

FastLog: Efficient End-to-end Rule Learning Over Large-scale Knowledge Graphs by Reduction to Vector Operations (Supplementary Material)

A PROOFS

In this section, we provide detailed proofs for all propositions in this work.

A.1 Proof of Proposition 1

PROOF. (I) We first prove that the time complexity of a forward computation step for TensorLog is $O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. Let $\text{nnz}(M_{r_i})$ be the number of non-zero elements in the sparse matrix M_{r_i} . From Equations (1-2), we know that the complexity for each step in TensorLog comes from $\sum_{i=1}^{2n+1} \phi_{r,x}^{(k,l-1)}(w_i^{(r,k,l)} M_{r_i})$. Since the time complexity of $\sum_{i=1}^{2n+1} \phi_{r,x}^{(k,l-1)}(w_i^{(r,k,l)} M_{r_i})$ is $\sum_{i=1}^{2n+1} (\text{nnz}(M_{r_i}) + |\mathcal{E}|)$, where $n = |\mathcal{R}|$. By $\sum_{i=1}^{2n+1} \text{nnz}(M_{r_i}) = |\mathcal{K}|$, we can infer that the time complexity of a forward computation step for TensorLog is $O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$.

(II) We then prove that the time complexity of a backward propagation step for TensorLog is $O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. For a backward propagation step, we know that only $w^{(r,k,l)}$ is trainable. The time complexity for calculating $\frac{\partial \mathcal{L}}{\partial \phi_{r,x}^{(k,l)}} M_{r_i}^T$ is $\text{nnz}(M_{r_i}) + |\mathcal{E}|$. Therefore, the time complexity of a backward propagation step for TensorLog is $O(NL(\sum_{i=1}^{2n+1} (\text{nnz}(M_{r_i}) + |\mathcal{E}|))) = O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. \square

A.2 Proof of Proposition 2

PROOF. (I) From Proposition 1 we know that the time complexity of a forward computation step for TensorLog is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. From Equations (3-6), we know that the time complexity of a forward computation step for NeuralLP is

$$\underbrace{L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|)}_{\text{TensorLog}} + \underbrace{\frac{L(L-1)}{2}|\mathcal{E}|}_{\text{Aggregation}} + \underbrace{(L+1)(8d^2)}_{\text{LSTM network}} + \underbrace{(d^2+d)}_{\text{MLP}}$$

where d denotes the hidden size. In general, it holds that $L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) + \frac{L(L-1)}{2}|\mathcal{E}| \gg (L+1)(8d^2) + (d^2+d)$. Therefore, we can infer that the time complexity of a forward computation step for NeuralLP is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) + L^2|\mathcal{E}|)$.

(II) From Proposition 1 we know that the time complexity of a backward propagation step for TensorLog is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. From Equations (3-6), we know that the time complexity of a backward propagation step for NeuralLP is

$$\underbrace{2L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|)}_{\text{TensorLog}} + \underbrace{L(L-1)|\mathcal{E}|}_{\text{Aggregation}} + \underbrace{2(L+1)(8d^2)}_{\text{LSTM network}} + \underbrace{2(d^2+d)}_{\text{MLP}}$$

In general, it holds that $L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) + L(L-1)|\mathcal{E}| \gg +2(L+1)(8d^2) + 2(d^2+d)$. Therefore, we can infer that the time complexity of a forward computation step for NeuralLP is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) + L^2|\mathcal{E}|)$. \square

A.3 Proof of Proposition 3

PROOF. From Equations (7-13), we know that DRUM, smDRUM and mmDRUM has the same training time complexity.

(I) From Proposition 1 we know that the time complexity of a forward computation step for TensorLog is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. From Equations (7-9), we know that the time complexity of a forward computation step for DRUM is

$$\underbrace{NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|)}_{\text{TensorLog}} + \underbrace{2N(L+1)(8d^2)}_{\text{BiLSTM networks}} + \underbrace{N((2d)^2 + 2d)}_{\text{MLPs}}$$

where d denotes the hidden size. In general, it holds that $NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) \gg N(L+1)(8d^2) + N((2d)^2 + 2d)$. Therefore, we can infer that the time complexity of a forward computation step for DRUM, smDRUM, and mmDRUM is $O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$.

