TOWARDS A GENERAL TEMPORAL ONTOLOGY FOR KNOWLEDGE INTEGRATION

[1]Yi Qiang, [2]Femke Reitsma and [1]Nico Van de Weghe

[1] CartoGIS Cluster, Department of Geography, Ghent University, Ghent, Belgium
[2] Department of Geography, University of Canterbury, New Zealand
yi.qiang@ugent.be, femke.reitsma@canterbury.ac.nz, nico.vandeweghe@ugent.be

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Abstract: Practically, temporal information is related to every aspect of our world. A temporal ontology may effectively negotiate the meanings between different time concepts. Though some temporal ontologies have been developed, their uses are still narrow and cannot apply into a broader range of knowledge domains. Our work aims to develop a general ontology of time which can negotiate the heterogeneities in different time conceptualizations. It is not only a framework for annotating everyday temporal terms on the Web but also lays a foundation for knowledge infrastructures with more domain-specific time concepts.

1 INTRODUCTION

Practically, temporal information can be found in every aspect in our daily life. However, heterogeneities in time conceptualizations cause ambiguities when people are exchanging time-related information. For example, if you are searching through the Web for holiday promotions this summer, errors may occur when searching from the Northern Hemisphere for countries in the Southern Hemisphere. Also, temporal information in ancient documents is recorded using different calendars and year-marking systems, which may cause misunderstandings when they are integrated together. In recent years, the development of Semantic Web and ontologies has greatly improved information sharing and interoperation in many fields such as Web Services interoperation (Traverso and Pistore 2004), knowledge management (Takeda 2004; Brodaric *et al.* 2008) and information retrieval (Jones *et al.* 2001). Many ontologies have been developed and proved their advantages in facilitating the communication between various information domains (Hiramatsu and Reitsma 2004; Bard *et al.* 2005; Raimond *et al.* 2007; Brodaric *et al.* 2008). Also, some attention has been paid to developing temporal specifications or ontologies for temporal information on the Web, such as KSL-time (Zhou and Fikes 2000), OWL-Time (Hobbs and Pan 2006), TimeML specification (Pustejovsky *et al.* 2003) and temporal parts of fundamental ontologies (Navigli *et*

al. 2003; Herre *et al.* 2006). The most complete work of temporal ontology is OWL-Time developed by Hobbs and Pan (2006), which represents the commonly-used temporal concepts as well as temporal aggregates composed of simple time entities. OWL-Time restricted to temporal concepts that are frequently used in Web content and Web Services, but is insufficient in representing time concepts in some particular domains such as archaeology, geology and music.

The goal of our work is building a General Temporal Ontology (GTO) in order to overcome this problem. The idea of GTO is similar to that of most fundamental ontologies (e.g. DOLCE[1], BFO[2], GFO[3], SUMO[4]) which attempt to describe very general concepts that are the same across all domains. These fundamental ontologies are designed for integrating heterogeneous knowledge coming from different sources, most of which already involve very basic temporal portions. Similarly, GTO is also built at the most general level of abstraction, but particularly for time conceptualizations (Figure 1). In other words, GTO can be understood as a temporal portion of a fundamental ontology. With GTO, heterogeneous temporal semantics can be negotiated. Extensions or sub-ontologies can be developed from it in order to

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[1] http://www.loa-cnr.it/DOLCE.html
[2] http://www.ifomis.org/bfo
[3] http://www.onto-med.de/ontologies/gfo/
[4] http://www.ontologyportal.org/

annotate domain-specific time concepts. Since the goal of our work is implementing GTO with the most prevalent ontology language (i.e. OWL), the expressiveness of the ontology is restricted to Description Logic.
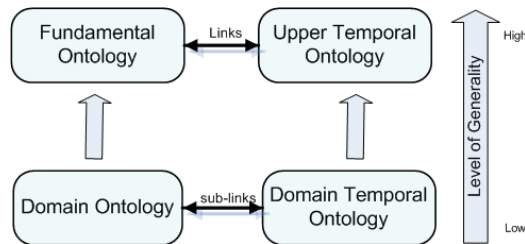

Figure 1: GTO plays similar role as fundamental ontologies.

