Modern Computational Statistics

Lecture 1: Introduction



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School of Mathematical Sciences, Peking University

September 9, 2019

- ► Class times:
 - ▶ Monday 6:40-8:30pm, odd Wednesday 8:00-9:50pm
 - ► Classroom Building No.3, Room 504
- ► Tentative office hours:
 - ► Wednesday 10:00-11:00am
 - ► By appointment
- ► Website:

https://zcrabbit.github.io/courses/msc-f19.html

► Join us at Piazza:
https://piazza.com/peking_university/fall2019/00113730



- ► A branch of mathematical sciences focusing on efficient numerical methods for statistically formulated problems
- ► The focus lies on computer intensive statistical methods and efficient modern statistical models.
- ▶ Developing rapidly, leading to a broader concept of computing that combines the theories and techniques from many fields within the context of statistics, mathematics and computer sciences.



Goals 4/30

- ▶ Become familiar with a variety of modern computational statistical techniques and knows more about the role of computation as a tool of discovery
- ▶ Develop a deeper understanding of the mathematical theory of computational statistical approaches and statistical modeling.
- ▶ Understand what makes a good model for data.
- ▶ Be able to analyze datasets using a modern programming language (e.g., python).



- ► Optimization Methods
 - ► Gradient Methods
 - ► Expectation Maximization
- ► Approximate Bayesian Inference Methods
 - ▶ Markov chain Monte Carlo
 - ► Variational Inference
 - ► Scalable Approaches
- ► Applications in Machine Learning
 - ► Variational Autoencoder
 - ► Generative Adversarial Networks
 - ► Flow-based Generative Models



Familiar with at least one programming language (with python preferred!).

- ► All class assignments will be in python (and use numpy).
- ► You can find a good Python tutorial at

http://www.scipy-lectures.org/

You may also find another shorter python+numpy tutorial useful at **here**

Familiar with the following subjects (better if have taken related courses)

- Probability and Statistical Inference
- ► Stochastic Processes



- ▶ 4 Problem Sets: $4 \times 15\% = 60\%$
- ► Final Course Project: 40%
 - ► Midterm proposal: 5%
 - ► Final write-up: 35%
 - ▶ Bonus point for exceptional oral presentation
- ► Late policy
 - ▶ 7 free late days, use them in your ways
 - ► Afterward, 25% off per late day
 - ▶ Not accepted after 3 late days per PS
 - ▶ Does not apply to Final Course Project
- ► Collaboration policy
 - ► Finish your work independently, verbal discussion allowed



- ➤ You may structure your project exploration around a general problem type, algorithm, or data set, but should explore around your problem, testing thoroughly or comparing to alternatives.
- ➤ You should submit a project proposal that briefly describe your project concept and goals in one page by 11/04.
- ► There will be in class project presentation at the end of the term. Not presenting your projects will be taken as voluntarily giving up the opportunity for the final write-ups.
- ▶ You should turn in a write-up (< 10 pages) describing your project and its outcomes, similar to a research-level publication.



▶ A brief overview of statistical approaches

 \blacktriangleright Basic concepts in statistical computing





















 \mathcal{D}



Linear Models

Neural Networks

Bayesian Nonparametric Models

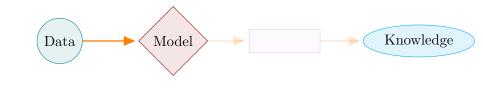
Generalized Linear Models



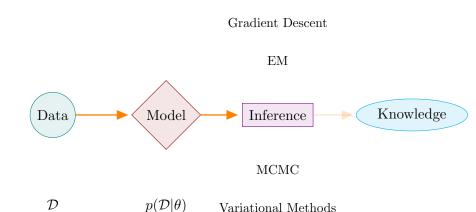
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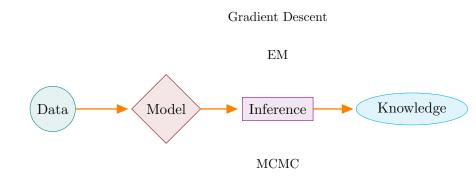
 \mathcal{D}



 $p(\mathcal{D}|\theta)$



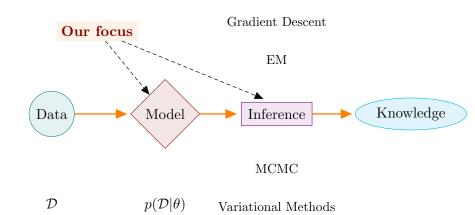
 \mathcal{D}



Variational Methods

 $p(\mathcal{D}|\theta)$





"All models are wrong, but some are useful."