(II) From Proposition 1 we know that the time complexity of a backward propagation step for TensorLog is $O(L(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. From Equations (7-9), we know that the time complexity of a backward propagation step for DRUM, smDRUM, and mmDRUM is

$$\underbrace{2NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|)}_{\text{TensorLog}} + \underbrace{4N(L+1)(8d^2)}_{\text{BiLSTM networks}} + \underbrace{2N((2d)^2 + 2d)}_{\text{MLPs}}$$

In general, it holds that $2NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|) \gg 4N(L+1)(8d^2) + 2N((2d)^2 + 2d)$. Therefore, we can infer that the time complexity of a forward computation step for DRUM, smDRUM, and mmDRUM is $O(NL(|\mathcal{K}| + |\mathcal{R}||\mathcal{E}|))$. \square

A.4 Proof of Proposition 4

PROOF. (I) From Equation (15), we know that the time complexity of the function \mathcal{F}_{e2f} is $|\mathcal{K}|$. From Equation (16), we know that the time complexity of the function \mathcal{F}_{r2f} is $|\mathcal{K}|$. From Equation (17), we know that the time complexity of the function \mathcal{F}_{f2e} is $2|\mathcal{K}|$. From Equation (18), we know that the time complexity of a forward computation step for FastLog is

$$NL(\underbrace{|\mathcal{K}|}_{\mathcal{F}_{\text{e2f}}} + \underbrace{|\mathcal{K}|}_{\mathcal{F}_{\text{r2f}}} + \underbrace{|\mathcal{K}|}_{\odot} \underbrace{2|\mathcal{K}|}_{\mathcal{F}_{\text{f2e}}})$$

Therefore, we can infer that the time complexity of a forward computation step for FastLog is $O(NL|\mathcal{K}|)$.

(II) For a backward propagation step of FastLog, we know that only $w^{(r,k,l)}$ is trainable. Let $z = \mathcal{F}_{\text{e2f}}(\phi_{r,x}^{(k,l-1)}) \odot \mathcal{F}_{\text{r2f}}(w^{(r,k,l)})$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{f2e}}(z)}{\partial z}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{e2f}}(\phi_{r,x}^{(k,l-1)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{r2f}}(w^{(r,k,l)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{r2f}}(w^{(r,k,l)})}{\partial w^{(r,k,l)}}$ is $O(|\mathcal{K}|)$. Therefore, the time complexity of a backward propagation step for FastLog is $O(NL|\mathcal{K}|)$. \square

A.5 Proof of Proposition 5

PROOF. From Proposition 4, we know that the time complexity of a forward computation step for FastLogis is $O(NL|\mathcal{K}|)$. From Equations (20-21), we know that the time complexity of a forward computation step for NeuralLP-FL is

$$\underbrace{L|\mathcal{K}|}_{\text{FastLog}} + \underbrace{\frac{L(L-1)}{2}|\mathcal{E}|}_{\text{Aggregation}} + \underbrace{(L+1)(8d^2)}_{\text{LSTM network}} + \underbrace{(d^2+d)}_{\text{MLP}}$$

where d denotes the hidden size. In general, it holds that $L|\mathcal{K}| + \frac{L(L-1)}{2}|\mathcal{E}| \gg (L+1)(8d^2) + (d^2+d)$. Therefore, we can infer that the time complexity of a forward computation step for NeuralLP-FL is $O(L|\mathcal{K}| + L^2|\mathcal{E}|)$.

