

More Efficient Sorting: Mergesort and Quicksort

Recursive Sorts

Recursive sorts Divide the data roughly in half and are called Again on the smaller data sets. This is called the Divide-and-Conquer paradigm. We will see 2 recursive sorts:

- Merge Sort
- QuickSort

Divide-and-Conquer

- ◆ **Divide-and-conquer** paradigm:
 - **Divide**: divide one large problem into 2 smaller problems of the same type.
 - **Recur**: solve the 2 subproblems.
 - **Conquer**: combine the 2 solutions into a solution to the larger problem.
- ◆ The base case for the recursion are subproblems of manageable size, usually 0 or 1.

Merge-sort is a sorting algorithm based on the divide-and-conquer paradigm

Merge Sort

Merge-Sort

Merge-sort on an input sequence S with n elements consists of three steps:

- **Divide**: partition into 2 groups of about $n/2$ each
- **Recur**: recursively sort S_1 and S_2
- **Conquer**: merge S_1 and S_2 into a unique sorted sequence

Merging Two Sorted Sequences

- ◆ The conquer step merges the 2 sorted sequences A and B into one sorted sequence S
- ◆ *How: Compare the lowest element of each of A and B and insert whichever is smaller.*
- ◆ Merging two sorted sequences, each with $n/2$ elements and implemented by means of a doubly linked list, takes $O(n)$ time



2 5 6 9 12 15 20 27 A

4 7 10 13 16 B



S 2 4 5 6

Merging Two Sorted Sequences

Algorithm *merge*(*A*, *B*)

Input sorted sequences *A* and *B*

Output sorted sequence of $A \cup B$

S \leftarrow empty sequence

while *!A.isEmpty()* \wedge *!B.isEmpty()*

if *isLessThan*(*A.first().element()*, *B.first().element()*)

S.insertLast(*A.remove(A.first())*)

else

S.insertLast(*B.remove(B.first())*)

while *!A.isEmpty()*

S.insertLast(*A.remove(A.first())*)

while *!B.isEmpty()*

S.insertLast(*B.remove(B.first())*)

return *S*

Not In-Place

Merge-Sort

Algorithm *mergeSort(S)*

Input sequence S with n elements,

Output sequence S sorted

if $S.size() > 1$

$(S_1, S_2) \leftarrow partition(S, n/2)$

mergeSort(S_1)

mergeSort(S_2)

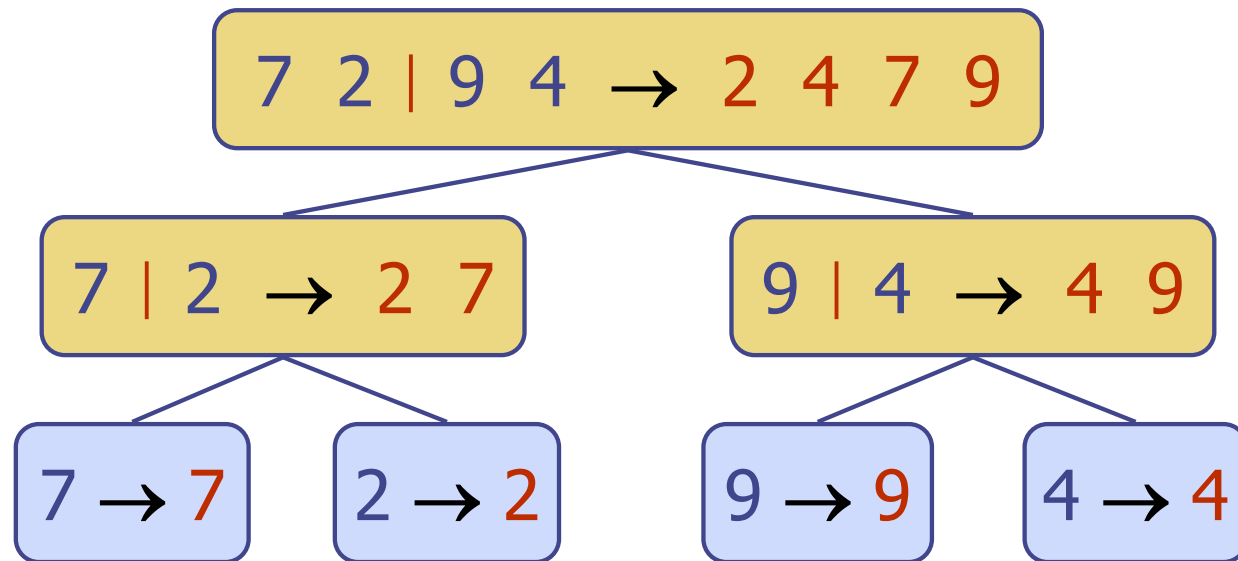
$S \leftarrow merge(S_1, S_2)$

Not In-Place

Merge-Sort Tree

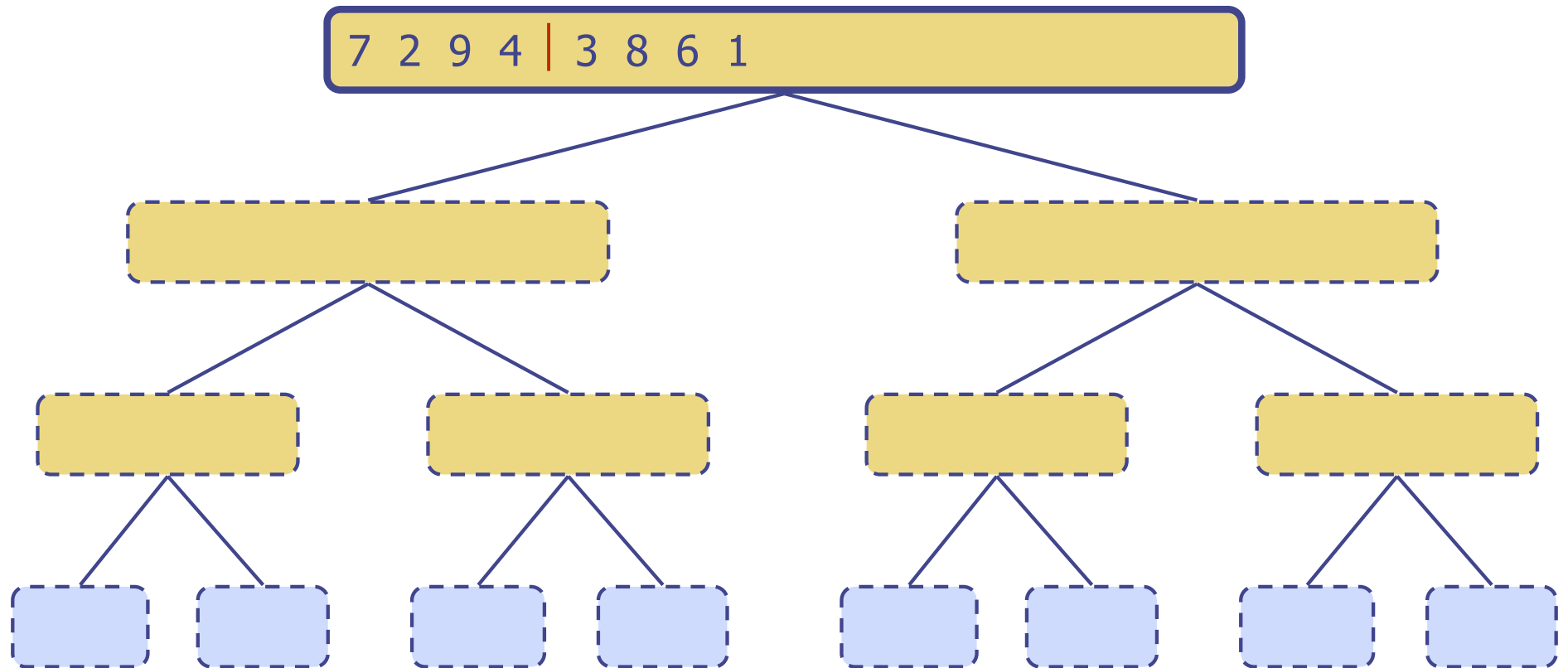
An execution of merge-sort is depicted by a binary tree

- each node represents a recursive call of merge-sort and stores
 - ◆ unsorted sequence before the execution and its partition
 - ◆ sorted sequence at the end of the execution
- the root is the initial call
- the children are calls on subsequences
- the leaves are calls on sequences of size 0 or 1



