

EE360T/382V Software Testing

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Overview

Today – Chapter 2: Graph coverage criteria

Last class – Chapter 1: Introduction

Next class – Chapter 2: Graph coverage for source code

- Read: Section 2.3

Recall: Coverage criteria for testing

D1.20 Test requirement – specific element of the software artifact that a test case must cover (satisfy)

- Some requirements may be infeasible

D1.21 Coverage criterion – rule or collection of rules that impose test requirements on a test suite

- Criterion defines requirements precisely

D1.22 Coverage – given test requirements TR for coverage criterion C , test suite T satisfies C if and only if for each $tr \in TR$, at least one test in T satisfies tr

D1.23 Coverage level – given requirements TR and suite T , coverage level is

Recall: Subsumption

D1.24 Criteria subsumption – criterion C_1 subsumes criterion C_2 if and only if every test suite that satisfies C_1 also satisfies C_2

Note: must be true for every test suite

Example: if a test suite covers every branch, it covers every statement

Black-box or white-box?

D1.25 Black-box testing – deriving tests from external descriptions

- E.g., specs, designs, and requirements

D1.26 White-box testing – deriving tests from the source-code internals

- E.g., branches, conditions, and statements

Modern testing techniques often use both black-box and white-box approaches

Recall: Criteria based on structures

The textbook focuses on four kinds of structures to define criteria:

- **Graphs** (Chapter 2)
 - E.g., control-flow graphs (CFGs)
- **Logical expressions** (Chapter 3)
 - E.g., if-conditions
- **Input domain characterization** (Chapter 4)
 - E.g., sorted array
- **Syntactic structures** (Chapter 5)
 - E.g., mutation

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Chapter 2*: Graph Coverage

*Introduction to Software Testing by Ammann and Offutt

Overview

Graphs form the basis for many coverage criteria

- Define test requirements using graph elements
- Given an artifact:
 - Create a graph abstraction, e.g., control-flow
 - Evaluate how test execution paths cover test requirements