(II) For a backward propagation step for NeuralLP-FL, we know that both $\mathbf{w}^{(r,1,l)}$ and $\alpha^{(r,1,l)}$ are trainable. Let $z = \mathcal{F}_{\text{e2f}}(\sum_{j=0}^{l-1} \alpha_j^{(r,1,l)} \phi_{r,x}^{(1,j)}) \odot \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,1,l)})$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{f2e}}(z)}{\partial z}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{e2f}}(\sum_{j=0}^{l-1} \alpha_j^{(r,1,l)} \phi_{r,x}^{(1,j)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \alpha^{(r,1,l)}}$ is $O(L^2|\mathcal{E}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,1,l)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,1,l)})}{\partial \mathbf{w}^{(r,1,l)}}$ is $O(|\mathcal{K}|)$. Therefore, the time complexity of a backward propagation step for NeuralLP-FL is $O(L|\mathcal{K}| + L^2|\mathcal{E}|)$. \square

A.6 Proof of Proposition 6

To prove Proposition 6, we first introduce three sparse matrices M_{e2f} , M_{r2f} , and M_{f2e} , where $M_{\text{e2f}} \in \mathbb{R}^{|\mathcal{E}| \times |\mathcal{K}|}$ (resp. $M_{\text{r2f}} \in \mathbb{R}^{2n \times |\mathcal{K}|}$ or $M_{\text{f2e}} \in \mathbb{R}^{|\mathcal{K}| \times |\mathcal{E}|}$) stores the mapping between a head entity (resp. relation or fact) and its corresponding fact (resp. fact or tail entity).

PROOF. For all $1 \leq l \leq L$, it holds that

$$\begin{aligned} \phi_{r,a}^{(l)} &= \mathcal{F}_{\text{f2e}}(\mathcal{F}_{\text{e2f}}(\sum_{j=0}^{l-1} \alpha_j^{(r,l)} \phi_{r,a}^{(j)}) \odot \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,l)})) \\ &= ((\sum_{j=0}^{l-1} \alpha_j^{(r,l)} \phi_{r,a}^{(j)}) M_{\text{e2f}} \odot (\mathbf{w}^{(r,l)} M_{\text{r2f}})) M_{\text{f2e}} \\ &= (\sum_{j=0}^{l-1} \alpha_j^{(r,l)} \phi_{r,a}^{(j)}) ((M_{\text{e2f}} \odot (\mathbf{w}^{(r,l)} M_{\text{r2f}})) M_{\text{f2e}}) \\ &= (\sum_{j=0}^{l-1} \alpha_j^{(r,l)} \phi_{r,a}^{(j)}) (\sum_{i=1}^{2n} \mathbf{w}_i^{(r,l)} M_{r_i}) \\ &= \sum_{i=1}^{2n} (\sum_{j=0}^{l-1} \alpha_j^{(r,l)} \phi_{r,a}^{(j)}) (\mathbf{w}_i^{(r,l)} M_{r_i}) \end{aligned}$$

Therefore, we have

$$\begin{aligned} \text{NeuralLP-FL}(\theta_r^L, a, b) &= \phi_{r,a}^{(L+1)} v_b \\ &= \sum_{j=0}^L \alpha_j^{(r,L+1)} \phi_{r,x}^{(j)} \\ &= \sum_{j=0}^L \alpha_j^{(r,L+1)} (\sum_{i=1}^{2n} (\sum_{k=0}^{j-1} \alpha_k^{(r,j)} \phi_{r,a}^{(k)}) (\mathbf{w}_i^{(r,j)} M_{r_i})) \\ &= \text{NeuralLP}(\theta_r^L, a, b) \end{aligned}$$

\square

A.7 Proof of Proposition 7

PROOF. (I) From Proposition 4, we know that the time complexity of a forward computation step for FastLogis is $O(NL|\mathcal{K}|)$. From Equations (22-23), we know that the time complexity of a forward computation step for DRUM-FL is

$$\underbrace{NL|\mathcal{K}|}_{\text{FastLog}} + \underbrace{2N(L+1)(8d^2)}_{\text{BiLSTM networks}} + \underbrace{N((2d)^2 + 2d)}_{\text{MLPs}}$$

where d denotes the hidden size. In general, it holds that $NL|\mathcal{K}| \gg 2N(L+1)(8d^2) + ((2d)^2 + 2d)$. Therefore, we can infer that the time complexity of a forward computation step for DRUM-FL is $O(NL|\mathcal{K}|)$.