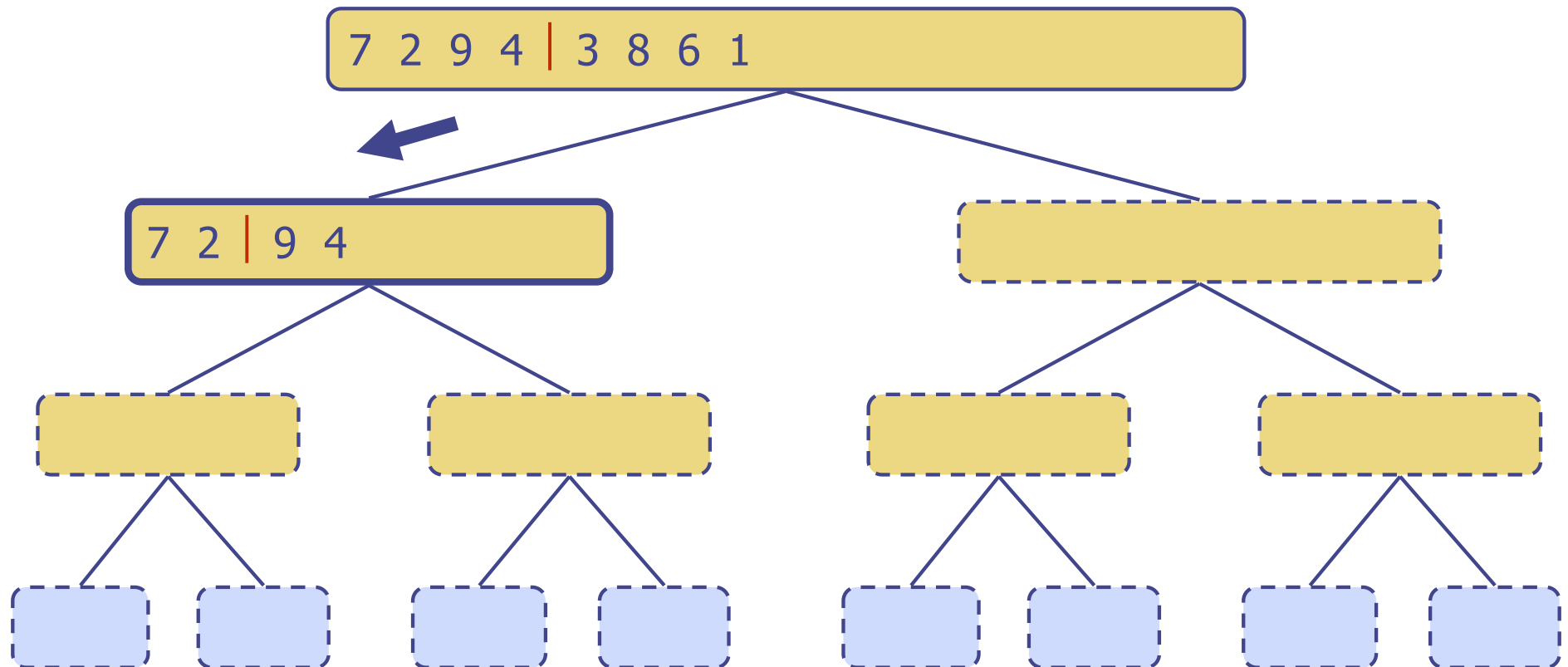
Execution Example

◆ Partition



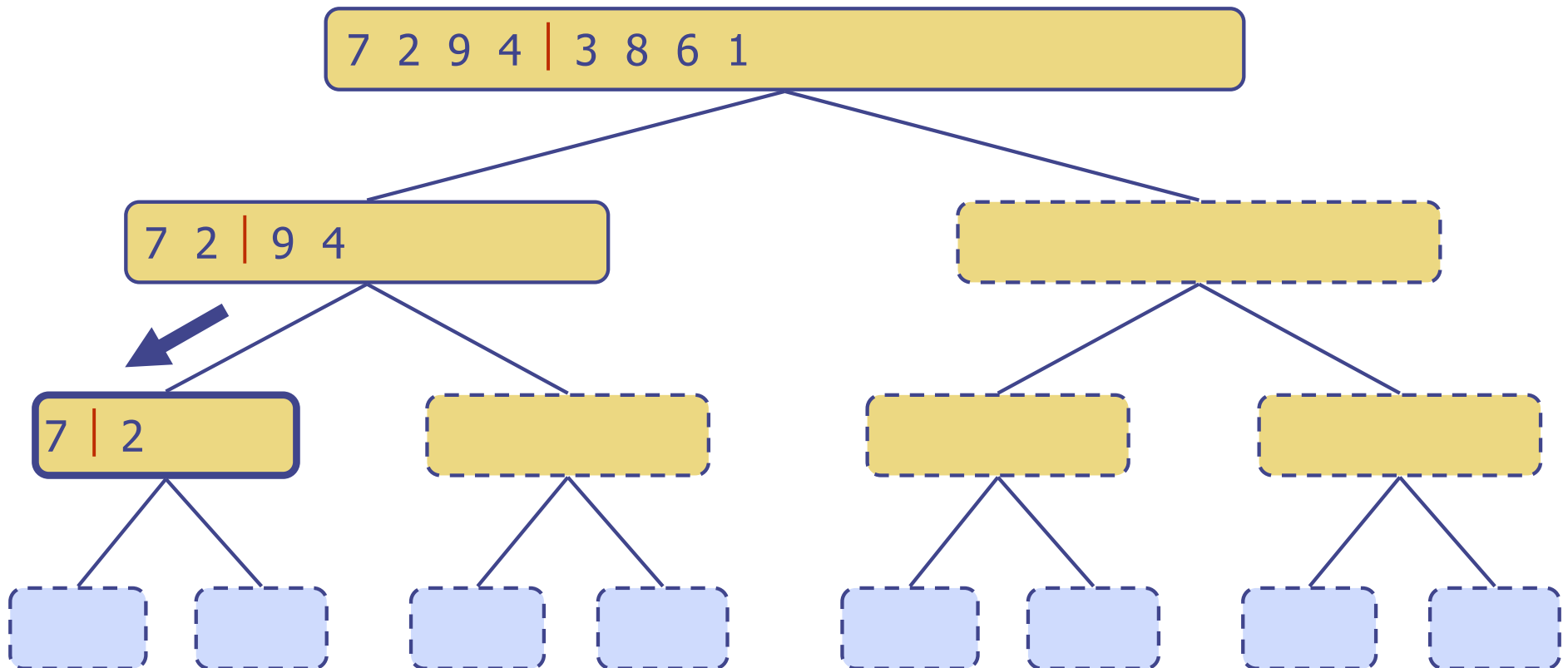
Execution Example (cont.)

◆ Recursive call, partition



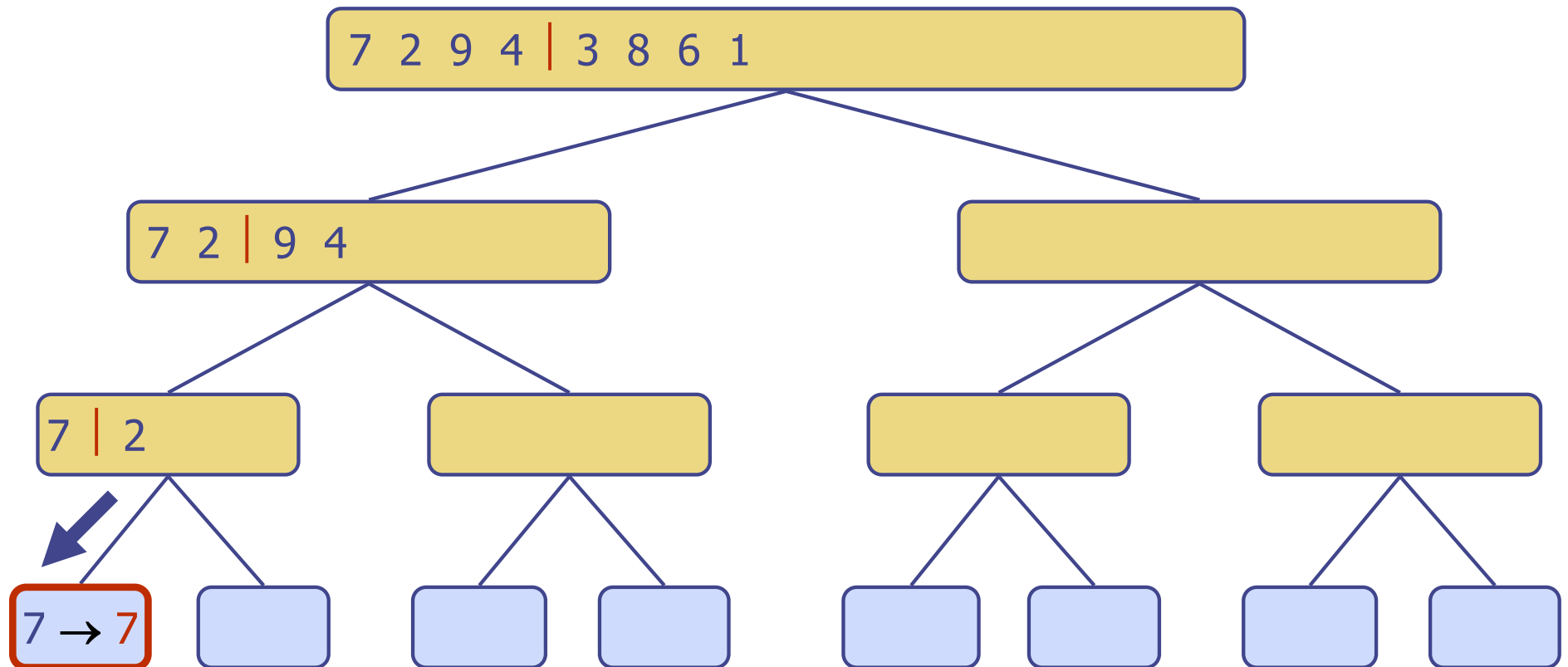
Execution Example (cont.)

◆ Recursive call, partition



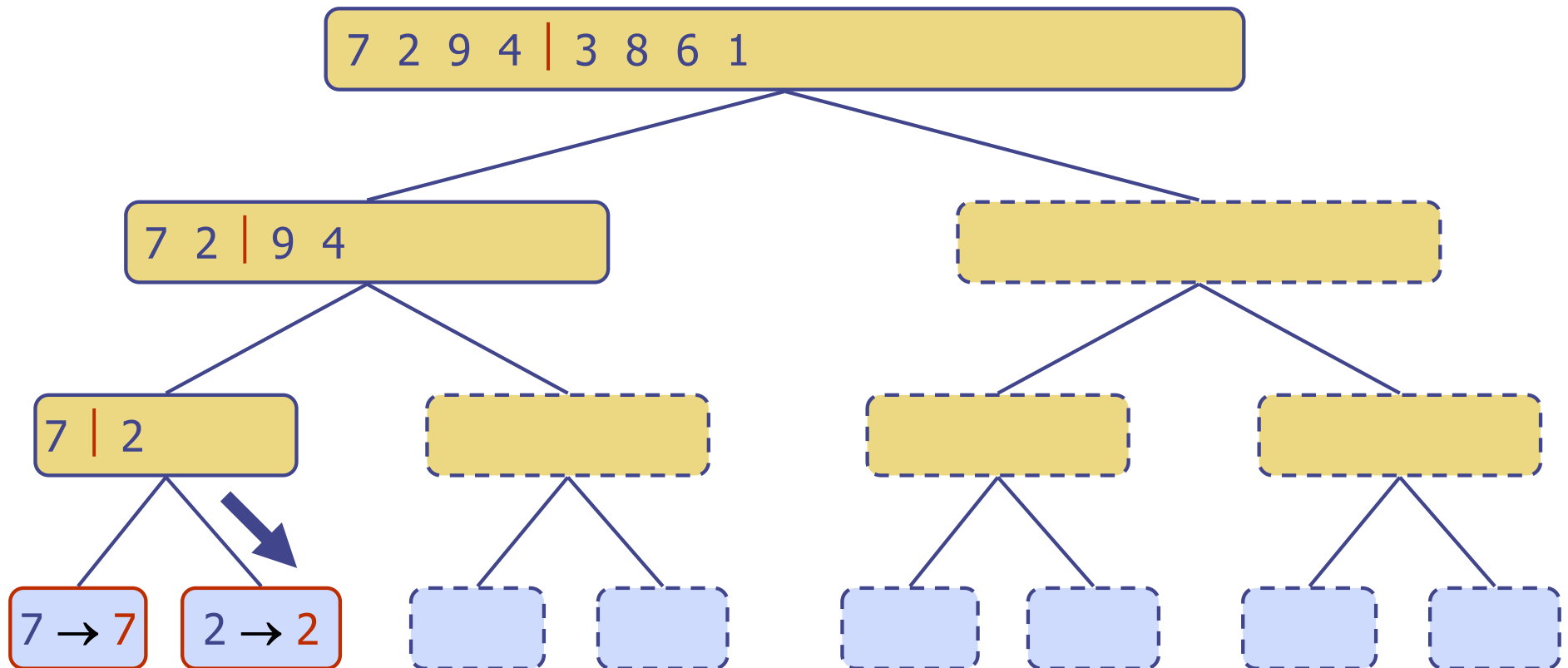
Execution Example (cont.)

◆ Recursive call, base case



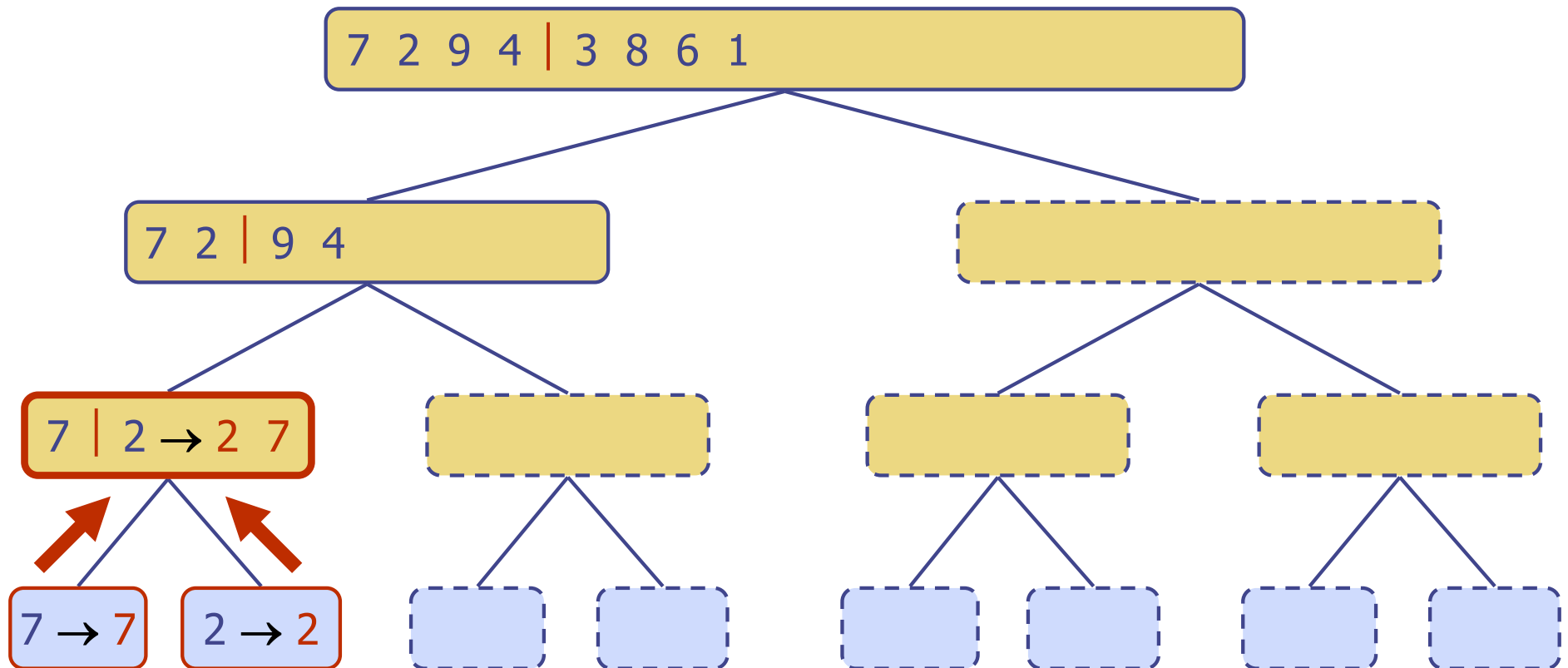
Execution Example (cont.)

