()                     # We know arguments when exiting the function

    ret = mu.reg_read(UC_ARM_REG_R0)        # Read the return value (R0)
    d[arg0] = ret                          # Remember the return value for this argument

mu.hook_add(UC_HOOK_CODE, hook_code)
mu.emu_start(0x00010584, 0x000105A8)
return_value = mu.reg_read(UC_ARM_REG_R1)      # We end the emulation at printf("%d\n", ccc(x)).
print "The return value is %d" % return_value

```

关键点，用一个数组存储了参数：返回值 对，从而规避一些冗余的运算。

参考

<http://eternal.red/2018/unicorn-engine-tutorial/>

来源：<https://www.cnblogs.com/hac425/p/9416898.html>