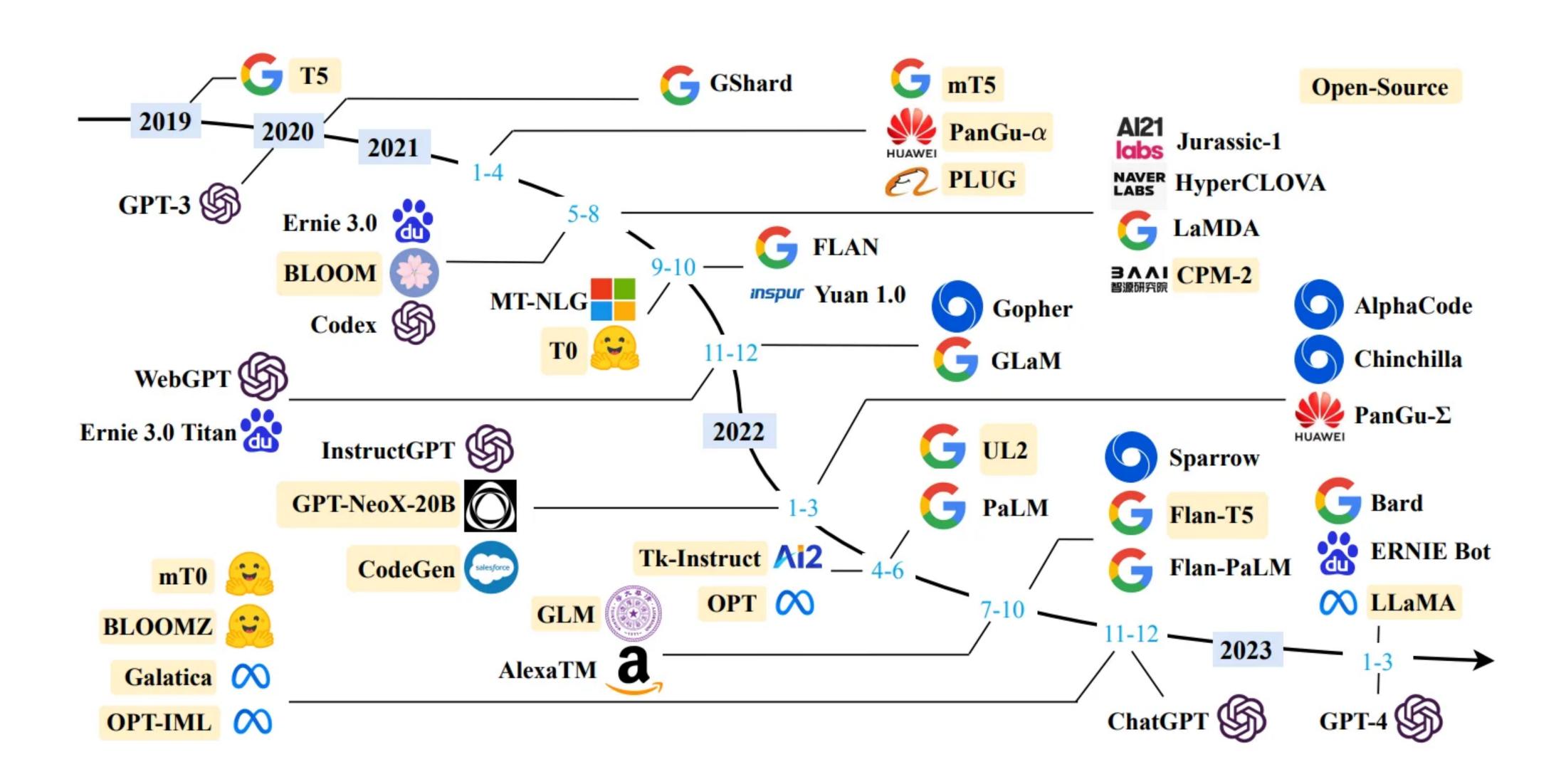