◆ Recursive call, base case



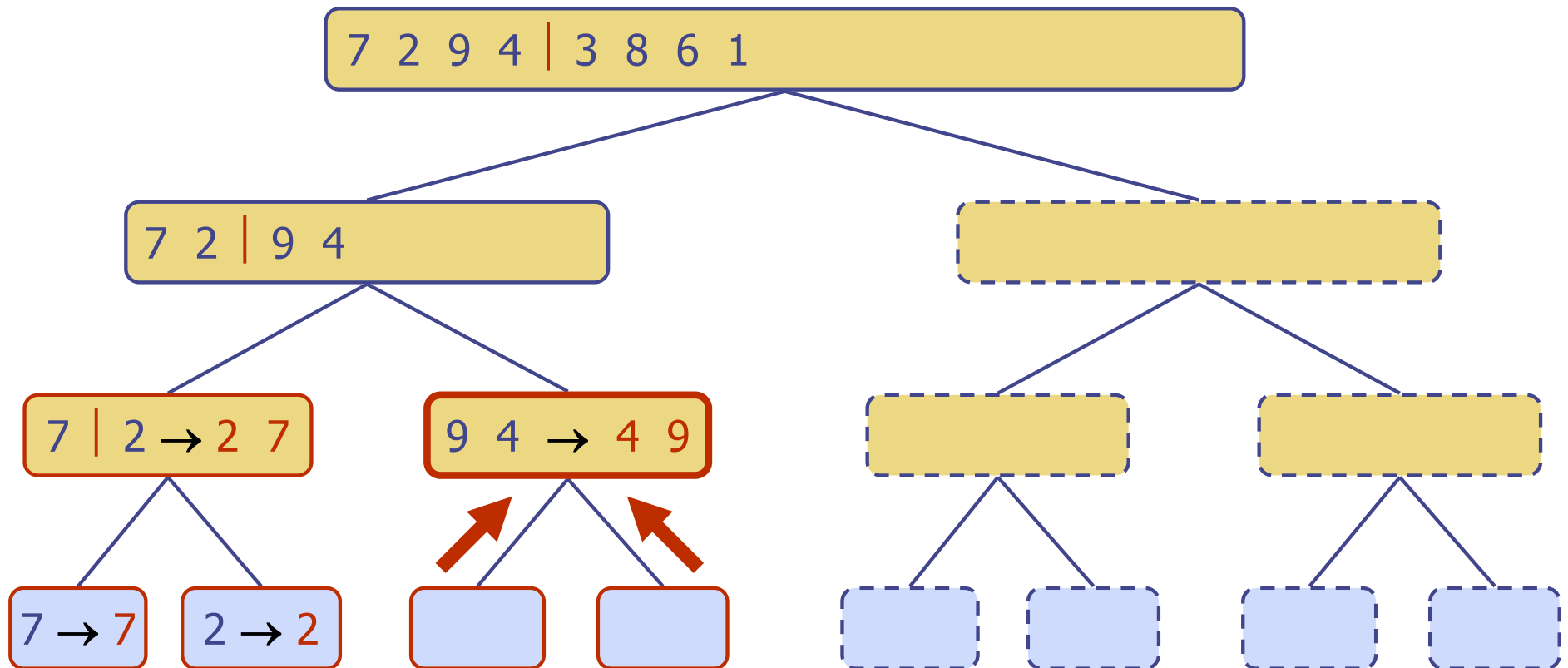
Execution Example (cont.)

◆ Merge



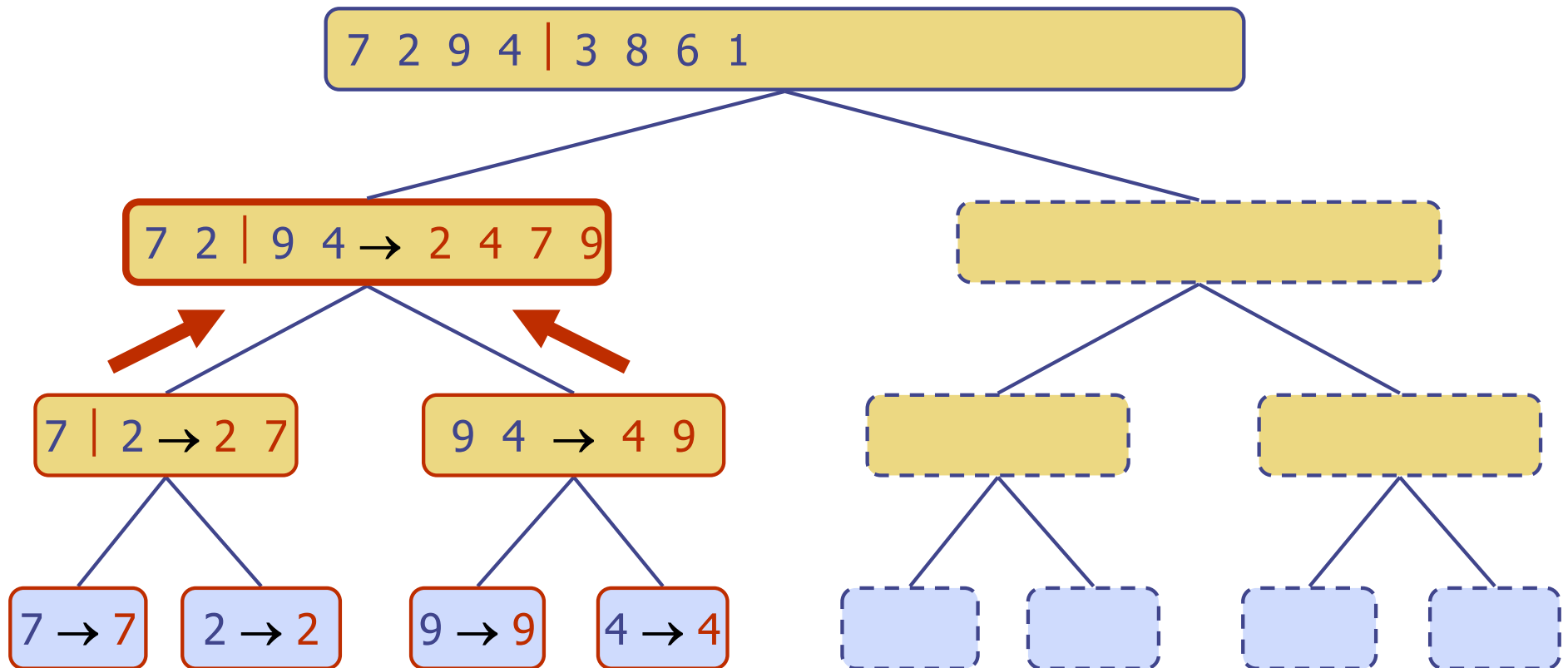
Execution Example (cont.)

◆ Recursive call, ..., base case, merge



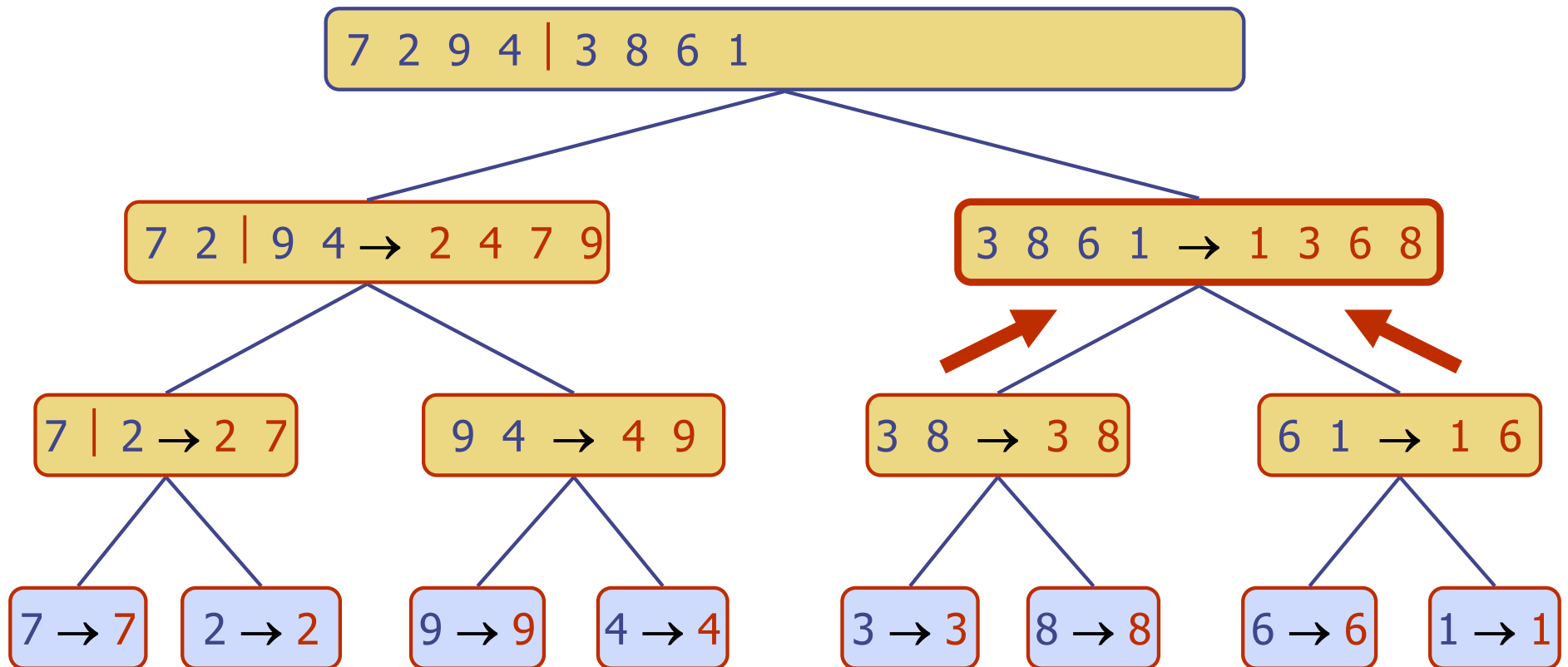
Execution Example (cont.)

◆ Merge



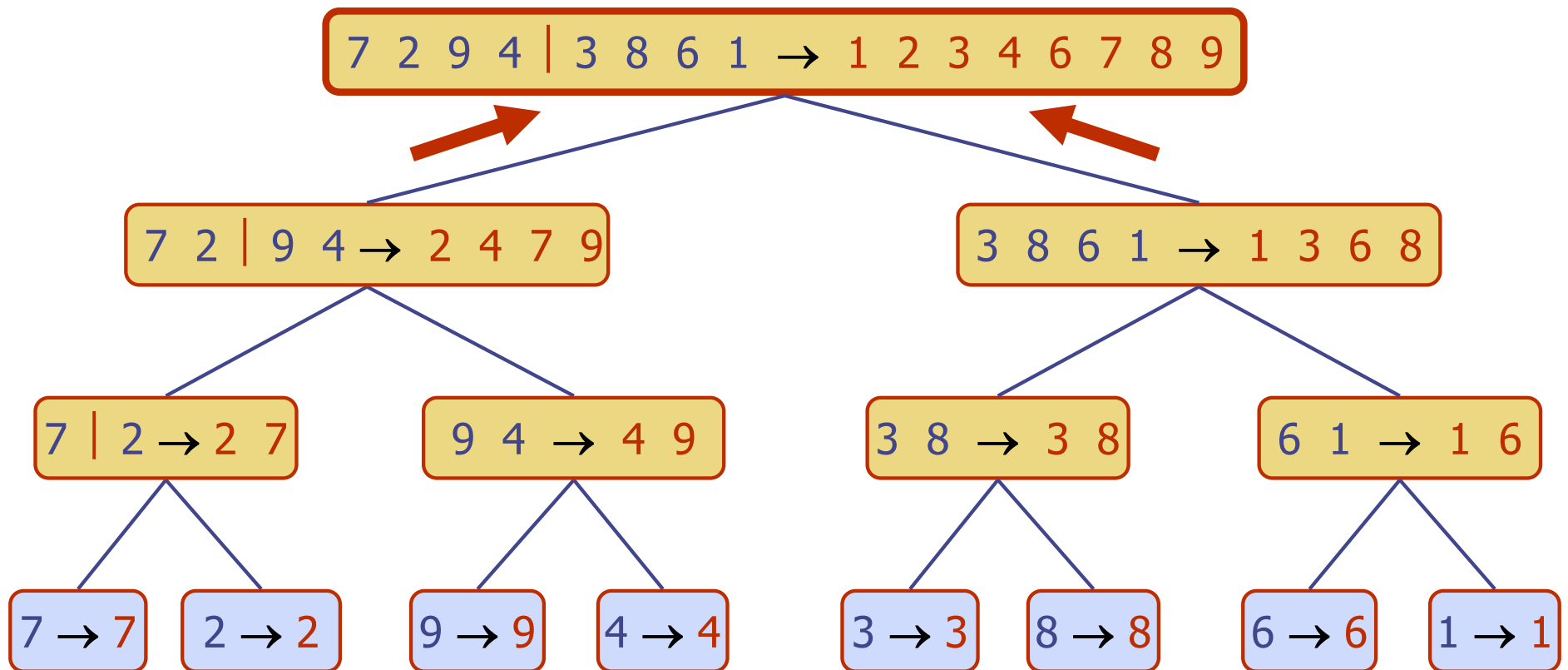
Execution Example (cont.)

