Self-Driving Car Engineer Nanodegree

Deep Learning

Project: Build a Traffic Sign Recognition Classifier

In this notebook, a template is provided for you to implement your functionality in stages, which is required to successfully complete this project. If additional code is required that cannot be included in the notebook, be sure that the Python code is successfully imported and included in your submission if necessary.

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the iPython Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to \n", "**File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there is a writeup to complete. The writeup should be completed in a separate file, which can be either a markdown file or a pdf document. There is a <u>write up template (https://github.com/udacity/CarND-Traffic-Sign-Classifier-Project/blob/master/writeup_template.md)</u> that can be used to guide the writing process. Completing the code template and writeup template will cover all of the <u>rubric points (https://review.udacity.com/#!/rubrics/481/view)</u> for this project.

The <u>rubric (https://review.udacity.com/#!/rubrics/481/view)</u> contains "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. The stand out suggestions are optional. If you decide to pursue the "stand out suggestions", you can include the code in this lpython notebook and also discuss the results in the writeup file.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. In addition, Markdown cells can be edited by typically double-clicking the cell to enter edit mode.

Step 0: Load The Data

```
In [1]: # Load pickled data
import pickle

# TODO: Fill this in based on where you saved the training and testing data

training_file = 'traffic-signs-data/train.p'
    validation_file = 'traffic-signs-data/valid.p'
    testing_file = 'traffic-signs-data/test.p'

with open(training_file, mode='rb') as f:
        train = pickle.load(f)
    with open(validation_file, mode='rb') as f:
        valid = pickle.load(f)

with open(testing_file, mode='rb') as f:
        test = pickle.load(f)

X_train, y_train = train['features'], train['labels']
    X_valid, y_valid = valid['features'], valid['labels']
    X_test, y_test = test['features'], test['labels']
```

Step 1: Dataset Summary & Exploration

The pickled data is a dictionary with 4 key/value pairs:

- 'features' is a 4D array containing raw pixel data of the traffic sign images, (num examples, width, height, channels).
- 'labels' is a 1D array containing the label/class id of the traffic sign. The file signnames.csv contains id -> name mappings for each id.
- 'sizes' is a list containing tuples, (width, height) representing the original width and height the image.
- 'coords' is a list containing tuples, (x1, y1, x2, y2) representing coordinates of a bounding box around the sign in the image. THESE COORDINATES ASSUME THE ORIGINAL IMAGE. THE PICKLED DATA CONTAINS RESIZED VERSIONS (32 by 32) OF THESE IMAGES

Complete the basic data summary below. Use python, numpy and/or pandas methods to calculate the data summary rather than hard coding the results. For example, the <u>pandas shape method</u> (http://pandas.pydata.org/pandas-docs/stable/generated/pandas.DataFrame.shape.html) might be useful for calculating some of the summary results.

Provide a Basic Summary of the Data Set Using Python, Numpy and/or Pandas

Out[3]: 4410

```
In [2]: ### Replace each question mark with the appropriate value.
        ### Use python, pandas or numpy methods rather than hard coding the results
        import numpy as np
        # TODO: Number of training examples
        n_train = X_train.shape[0]
        # TODO: Number of validation examples
        n_validation = X_valid.shape[0]
        # TODO: Number of testing examples.
        n_test = X_test.shape[0]
        # TODO: What's the shape of an traffic sign image?
        image_shape = X_train.shape[1:]
        # TODO: How many unique classes/labels there are in the dataset.
        n_classes = len(set(y_train))
        print("Number of training examples =", n train)
        print("Number of testing examples =", n_test)
        print("Image data shape =", image_shape)
        print("Number of classes =", n_classes)
        Number of training examples = 34799
        Number of testing examples = 12630
        Image data shape = (32, 32, 3)
        Number of classes = 43
In [3]: n validation
```

Include an exploratory visualization of the dataset

Visualize the German Traffic Signs Dataset using the pickled file(s). This is open ended, suggestions include: plotting traffic sign images, plotting the count of each sign, etc.

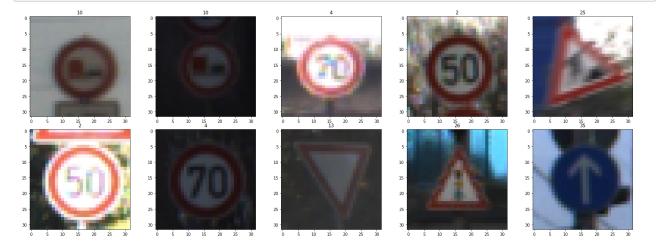
The <u>Matplotlib (http://matplotlib.org/) examples (http://matplotlib.org/examples/index.html)</u> and gallery (http://matplotlib.org/gallery.html) pages are a great resource for doing visualizations in Python.