(II) For a backward propagation step of DRUM-FL, we know that only $\mathbf{w}^{(r,k,l)}$ is trainable. Let $z = \mathcal{F}_{\text{e2f}}(\phi_{r,x}^{(k,l-1)}) \odot \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,k,l)})$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{f2e}}(z)}{\partial z}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{e2f}}(\phi_{r,x}^{(k,l-1)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial z}{\partial \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,k,l)})}$ is $O(|\mathcal{K}|)$. The time complexity for calculating $\frac{\partial \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,k,l)})}{\partial \mathbf{w}^{(r,k,l)}}$ is $O(|\mathcal{K}|)$. Therefore, the time complexity of a backward propagation step for DRUM-FL is $O(NL|\mathcal{K}|)$. \square

A.8 Proof of Proposition 8

To prove Proposition 8, we first introduce three sparse matrices M_{e2f} , M_{r2f} , and M_{f2e} , where $M_{\text{e2f}} \in \mathbb{R}^{|\mathcal{E}| \times |\mathcal{K}|}$ (resp. $M_{\text{r2f}} \in \mathbb{R}^{(2n+1) \times |\mathcal{K}|}$ or $M_{\text{f2e}} \in \mathbb{R}^{|\mathcal{K}| \times |\mathcal{E}|}$) stores the mapping between a head entity (resp. relation or fact) and its corresponding fact (resp. fact or tail entity).

PROOF. For all $1 \leq k \leq N, 1 \leq l \leq L$, it holds that

$$\begin{aligned} \phi_{r,a}^{(k,l)} &= \mathcal{F}_{\text{f2e}}(\mathcal{F}_{\text{e2f}}(\phi_{r,a}^{(k,l-1)}) \odot \mathcal{F}_{\text{r2f}}(\mathbf{w}^{(r,k,l)})) \\ &= ((\phi_{r,a}^{(k,l-1)} M_{\text{e2f}}) \odot (\mathbf{w}^{(r,k,l)} M_{\text{r2f}})) M_{\text{f2e}} \\ &= \phi_{r,a}^{(k,l-1)} ((M_{\text{e2f}} \odot (\mathbf{w}^{(r,k,l)} M_{\text{r2f}})) M_{\text{f2e}}) \\ &= \phi_{r,a}^{(k,l-1)} (\sum_{i=1}^{2n+1} \mathbf{w}_i^{(r,k,l)} M_{r_i}) \end{aligned}$$

Therefore, we have

$$\begin{aligned}
\text{DRUM-FL}(\theta_r^{N,L}, a, b) &= \left(\sum_{k=1}^N \phi_{r,a}^{(k,L)} \right) v_b \\
&= \left(\sum_{k=1}^N ((\cdots (v_a^\top \left(\sum_{i=1}^{2n+1} w_i^{(r,k,1)} M_{r_i} \right)) \right. \\
&\quad \left. \left(\sum_{i=1}^{2n+1} w_i^{(r,k,2)} M_{r_i} \right) \right. \\
&\quad \left. \cdots \right. \\
&\quad \left. \left. \left(\sum_{i=1}^{2n+1} w_i^{(r,k,L)} M_{r_i} \right) \right) \right) v_b \\
&= v_a^\top \left(\sum_{k=1}^N \prod_{l=1}^L \sum_{i=1}^{2n+1} w_i^{(r,k,l)} M_{r_i} \right) v_b \\
&= \text{DRUM}(\theta_r^{N,L}, a, b)
\end{aligned}$$

□

A.9 Proof of Proposition 9

To prove Proposition 9, we first introduce three sparse matrices M_{e2f} , M_{r2f} , and M_{f2e} , where $M_{e2f} \in \mathbb{R}^{|\mathcal{E}| \times |\mathcal{K}|}$ (resp. $M_{r2f} \in \mathbb{R}^{(2n+1) \times |\mathcal{K}|}$ or $M_{f2e} \in \mathbb{R}^{|\mathcal{K}| \times |\mathcal{E}|}$) stores the mapping between a head entity (resp. relation or fact) and its corresponding fact (resp. fact or tail entity).

