view frames Result Recorded at time: 1755314824.719 world link Broadcaster: /static_transform_publisher_1755314635605362082 Average rate: 10000.000 Hz

Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 0.000 sec world base_link Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Buffer length: 0.000 sec box Link lidar_Link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1755314824.719 sec old) Average rate: 10000.000 Hz

Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec lifting_Link arm base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 33.152 Hz
Most recent transform: 1755314824.712 (0.008 sec old) Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 4.977 sec Buffer length: 0.000 sec top_camera_Link link1 Broadcaster: /robot_state_publisher Average rate: 33.152 Hz Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec link2 Broadcaster: /robot state publisher Average rate: 33.152 Hz Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec link3 Broadcaster: /robot_state_publisher Average rate: 33.152 Hz
Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec link4 Broadcaster: /robot state publisher Average rate: 33.152 Hz Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec link5 Broadcaster: /robot_state_publisher Average rate: 33.152 Hz
Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec link6 Broadcaster: /robot state publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 0.000 sec gripper_base Broadcaster: /robot_state_publisher Average rate: 33.152 Hz Broadcaster: /robot_state_publisher Average rate: 33.152 Hz
\Most recent transform: 1755314824.712 (0.008 sec old) Most recent transform: 1755314824.712 (0.008 sec old) Buffer length: 4.977 sec Buffer length: 4.977 sec link8

Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz
\Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 0.000 sec Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1755314824.719 sec old) Most recent transform: 0.000 (1755314824.719 sec old) Most recent transform: 0.000 (1755314824.719 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec under_camera_Link