NOTE: It's recommended you start with something simple first. If you wish to do more, come back to it after you've completed the rest of the sections. It can be interesting to look at the distribution of classes in the training, validation and test set. Is the distribution the same? Are there more examples of some classes than others?

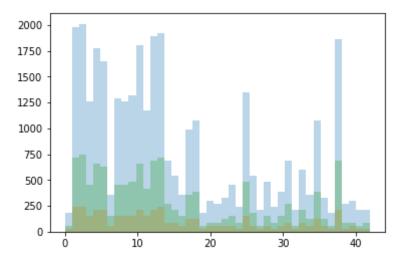
```
In [4]: ### Data exploration visualization code goes here.
### Feel free to use as many code cells as needed.
import matplotlib.pyplot as plt
import numpy as np
# Visualizations will be shown in the notebook.
%matplotlib inline
```

```
In [5]: # Draw some random traffic signs from the training set
    import random
    fig, axes = plt.subplots(2,5, figsize = (22,8))
    fig.tight_layout()
    axes = axes.ravel()

#i_label = []
for i in range(len(axes)):
    rand_fig_index = random.randint(0, len(X_train))
    j = y_train[rand_fig_index]
    #if j not in i_label:
    image = X_train[rand_fig_index]
    axes[i].imshow(image)
    axes[i].set_title(j)
    #i_label.append(j)
```



```
In [6]: # Plot different classes as histogram
   kwargs = dict(alpha=0.3, bins=n_classes)
   plt.hist(y_train, **kwargs)
   plt.hist(y_valid, **kwargs)
   plt.hist(y_test, **kwargs)
   plt.show()
```



Step 2: Design and Test a Model Architecture

Design and implement a deep learning model that learns to recognize traffic signs. Train and test your model on the <u>German Traffic Sign Dataset (http://benchmark.ini.rub.de/?section=gtsrb&subsection=dataset)</u>.

The LeNet-5 implementation shown in the classroom. <a href="(https://classroom.udacity.com/nanodegrees/nd013/parts/fbf77062-5703-404e-b60c-95b78b2f3f9e/modules/6df7ae49-c61c-4bb2-a23e-6527e69209ec/lessons/601ae704-1035-4287-8b11-e2c2716217ad/concepts/d4aca031-508f-4e0b-b493-e7b706120f81)) at the end of the CNN lesson is a solid starting point. You'll have to change the number of classes and possibly the preprocessing, but aside from that it's plug and play!

With the LeNet-5 solution from the lecture, you should expect a validation set accuracy of about 0.89. To meet specifications, the validation set accuracy will need to be at least 0.93. It is possible to get an even higher accuracy, but 0.93 is the minimum for a successful project submission.

There are various aspects to consider when thinking about this problem:

- Neural network architecture (is the network over or underfitting?)
- Play around preprocessing techniques (normalization, rgb to grayscale, etc)
- Number of examples per label (some have more than others).
- · Generate fake data.

Here is an example of a <u>published baseline model on this problem</u> (http://yann.lecun.com/exdb/publis/pdf/sermanet-ijcnn-11.pdf). It's not required to be familiar with the approach used in the paper but, it's good practice to try to read papers like these.

Pre-process the Data Set (normalization, grayscale, etc.)

Minimally, the image data should be normalized so that the data has mean zero and equal variance. For image data, (pixel - 128) / 128 is a quick way to approximately normalize the data and can be used in this project.

Other pre-processing steps are optional. You can try different techniques to see if it improves performance.

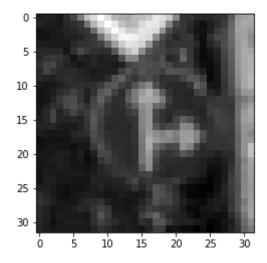
Use the code cell (or multiple code cells, if necessary) to implement the first step of your project.

```
In [7]: ### Preprocess the data here. It is required to normalize the data. Other pa
### converting to grayscale, etc.
### Feel free to use as many code cells as needed.
```

```
In [8]: # RGB images into grayscale
import tensorflow as tf
def rgbtogray(images):
    with tf.Session() as sess:
        images_coverted = sess.run(tf.image.rgb_to_grayscale(images))
    return images_coverted
```

```
In [9]: # Testing the function rgbtogray
img = rgbtogray(X_train[1000])
print(img.shape)
plt.imshow(np.squeeze(img), cmap='gray')
plt.show()
```