PROOF. For all $1 \leq k \leq N$, $1 \leq l \leq L$, it holds that

$$\begin{aligned}
\phi_{r,a}^{(k,l)} &= \mathcal{F}_{f2e}^{\max}(\mathcal{F}_{e2f}(\phi_{r,a}^{(k,l-1)}) \odot \mathcal{F}_{r2f}(w^{(r,k,l)})) \\
&= ((\phi_{r,a}^{(k,l-1)} M_{e2f}) \odot (w^{(r,k,l)} M_{r2f})) \otimes M_{f2e} \\
&= \phi_{r,a}^{(k,l-1)} ((M_{e2f} \odot (w^{(r,k,l)} M_{r2f})) \otimes M_{f2e}) \\
&= \phi_{r,a}^{(k,l-1)} \otimes ((M_{e2f} \odot (w^{(r,k,l)} M_{r2f})) M_{f2e}) \\
&= \phi_{r,a}^{(k,l-1)} \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,l)} M_{r_i} \right)
\end{aligned}$$

Therefore, we have

$$\begin{aligned}
\text{smDRUM-FL}(\theta_r^{N,L}, a, b) &= \left(\sum_{k=1}^N \phi_{r,a}^{(k,L)} \right) v_b \\
&= \left(\sum_{k=1}^N ((\cdots (v_a^\top \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,1)} M_{r_i} \right)) \right. \\
&\quad \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,2)} M_{r_i} \right) \\
&\quad \cdots \\
&\quad \left. \left. \left(\sum_{i=1}^{2n+1} w_i^{(r,k,L)} M_{r_i} \right) \right) \right) v_b \\
&= v_a^\top \left(\sum_{k=1}^N \bigotimes_{l=1}^L \sum_{i=1}^{2n+1} w_i^{(r,k,l)} M_{r_i} \right) v_b \\
&= \text{smDRUM}(\theta_r^{N,L}, a, b)
\end{aligned}$$

□

A.10 Proof of Proposition 10

To prove Proposition 10, we first introduce three sparse matrices M_{e2f} , M_{r2f} , and M_{f2e} , where $M_{e2f} \in \mathbb{R}^{|\mathcal{E}| \times |\mathcal{K}|}$ (resp. $M_{r2f} \in \mathbb{R}^{(2n+1) \times |\mathcal{K}|}$ or $M_{f2e} \in \mathbb{R}^{|\mathcal{K}| \times |\mathcal{E}|}$) stores the mapping between a head entity (resp. relation or fact) and its corresponding fact (resp. fact or tail entity).

PROOF. For all $1 \leq k \leq N$, $1 \leq l \leq L$, it holds that

$$\begin{aligned}
\phi_{r,a}^{(k,l)} &= \mathcal{F}_{f2e}^{\max}(\mathcal{F}_{e2f}(\phi_{r,a}^{(k,l-1)}) \odot \mathcal{F}_{r2f}(w^{(r,k,l)})) \\
&= ((\phi_{r,a}^{(k,l-1)} M_{e2f}) \odot (w^{(r,k,l)} M_{r2f})) \otimes M_{f2e} \\
&= \phi_{r,a}^{(k,l-1)} ((M_{e2f} \odot (w^{(r,k,l)} M_{r2f})) \otimes M_{f2e}) \\
&= \phi_{r,a}^{(k,l-1)} \otimes ((M_{e2f} \odot (w^{(r,k,l)} M_{r2f})) M_{f2e}) \\
&= \phi_{r,a}^{(k,l-1)} \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,l)} M_{r_i} \right)
\end{aligned}$$

Therefore, we have

$$\begin{aligned}
\text{mmDRUM-FL}(\theta_r^{N,L}, a, b) &= \left(\max_{k=1}^N \phi_{r,a}^{(k,L)} \right) v_b \\
&= \left(\max_{k=1}^N ((\cdots (v_a^\top \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,1)} M_{r_i} \right)) \right. \\
&\quad \otimes \left(\sum_{i=1}^{2n+1} w_i^{(r,k,2)} M_{r_i} \right) \\
&\quad \cdots \\
&\quad \left. \left. \left(\sum_{i=1}^{2n+1} w_i^{(r,k,L)} M_{r_i} \right) \right) \right) v_b \\
&= v_a^\top \left(\max_{k=1}^N \bigotimes_{l=1}^L \sum_{i=1}^{2n+1} w_i^{(r,k,l)} M_{r_i} \right) v_b \\
&= \text{mmDRUM}(\theta_r^{N,L}, a, b)
\end{aligned}$$

