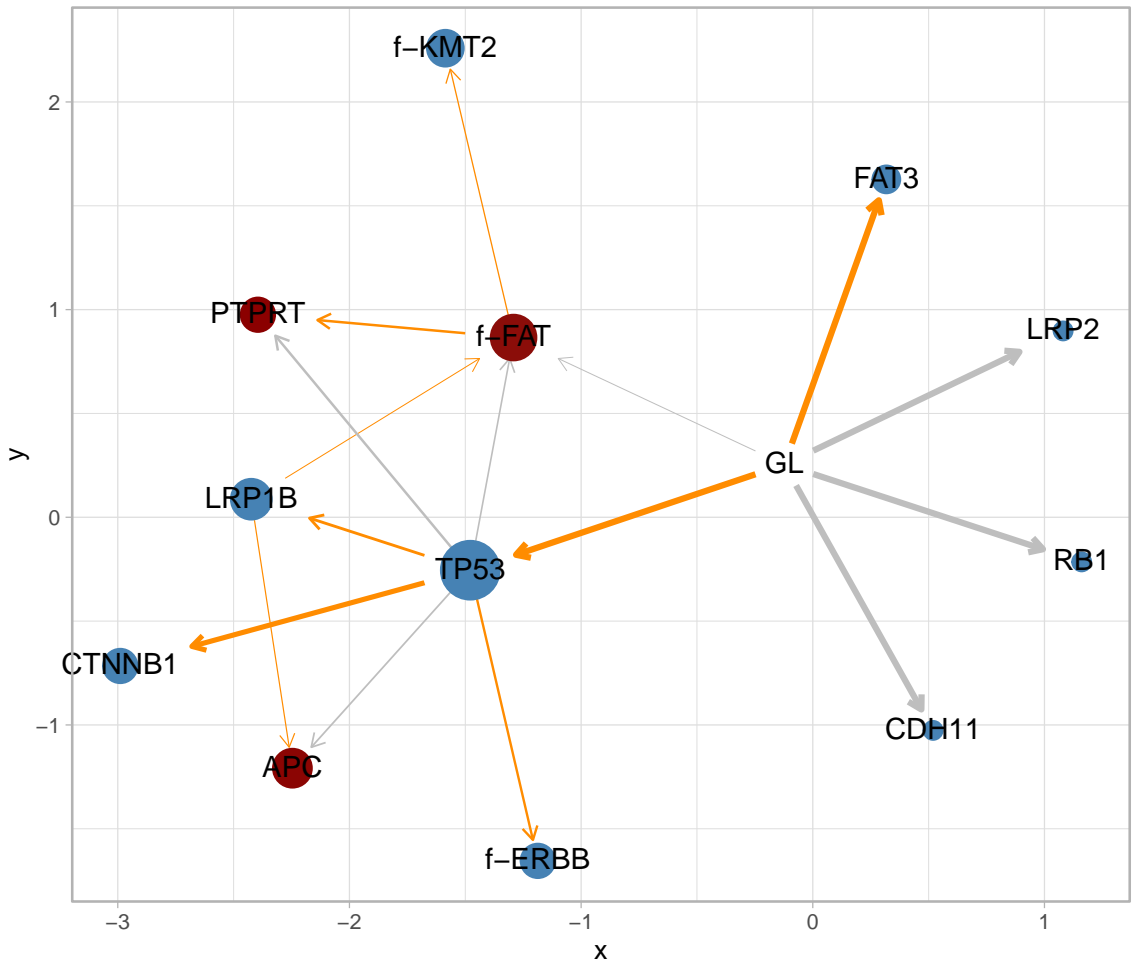


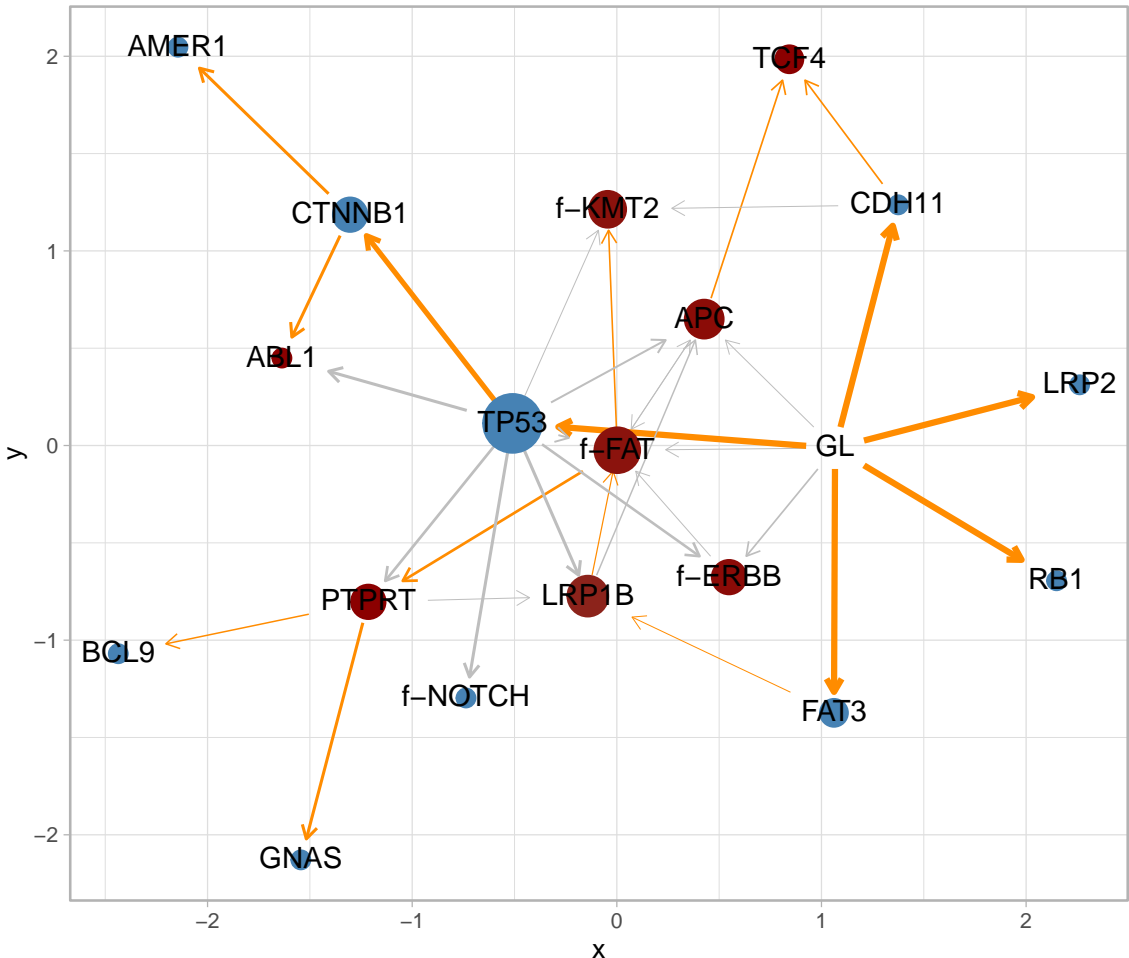
# Driver to driver trajectories



Penalty > 0.2 > 0.4 > 0.6 > 0.8 > 1.0

Significant enrichment at level 0.05 > FALSE > TRUE

## Driver to driver trajectories



Penalty  $\rhd$  0.25  $\rhd$  0.50  $\rhd$  0.75  $\rhd$  1.00

Significant enrichment at level 0.05 ➤ FALSE ➤ TRUE