◆ Recursive call, ..., merge, merge



Execution Example (cont.)

◆ Merge



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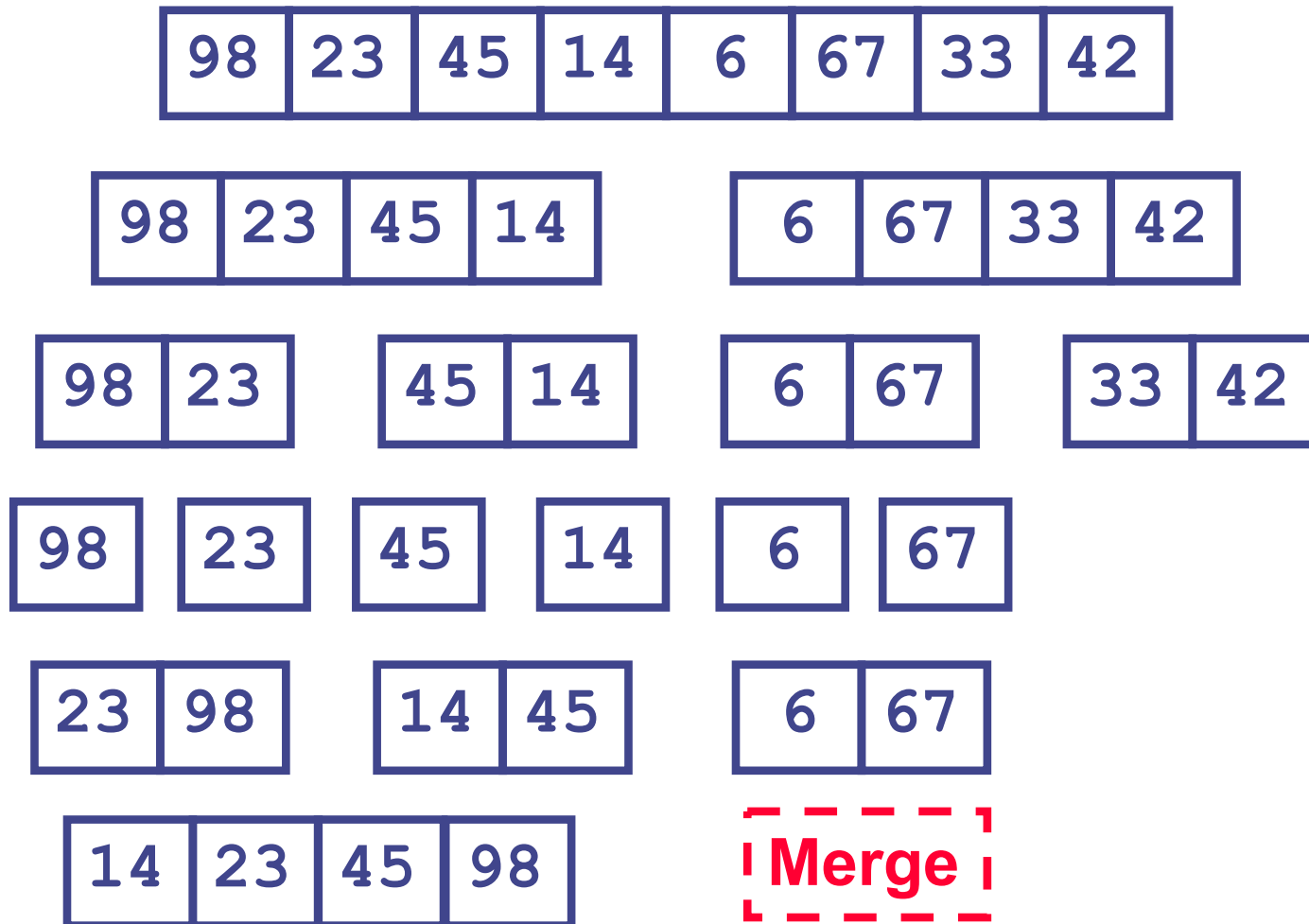
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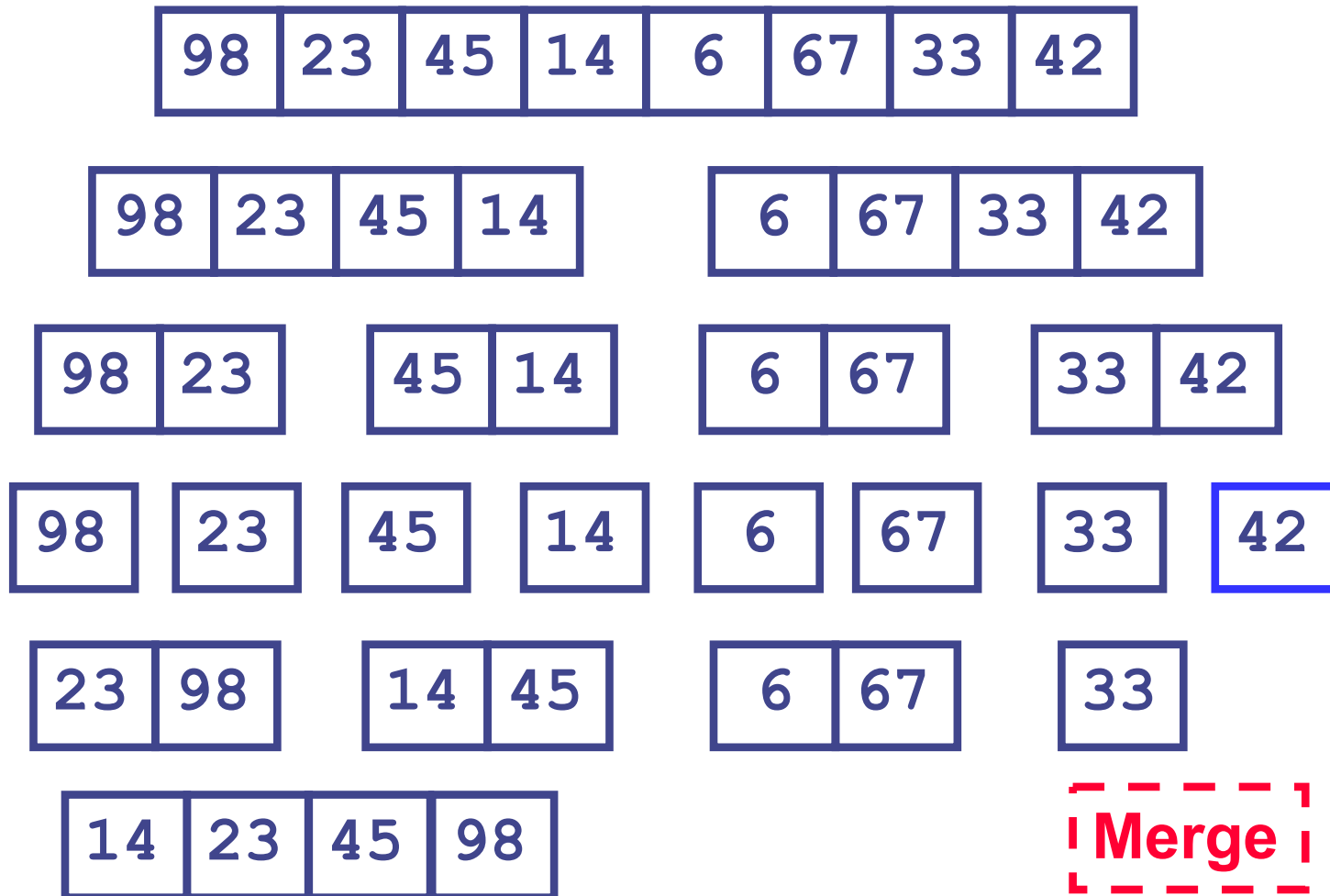
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Analysis of Merge-Sort

- ◆ The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- ◆ The overall amount of work done at the nodes of depth i is $O(n)$
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i+1} recursive calls
- ◆ Thus, the total running time of merge-sort is $O(n \log n)$