The paper is structured as follows: the paper starts with introducing the basic theories and general taxonomy of GTO. And then some issues in GTO have been discussed specifically. Finally, conclusions are drawn and future work is pointed out.

2 BASICS OF GTO

2.1 Time Theory Adopted by GTO

Two of the most fundamental questions in building a temporal ontology are choices of time models and time primitives. Considering the purpose of GTO is annotating temporal information rather than answering complex temporal queries, GTO puts more emphasis on the representation of temporal semantics than maintaining reasoning inconsistencies. GTO is mainly based on the linear model of time. Cyclic time concepts (such as month, season, day etc.) are viewed as recurring concepts on the infinite time line. For example, in the sentence 'flowers bloom in spring', 'spring' is treated as a period that regularly reoccurs every year, which is a kind of non-convex time region in GTO.

In terms of time primitives, GTO adopts both time instant and time interval. The relation and distinction between time interval and instance are always controversial. In one view, a time instant is considered as an infinitesimal point which is only used in dividing two time intervals. In the other view, whether a time region is viewed as an instant or an interval is a granularity decision that may vary according to the context of use. A time instant is undividable and occupies the minimum time unit under a certain granularity, while a time interval is a

dividable segment of time line and contains more than one instant. GTO adopts the latter view because people prefer to use time instants to describe those instantaneous events such as shooting a gun, turning off a light. An interval starts at an instant and ends at an instant, which are called beginning point and end point respectively. In other words, an interval is defined by two instants. This time theory may cause inconsistencies in temporal reasoning such as Divided Instant Problem (DIP) but is more expressive in representing temporal semantics in the natural language.

2.2 Taxonomy of GTO

In many fundamental ontologies (e.g. DOLCE and BFO), time entities are viewed as regions in time space, which is the root of temporal concepts. Convex region and non-convex region are the most general classes of time regions. Convex regions are connected and have no gap in it. Non-convex regions are not connected regions with gaps in it, which can be further categorized into regular non-convex regions and irregular non-convex regions. Non-convex regions are useful in representing time concepts like 'the opening hour of the clinic is 9am to 6pm, from Monday to Friday'. All cyclic time concepts can be represented by regular non-convex regions, for example, every spring, every Monday. Irregular non-convex regions are used to describe irregularly scattered time regions. Each temporal region may be described by one or more temporal descriptions. The general taxonomy of GTO is illustrated in the form of UML diagram (Figure 2). With UML diagram, not only the hierarchy of the ontology is shown, properties, objects of properties and cardinalities are also shown. Take *Instant* as an example, the upper part of the box contains the title of the class (i.e. *Instant*), the lower part of the box contains its properties (*DescribedBy*) and the object class (*TemporalDescription*). The number in [] denotes the cardinality of properties. For example, [1] denotes that the property has one objects and [1..] denotes that the property has at least one objects. For saving space, the diagram only displays some important properties of classes.