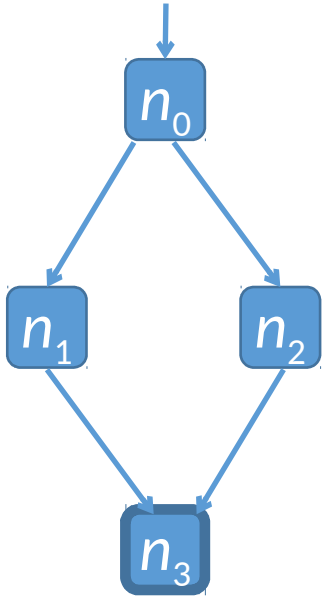
A graph $G = \langle N, E \rangle$

- N is a set of nodes and $E: N \times N$ is a set of edges

Let $N_0 \subseteq N$ be a set of *initial* nodes

Let $N_f \subseteq N$ be a set of *final* nodes

Example graphs

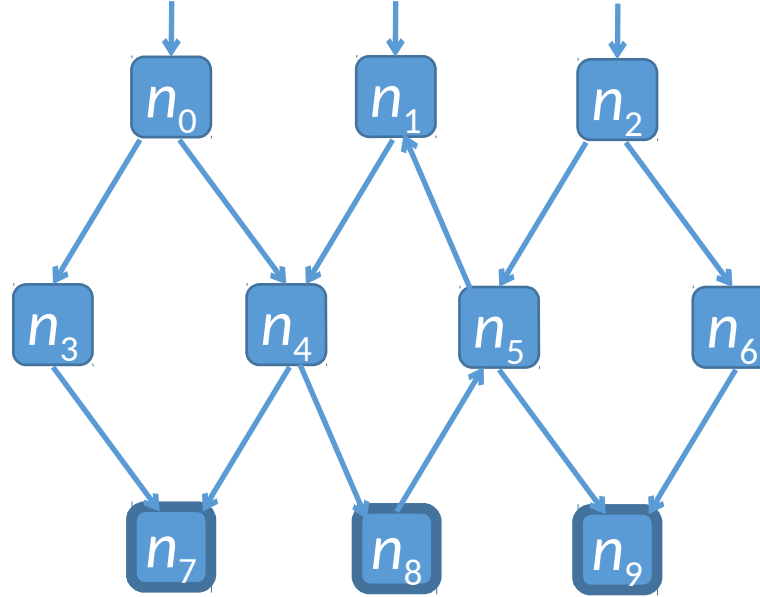


$$N = \{ n_0, \dots, n_3 \}$$

$$N_0 = \{ n_0 \}$$

$$E = \{ (n_0, n_1), (n_0, n_2), \\ (n_1, n_3), (n_2, n_3) \}$$

$$|E| = 4$$

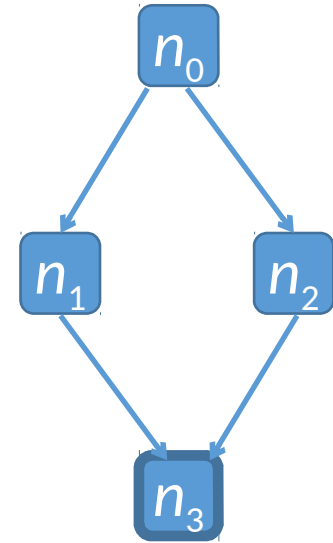


$$N = \{ n_0, \dots, n_9 \}$$

$$N_0 = \{ n_0, n_1, n_2 \}$$

$$E = \{ (n_0, n_3), (n_0, n_4), (n_1, n_4), \\ (n_2, n_5), (n_2, n_6), \dots \}$$

$$|E| = 12$$



$$N = \{ n_0, \dots, n_3 \}$$

$$N_0 = \{ \}$$

$$E = \{ (n_0, n_1), (n_0, n_2), \\ (n_1, n_3), (n_2, n_3) \}$$

$$|E| = 4$$

Path

A **path** $p = \langle n_1, n_2, \dots, n_t \rangle$ in graph $G = \langle N, E \rangle$ is a sequence of nodes such that $(n_i, n_{i+1}) \in E$ for $1 \leq i < t$

A **sub-path** of a path p is a sub-sequence of p

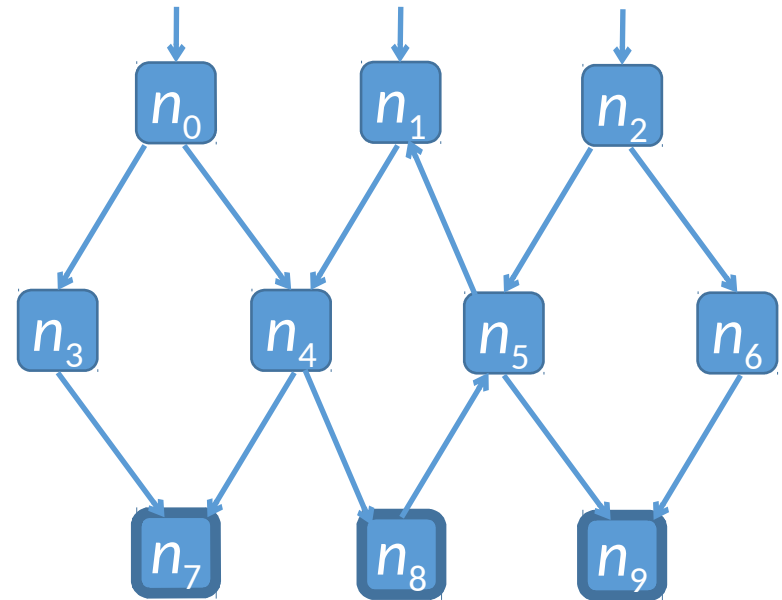
The **length** of a path is the number of edges it has

Example paths:

- $\langle n_0, n_3, n_7 \rangle$
- $\langle n_1, n_4, n_8, n_5, n_1 \rangle$
- $\langle n_4, n_8, n_5, n_9 \rangle$

Example non-path:

- $\langle n_0, n_7 \rangle$



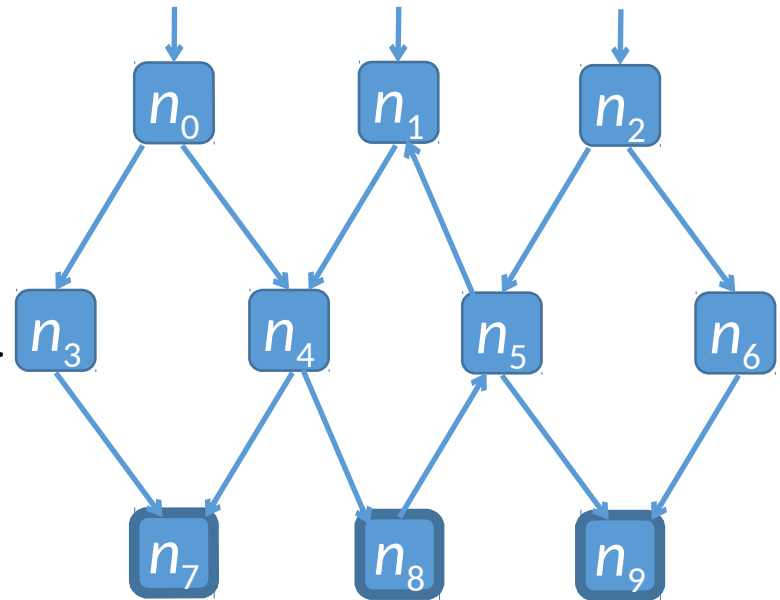
Syntactic reachability

A node n (or edge e) is **syntactically reachable** from from node m if there exists a path from m to n (or e)

