torch_debugging-help

November 1, 2022

1 Fully connected MLP with PyTorch

```
[1]: #import necessary packages.\ (we use torch to present results)
     print("PyTorch version:", torch.__version__)
    PyTorch version: 1.12.1
[2]: #read and process data (observations X and ground truth Ytrue)
     print('Observations (%d samples x %d variables per sample):' % (X.shape[0], X.
      ⇒shape[1]))
     print(X)
     print('Ground truth labels:', Ytrue.shape)
    Observations (10 samples x 1 variables per sample):
    tensor([[0.5503],
            [0.9206],
            [0.5359],
            [0.6081],
            [0.0202],
            [0.8545],
            [0.2357],
            [0.4847],
            [0.3996],
            [0.1957])
    Ground truth labels: torch.Size([10, 1])
    1.1 Create model
[3]: #for debugging purposes:
     def hook_print_values(m, in_, out_):
         print(m._get_name(), '(row per point)')
         print(out_.cpu().data.numpy().squeeze())
     # create model (we did it in form of a class)
     #class model
```

```
def __init__(self, ...):
             #...
         #define functions to do the forward pass
         #we added further hooks to execute printing function every fw-pass
         def forward(self, x):
             #...
         def add hooks(self):
             #...
         def reset hooks(self):
             #...
     #initialize weights (can also be done in a function)
     def print_response(...):
         #...
     #initialize number of layers and weights
     #call modelclass and print the layers of the model
     #for debugging purposes, we consider the tanh-function as an additional layer,
     →which is not intended
     #for the model construction.
     #As an additional layer, it provides information of "before and after effects"
     ⇔of the activation function.
     #This is not necessary and can be ommitted, since that layer can be given_
      →implicitly in a dense layer.
[3]: MyModel(
```

1.2 Perform a forward pass without any training

)

```
[4]: print("Initial parameter values:")
for param in model.parameters():
    print(param.data)
```

```
#add and reset hooks for debugging purposes (for prints below see function_
 →above)
#model.add hooks()
#with torch.no_grad():
     model(X)
#model.reset hooks()
Initial parameter values:
tensor([[-0.0224],
        [-0.4284].
        [0.0834]
tensor([ 0.2521, 0.2649, -0.3557])
tensor([[ 0.2152, -0.1047, 0.1244]])
tensor([-0.1316])
Linear (row per point)
[ 0.23148532 -0.12941168 -0.27899554]
 [ 0.24010374  0.03538335  -0.31106082]
 [ 0.23848625  0.00445483  -0.30504283]
 [ 0.25165692  0.25629523 -0.3540451 ]
 [ 0.23296615 -0.10109624 -0.28450507]
 [ 0.24682909  0.16398089  -0.33608288]
 [ 0.24125077  0.05731605 -0.3153284 ]
 [ 0.24315725  0.09377057 -0.3224216 ]
 [ 0.24772522  0.18111579 -0.33941695]]
Tanh (row per point)
[[ 0.235289
               0.02920647 - 0.30031022
 [ 0.22743732 -0.12869406 -0.2719752 ]
 [ 0.23559374  0.0353686  -0.30140185]
 [ 0.23406544  0.0044548  -0.2959207 ]
 [ 0.24647556  0.25082707 -0.33995804]
 [ 0.22884108 -0.10075322 -0.27706948]
 [ 0.24193566  0.16252673  -0.32397586]
 [ 0.23847568  0.0934967  -0.31169492]
 [ 0.24277915  0.17916106 -0.32695678]]
Linear (row per point)
 \begin{bmatrix} -0.12141277 & -0.10304759 & -0.12212807 & -0.11853886 & -0.14713818 & -0.10630424 \end{bmatrix} 
-0.13688318 -0.12466807 -0.12887354 -0.13881387]
MyModel (row per point)
 \begin{bmatrix} -0.12141277 & -0.10304759 & -0.12212807 & -0.11853886 & -0.14713818 & -0.10630424 \end{bmatrix} 
-0.13688318 -0.12466807 -0.12887354 -0.13881387]
```

1.3 Create the learning components and train the model for a single epoch

```
[5]: #choose the loss function
     #choose the method of optimization (e.g. gradient descent) and initialize its \sqcup
      ⇒parameters respectivly
     def train(model,
               loss fn,
               optimizer,
               num_iter,
               x_train, y_train):
         #implement the training for the model, return the loss.
     #train(model,...)
     print("New parameter values:")
     for param in model.parameters():
         print(param.data)
    0 loss = 0.48179250955581665
    New parameter values:
    tensor([[-0.0319],
            [-0.4235],
            [ 0.0778]])
    tensor([ 0.2902, 0.2461, -0.3352])
    tensor([[ 0.2628, -0.0357, 0.0564]])
    tensor([0.0571])
    1.4 Continue training
```

[6]: #train the model

```
0 loss = 0.4379696846008301
200 loss = 0.15191248059272766
400 loss = 0.09892342239618301
600 loss = 0.18876305222511292
800 loss = 0.13503369688987732
1000 loss = 0.12198492139577866
1200 loss = 0.10045844316482544
1400 loss = 0.08721771836280823
1600 loss = 0.08133644610643387
1800 loss = 0.07906016707420349
2000 loss = 0.07795830816030502
2200 loss = 0.07726430892944336
2400 loss = 0.07639358192682266
2800 loss = 0.07609931379556656
```

```
[6]: tensor(0.0759, grad_fn=<MseLossBackward0>)
[1]: #plot results: truth and predicted
[ ]:
```