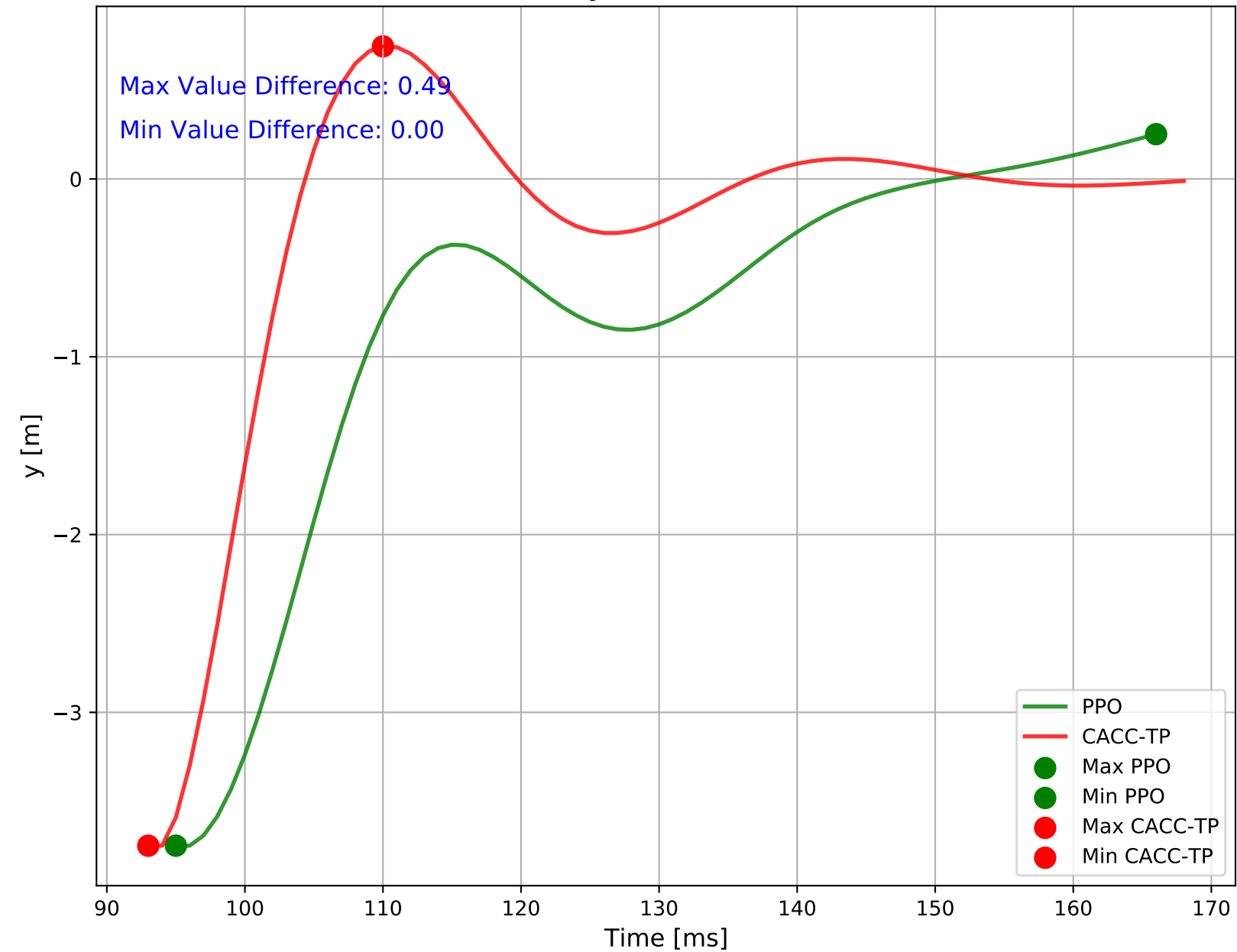


time-y (one vehicle)



time-y (all vehicles)