Let $reach_G(x)$ be set of nodes in G reachable from x

Reachability examples:

- $reach(n_0) = N - \{ n_2, n_6 \}$
- $reach(\{ n_0, n_1, n_2 \}) = N$
- $reach((n_6, n_9)) = \{ n_6, n_9 \}$



Test path

D2.31 Test path – a path p (possibly of length 0) that starts at an initial node and ends at a final node

- In deterministic code, each test executes a unique path
- In non-deterministic code, each test may execute multiple paths

Test path p **visits node** n if n is on p

Test path p **visits edge** e if e is on p

For test t , write **$path(t)$** for test path executed by t

For test suite T , **$path(T) = \{ path(t) \mid t \in T \}$**

Graph coverage criteria

Graph coverage criteria define requirements on properties of test paths in a graph, e.g., CFG

Two common forms of criteria

- Structural graph coverage criteria
- Data flow coverage criteria

A test requirement is **met** by *visiting* a particular node or edge or *touring* a particular path

D2.32 Graph coverage – Given test requirements TR for a graph criterion C , test suite T satisfies C if and only if $\forall tr \in TR \mid \exists p \in path(T) \mid p \text{ meets } tr$

Structural coverage criteria

Let G be the graph that models the software

D2.33 Node coverage – for each node $n \in \text{reach}(N_0)$, TR contains the predicate “visit n ”

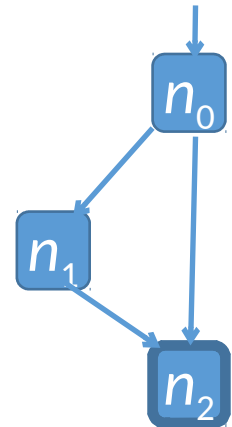
C2.1 Node coverage (NC) – TR contains each reachable node in G

C2.2 Edge coverage (EC) – TR contains each reachable path of length up to 1 (inclusive) in G

Example – Let tests t_1 and t_2 be such that:

- $\text{path}(t_1) = \langle n_0, n_1, n_2 \rangle$
- $\text{path}(t_2) = \langle n_0, n_2 \rangle$

Then $\{ t_1 \}$ gives NC and $\{ t_1, t_2 \}$ gives EC



EPC, PPC, and CPC

C2.2 Edge-pair coverage (EPC) – TR contains each reachable path of length up to 2 (inclusive) in G

A path p is **simple** if no node appears more than once on p except that first and last node may be the same

D2.35 Prime path – a prime path is a simple path that is not a proper subpath of another simple path

C2.3 Prime path coverage (PPC) – TR contains each prime path in G

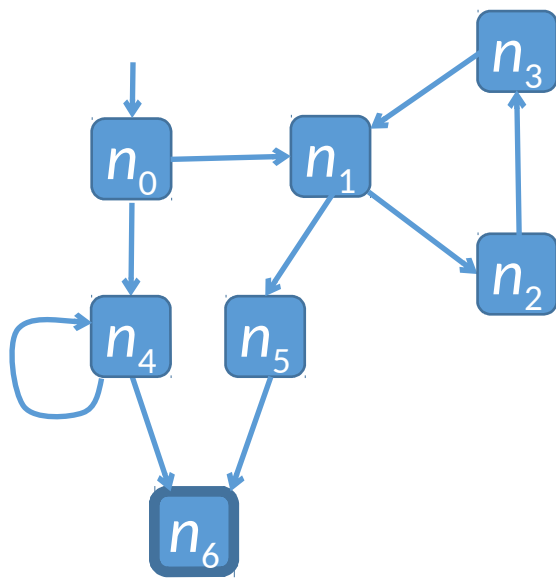
- Provides an elegant way to treat loops

C2.7 Complete path coverage (CPC) – TR contains all paths in G

Finding prime paths

Simple algorithm

- Start with paths of length 0, extend to length 1, ...
- Collect all simple paths, and filter for prime



Length 0:

[0]
[1]
[2]
[3]
[4]
[5]
[6]!

Length 1:

[0,1]
[0,4]
[1,2]
[1,5]
[2,3]
[3,1]
[4,4]*
[4,6]!
[5,6]!

Length 2:

[0,1,2]
[0,1,5]
[0,4,6]!
[1,2,3]
[1,5,6]!
[2,3,1]
[3,1,2]
[3,1,5]

Length 3:

[0,1,2,3]
[0,1,5,6]!
[1,2,3,1]*
[2,3,1,2]*
[2,3,1,5]
[3,1,2,3]*
[3,1,5,6]!

Length 4:

[2,3,1,5,6]!

?/!