(32, 32, 1)



```
In [10]: X_train = rgbtogray(X_train)
    X_valid = rgbtogray(X_valid)
    X_test = rgbtogray(X_test)
    print ('rbg to grayscale done!')
```

rbg to grayscale done!

```
In [11]: # Normalize the data

X_train = X_train - np.mean(X_train)
X_valid = X_valid - np.mean(X_valid)

X_test = X_test - np.mean(X_test)
print ('Normalization done!')
```

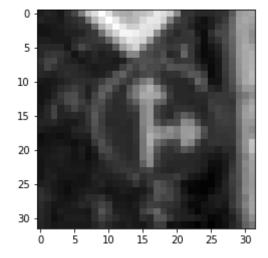
Normalization done!

```
In [12]: # Image augmentation, getting more training image data
```

```
In [13]: # Brightness adjustment method
def img_bright(img):
    with tf.Session() as sess:
        sess.run(tf.global_variables_initializer())
        img_randbright = sess.run(tf.image.random_brightness(img, max_delta
    return img_randbright
```

```
In [14]: img = img_bright(X_train[1000])
    plt.imshow(np.squeeze(img), cmap='gray')
```

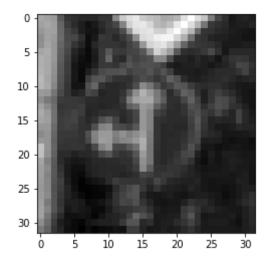
Out[14]: <matplotlib.image.AxesImage at 0x1098d2b00>



```
In [15]: # Hrizontal flipping images
    def img_hflip(img):
        with tf.Session() as sess:
            sess.run(tf.global_variables_initializer())
            img_hflip = sess.run(tf.image.flip_left_right(img))
        return img_hflip
```

```
In [16]: img = img_hflip(X_train[1000])
plt.imshow(np.squeeze(img), cmap='gray')
```

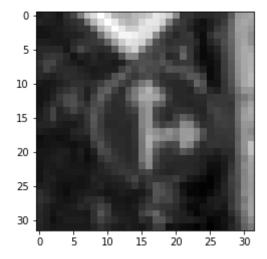
Out[16]: <matplotlib.image.AxesImage at 0x11167b278>



```
In [17]: # Contrat adjust images
def img_contrast(img):
    with tf.Session() as sess:
        sess.run(tf.global_variables_initializer())
        img_contrasted = sess.run(tf.image.random_contrast(img, lower=1, upg
    return img_contrasted
```

```
In [18]: img = img_contrast(X_train[1000])
   plt.imshow(np.squeeze(img), cmap='gray')
```

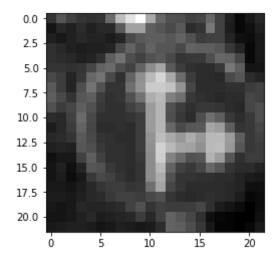
Out[18]: <matplotlib.image.AxesImage at 0x11170b4a8>



```
In [19]: # Central crop images
def img_ccrop(img):
    with tf.Session() as sess:
        sess.run(tf.global_variables_initializer())
        img_croped = sess.run(tf.image.central_crop(img, central_fraction=0.central_img_croped)
```

```
In [20]: img = img_ccrop(X_train[1000])
plt.imshow(np.squeeze(img), cmap='gray')
```

Out[20]: <matplotlib.image.AxesImage at 0x111802550>



```
In [21]: X_train.shape, y_train.shape
```

Out[21]: ((34799, 32, 32, 1), (34799,))

```
In [22]: X_train[1000].shape
```

Out[22]: (32, 32, 1)

```
# Augment the train images
In [23]:
         1.1.1
         The training data needed is 10 x 128. The average number of median sized tra
         And the upper number of validation classes is 750.
         While the lower number of the training classes is 250.
         In consideration of the sizes above, augment the lower parts of the training
         1 1 1
         1 1 1
         The brightness and contrast adjustment will be applied to all the operations
         the other one with central cropping. All these will add up to about 750 imag
         1 1 1
         def DataAug flip(images):
             images bright = img bright(images)
             images flip = img hflip(images bright)
             images_flip = img_contrast(images_flip)
             return images flip
         def DataAug crop(images):
             images bright = img bright(images)
             images_crop = img_ccrop(images_bright)
             images crop = img contrast(images crop)
             return images_crop
         X_train_aug = []
         y train aug = []
         for class n in range(1):
             pictures = np.where(y train == class n)
             samples num = len(pictures[0])
             if samples num < 500:
                  for images in range(samples num):
                      images_flipped = DataAug_flip(X_train[images])
                      #images cropped = DataAug crop(images)
                      X train aug.append(images flipped)
                      #X train aug.append(images cropped)
                      y train aug.append(class n)
                      #y train aug.append(class n)
         return X_train_aug, y_train_aug
         print ('Data augment done!')
```