George E. P. Box

Models are used to describe the data generating process, hence prescribe the probabilities of the observed data \mathcal{D}

$$p(\mathcal{D}|\theta)$$

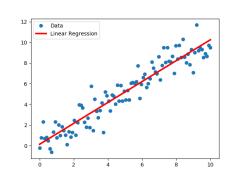
also known as the **likelihood**.



Data:
$$\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$$

Model:

$$Y = X\theta + \epsilon, \ \epsilon \sim \mathcal{N}(0, \sigma^2 I_n)$$
$$\Rightarrow Y \sim \mathcal{N}(X\theta, \sigma^2 I_n)$$



$$p(Y|X,\theta) = (2\pi\sigma^2)^{-n/2} \exp\left(-\frac{\|Y - X\theta\|_2^2}{2\sigma^2}\right)$$



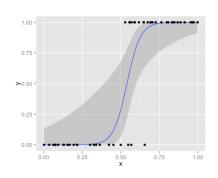
Data:

$$\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n, \ y_i \in \{0, 1\}$$

Model:

$$Y \sim \text{Bernoulli}(p)$$

$$p = \frac{1}{1 + \exp(-X\theta)}$$



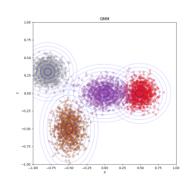
$$p(Y|X,\theta) = \prod_{i=1}^{n} p_i^{y_i} (1-p_i)^{1-y_i}$$

Data:
$$\mathcal{D} = \{y_i\}_{i=1}^n, \ y_i \in \mathbb{R}^d$$

Model:

$$y|Z=z \sim \mathcal{N}(\mu_z, \sigma_z^2 I_d)$$

 $Z \sim \text{Categorical}(\alpha)$



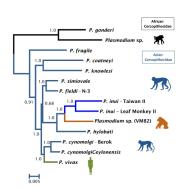
$$p(Y|\mu, \sigma, \alpha) = \prod_{i=1}^{n} \sum_{k=1}^{K} \alpha_k (2\pi\sigma_k^2)^{(-d/2)} \exp\left(-\frac{\|y_i - \mu_k\|_2^2}{2\sigma_k^2}\right)$$



CTITICAAGG AGTATITCCT ATGAACGAGT TAGACGGCAT
CATTGCAAAG GGAATAATCT ATGAACGCAA TAATTATIGA
CATTITCAGG ATAACTTICT ATGAAAGTAA ACTTAATACT
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GTTATTAAGG ATATGTTCAT ATGTTTTTCA AAAAGAACCT
TACCCACCGG ATTTTTTACC ATGCTCACCG TTAAGCAGAT
AATCAAAATG GAATAAAATC ATGCTACCAT CTATTTCAAT
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ACATCCAGTG AGAGAACCG ATGCATCCGA TGCTGCAACAT



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TGCAAAAAAA GGAAGACCAT ATGCTTGACG CTCAAACCAT
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TACCCACCGG ATTTTTACCC ATGCTCACCG TAAGCAGAT
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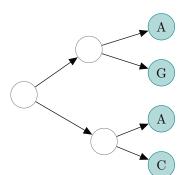




Model: Phylogenetic tree: (τ, q) . Substitution model:

- stationary distribution: $\eta(a_{\rho})$.
- ► transition probability:

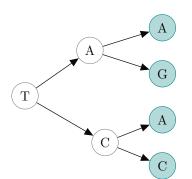
$$p(a_u \to a_v | q_{uv}) = P_{a_u a_v}(q_{uv})$$



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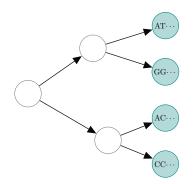
$$\eta(a_{\rho}^i) \prod_{(u,v) \in E(\tau)} P_{a_u^i a_v^i}(q_{uv})$$



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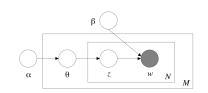


$$p(Y|\tau, q) = \prod_{i=1}^{n} \sum_{a^{i}} \eta(a_{\rho}^{i}) \prod_{(u,v) \in E(\tau)} P_{a_{u}^{i} a_{v}^{i}}(q_{uv})$$

where a^i agree with y^i at the tips.