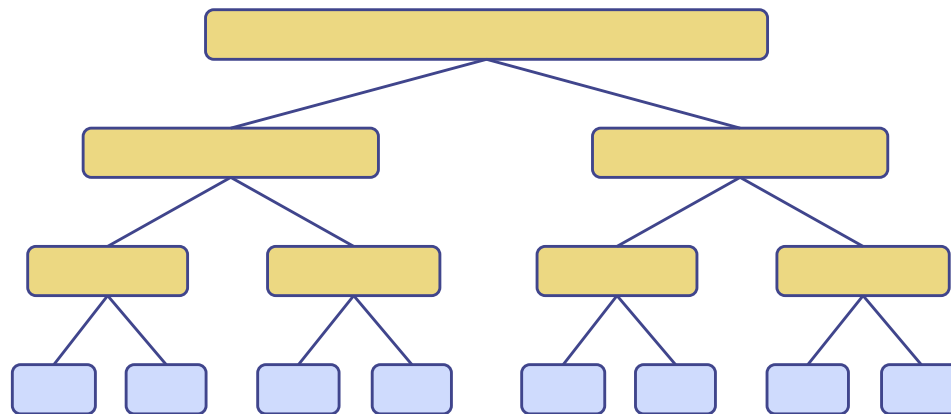
depth	#seqs	size
-------	-------	------

0	1	n
---	---	-----

1	2	$n/2$
---	---	-------

i	2^i	$n/2^i$
-----	-------	---------

...
-----	-----	-----

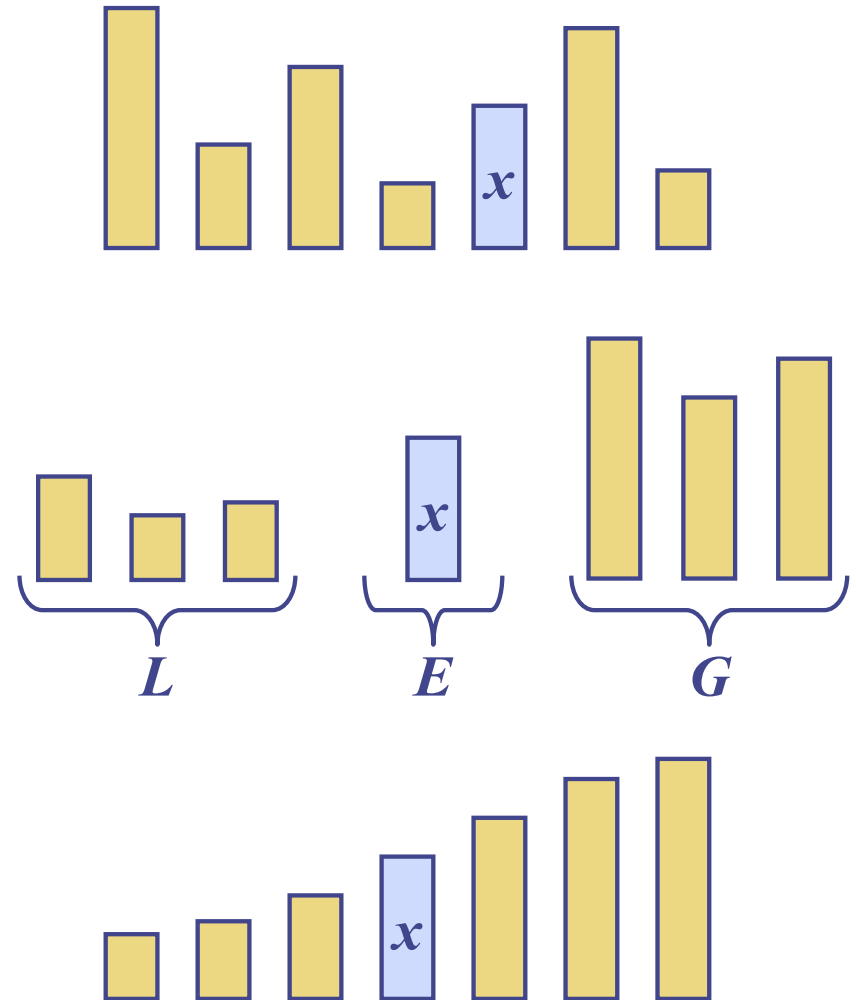


Quick-Sort

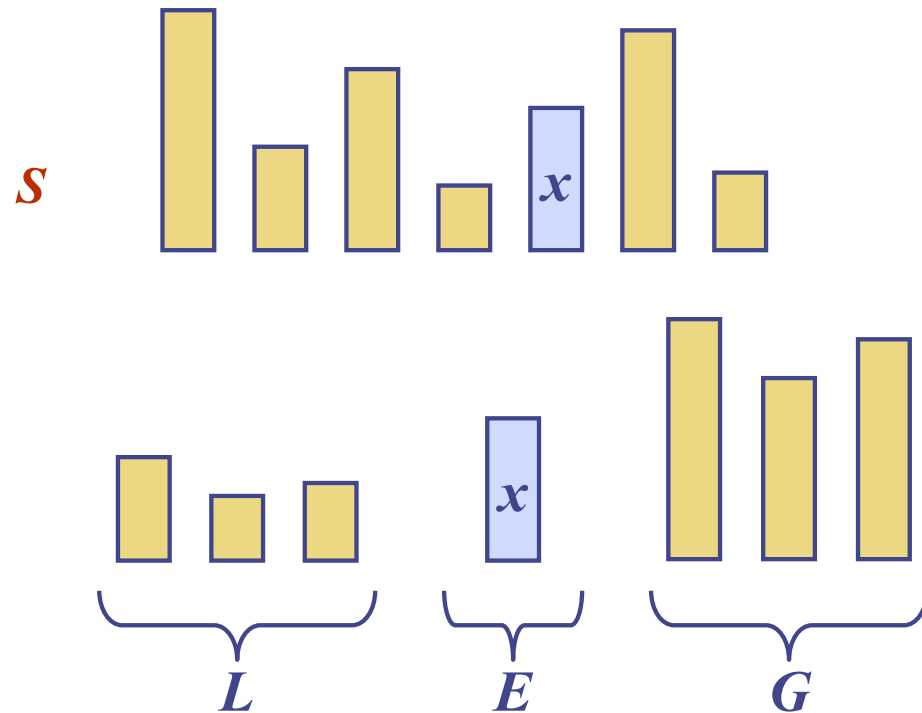
Quick-Sort

◆ **Quick-sort** is a sorting algorithm based on the divide-and-conquer paradigm:

- **Divide**: pick an element x (called **pivot**) and partition S into
 - ◆ L elements less than x
 - ◆ E elements equal x
 - ◆ G elements greater than x
- **Recur**: sort L and G
- **Conquer**: join L , E and G



Not In-Place



QuickSort(S)

$i \leftarrow \text{PIVOT}$

$x \leftarrow S.\text{elemAtRank}(i)$

$(L, E, G) \leftarrow \text{Partition}(S, x)$

QuickSort(L)

QuickSort(G)

combine L, E, G

In this example the PIVOT is chosen randomly, but we could decide always to choose the first element of the array, or the last.

Partition

Not in-place

- ◆ We partition an input sequence as follows:
 - We remove, in turn, each element y from S and
 - We insert y into L , E or G , depending on the result of the comparison with the pivot x
- ◆ Each insertion and removal is at the beginning or at the end of a sequence, and hence takes $O(1)$ time
- ◆ Thus, the partition step of quick-sort takes $O(n)$ time

Algorithm *partition*(S, p)

Input sequence S , position p of pivot
Output subsequences L , E , G of the elements of S less than, equal to, or greater than the pivot, resp.

$L, E, G \leftarrow$ empty sequences

$x \leftarrow S.remove(p)$

while $!S.isEmpty()$

$y \leftarrow S.remove(S.first())$

if $y < x$

$L.insertLast(y)$

else if $y = x$

$E.insertLast(y)$

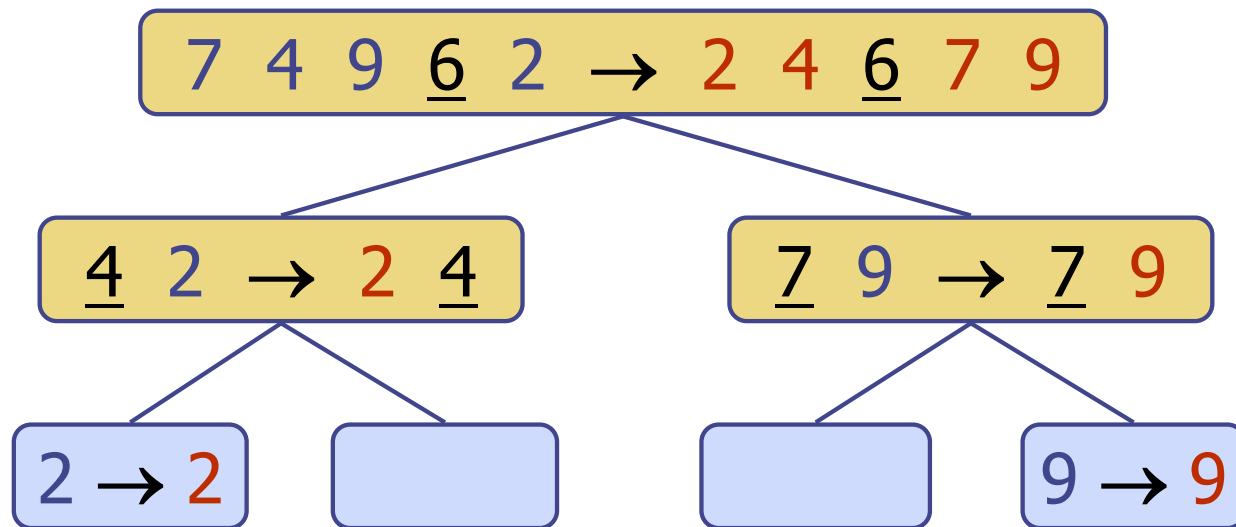
else $\{ y > x \}$

$G.insertLast(y)$

return L, E, G

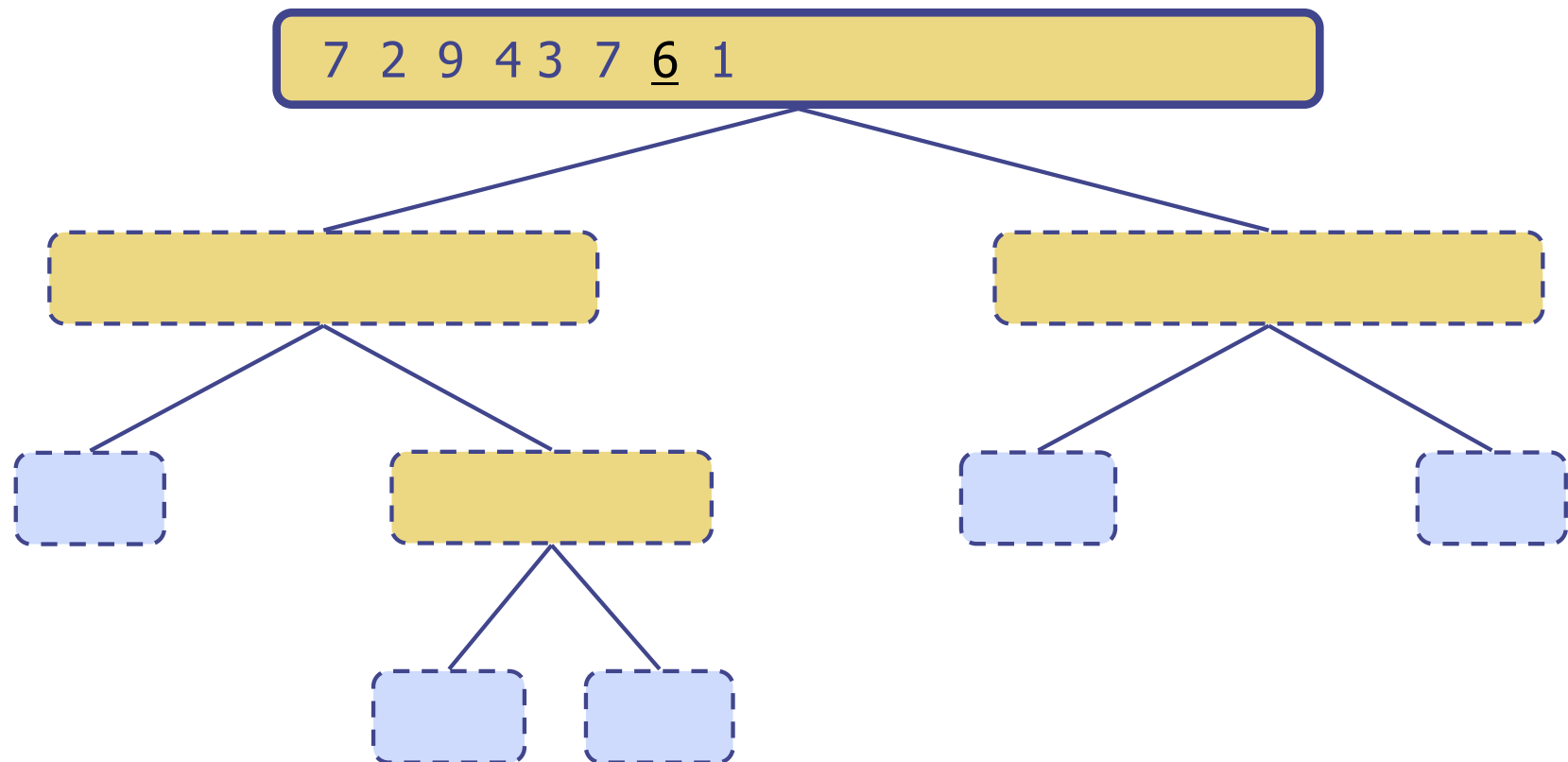
Quick-Sort Tree

- ◆ An execution of quick-sort is depicted by a binary tree
 - Each node represents a recursive call of quick-sort and stores
 - ◆ Unsorted sequence before the execution and its pivot
 - ◆ Sorted sequence at the end of the execution
 - The root is the initial call
 - The leaves are calls on subsequences of size 0 or 1