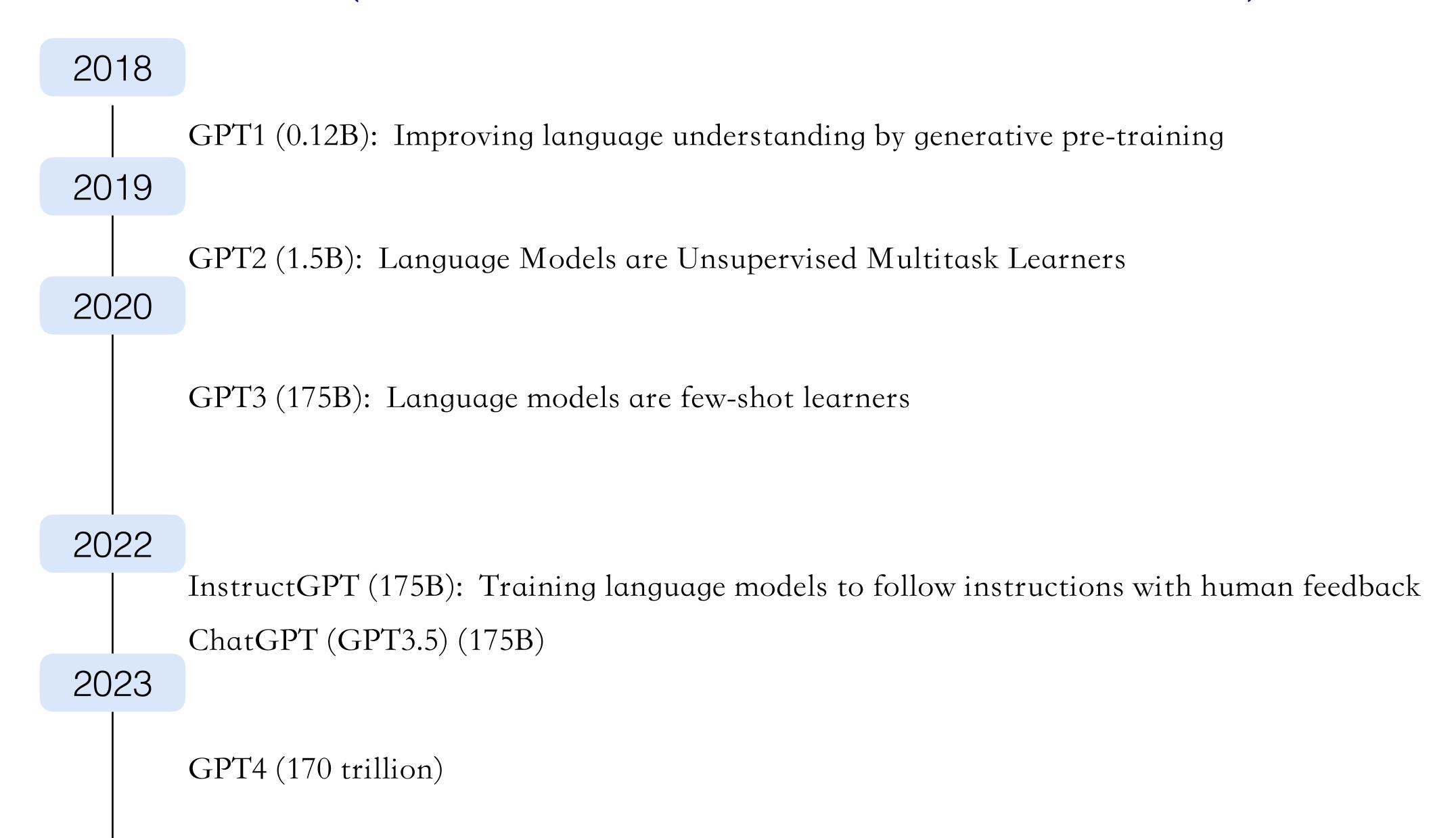
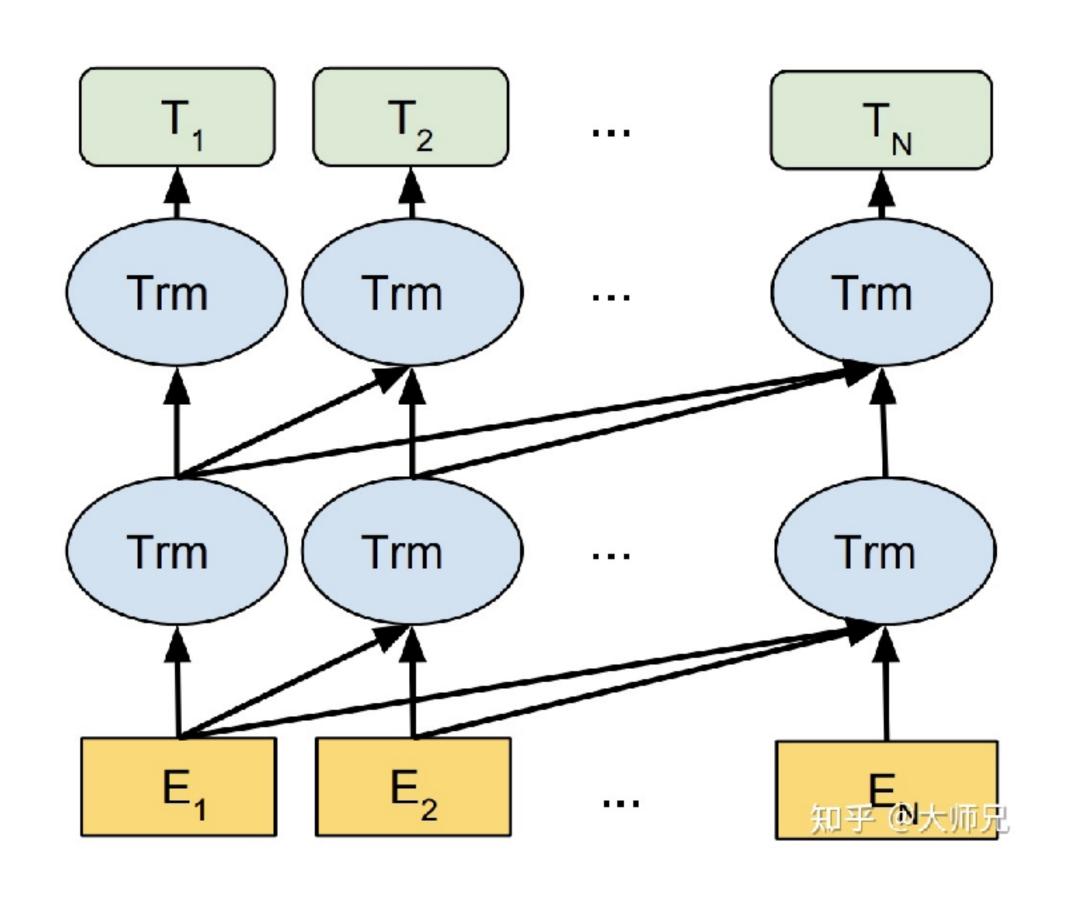
LLM (Large Language Models)



