Dan Qiao

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EDUCATION

PhD student, Computer Science Sep. 2022 - Present Shenzhen, China Chinese University of Hong Kong, Shenzhen Master of Science, Automotive Engineering Sep. 2018 – Jul. 2021 Beijing University of Aeronautics and Astronautics | GPA: 3.6 Beijing, China Bachelor of Science, Automotive Engineering Sep. 2014 – Jul. 2018 Beijing University of Aeronautics and Astronautics | GPA: 3.2 Beijing, China

Internship

RL Researcher Dec. 2024 - Present

Moza Racing Company, working on building distributed training clusters for SAC in racing games. Shenzhen, China

RA, Computer Science

Sep. 2021 – June. 2022

Chinese Academy of Science, Institute of Automation, working on privacy-preserving MARL.

Beijing, China

Publications & Preprints

D. Qiao, W. Li, S. Yang, H. Zha, B. Wang*, Beyond Value Decomposition: Constraining Multi-Modality in Offline Multi-Agent Reinforcement Learning via Score Decomposition, Preprint, 2025.

W. Li, D. Qiao, B. Wang, X. Wang, B. Jin, H. Zha*, Semantically Aligned Task Decomposition in Multi-Agent Reinforcement Learning, Preprint, arXiv:2305.10865. 2023.

D. Qiao, J. Zhang*, Y. Zhang, S. Xiao, H. Chen, Privacy-preserved Fully Decentralized Multi-agent Reinforcement Learning for Networked Social Systems, Draft & Patent. 2022.

D. Qiao, G. Wen, Z. Peng*, Novel Saturated Nussbaum-type Function based Adaptive Distributed Consensus Control of Multi-agent Systems with Unknown Arbitrary Control Directions, Preprint, arXiv:2201.09453. 2021.

S. Yang, Y. Hua, D. Qiao, Y. Lian, Y. Pan*, Y. He, A coupled electrochemical-thermal-mechanical degradation modelling approach for lifetime assessment of lithium-ion batteries, Electrochimica Acta, vol. 326, 2020.

Research Experience

Diffusion Models in Offline MARL

Diffusion Models, Offline MARL

• Recognizing the behavior policy infactorization property in multi-modality offline MARL datasets. Developing offline policy decomposition methods with diffusion models to handle the OOD joint policy distribution problems.

Dec. 2023 - Jan. 2025

Mar. 2023 - Oct. 2023

Semantically Aligned Task Decomposition in MARL

MARL, Language Model-based Subgoal Generation, Credit Assignment

• Leveraging Pretrained Language Models prompting with Chain of Thought (CoT) to articulate potential task goals and facilitate goal decomposition. Incorporate language-grounded RL to train each agent's goal-conditioned policy with self-reflection mechanism to re-planning.

Differential Privacy Preserved Decentralized MARL for Social Networked SystemsNov. 2021 – Mar. 2022 Fully Decentralized MARL, Differential Privacy, Social Foundation Systems

• Introduce the Laplace noise-based Differential Privacy technique into the QD-Learning to protect the Q-value which may be associated with the agent's privacy information. Provide the theoretical boundary analysis with mean square convergence and expectation convergence of the Q-value.

Nussbaum Functions based Formation Control with Unknown Control Directions July 2020 – Apr. 2021 Unknown Actuator Failures and Nonlinearities, Control Theory

Propose a novel lemma of Nussbaum-type functions to overcome the limitation of the identical unknown control directions assumptions and control shock. Designed a distributed control algorithm for the consensus problem of multi-agent system with Lyapunov stability analysis.

Other Minor Topics

Social Dilemmas, Opinion Dynamics, Multi-agent Consensus Control

- Learning direct reciprocity and indirect reciprocity to coordinate among independent learning MARL algorithms.
- Consensus of opinion-dynamics in social systems.
- Observer-based distributed sliding mode formation tracking control of multiple vehicles. (Master Degree Thesis)

SKILLS & INTEREST