

Deep Learning Exercise 07 Loss function

• $f(u, \sigma) = -\frac{(t-u)^2}{2\sigma^2} - \log(\sqrt{2\pi}\sigma)$

a) $\frac{\partial f}{\partial u} = \frac{2t-2u}{2\sigma^2} = \frac{(t-u)}{\sigma^2}$

$$\begin{aligned} \frac{\partial f}{\partial \sigma} &= -\frac{(t-u)^2}{2} \cdot (-2) \cdot \sigma^{-3} - \left[\frac{1}{\sqrt{2\pi} \cdot \sigma} \right] \cdot \\ &= \frac{(t-u)^2}{\sigma^3} - \frac{1}{\sigma} \end{aligned}$$

b) $g(z) = \sqrt{1+z^2}$ * nonlinear activation function

$$\begin{aligned} \frac{\partial g(z)}{\partial z} &= \frac{1}{2} \cdot (1+z^2)^{-\frac{1}{2}} \cdot 2z \\ &= z \cdot (1+z^2)^{-\frac{1}{2}} \\ &= z \cdot (1+z^2)^{\frac{1}{2}} \cdot (-1) \\ &= z \cdot \frac{1}{\sigma} \end{aligned}$$

$$\frac{\partial f}{\partial z} = \frac{\partial f}{\partial \sigma} \cdot \frac{\partial \sigma}{\partial z}$$

$$\begin{aligned} &= \left(\frac{(t-u)^2}{\sigma^3} - \frac{1}{\sigma} \right) \cdot \frac{z}{\sigma} \\ &= \left(\frac{(t-u)^2}{\sigma^4} - \frac{1}{\sigma^2} \right) \cdot z \end{aligned}$$

c) $\left| \frac{\partial f}{\partial z} \right| = \left| \left[\frac{(t-u)^2}{\sigma^4} - \frac{1}{\sigma^2} \right] \cdot z \right|$
 $\sigma \geq 1 \text{ and } \sigma \geq |z| \Rightarrow |z| \leq 1$

$$\begin{aligned} \Rightarrow \left| \frac{\partial f}{\partial z} \right| &\leq \left| \left[\frac{(t-u)^2}{\sigma^4} - \frac{1}{\sigma^2} \right] \right| \cdot |z| \\ &\leq \left[\left[\frac{(t-u)^2}{\sigma^2} - 1 \right] \cdot \frac{1}{\sigma^2} \right] \cdot 1 \end{aligned}$$

because $\sigma \geq 1 \Rightarrow \sigma^2 \geq 1 \Rightarrow \frac{1}{\sigma^2} \leq 1$

$$\Rightarrow \left| \frac{\partial f}{\partial z} \right| \leq \left[\left[\frac{(t-u)^2}{\sigma^2} - 1 \right] \cdot 1 \right]$$

$$= \left| \frac{(t-u)^2 - \sigma^2}{\sigma^2} \right|$$

$$\leq \left| (t-u)^2 - \sigma^2 \right|$$

rewrite σ as $(1+\varepsilon)$, $\varepsilon \geq 0$

$$\left| \frac{\partial f}{\partial z} \right| \leq \left| (t-u)^2 - (1+\varepsilon)^2 \right|$$

$$= \left| (t-u)^2 - 1 - 2\varepsilon - \varepsilon^2 \right|$$

because $(1+\varepsilon)^2 \geq 1$

$$\begin{aligned} \Rightarrow \left| \frac{\partial f}{\partial z} \right| &\leq \left| (t-u)^2 - 1 \right| \\ &\leq (t-u)^2 + 1 \end{aligned}$$

~~Difficult~~

d)

$$J(\theta) = \frac{1}{N} \sum_{i=1}^N \left(-\frac{|t_i - u_i|^2}{2\sigma_i^2} - \log(\sqrt{2\pi} \cdot \sigma_i) \right)$$

$$\frac{\partial f}{\partial u} = \frac{(t-u)}{\sigma^2}$$

$$\frac{\partial f}{\partial z} = \left(\frac{(t-u)^2}{\sigma^4} - \frac{1}{\sigma^2} \right) \cdot z \quad , \text{ with } \sigma = \sigma(z)$$

$$f_i(u_i, z_i) = -\frac{|t_i - u_i|^2}{2\sigma_i^2} - \log(\sqrt{2\pi} \cdot \sigma_i)$$

$$J(\theta) = \frac{1}{N} \sum_{i=1}^N f_i(u_i(\theta), z_i(\theta))$$

$$\frac{\partial f_i}{\partial \theta} = \frac{\partial f_i}{\partial u_i} \cdot \frac{\partial u_i}{\partial \theta} + \frac{\partial f_i}{\partial z_i} \cdot \frac{\partial z_i}{\partial \theta}$$

$$\frac{\partial J}{\partial \theta} = \frac{1}{N} \sum_{i=1}^N \left(\frac{\partial f_i}{\partial u_i} \cdot \frac{\partial u_i}{\partial \theta} + \frac{\partial f_i}{\partial z_i} \cdot \frac{\partial z_i}{\partial \theta} \right)$$

(e) $\theta = (w, v)$, $u_i = w^T x_i$, $z_i = v^T \cdot x_i$

$$\frac{\partial u_i}{\partial w} = x_i \quad , \quad \cancel{\frac{\partial z_i}{\partial v}} = x_i$$

$$\frac{\partial u_i}{\partial v} = 0 \quad , \quad \cancel{\frac{\partial z_i}{\partial w}} = 0$$

$$\frac{\partial f_i}{\partial z_i} = \left(\frac{(t_i - u_i)^2}{\sigma_i^4} - \frac{1}{\sigma_i^2} \right) \cdot z_i$$

$$\frac{\partial f_i}{\partial u_i} = \frac{t_i - u_i}{\sigma_i^2}$$

$$\frac{\partial J}{\partial w} = \frac{1}{N} \sum_{i=1}^N \frac{\partial f_i}{\partial w_i} = \frac{1}{N} \sum_{i=1}^N \frac{\partial f_i}{\partial u_i} \cdot \frac{\partial u_i}{\partial w_i}$$

$$= \frac{1}{N} \sum_{i=1}^N \frac{(t_i - u_i)}{\sigma_i^2} \cdot x_i = \frac{1}{N} \sum_{i=1}^N \frac{(t_i - w^T x_i)}{\sigma_i^2} \cdot x_i$$

$$\begin{aligned} \frac{\partial J}{\partial v} &= \frac{1}{N} \sum_{i=1}^N \frac{\partial f_i}{\partial v} = \frac{1}{N} \sum_{i=1}^N \frac{\partial f_i}{\partial z_i} \cdot \frac{\partial z_i}{\partial v} \\ &= \frac{1}{N} \sum_{i=1}^N \left(\frac{(t_i - u_i)^2}{\sigma_i^4} - \frac{1}{\sigma_i^2} \right) z_i \cancel{x_i} \\ &= \frac{1}{N} \sum_{i=1}^N \left(\frac{(t_i - u_i)^2}{\sigma_i^4} - \frac{1}{\sigma_i^2} \right) \cdot (v^T \cdot x_i) x_i \end{aligned}$$

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