GPT (Generative Pre-Trained Transformer)



GPT (Generative Pre-Trained Transformer)



$$L_1(\mathcal{U}) = \sum_{i} \log P(u_i|u_{i-k}, \dots, u_{i-1}; \Theta)$$

GPT1:

Unsupervised generative pre-training

GPT2:

Zero-shot learning

GPT3:

In-context learning

InstructGPT:

Instruct-tuning with RLHF

An Example of ChatGPT

In the following sample, ChatGPT asks the clarifying questions to debug code.

User this code is not working like i expect — how do i fix it?

```
resultWorkerErr := make(chan error)
defer close(resultWorkerErr)
go func() {
    defer cancel()
    resultWorkerErr <- b.resultWorker(ctx)
}()

err := b.worker(ctx)
cancel()
if err == nil {
    return <-resultWorkerErr
}
return multierror.Append(err, <-resultWorkerErr)</pre>
```

It's difficult to say what's wrong with the code without more context. Can you provide more information about what the code is supposed to do and what isn't working as expected? Also, is this the entire code or just a part of it?

User just part of it — the error never surfaces. I think there is something wrong with the channel

It's difficult to say without more information about what the code is supposed to do and what's happening when it's executed. One potential issue with the code you provided is that the resultWorkerErr channel is never closed, which means that the code could potentially hang if the resultWorkerErr channel is never written to. This could happen if b.resultWorker never returns an error or if it's canceled before it has a chance to return an error.

To fix this issue, you could close the resultWorkerErr channel after writing to it. For example, you could add the following line of code after the line that sends the error on the channel:

close(resultworkerErr)

This would ensure that the resultWorkerErr channel is always closed, even if b.resultWorker never returns an error. Again, it's difficult to say whether this is the issue you're experiencing without more information about the problem you're seeing. Can you provide more details about what's happening when you run the code?

InstructGPT

Training language models to follow instructions with human feedback

Long Ouyang* Jeff Wu* Xu Jiang* Diogo Almeida* Carroll L. Wainwright*

Pamela Mishkin* Chong Zhang Sandhini Agarwal Katarina Slama Alex Ray

John Schulman Jacob Hilton Fraser Kelton Luke Miller Maddie Simens

Amanda Askell[†] Peter Welinder Paul Christiano*[†]

Jan Leike* Ryan Lowe*

OpenAI

Method

Language Models

Align with

Human Intentions

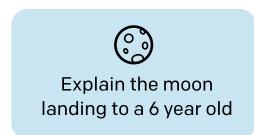
具体方法: Finetune language models with human feedback

Workflow

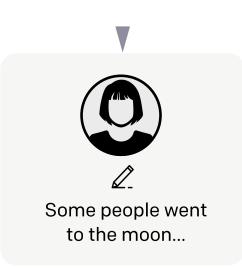
Step 1

Collect demonstration data, and train a supervised policy.

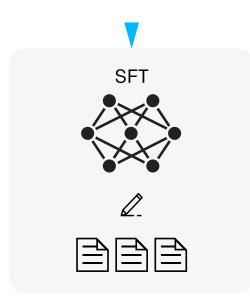
A prompt is sampled from our prompt dataset.



A labeler demonstrates the desired output behavior.



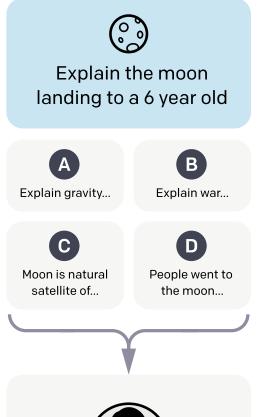
This data is used to fine-tune GPT-3 with supervised learning.



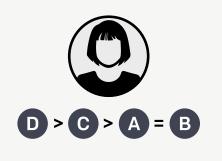
Step 2

Collect comparison data, and train a reward model.

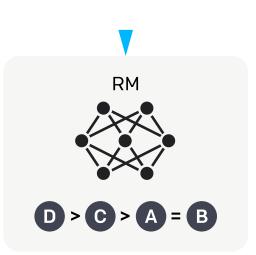
A prompt and several model outputs are sampled.



A labeler ranks the outputs from best to worst.



This data is used to train our reward model.



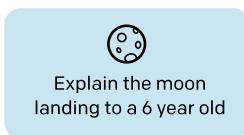
Step 3

Optimize a policy against the reward model using reinforcement learning.

Step 1

Collect demonstration data, and train a supervised policy.