Out[23]: "\ndef DataAug flip(images):\n images bright = img bright(images)\n images flip = img hflip(images bright)\n images flip = img contrast(im return images flip\n\n\ndef DataAug crop(images):\n ages flip)\n ages bright = img bright(images)\n images crop = img ccrop(images brig ht)\n images crop = img contrast(images crop)\n return images crop \n\nX_train_aug = []\ny_train_aug = []\n\nfor class_n in range(1):\n ictures = np.where(y train == class n)\n samples num = len(pictures if samples num < 500:\n for images in range(sample [0])\n \n s num):\n images flipped = DataAug flip(X train[images])\n #images cropped = DataAug crop(images)\n X train aug.a ppend(images flipped)\n #X train aug.append(images cropped)\n

```
y_train_aug.append(class_n)\n #y_train_aug.append(c
lass_n)\nreturn X_train_aug, y_train_aug\n\n \nprint ('Data au
gment done!')\n"
```

In [52]: # Data augment, two ways of data aument, take too much time to be done, used

```
if samples num <= 400:
                                        for i in range(samples_num):
                                                 img num = pictures[0][i]
                                                 image = img bright(X train[img num])
                                                 X train aug.append(image)
                                                y train aug.append(class n)
                     X_train_aug = []
                     y train aug = []
                     for class_n in range(n_classes):
                              pictures = np.where(y train == class n)
                              samples_num = len(pictures[0])
                              if samples num <= 300:
                                        for i in range(samples num):
                                                 img_num = pictures[0][i]
                                                 image = img hflip(X train[img num])
                                                 X train aug.append(image)
                                                y train aug.append(class n)
                              else:
                                       print ('Class ', class_n, ' is not augmented!')
                     #return X train aug, y train aug
                     print ('Partial Augment done!')
Out[52]: "\n
                                     if samples num <= 400:\n
                                                                                                              for i in range(samples num):\n
                                       img num = pictures[0][i]\n
                                                                                                                              image = img bright(X train
                                                                           X_train_aug.append(image)\n
                     [img num])\n
                                                                                                                                                                    y train au
                     g.append(class n)\n\nX train aug = []\ny tr
                     in range(n classes):\n pictures = np.where(y train == class n)\n
                                                                                                                                                                                       sa
                     mples_num = len(pictures[0])\n\n
                                                                                                      if samples num <= 300:\n
                     in range(samples num):\n
                                                                                                       img num = pictures[0][i]\n
                     image = img hflip(X train[img num])\n
                                                                                                                                    X train aug.append(imag
                                                                                                                                    else:\n
                                                         y train aug.append(class n)\n
                     lass ', class n, ' is not augmented!')\n#return X train aug, y train aug
                     \nprint ('Partial Augment done!')\n"
In [53]:
                     np.array(X_train_aug).shape
Out[53]: '\nnp.array(X train aug).shape\n'
  In [ ]: | X_train = np.append(X_train, X_train aug, axis=0)
                     y train = np.append(y train, y train aug, axis=0)
```

```
In [25]: X_train.shape
Out[25]: (34799, 32, 32, 1)
```