3 ISSUES IN REPRESENTING TEMPORAL SEMANTICS

GTO aims to providing a general and widely-applicable framework for representing temporal
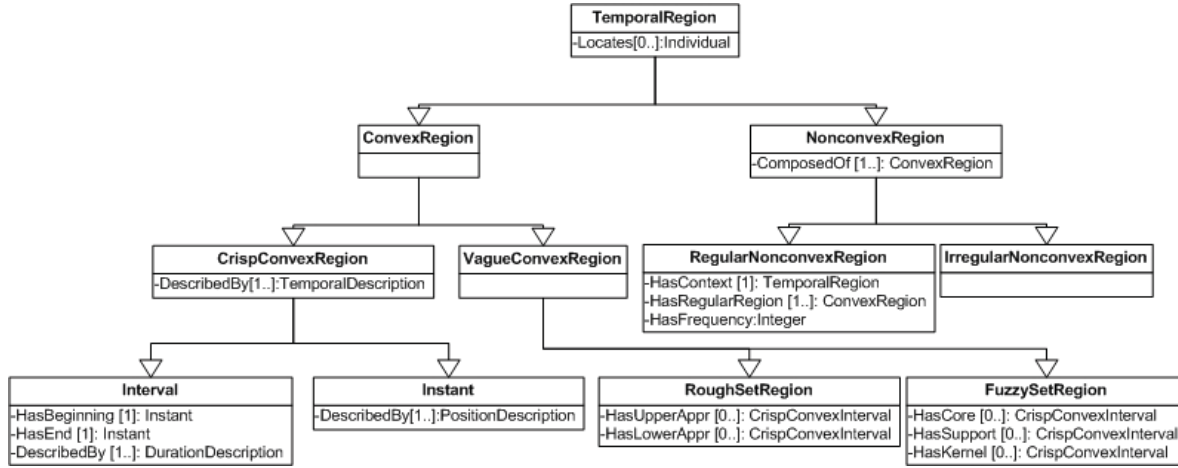
Figure 2: General taxonomy of the temporal ontology.

semantics. We have attempted to make GTO adoptable to temporal concepts in a broad range of domains. We adopted merits from relevant work (e.g. KIF-Time, OWL-Time and fundamental ontologies), but also posed our solutions on some issues (e.g. time description, non-convex regions, vague time regions and links between time and other individuals). This section discusses about how GTO solves these specific issues.

3.1   Time Description

Position and duration are the two main properties of time regions. These two properties can be described differently. For instance, 'the first Monday in 2009' and '5th January 2009' actually point to the same day; '7 days' and '1 week' are intervals of the same length. Similar to OWL-Time, we defined a class of temporal descriptions to describe time position and duration (Equation 1). In this way, time regions may have diverse position or duration descriptions. We only create the description class for crisp convex region (i.e. instant and interval) because all other time regions can be described by instant and interval descriptions in some ways. Instants have position descriptions but no duration description (Equation 2). Intervals have duration descriptions but no position description (Equation 3). The positions of intervals are derived from position descriptions of their beginning   and   end   instants.   Class *TemporalDescription* uses integer data properties to describe time regions. For example, in Figure 2 the *ISPositionDescription* (i.e. international standard time position description) uses properties such as *Year*, *Month*, *Date* and so on to describe time positions. For instance, 1st Jan 2009 can be represented as [Year (2009), Month (1), Date (1)].

However, if you look at some ancient text in China, time positions and durations are described differently from that in western world. GTO is also open for adding classes for such special time descriptions. Additionally, each position description has a property *HasGranularity* to denote the granularity of the instant.

$$Describes(D, T) \equiv DescribedBy(T, D) \tag{1}$$

$$\forall(i)Instant(i) \equiv \exists(p)[DescribedBy(i, p) \wedge \tag{2}$$
$$PositionDescription(p)]$$

$$\forall(I)Interval(I) \equiv \exists(d)[DescribedBy(I, d) \wedge \tag{3}$$
$$DurationDescription(d)]$$

Most time regions can be located in the absolute time line of the real world, in the most common knowledge, started from the Big Bang and flowing to the infinite future. But there are some exceptions. For example, when we say there is a drum beat at the 13th second in a music track, it is impossible to locate the drum beat in the time line of the world. Therefore, we defined a class of time lines where position descriptions can be located (Equation 4). Instances of Class *TimeLine* could be the time line in a music track, a workflow of automatic control or the 90 minutes of a football game. Then we are able to express the temporal semantics in the sentence like 'the rocket discard its fuel container at the 15th minute after fire' or 'the manager usually substitutes the No.10 player at the 75 minute in a football game'. Here actions take place in the time line of the rocket launching process or the football game.

The taxonomy of temporal descriptions is illustrated in   Figure   3.   *ISDurationDescription*   and *ISPositionDescription*   stand   for   international standard time duration description and international standard   time   position   description   respectively.

