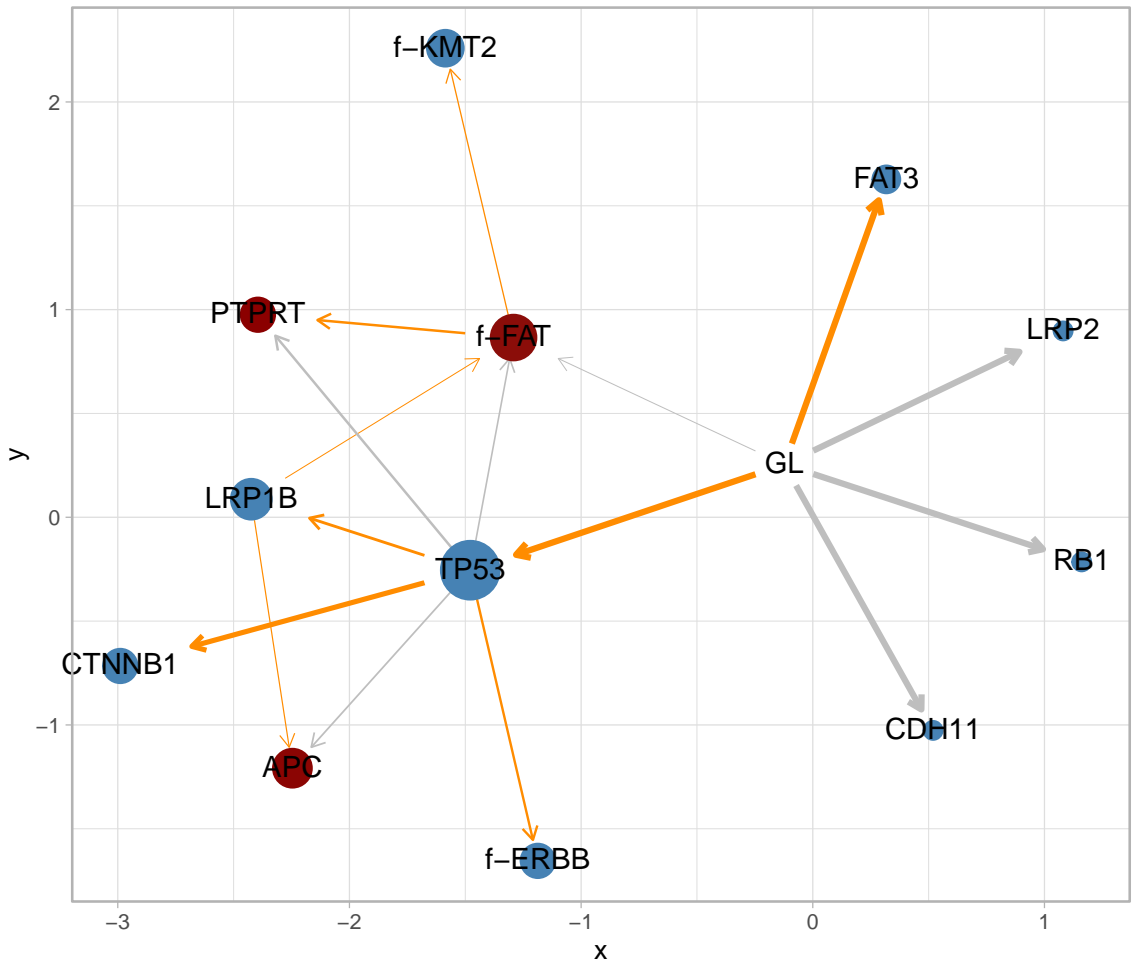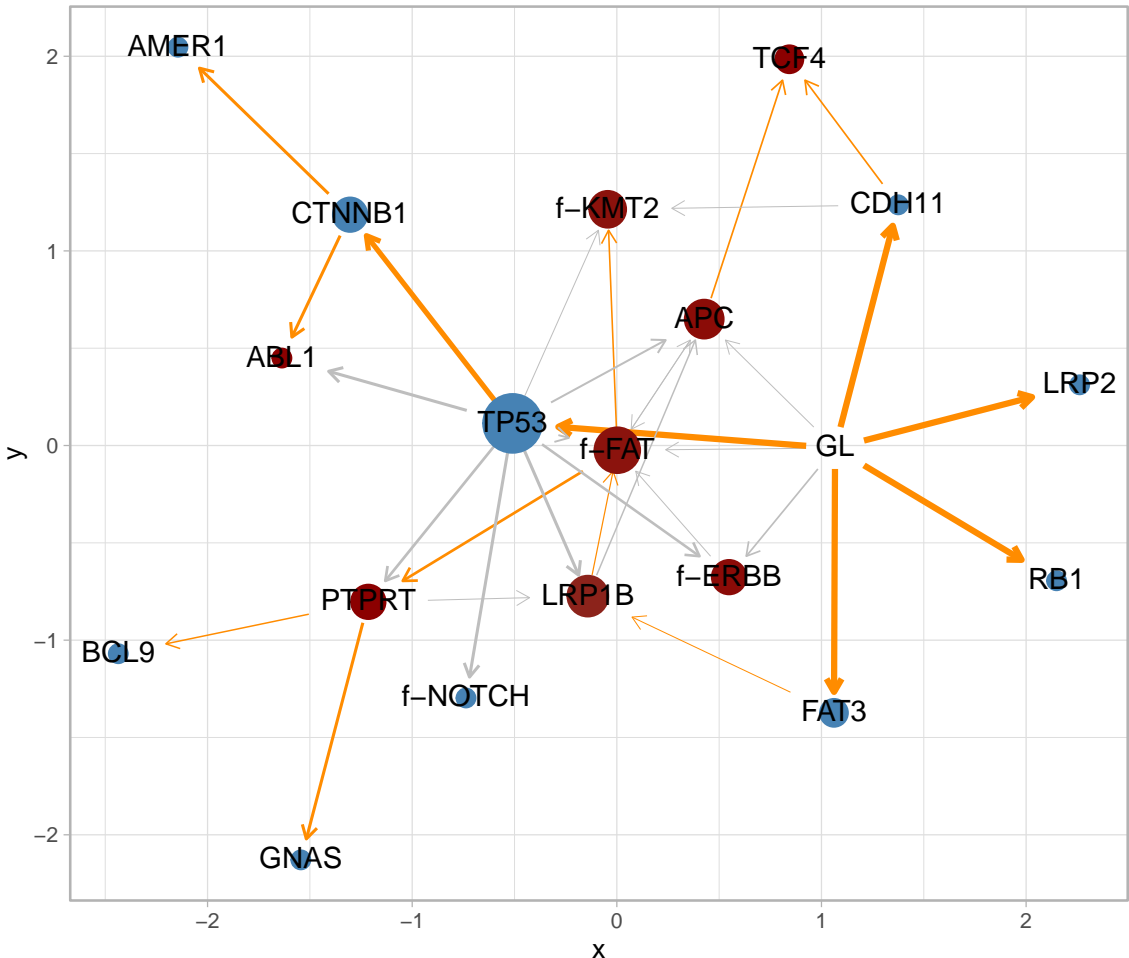Driver to driver trajectories

Penalty: > 0.2 > 0.4 > 0.6 > 0.8 > 1.0   Significant enrichment at level 0.05: > FALSE > TRU

Driver to driver trajectories