Model Architecture

 $BATCH_SIZE = 128$

keep_prob = tf.placeholder(tf.float32)

```
In [26]: ### Define your architecture here.
### Feel free to use as many code cells as needed.

In [27]: # Shuffle the training data set
    from sklearn.utils import shuffle
    X_train, y_train = shuffle(X_train, y_train)

In [28]: # Import tensorflow and set the hyperparamters
    import tensorflow as tf

EPOCHS = 15
```

```
In [29]: | # Set the archetiete of TrafficNet
         from tensorflow.contrib.layers import flatten
         def TrafficNet(x):
             # Arguments used for tf.truncated normal, randomly defines variables for
             mu = 0
             sigma = 0.1
             # TODO: Layer 1: Convolutional. Input = 32x32x1. Output = 28x28x6.
             conv1_w = tf.Variable(tf.truncated_normal((5,5,1,6), mean = mu, stddev =
             conv1 b =tf.Variable(tf.zeros(6))
             conv1 = tf.nn.conv2d(x, conv1_w, strides=[1,1,1,1], padding='VALID') + c
             # TODO: Activation.
             conv1 = tf.nn.relu(conv1)
             # TODO: Pooling. Input = 28x28x6. Output = 14x14x6.
             conv1 = tf.nn.max_pool(conv1, ksize=(1,2,2,1), strides=(1,2,2,1), paddir
             conv1 = tf.nn.dropout(conv1, keep prob)
             # TODO: Layer 2: Convolutional. Output = 10x10x16.
             conv2 w = tf.Variable(tf.truncated_normal((5,5,6,16), mean = mu, stddev
             conv2_b = tf.Variable(tf.zeros(16))
             conv2 = tf.nn.conv2d(conv1, conv2 w, strides=[1,1,1,1], padding = 'VALII
             # TODO: Activation.
             conv2 = tf.nn.relu(conv2)
             # TODO: Pooling. Input = 10x10x16. Output = 5x5x16.
             conv2 = tf.nn.max pool(conv2, ksize=(1,2,2,1), strides=(1,2,2,1), paddir
             conv2 = tf.nn.dropout(conv2, keep prob)
             # TODO: Flatten. Input = 5x5x16. Output = 400.
             conv2 = flatten(conv2)
             # TODO: Layer 3: Fully Connected. Input = 400. Output = 240.
             fc1 w = tf.Variable(tf.truncated normal((400,240), mean=mu, stddev=sigma
             fc1 b = tf.Variable(tf.zeros(240))
             fc1 = tf.matmul(conv2, fc1 w) + fc1 b
             # TODO: Activation.
             fc1 = tf.nn.relu(fc1)
             fc1 = tf.nn.dropout(fc1, keep prob)
             # TODO: Layer 4: Fully Connected. Input = 240. Output = 160.
             fc2_w = tf.Variable(tf.truncated_normal((240,160), mean=mu, stddev=sigma
             fc2 b = tf.Variable(tf.zeros(160))
             fc2 = tf.matmul(fc1, fc2 w) + fc2 b
             # TODO: Activation.
             fc2 = tf.nn.relu(fc2)
             fc2 = tf.nn.dropout(fc2, keep prob)
             # TODO: Layer 5: Fully Connected. Input = 160. Output = 43.
             fc3 w = tf.Variable(tf.truncated normal((160,43), mean=mu, stddev=sigma)
             fc3 b = tf.Variable(tf.zeros(43))
```

```
logits = tf.matmul(fc2, fc3_w) + fc3_b
return logits
```

Train, Validate and Test the Model

A validation set can be used to assess how well the model is performing. A low accuracy on the training and validation sets imply underfitting. A high accuracy on the training set but low accuracy on the validation set implies overfitting.

```
In [30]: ### Train your model here.
                                        ### Calculate and report the accuracy on the training and validation set.
                                        ### Once a final model architecture is selected,
                                        ### the accuracy on the test set should be calculated and reported as well.
                                        ### Feel free to use as many code cells as needed.
In [31]: x = tf.placeholder(tf.float32, (None, 32, 32, 1))
                                       y = tf.placeholder(tf.int32, (None))
                                       one_hot_y = tf.one_hot(y, 43)
In [32]: | rate = 0.001
                                        logits = TrafficNet(x)
                                        cross entropy = tf.nn.softmax cross entropy with logits(labels=one hot y, lo
                                        loss operation = tf.reduce mean(cross entropy)
                                        optimizer = tf.train.AdamOptimizer(learning rate = rate)
                                        training operation = optimizer.minimize(loss operation)
In [33]: correct prediction = tf.equal(tf.argmax(logits, 1), tf.argmax(one hot y, 1)
                                        accuracy operation = tf.reduce mean(tf.cast(correct prediction, tf.float32))
                                        saver = tf.train.Saver()
                                        def evaluate(X data, y data):
                                                        num examples = len(X data)
                                                        total accuracy = 0
                                                        sess = tf.get default session()
                                                        for offset in range(0, num examples, BATCH SIZE):
                                                                         batch x, batch y = X data[offset:offset+BATCH SIZE], y data[offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:offset:
                                                                         accuracy = sess.run(accuracy_operation, feed_dict={x: batch_x, y: 
                                                                         total accuracy += (accuracy * len(batch x))
                                                        return total accuracy / num_examples
```

```
In [34]: with tf.Session() as sess:
             sess.run(tf.global variables initializer())
             num_examples = len(X_train)
             print("Training...")
             print()
             for i in range(EPOCHS):
                 X train, y train = shuffle(X train, y train)
                  for offset in range(0, num_examples, BATCH_SIZE):
                      end = offset + BATCH_SIZE
                      batch x, batch y = X train[offset:end], y train[offset:end]
                      sess.run(training operation, feed dict={x: batch x, y: batch y,
                 validation accuracy = evaluate(X valid, y valid)
                 print("EPOCH {} ...".format(i+1))
                 print("Validation Accuracy = {:.3f}".format(validation_accuracy))
                 print()
             saver.save(sess, './trafficnet')
             print("Model saved")
         Training...
         EPOCH 1 ...
         Validation Accuracy = 0.600
         EPOCH 2 ...
         Validation Accuracy = 0.801
         EPOCH 3 ...
         Validation Accuracy = 0.856
         EPOCH 4 ...
         Validation Accuracy = 0.876
         EPOCH 5 ...
         Validation Accuracy = 0.905
         EPOCH 6 ...
         Validation Accuracy = 0.906
         EPOCH 7 ...
         Validation Accuracy = 0.922
         EPOCH 8 ...
         Validation Accuracy = 0.915
         EPOCH 9 ...
         Validation Accuracy = 0.930
         EPOCH 10 ...
         Validation Accuracy = 0.925
         EPOCH 11 ...
         Validation Accuracy = 0.926
         EPOCH 12 ...
```

```
Validation Accuracy = 0.916
         EPOCH 13 ...
         Validation Accuracy = 0.938
         EPOCH 14 ...
         Validation Accuracy = 0.938
         EPOCH 15 ...
         Validation Accuracy = 0.944
         Model saved
In [35]: with tf.Session() as sess:
             saver.restore(sess, tf.train.latest_checkpoint('.'))
             test accuracy = evaluate(X test, y test)
             print("Test Accuracy = {:.3f}".format(test_accuracy))
         INFO:tensorflow:Restoring parameters from ./trafficnet
         Test Accuracy = 0.927
In [36]: with tf.Session() as sess:
             saver.restore(sess, tf.train.latest checkpoint('.'))
             test_accuracy = evaluate(X_train, y_train)
             print("Test Accuracy = {:.3f}".format(test accuracy))
         INFO:tensorflow:Restoring parameters from ./trafficnet
```