More parallel subclasses can be developed at the same level in order to describe time durations and positions in diverse time systems.

$$(\forall d)[PositionDescription(d) \rightarrow$$
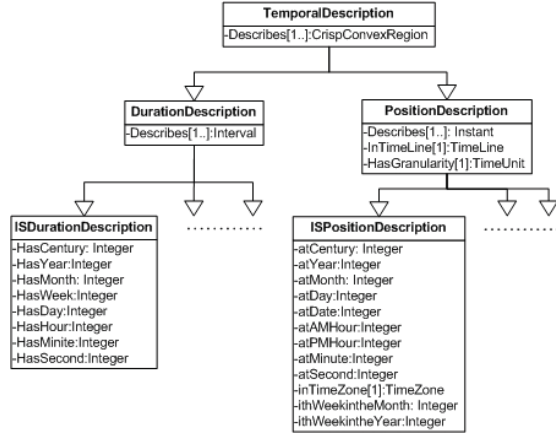$$(\exists s)[InTimeLine(d,s) \wedge TimeLine(s)]] \qquad (4)$$

Figure 3: The sub-ontology of time descriptions.

3.2 Temporal Relations

In GTO, temporal relations are represented as properties between classes. Because we take account of the time granularity, the temporal relations between time regions under different granularity are getting complicated. For example, two instants can only be equal when they not only have the same position but also have the same granularity (Equation 5). More complicated situations may arise for other relations. Considering the purpose of GTO is not performing complex reasoning about temporal relations, we only represent temporal relations as properties between time regions but have not given complete definitions. This task will be left in the future work. The thirteen relations between interval and interval are based on Allen's model (Allen 1983). Additionally, three relations (before, equal and after) are defined between instants and instants, eight relations (before, starts, during, finishes, after and the inverse ones) are defined between instant and interval.

$$Instant(i_1) \wedge Instant(i_2) \wedge Equal(i_1,i_2) \equiv$$
$$HasDescription(i_1,d_1) \wedge PositionDescription(d_1) \wedge$$
$$HasDescription(i_2,d_2) \wedge PositionDescription(d_2) \wedge$$
$$(d_1 = d_2) \wedge HasGranularity(i_1,g_1) \wedge \qquad (5)$$
$$HasGranularity(i_2,g_2) \wedge (g_1 = g_2)$$

3.3 Non-Convex Time Regions

Non-convex time regions have gaps in them. In other words, non-convex time regions are composed of many convex time regions. Hobbs (2006) also proposed representations for this kind of temporal regions (called temporal aggregate in his work). However, the representation in GTO is simpler but more expressive. Non-convex time regions are categorised into regular non-convex regions and irregular non-convex regions. Zhou and Fikes (2000) also used this distinction but gave no concrete representation for them. Irregular non-convex regions are composed of irregularly scattered convex regions. To the contrary, regular non-convex intervals are composed of regularly scattered regions, for example, 'every Monday in May of 2009' and 'every Christmas'. In GTO, a regular non-convex region consists of a regular region and a context region. The regular region is the regularly recurring region, while the context region is the range in which the regular region is recurring. Taking 'every Monday during May 2009' as an example, 'every Monday' is the regular region recurring in the context region 'May 2009'. The frequency of the regular region is set by a float data property (i.e. *HasFreqency*). This property is used to describe the semantics like 'every other Monday in May of 2009' where the frequency of the regular region is 0.5. There may be more than one regular region in a context region, for example, 'every Monday, Wednesday and Friday in May 2009'. Additionally, context regions can be convex intervals or non-convex intervals. Non-convex context regions are used to represent nested regular non-convex intervals such as 'every Monday in May'. Here, May (actually means May every year) is the context which itself is a regular non-convex interval. Non-convex regions can be described on the basis of convex regions. Thus we did not create a description class especially for non-convex regions. Following is pseudocode of "every Monday in May".

```
EveryMondayinMay
    Type: RegularNonconvexRegion
    HasRegularRegion: Monday
    HasContextRegion: EveryMay
    HasFrequency: "1"
EveryMay
    Type: RegularNonconvexRegion
    HasRegularRegion: May
    HasContextRegion: Null
    HasFrequency: "1"
May
    Type: Interval
    HasDescription: 1Month
```

```
HasEnd: EndofMay
HasBeginning: BeginningofMay
```