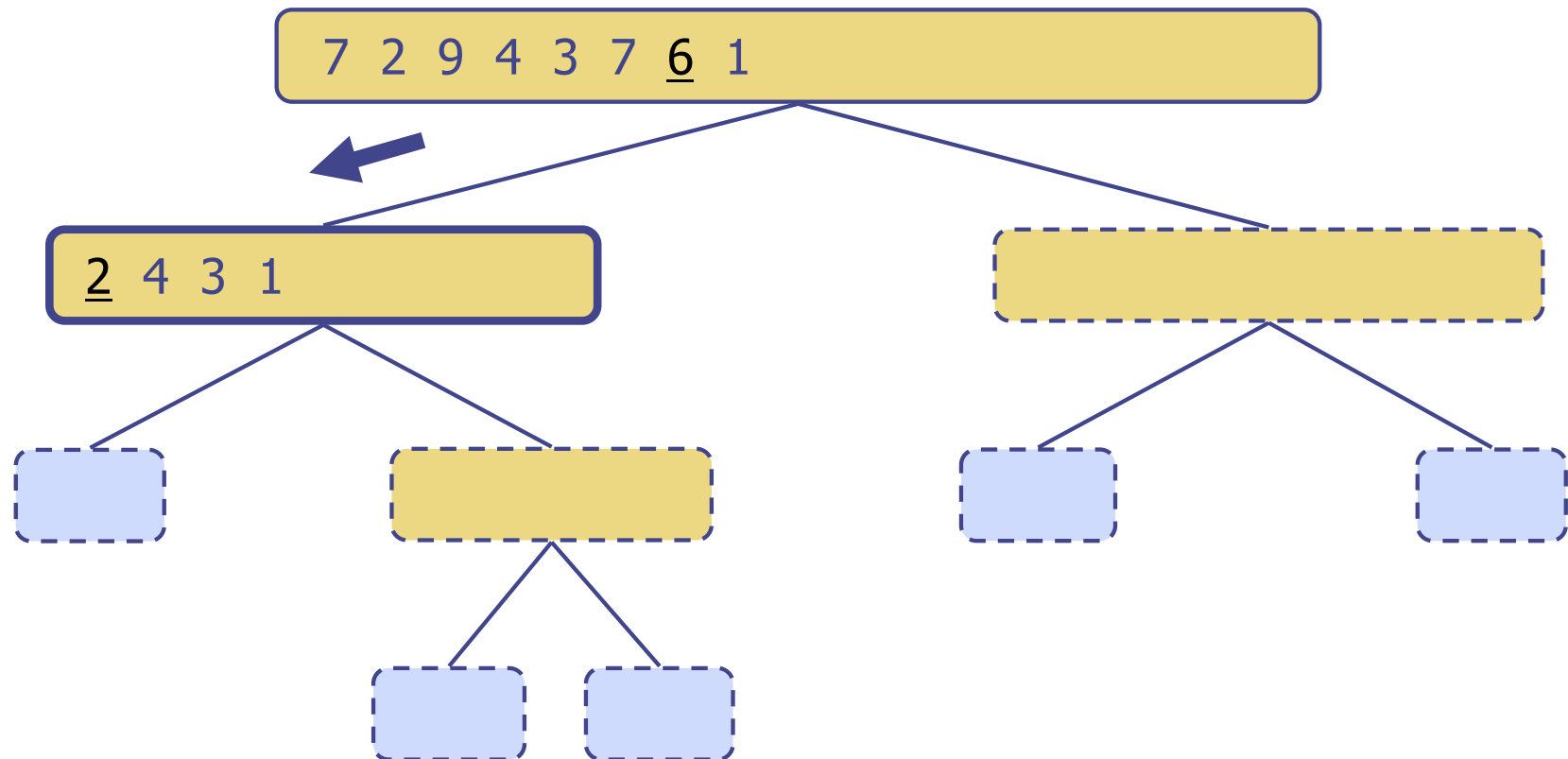
Execution Example

◆ Pivot selection



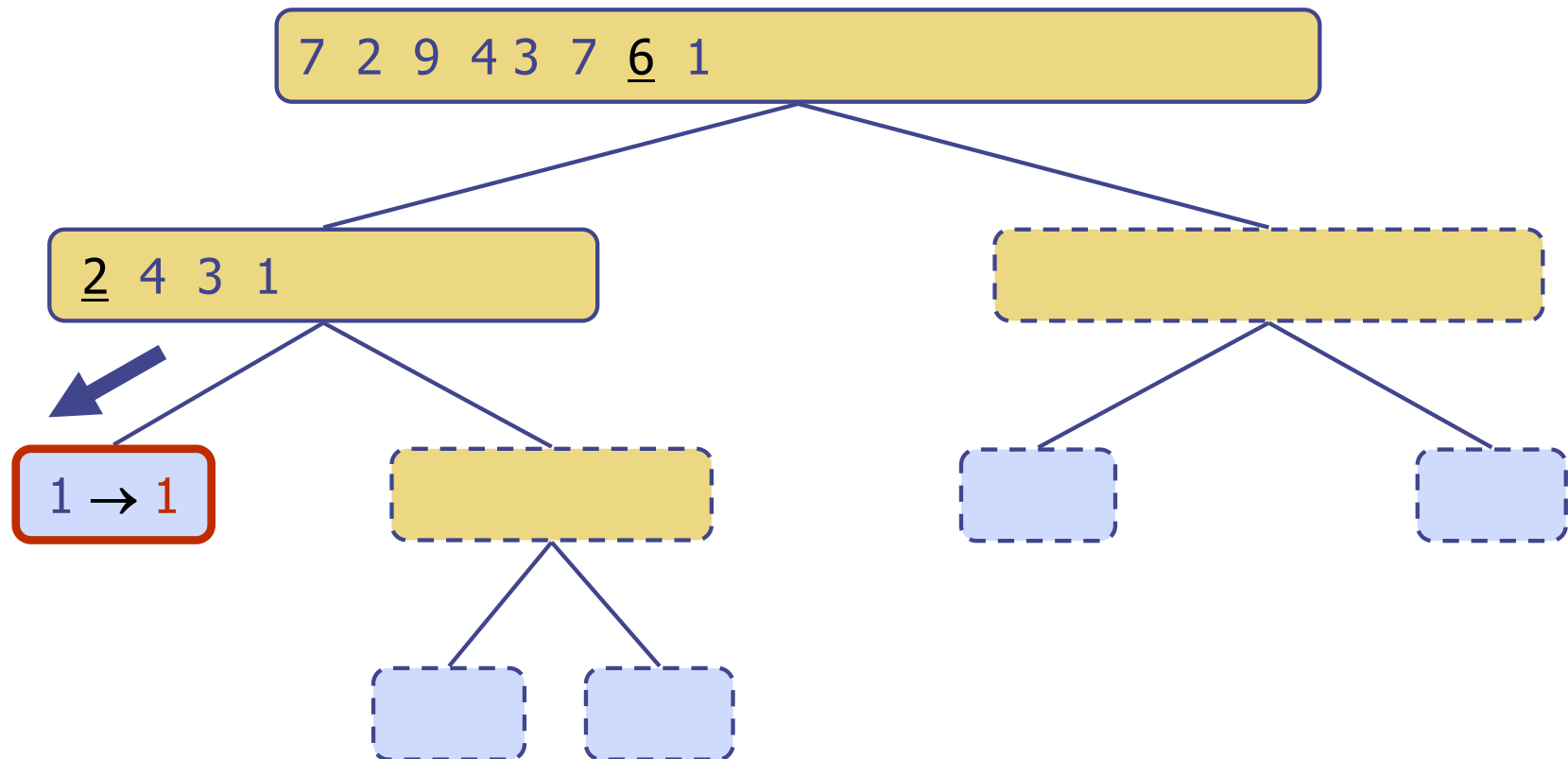
Execution Example (cont.)

◆ Partition, recursive call, pivot selection



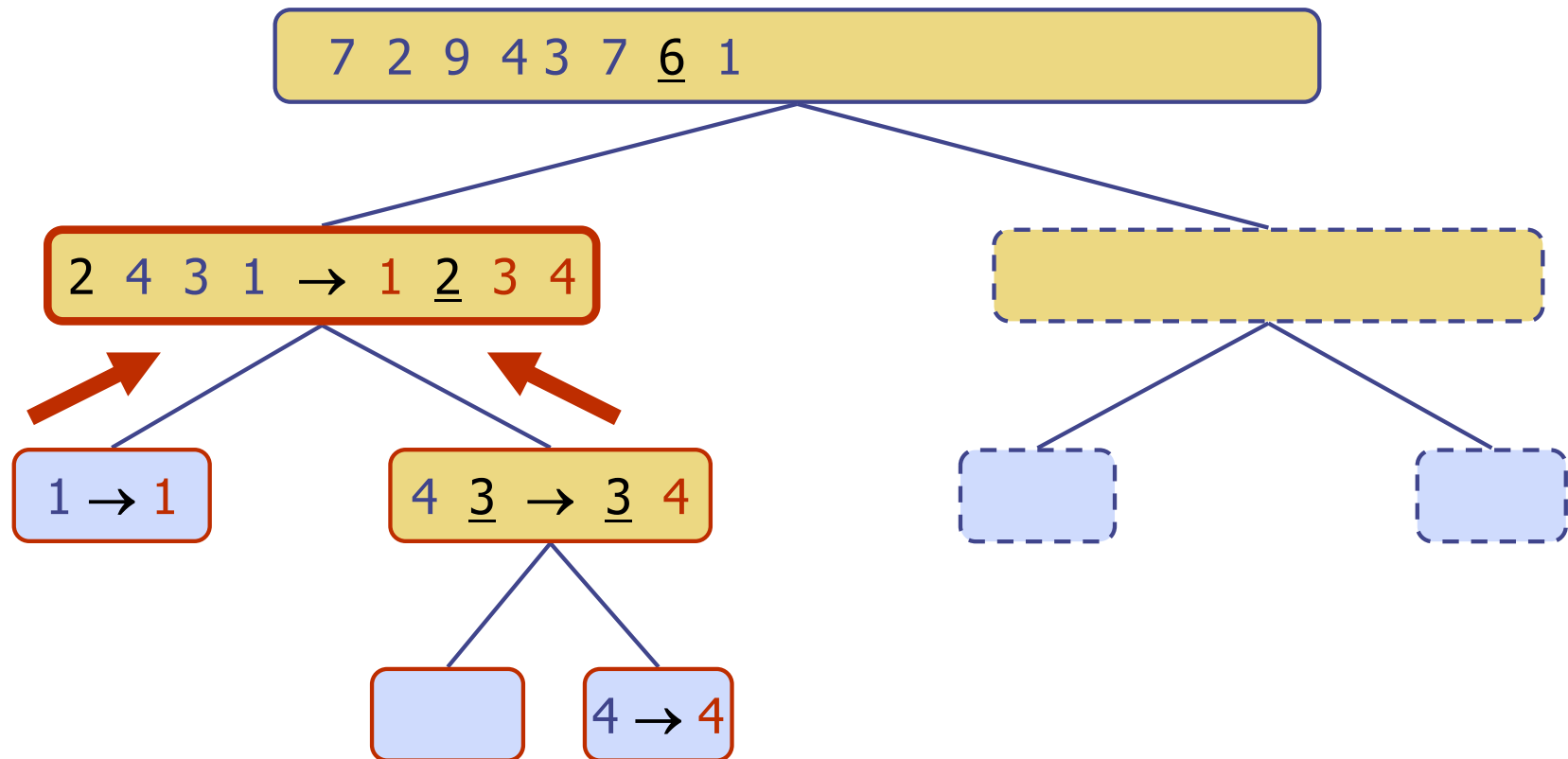
Execution Example (cont.)

◆ Partition, recursive call, base case



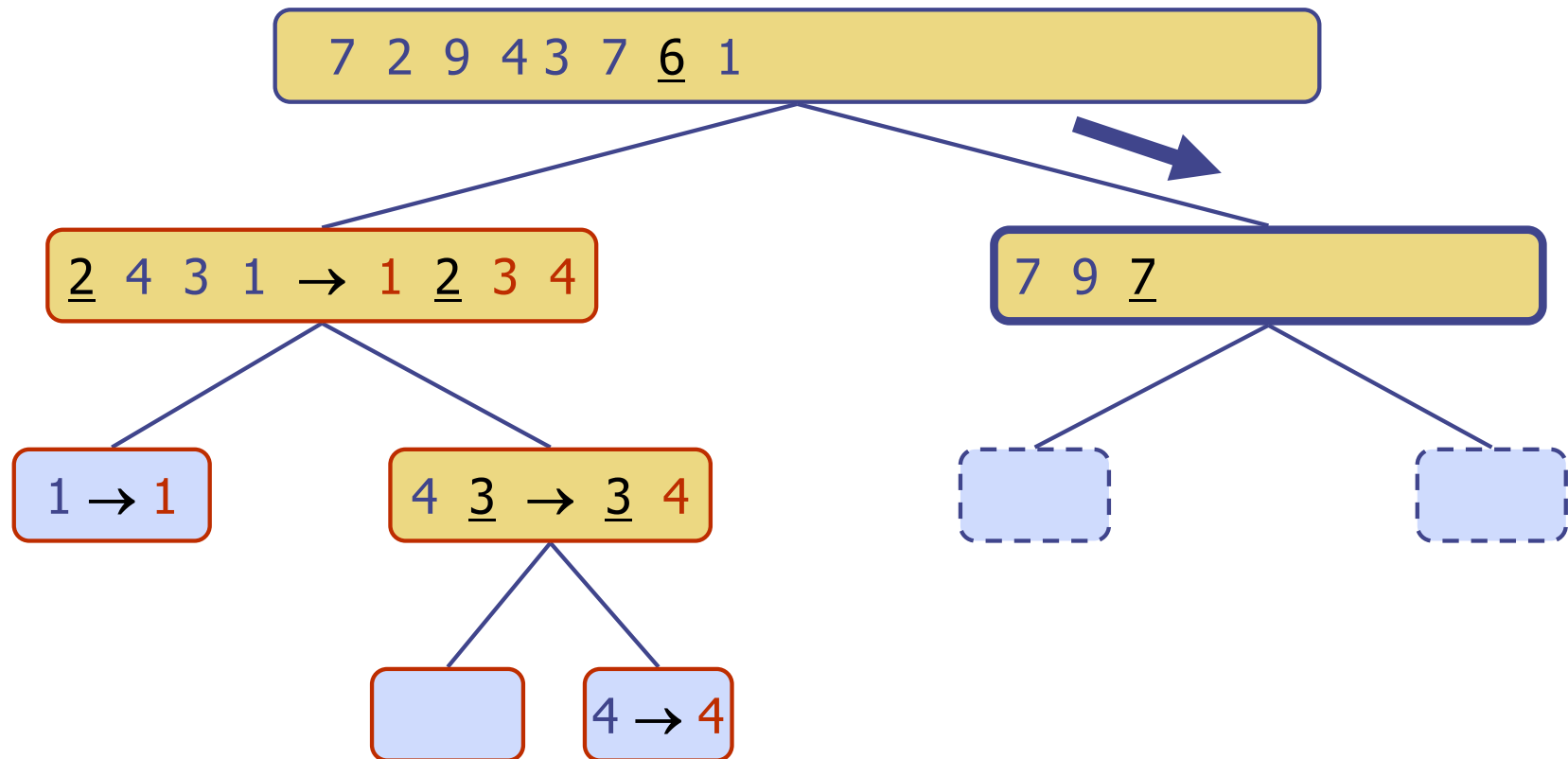
Execution Example (cont.)