Data: a corpus $\mathcal{D} = \{\boldsymbol{w}_i\}_{i=1}^M$



Model: for each document w in \mathcal{D} ,

- choose a mixture of topics $\theta \sim \text{Dir}(\alpha)$
- for each of the N words w_n ,

$$z_n \sim \text{Multinomial}(\theta), \quad w_n|z_n, \beta \sim p(w_n|z_n, \beta)$$

$$p(\mathcal{D}|\alpha,\beta) = \prod_{d=1}^{M} \int p(\theta_d|\alpha) \prod_{n=1}^{N_d} \sum_{z_{dn}} p(z_{dn}|\theta_d) p(w_{dn}|z_{dn},\beta) d\theta_d$$

Many well-known distributions take the following form

$$p(y|\theta) = h(y) \exp (\phi(\theta) \cdot T(y) - A(\theta))$$

- $\phi(\theta)$: natural/canonical parameters
- ightharpoonup T(y): sufficient statistics
- \blacktriangleright $A(\theta)$: log-partition function

$$A(\theta) = \log \left(\int_{y} h(y) \exp(\phi(\theta) \cdot T(y)) \ dy \right)$$

 $Y = \{y_i\}_{i=1}^n, y_i \sim p(y_i|\theta), \text{ the Log-likelihood}$

$$L(\theta; Y) = \sum_{i=1}^{n} \log p(y_i | \theta)$$

The gradient of L with respect to θ is called the **score**

$$s(\theta) = \frac{\partial L}{\partial \theta}$$

The expected value of the score is zero

$$\mathbb{E}(s) = n \int \frac{\partial \log p(y|\theta)}{\partial \theta} p(y|\theta) \ dy = n \frac{\partial}{\partial \theta} \int p(y|\theta) \ dy = 0$$



Fisher information is the variance of the score.

$$\mathcal{I}(\theta) = E(ss^T)$$

Under mild assumptions (e.g., exponential families),

$$\mathcal{I}(\theta) = -\mathbb{E}\left(\frac{\partial^2 L}{\partial \theta \partial \theta^T}\right)$$

Intuitively, Fisher information captures the variability of the score. Therefore, it reflects the sensitivity of model about the parameter at its current value.

$$\hat{\theta}_{MLE} = \operatorname*{arg\,max}_{\theta} L(\theta)$$

- ▶ Consistency. Under weak regularity condition, $\hat{\theta}_{MLE}$ is consistent: $\hat{\theta}_{MLE} \to \theta_0$ in probability as $n \to \infty$, where θ_0 is the "true" parameter
- ► Asymptotical Normality.

$$\sqrt{n}(\hat{\theta}_{MLE} - \theta_0) \to \mathcal{N}(0, \mathcal{I}^{-1}(\theta_0))$$

See Rao 1973 for more details.

$$L(\theta; y) = y \log \theta - \theta - \log y!$$

$$s(\theta) = \frac{y}{\theta} - 1, \quad \mathcal{I}(\theta) = \frac{1}{\theta}$$

$$\hat{\theta}_{MLE} = \arg \max_{\theta} \sum_{i=1}^{n} y_i \log \theta - n\theta = \frac{\sum_{i=1}^{n} y_i}{n}$$

By the Law of large numbers

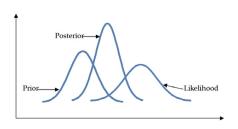
$$\hat{\theta}_{MLE} \xrightarrow{p} \theta_0$$

By central limit theorem

$$\sqrt{n}(\hat{\theta}_{MLE} - \theta_0) \xrightarrow{d} \mathcal{N}(0, \theta_0)$$



In Bayesian statistics, besides specifying a model $p(y|\theta)$ for the observed data, we also specify our **prior** $p(\theta)$ for the model parameters.



Bayes rule for inverse probability

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) \cdot p(\theta)}{p(\mathcal{D})} \propto p(\mathcal{D}|\theta) \cdot p(\theta)$$

known as the **posterior**.



