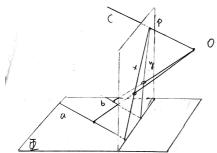
Homework #1

Problem 1.

Vanishing Line:

Geometrically Prove:



Consider we have two parallel line a, b in plane Φ . And there is a line cpassing through the pinhole **O** which is parallel to line a, b. Line c intersects with the image plane Π at point p. Also line a and line c form a plane, A, and line b and line c form a plane, **B**. The intersection line x between plane A and image plane Π is the projection of line a on image plane. The intersection line y between plane B and image plane Π is the projection of line b on image plane. Line x and y converge at point p, meanwhile p is on line c. Consider we form a line h passing through p on plane Π which is parallel with the intersection line n of plane Φ and plane Π . And line c is parallel with line b, and b is not parallel with n, so the plane formed by b and **O** is parallel with plane Φ . In this case, we can say that the vanishing point p lies on the intersection line of image plane and the parallel plane of Φ passing through the pinhole. The intersection line is the vanishing line. Also, we can do the same thing with other pair of parallel lines in plane Φ . Since there is only one plane passing through a point which is parallel to the same plane, every h is a same line. So we can conclude that all the parallel line on a plane k have a same vanishing line which is the intersection line of image plane and the plane passing through the pinhole and parallel with plane k.

Algebraically Prove:

Vanishing point:

We can use perspective projection function to get P1, iq1, P2 and q2 in homogeneous. Coordinate from P1. Q1 P2 and Q2.

Then the line
$$\beta_1 q_1$$
, $\beta_2 q_2$, line, $= P_1 \times q_1$
 $\beta_2 q_2$, line, $= P_2 \times q_2$
Varishing point $h = \lim_{n \to \infty} |x| \ln e_2$.

$$h = (P_1 \times f_1) \times (P_2 \times f_2)$$

Problem 2

 $\begin{pmatrix}
I_{1}(\rho) \\
I_{2}(\rho) \\
\vdots \\
V_{n}^{T}
\end{pmatrix} = \begin{pmatrix}
V_{1}^{T} \\
V_{2}^{T} \\
\vdots \\
V_{n}^{T}
\end{pmatrix} S(\rho)$

In in this case $\text{Li}(p) = V_i^T \cdot S(p) = S^T(p) V_i$ Li(p) is the image intensity of p with light source V_i V_i is the light source i. $S^T(p)$ is the transpose of the normal vector at p.

2. Because there one three verificities in S(p) to be determined, no need 3 function to determine each possible variables. So we need on least 3 light source.

$$I = \begin{pmatrix} I_{\mathbf{0}}(\mathbf{p}_{i}) \\ I_{\mathbf{0}}(\mathbf{p}_{i}) \\ \vdots \\ I_{\mathbf{0}}(\mathbf{p}_{n}) \end{pmatrix} = \begin{pmatrix} \mathbf{g}^{\mathsf{T}}(\mathbf{p}_{i}) \\ \mathbf{s}^{\mathsf{T}}(\mathbf{p}_{i}) \\ \vdots \\ \mathbf{s}^{\mathsf{T}}(\mathbf{p}_{n}) \end{pmatrix} \cdot \mathbf{V} \qquad \mathbf{S} = \begin{pmatrix} \mathbf{g}^{\mathsf{T}}(\mathbf{p}_{i}) \\ \mathbf{s}^{\mathsf{T}}(\mathbf{p}_{i}) \\ \vdots \\ \mathbf{s}^{\mathsf{T}}(\mathbf{p}_{n}) \end{pmatrix}$$

! There are at least 3 not coplaine. (DS(P-)

2. 19 rank (S)=3

:. There are out least 3 st(P1) that the linearly independent.

So S is a linear basis,

And V can serve as a coefficient for 3 independent $S^T(P)$: P S is a linear basis for all I,

- 4.
- a. General surface have some mirror-like reflections
- b. General surface will absorb some light intensity.
- c. The reflection brightness from different angle will be different.