□

A.11 Proof of Proposition 11

PROOF. (I) We first prove that the space complexity of a forward computation step for TensorLog is $O(m|\mathcal{E}|)$. For all $1 \leq k \leq N$, $1 \leq l \leq L$, TensorLog requires a space of $m|\mathcal{E}|$ to store the intermediate estimated truth degrees. Since the summation of predicate selection is serial, this process does not require additional space. Therefore, a forward computation step for TensorLog is $O(m|\mathcal{E}|)$.

(II) We then prove that the space complexity of a backward propagation step for TensorLog is $O(mNL(2|\mathcal{R}|+1)|\mathcal{E}|)$. For a backward propagation step, TensorLog requires to store all intermediate estimated truth degrees for all L steps for all N rules to calculate the gradient. Therefore, the space complexity of a backward propagation step for TensorLog is $O(mNL(2|\mathcal{R}|+1)|\mathcal{E}|)$. □

A.12 Proof of Proposition 12

PROOF. (I) We first prove that the space complexity of a forward computation step for FastLog is $O(m|\mathcal{K}|)$. For all $1 \leq k \leq N$, $1 \leq l \leq L$, FastLog requires a space of the size $m|\mathcal{K}|$ to store the intermediate hidden state for all facts. Although FastLog also requires a space of $m|\mathcal{E}|$ to store the intermediate estimated truth degrees,

it can reuse the previously opened space. In general, it holds that $|\mathcal{K}| > |\mathcal{E}|$. Therefore, a forward computation step for FastLog is $O(m|\mathcal{K}|)$.

(II) We then prove that the space complexity of a backward propagation step for FastLog is $O(mNL(|\mathcal{K}|+|\mathcal{E}|))$. For a backward propagation step, FastLog requires storing the intermediate hidden states for all L steps for all N rules to calculate the gradients. It also requires storing the intermediate estimated truth degrees for all L steps for all N rules to calculate the gradients. Therefore, the space complexity of a backward propagation step for TensorLog is $O(mNL(|\mathcal{K}| + |\mathcal{E}|))$. \square

A.13 Proof of Proposition 13

PROOF. (I) From Proposition 4, we know that the time complexity of a forward computation step for FastLog is $O(NL|\mathcal{K}|)$. From Equation (29), we know that the dynamic pruning strategy introduces an additional complexity of $O(NL|\mathcal{E}|)$ to calculate top- c_1 intermediate estimated truth degrees. From Equation (30), we know that the dynamic pruning strategy introduces an additional complexity of $O(NL|\mathcal{K}|)$ to calculate top- c_2 intermediate hidden states. Therefore, the time complexity of a forward computation step for FastLog $^{c_1, c_2}$ is $O(NL(|\mathcal{K}| + |\mathcal{E}|))$.

(II) From Equations (29), we know that only top- c_1 intermediate estimated truth degrees are used to calculate the gradients. From Equations (30), we know that only top- c_2 intermediate hidden states are used to calculate the gradients. Let $z = \hat{\mathcal{F}}_{\text{r2f}}^{c_2}(\hat{\mathcal{F}}_{\text{e2f}}^{c_1}(\phi_{r,x}^{(k,l-1)}), w^{(r,k,l)})$. The time complexity for calculating $\frac{\partial \hat{\mathcal{F}}_{\text{e2f}}^{c_2}(z)}{\partial z}$ is $O(c_2)$ because z only has c_2 elements. The time complexity for calculating $\frac{\partial z}{\partial w^{(r,k,l)}}$ is $O(c_2)$ because only the top- c_2 elements in $\hat{\mathcal{F}}_{\text{e2f}}^{c_1}(\phi_{r,x}^{(k,l-1)})$ are used to calculate gradients. The time complexity for calculating $\frac{\partial \hat{\mathcal{F}}_{\text{e2f}}^{c_1}(\phi_{r,x}^{(k,l-1)})}{\partial \phi_{r,x}^{(k,l-1)}}$ is $O(c_2)$ because only the top- c_2 elements in $\hat{\mathcal{F}}_{\text{e2f}}^{c_1}(\phi_{r,x}^{(k,l-1)})$ are used to calculate gradients. Therefore, the time complexity of a backward propagation step for FastLog is reduced to $O(NLc_2)$. \square