◆ Recursive call, ..., base case, join



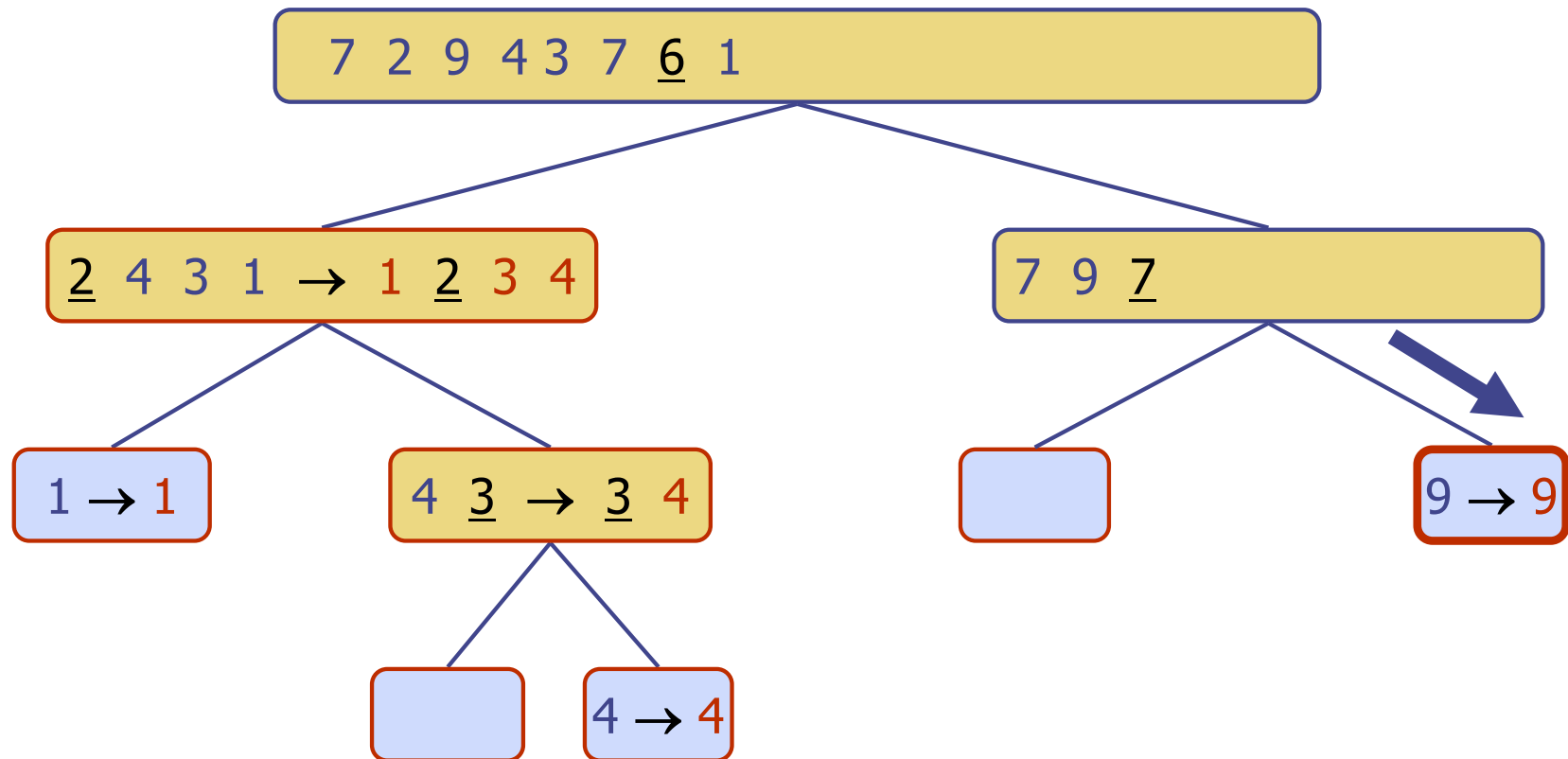
Execution Example (cont.)

◆ Recursive call, pivot selection



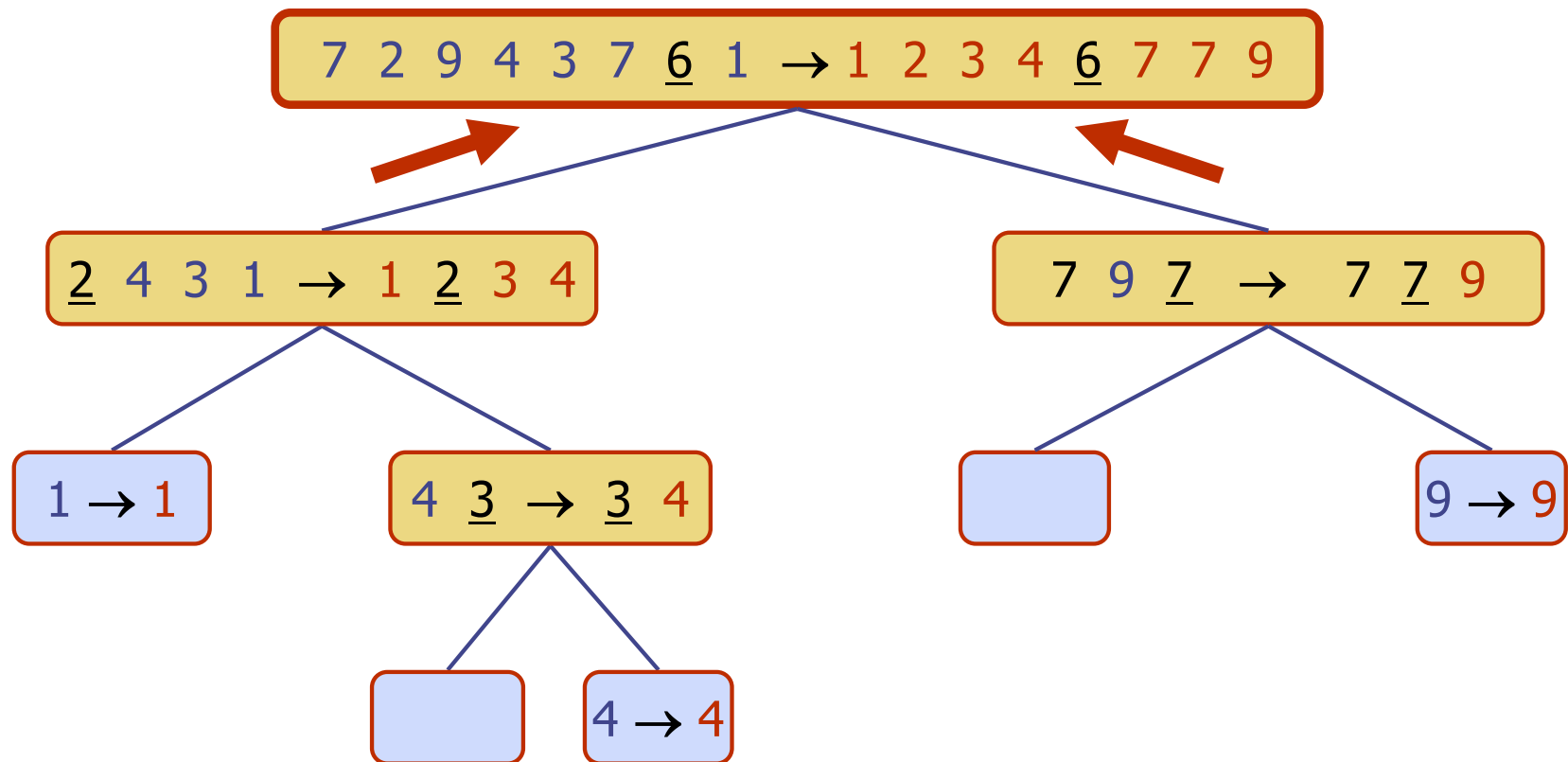
Execution Example (cont.)

◆ Partition, ..., recursive call, base case



Execution Example (cont.)

◆ Join, join



In-Place Quick-Sort

In the partition step, we use replace operations to rearrange the elements of the input sequence such that

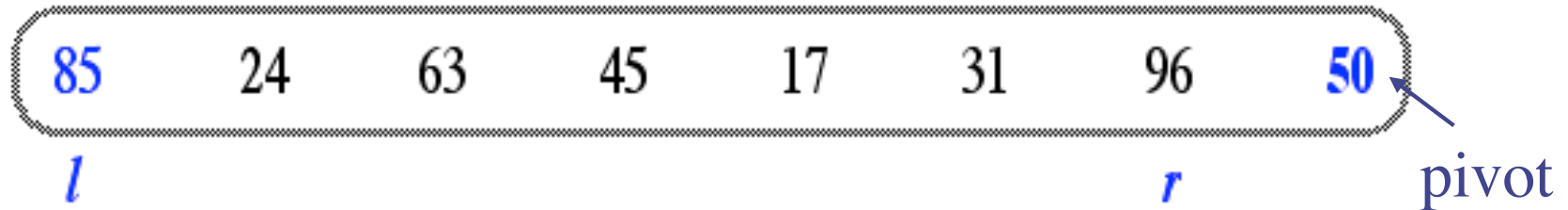
- the elements less than the pivot have rank less than h
- the elements equal to the pivot have rank between h and k
- the elements greater than the pivot have rank greater than k

◆ The recursive calls consider

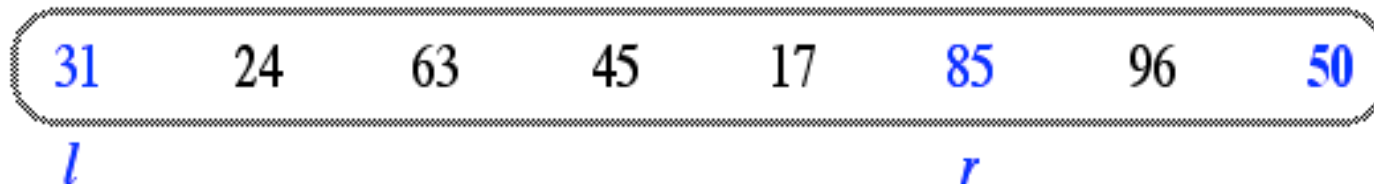
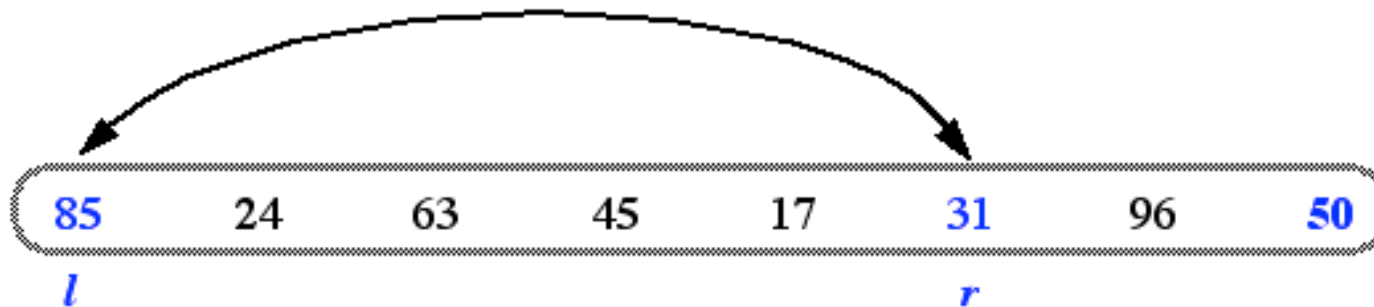
- elements with rank less than h
- elements with rank greater than k

In-Place Quick-Sort

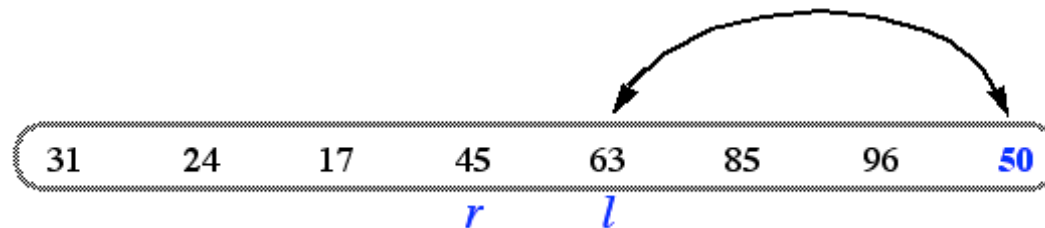
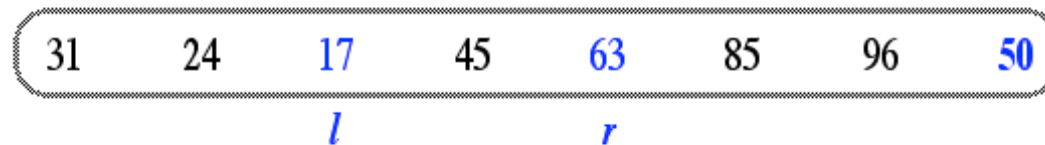
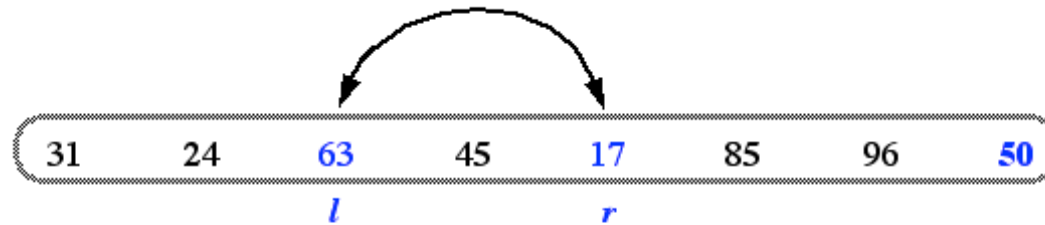
Divide step: l scans the sequence from the left, and r from the right.