3.4 Vague Time Intervals

Many domains (geology, history and geography) are faced with the problem of having vague temporal information. In these cases, instants have no precise position and intervals have no precise beginning and end. This may also refer to the granularity issue. A crisp time interval may become vague when the working context shifts from a coarser granularity to a finer granularity. In GTO, the class of vague convex regions is used for representing the vague temporal information (Figure 2). Rough set (Pawlak 1982) and fuzzy set (Zadeh 1965; Pawlak 1982) are currently the most frequently used theories in dealing with vague temporal information. The main difference between them is that fuzzy set has gradually-changing confidence (between 0 and 1) according to a function while rough set only has triplex value (0, 1 or uncertain). In GTO rough set regions have properties such as upper approximation, lower approximation whilst fuzzy set regions have properties such as core, support and kernel (Figure 2).

3.5 Linking Time and Individuals

Because temporal information only makes sense when it is associated with atemporal individuals (e.g. process, event or object), it is important to formalise the links between time and individuals. Currently, most fundamental ontologies accept the distinction between endurant individuals and perdurant individuals, which are called differently in fundamental ontologies (Table 1). The difference between endurants and perdurants derives from their relations to time (Bittner *et al.* 2004). Endurants are wholly present at any time they are present, for example, a book, a lake. Perdurants are wholly present at any time they are present but extend in time by accumulating different time parts (Navigli *et al.* 2003), for example, a war, a storm. All individuals are located in time regions that are similar to spatial locations in the physical space. In most fundamental ontologies, there is a basic link between time and individuals (Table 1). For example, GFO and SUMO only defines the most general link between time and individual. DOLCE views time as a subtype of quality like colour, size or weight. This representation is unintuitive and also problematic because other qualities also (e.g. colour, size) exist in time. In our view, both endurants and perdurants are located in time regions. More specifically, endurants are wholly present during intervals or present at instants, whilst perdurants persist during intervals (e.g. state, process) or happen at instants (e.g. event, changes). All other specific links between time and individuals can be developed from them.

Table 1: Distinction of Individuals in Fundamental Ontologies.

Fundamental Ontology	Perduring Individual	Enduring Individual	Links between Time and Individuals
DOLCE	Perdurant	Endurant	has-quality (individuals, temporal-quality) q-location (temporal-quality, temporal region)
GFO	Process	Persential	project-to (entities, temporal region)
BFO	Occurrent	Continuant	N/A
SUMO	Process	Object	when (Individuals, Time)

4 CONCLUSIONS AND FUTURE WORK

This paper sketched GTO, which is a framework of an upper ontology for temporal concepts. We integrated merits from existing temporal ontologies but also proposed our view on some specific issues (general taxonomy, time description and non-convex region, granularity and vague time intervals). Compared with existing temporal ontologies, GTO aims to provid a more complete framework of time abstraction that can be applied into in a broad range of domains. It not only can annotate everyday temporal terms on the Web, but can also be further extended for temporal concepts in particular domains such as history, geography and archeology. Thus, GTO may be useful in a knowledge infrastructure which stores temporal information in different time systems, for example, cooperating with the SKI ontology (Brodaric *et al.* 2008). GTO emphasizes on the representation of more complete temporal semantics but ignores some reasoning problems such as granularity and topological relations.

In the next step, more work is needed for improving the GTO ontology, including defining temporal relations, representing more complex non-convex regions and coupling GTO with fundamental ontologies. Additionally, some use cases will be developed to assess the utility of GTO in negotiating different temporal semantics. Its applications in knowledge management will be further studied, which may lay a foundation for a temporally robust knowledge infrastructure.

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