A.14 Proof of Proposition 14

PROOF. (I) We first prove that the space complexity of a forward computation step for FastLog is $O(m|\mathcal{K}|)$. For all $1 \leq k \leq N, 1 \leq l \leq L$, FastLog requires a space of the size $m|\mathcal{K}|$ to store the intermediate hidden state for all facts. Although FastLog also requires a space of $m|\mathcal{E}|$ to store the intermediate estimated truth degrees, it can reuse the previously opened space. In general, it holds that $|\mathcal{K}| > |\mathcal{E}|$. Therefore, a forward computation step for FastLog is $O(m|\mathcal{K}|)$.

(II) We then prove that the space complexity of a backward propagation step for FastLog is $O(mNL(c_1 + c_2))$. For a backward propagation step, FastLog requires storing the intermediate estimated truth degrees with the size of c_1 for all L steps for all N rules to calculate the gradients. It also requires storing the intermediate hidden states with the size of c_2 for all L steps for all N rules to calculate the gradients. Therefore, the space complexity of a backward propagation step for TensorLog is $O(mNL(c_1 + c_2))$. \square

A.15 Proof of Proposition 15

From Equations (15-17) and (29-31), we know that $\hat{\mathcal{F}}_{\text{e2f}}^{|\mathcal{E}|}$ (resp. $\hat{\mathcal{F}}_{\text{r2f}}^{|\mathcal{K}|}$ or $\hat{\mathcal{F}}_{\text{f2e}}^{|\mathcal{K}|}$) is equivalent to \mathcal{F}_{e2f} (resp. \mathcal{F}_{r2f} or \mathcal{F}_{f2e}) because both $\mathcal{T}^{|\mathcal{E}|}(\mathbb{T})$ and $\mathcal{T}^{|\mathcal{K}|}(\mathbb{T})$ return the original set \mathbb{T} of tuples. Therefore, Equation (18) can be derived by:

$$\begin{aligned} \text{FastLog}(\theta_r^{N,L}, a, b) &= \sum_{k=1}^N \phi_{r,a}^{(k,L)} v_b \\ &= \sum_{k=1}^N \mathcal{F}_{\text{f2e}}(\mathcal{F}_{\text{r2f}}(w^{(r,k,L)}) \odot \mathcal{F}_{\text{e2f}}(\dots \\ &\quad \mathcal{F}_{\text{f2e}}(\mathcal{F}_{\text{r2f}}(w^{(r,k,2)}) \odot \mathcal{F}_{\text{e2f}}(\mathcal{F}_{\text{f2e}}(\mathcal{F}_{\text{r2f}}(w^{(r,k,1)}) \odot \mathcal{F}_{\text{e2f}}(v_x^\top)))) \dots)) v_b \\ &= \sum_{k=1}^N \hat{\mathcal{F}}_{\text{f2e}}(\hat{\mathcal{F}}_{\text{r2f}}^{|\mathcal{K}|}(\hat{\mathcal{F}}_{\text{e2f}}^{|\mathcal{E}|}(\dots \\ &\quad \hat{\mathcal{F}}_{\text{f2e}}^{|\mathcal{K}|}(\hat{\mathcal{F}}_{\text{r2f}}^{|\mathcal{K}|}(\hat{\mathcal{F}}_{\text{e2f}}^{|\mathcal{E}|}(v_x^\top), w^{(r,k,1)}), \dots), \\ &\quad w^{(r,k,L)})) \\ &= \text{FastLog}^{|\mathcal{E}|, |\mathcal{K}|}(\theta_r^{N,L}, a, b) \end{aligned}$$