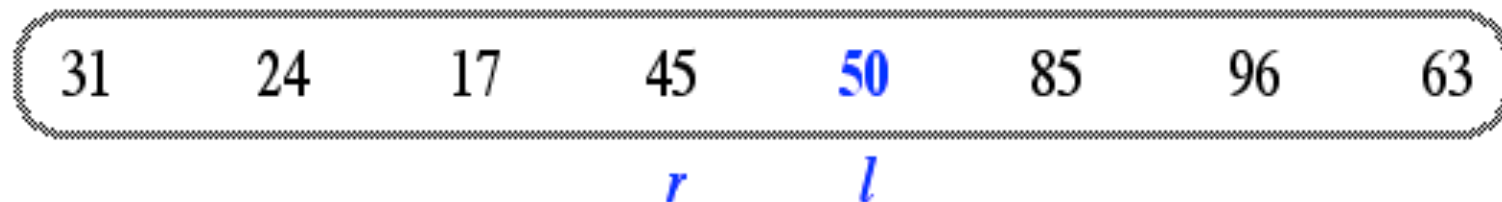
A swap is performed when l is at an element larger than the pivot and r is at one smaller than the pivot.



In Place Quick Sort (contd.)



A final swap with the pivot completes the divide step



In-Place Quick-Sort

Algorithm *inPlaceQuickSort*(S, l, r)

Input sequence S , ranks l and r

Output sequence S with the elements of rank between l and r
rearranged in increasing order

if $l \geq r$

return

$i \leftarrow$ a random integer between l and r

$(h, k) \leftarrow \text{inPlacePartition}(i, l, r)$

inPlaceQuickSort($S, l, h - 1$)

inPlaceQuickSort($S, k + 1, r$)

In Place Partition

- ◆ Repeat until l and r cross:
 - l traverse the array from left to right until it finds an element \geq pivot
 - r traverse the array from right to left until it finds an element $<$ pivot
 - Swap elements at indices l and r

Algorithm *inPlacePartition*(p, s, e)

Input: position p of the pivot; s and e are the sequence limits

Output: l and r such that:

$r-1$ = index of the last element smaller than the pivot

$l+1$ = index of the first element larger than the pivot

$l \leftarrow s, r \leftarrow e-1$

swap $S[p]$ with $S[e], p \leftarrow e$

while $l \leq r$

 while $S[l] < S[p]$ and $r \geq l$

$l \leftarrow l+1$

 while $S[r] \geq S[p]$ and $r \geq l$

$r \leftarrow r-1$

 if $r > l$ swap $S[r]$ with $S[l]$

swap $S[l]$ with $S[p]$

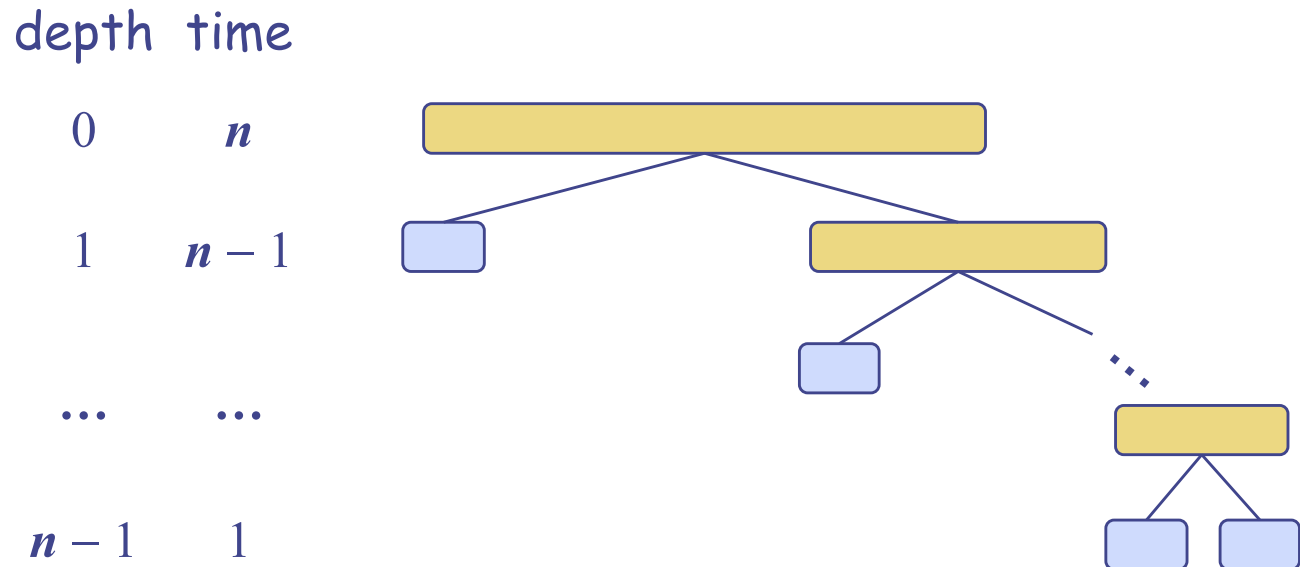
return $r+1, l$

In Place Quick-sort

```
1  /** Sort the subarray S[a..b] inclusive. */
2  private static <K> void quickSortInPlace(K[ ] S, Comparator<K> comp,
3                                          int a, int b) {
4      if (a >= b) return;          // subarray is trivially sorted
5      int left = a;
6      int right = b-1;
7      K pivot = S[b];
8      K temp;                      // temp object used for swapping
9      while (left <= right) {
10         // scan until reaching value equal or larger than pivot (or right marker)
11         while (left <= right && comp.compare(S[left], pivot) < 0) left++;
12         // scan until reaching value equal or smaller than pivot (or left marker)
13         while (left <= right && comp.compare(S[right], pivot) > 0) right--;
14         if (left <= right) {      // indices did not strictly cross
15             // so swap values and shrink range
16             temp = S[left]; S[left] = S[right]; S[right] = temp;
17             left++; right--;
18         }
19     }
20     // put pivot into its final place (currently marked by left index)
21     temp = S[left]; S[left] = S[b]; S[b] = temp;
22     // make recursive calls
23     quickSortInPlace(S, comp, a, left - 1);
24     quickSortInPlace(S, comp, left + 1, b);
25 }
```


Worst-case Running Time

- ◆ The worst case for quick-sort occurs when the pivot is the unique minimum or maximum element
- ◆ One of L and G has size $n - 1$ and the other has size 0
- ◆ The running time is proportional to the sum
$$n + (n - 1) + \dots + 2 + 1$$
- ◆ Thus, the worst-case running time of quick-sort is $O(n^2)$



Expected Running Time

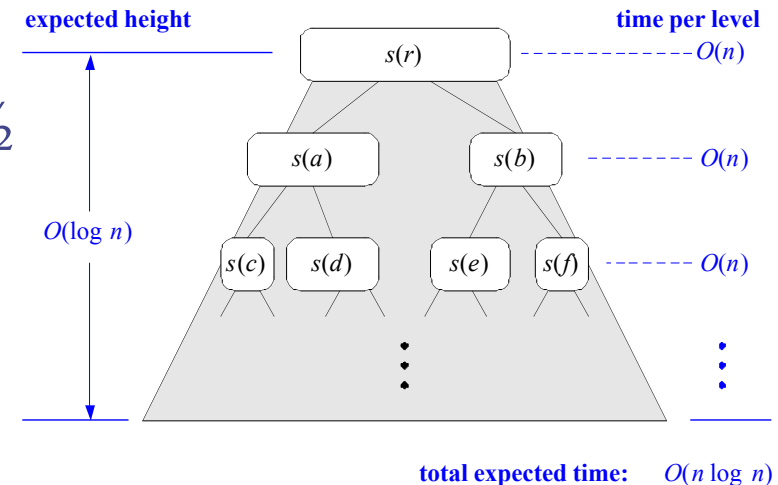
Consider a recursive call of quick-sort on a sequence of size s

- **Good call:** the sizes of L and G are each less than $3s/4$
- **Bad call:** one of L and G has size greater than $3s/4$

◆ A call is good with probability $1/2$
(for an element, the expected number of calls until a good call is 2)

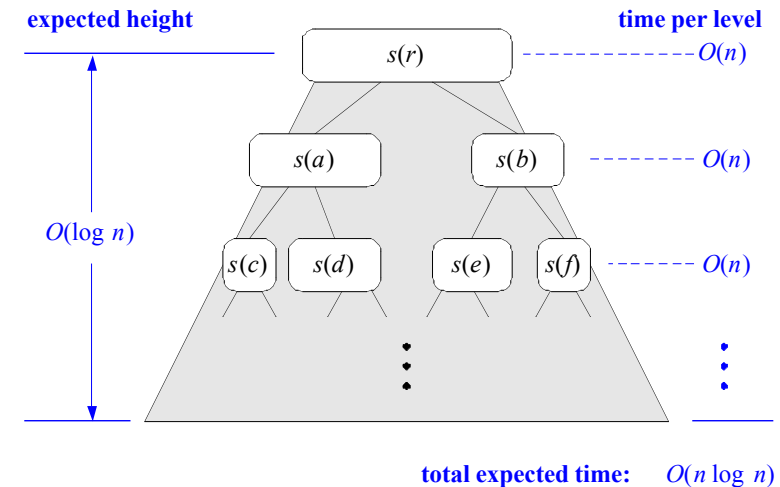
◆ Hence, for a node of depth i , we expect that

- $i/2$ ancestor nodes are associated with good calls
- the expected size of the input sequence for the current call is at most $(3/4)^{i/2}n$



Expected Running Time

- ◆ Thus, we have
 - For a node of depth $2\log_{4/3} n$, the expected size of the input sequence is one $((3/4)^{((2\log_{4/3} n)/2)} n = 1)$
 - The expected height of the quick-sort tree is $O(\log n)$
- ◆ The overall amount of work done at the nodes of the same depth of the quick-sort tree is $O(n)$
- ◆ Thus, the expected running time of quick-sort is $O(n \log n)$



Algorithm	Time	Notes
selection-sort	$O(n^2)$ w.c. and av.	<ul style="list-style-type: none"> ◆ in-place ◆ slow (good for small inputs)
insertion-sort	$O(n^2)$ w.c. and av.	<ul style="list-style-type: none"> ◆ in-place ◆ slow (good for small inputs)
quick-sort	$O(n^2)$ w.c. $O(n \log n)$ average	<ul style="list-style-type: none"> ◆ in-place, randomized ◆ fastest (good for large inputs)
heap-sort	$O(n \log n)$ w.c. and av.	<ul style="list-style-type: none"> ◆ in-place ◆ fast (good for large inputs)
merge-sort	$O(n \log n)$ w.c. and av.	<ul style="list-style-type: none"> ◆ sequential data access ◆ fast (good for huge inputs)