- uncertainty quantification, provides more useful information
- ightharpoonup reducing overfitting. Regularization \iff Prior.

Prediction

$$p(x|\mathcal{D}) = \int p(x|\theta, \mathcal{D})p(\theta|\mathcal{D})d\theta$$

Model Comparison

$$p(m|\mathcal{D}) = \frac{p(\mathcal{D}|m)p(m)}{p(\mathcal{D})}$$

$$p(\mathcal{D}|m) = \int p(\mathcal{D}|\theta, m) p(\theta|m) d\theta$$

- ▶ Subjective Priors. Priors should reflect our beliefs as well as possible. They are subjective, but not arbitrary.
- ▶ **Hierarchical Priors**. Priors of multiple levels.

$$p(\theta) = \int p(\theta|\alpha)p(\alpha) d\alpha$$
$$= \int p(\theta|\alpha) d\alpha \int p(\alpha|\beta)p(\beta) d\beta$$

▶ Conjugate Priors. Priors that ease computation, often used to facilitate the development of inference and parameter estimation algorithms.

- ▶ Conjugacy: prior $p(\theta)$ and posterior $p(\theta|Y)$ belong to the same family of distribution
- ► Exponential family

$$p(Y|\theta) \propto \exp\left(\phi(\theta) \cdot \sum_{i} T(y_i) - nA(\theta)\right)$$

Conjugate prior

$$p(\theta) \propto \exp(\phi(\theta) \cdot \nu - \eta A(\theta))$$

► Posterior

$$p(\theta|Y) \propto \exp\left(\phi(\theta) \cdot (\nu + \sum_{i} T(y_i)) - (n+\eta)A(\theta)\right)$$



Data: $\mathcal{D} = \{x_i\}_{i=1}^m$. For each x in \mathcal{D}

$$p(\boldsymbol{x}|\theta) \propto \exp\left(\sum_{k=1}^{K} x_k \log \theta_k\right)$$

Use $Dir(\alpha)$ as the conjugate prior

$$p(\theta) \propto \exp\left(\sum_{k=1}^{K} (\alpha_k - 1) \log \theta_k\right)$$

$$p(\theta|\mathcal{D}) \propto \exp\left(\sum_{k=1}^{K} \left(\alpha_k - 1 + \sum_{i=1}^{M} x_{ik}\right) \log \theta_k\right)$$

Consider random variables $\{X_t\}, t = 0, 1, \dots$ with state space \mathcal{S}

Markov Property

$$p(X_{n+1} = x | X_0 = x_0, \dots, X_n = x_n) = p(X_{n+1} = x | X_n = x_n)$$

Transition Probability

$$P_{ij}^n = p(X_{n+1} = j | X_n = i), \quad i, j \in \mathcal{S}.$$

A Markov chain is called *time homogeneous* if $P_{ij}^n = P_{ij}, \forall n$.

A Markov chain is governed by its transition probability matrix.

► Stationary Distribution.

$$\pi^T P = \pi^T$$
.

▶ Ergodic Theorem. If the Markov chain is irreducible and aperiodic, with stationary distribution π , then

$$X_n \xrightarrow{d} \pi$$

and for any function h

$$\frac{1}{n} \sum_{t=1}^{n} h(X_t) \to \mathbb{E}_{\pi} h(X), \quad n \to \infty$$

given $\mathbb{E}_{\pi}|h(X)|$ exists.

- ▶ In general, finding MLE and posterior analytically is difficult. We almost always have to resort to computational methods.
- ▶ In this course, we'll discuss a variety of computational techniques for numerical optimization and integration, approximate Bayesian inference methods, with applications in statistical machine learning, computational biology and other related field.

Signup in Piazza:

https://piazza.com/peking_university/fall2019/00113730



References 30/30

▶ J. Felsenstein. Evolutionary trees from DNA sequences: a maximum likelihood approach. J. Mol. Evol. 17, 368–376 (1981)

- ▶ D. M. Blei, A. Y. Ng, and M. I. Jordan. Latent dirichlet allocation. JMLR 3, 2003.
- ► C. R. Rao. Linear Statistical Inference and its Applications. 2nd edition. New York: Wiley, 1973.
- ► S. M. Ross. Introduction to Probability Models, 7th ed. Academic, 2000.