Step 3: Test a Model on New Images

To give yourself more insight into how your model is working, download at least five pictures of German traffic signs from the web and use your model to predict the traffic sign type.

You may find signnames.csv useful as it contains mappings from the class id (integer) to the actual sign name.

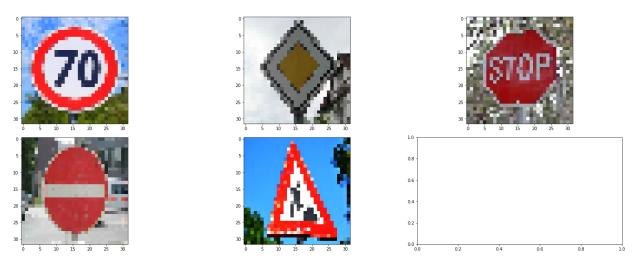
Load and Output the Images

Test Accuracy = 0.996

```
In [37]: ### Load the images and plot them here.
### Feel free to use as many code cells as needed.
```

```
In [38]:
         import matplotlib.pyplot as plt
         import matplotlib.image as mpimg
         import numpy as np
         import cv2
         # Visualizations will be shown in the notebook.
         %matplotlib inline
         # Layout the subplots
         fig, axes = plt.subplots(2,3, figsize=(22,8))
         fig.tight_layout()
         axes = axes.ravel()
         # Read the test images
         img0 = mpimg.imread('test-data/4.jpg')
         img1 = mpimg.imread('test-data/12.jpg')
         img2 = mpimg.imread('test-data/14.jpg')
         img3 = mpimg.imread('test-data/17.jpg')
         img4 = mpimg.imread('test-data/25.jpg')
         img0 = cv2.resize(img0, (32,32))
         img1 = cv2.resize(img1, (32,32))
         img2 = cv2.resize(img2, (32,32))
         img3 = cv2.resize(img3, (32,32))
         img4 = cv2.resize(img4, (32,32))
         # Display the test images in the subplots
         axes[0].imshow(img0)
         axes[1].imshow(img1)
         axes[2].imshow(img2)
         axes[3].imshow(img3)
         axes[4].imshow(img4)
```

Out[38]: <matplotlib.image.AxesImage at 0x139537b70>



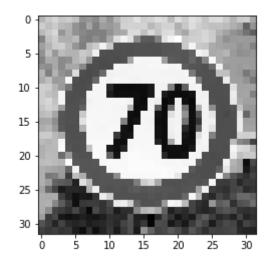
```
In [39]: # Collect the test data set
  test_data = np.array([img0, img1, img2, img3, img4])
  test_data.shape
```

Out[39]: (5, 32, 32, 3)

```
In [40]: # Preprocessing the test images
    import numpy as np
    test_data_p = rgbtogray(test_data)
    test_data_p = test_data_p - np.mean(test_data_p)
    print(test_data_p.shape)

plt.imshow(np.squeeze(test_data_p[0]), cmap='gray')
    plt.show()
```