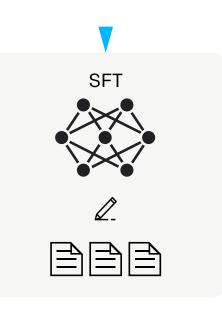
A prompt is sampled from our prompt dataset.



A labeler demonstrates the desired output behavior.



This data is used to fine-tune GPT-3 with supervised learning.



Workflow

Step 1: Collect demonstration data, and train a supervised policy.

- Labelers demonstrate desired behavior on input prompts.
- Pretrained GPT-3 model is fine-tuned using supervised learning on this data.

Workflow

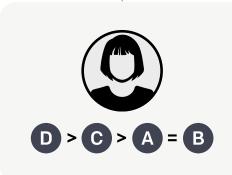
Step 2

Collect comparison data, and train a reward model.

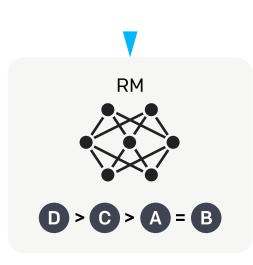
A prompt and several model outputs are sampled.



A labeler ranks the outputs from best to worst.



This data is used to train our reward model.



Step 2: Collect comparison data, and train a reward model.

- Collect dataset of model output comparisons.
- Labelers indicate preferred output for a given input.
- Train reward model to predict human-preferred output.

Workflow

Step 3

Optimize a policy against the reward model using reinforcement learning.

Step 3: Optimize a policy against the reward model using Proximal Policy Optimization (PPO).

- Utilize RM output as scalar reward.
- Fine-tune supervised policy with PPO algorithm to optimize reward.

Self-supervised
Fine-tuning (SFT)

Models

- Fine-tune GPT-3 on labeler demonstrations.
 - Trained for 16 epochs
 - Use cosine learning rate decay
 - Residual dropout of 0.2
- Choose the final SFT model based on the RM score on the validation set.
- More epochs enhance RM score and human preference ratings, despite overfitting.

Reward Model (RM)

Models

- Labelers rank the output of SFT model from high to low.
- Based on SFT model with final unembedding layer removed, train the reward model.
- The reward model takes prompt and rank as input, and output scalar reward.

Pairwise ranking loss

$$loss(\theta) = -\frac{1}{\binom{K}{2}} E_{(x,y_w,y_l)\sim D} \left[log\left(\sigma\left(r_{\theta}\left(x,y_w\right) - r_{\theta}\left(x,y_l\right)\right)\right)\right]$$

 $r_{\theta}(x,y)$ Scalar output of the reward model for prompt x and answer y

Models

Proximal Policy Optimization (PPO)

PPO

objective
$$(\phi) = E_{(x,y) \sim D_{\pi_{\phi}^{\text{RL}}}} \left[r_{\theta}(x,y) - \beta \log \left(\pi_{\phi}^{\text{RL}}(y \mid x) / \pi^{\text{SFT}}(y \mid x) \right) \right] + \gamma E_{x \sim D_{\text{pretrain}}} \left[\log (\pi_{\phi}^{\text{RL}}(x)) \right]$$

Reinforce Learning

$$\pi_{\phi}^{\mathrm{RL}}$$
 Learned RL policy

 π^{SFT} Supervised trained model

Models

Proximal Policy Optimization (PPO)

objective
$$(\phi) = E_{(x,y) \sim D_{\pi_{\phi}^{\text{RL}}}} \left[r_{\theta}(x,y) - \beta \log \left(\pi_{\phi}^{\text{RL}}(y \mid x) / \pi^{\text{SFT}}(y \mid x) \right) \right] + \gamma E_{x \sim D_{\text{pretrain}}} \left[\log (\pi_{\phi}^{\text{RL}}(x)) \right]$$
Origin GPT3 objective

$$\pi_{\phi}^{\mathrm{RL}}$$
 Learned RL policy

 π^{SFT} Supervised trained model

Reinforce Learning