(5, 32, 32, 1)



Predict the Sign Type for Each Image

In [41]: ### Run the predictions here and use the model to output the prediction for ### Make sure to pre-process the images with the same pre-processing pipeling ### Feel free to use as many code cells as needed.

```
In [42]: # Read the sign number and name list
import pandas as pd

TrafficSignNames = pd.read_csv('signnames.csv')
TrafficSignNames
```

Out[42]:

	ClassId	SignName
0	0	Speed limit (20km/h)
1	1	Speed limit (30km/h)
2	2	Speed limit (50km/h)
3	3	Speed limit (60km/h)
4	4	Speed limit (70km/h)
5	5	Speed limit (80km/h)
6	6	End of speed limit (80km/h)
7	7	Speed limit (100km/h)
8	8	Speed limit (120km/h)
9	9	No passing
10	10	No passing for vehicles over 3.5 metric tons
11	11	Right-of-way at the next intersection
12	12	Priority road
13	13	Yield
14	14	Stop
15	15	No vehicles
16	16	Vehicles over 3.5 metric tons prohibited
17	17	No entry
18	18	General caution
19	19	Dangerous curve to the left
20	20	Dangerous curve to the right
21	21	Double curve
22	22	Bumpy road
23	23	Slippery road
24	24	Road narrows on the right
25	25	Road work
26	26	Traffic signals
27	27	Pedestrians
28	28	Children crossing
29	29	Bicycles crossing

	ClassId	SignName
30	30	Beware of ice/snow
31	31	Wild animals crossing
32	32	End of all speed and passing limits
33	33	Turn right ahead
34	34	Turn left ahead
35	35	Ahead only
36	36	Go straight or right
37	37	Go straight or left
38	38	Keep right
39	39	Keep left
40	40	Roundabout mandatory
41	41	End of no passing
42	42	End of no passing by vehicles over 3.5 metric

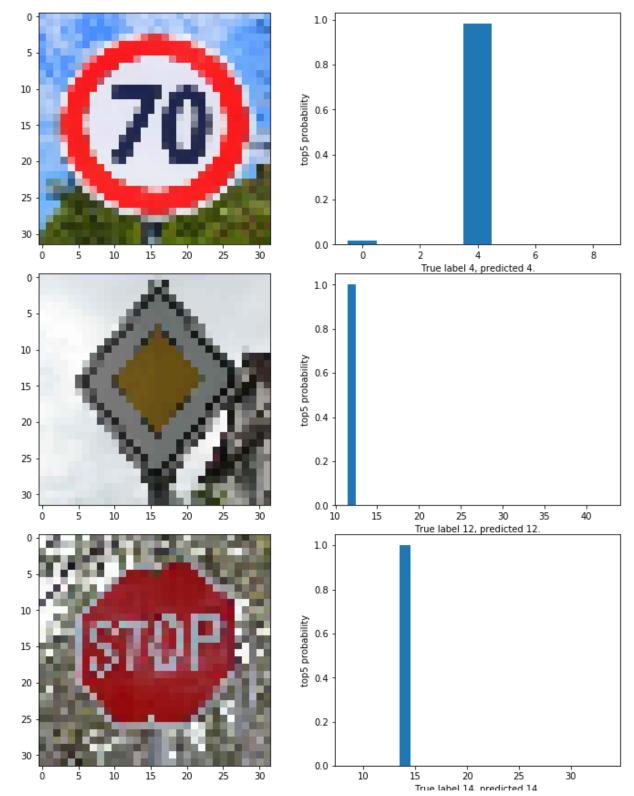
```
In [43]: test_data_label = [4, 12, 14, 17, 25]
```

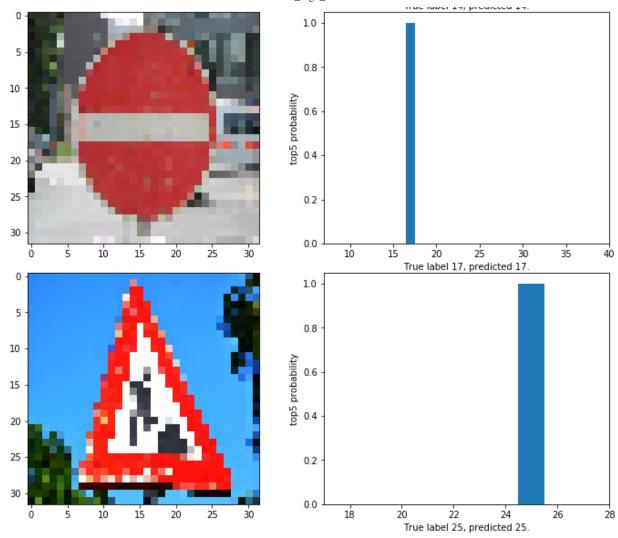
Analyze Performance

```
In [44]: ### Calculate the accuracy for these 5 new images.
    ### For example, if the model predicted 1 out of 5 signs correctly, it's 203
In [45]: import tensorflow as tf
    prob = tf.nn.softmax(logits)
        with tf.Session() as sess:
            saver.restore(sess, tf.train.latest_checkpoint('./'))
            predicted_class = sess.run(prob, feed_dict={x: test_data_p, keep_prob: 1

        In [46]: predicted_class.shape
Out[46]: (5, 43)
In [47]: with tf.Session() as sess:
        values, indices = sess.run(tf.nn.top_k(predicted_class, k=5))
```

```
In [48]:
         values
Out[48]: array([[
                   9.80768621e-01,
                                     1.90075450e-02,
                                                        2.23854498e-04,
                   3.15457704e-09,
                                     9.39693767e-10],
                   1.00000000e+00,
                                     6.70707623e-09,
                                                        3.30949512e-09,
                [
                   6.46404597e-10,
                                     5.15818638e-11],
                   9.99996901e-01,
                                     3.04855416e-06,
                                                        4.61806549e-09,
                   1.27681843e-09,
                                     9.48653711e-10],
                   1.00000000e+00,
                                     5.31074797e-27,
                                                        5.51634003e-29,
                   4.53332673e-29,
                                     3.20029462e-29],
                   1.00000000e+00,
                                     3.38783499e-13,
                                                        1.77561484e-14,
                                     6.43854889e-18]], dtype=float32)
                   4.24490595e-17,
In [49]: | indices
Out[49]: array([[ 4, 0, 1,
                              8,
                                  2],
                [12, 40, 13, 42, 41],
                [14, 33, 13, 17, 9],
                [17, 38, 9, 10, 13],
                [25, 20, 21, 27, 18]], dtype=int32)
In [50]: # The accuracy of classification of the 5 test images
         with tf.Session() as sess:
             accuracy = sess.run(tf.equal(test_data_label, indices[:,0]))
         print (accuracy)
         accuracy = sum(accuracy)/len(accuracy)
         accuracy
         [ True True True True]
Out[50]: 1.0
```





Output Top 5 Softmax Probabilities For Each Image Found on the Web

The example below demonstrates how tf.nn.top_k can be used to find the top k predictions for each image.

tf.nn.top_k will return the values and indices (class ids) of the top k predictions. So if k=3, for each sign, it'll return the 3 largest probabilities (out of a possible 43) and the corresponding class ids.

Take this numpy array as an example. The values in the array represent predictions. The array contains softmax probabilities for five candidate images with six possible classes. tf.nn.top_k is used to choose the three classes with the highest probability:

```
# (5, 6) array
a = np.array([[0.24879643, 0.07032244, 0.12641572, 0.34763842,
 0.07893497,
        0.12789202],
      [ 0.28086119, 0.27569815, 0.08594638, 0.0178669 ,
                                                           0.18063
401,
        0.15899337],
      [0.26076848, 0.23664738, 0.08020603, 0.07001922, 0.11343]
71,
        0.23892179],
      [ 0.11943333, 0.29198961, 0.02605103, 0.26234032,
                                                           0.13513
48 ,
        0.16505091],
      [ 0.09561176, 0.34396535, 0.0643941, 0.16240774, 0.24206 ]
137,
        0.09155967]
```

Running it through sess.run(tf.nn.top k(tf.constant(a), k=3)) produces:

Looking just at the first row we get [0.34763842, 0.24879643, 0.12789202], you can confirm these are the 3 largest probabilities in a . You'll also notice [3, 0, 5] are the corresponding indices.

```
In [ ]: ### Print out the top five softmax probabilities for the predictions on the ### Feel free to use as many code cells as needed.
```

Project Writeup

Once you have completed the code implementation, document your results in a project writeup using this <u>template (https://github.com/udacity/CarND-Traffic-Sign-Classifier-Project/blob/master/writeup_template.md)</u> as a guide. The writeup can be in a markdown or pdf file.

Note: Once you have completed all of the code implementations and successfully answered each question above, you may finalize your work by exporting the iPython Notebook as an HTML document. You can do this by using the menu above and

navigating to \n", "File -> Download as -> HTML (.html). Include the finished document along with this notebook as your submission.