

## Bit Twiddling

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### Why bit twiddling?

- When setting PORTs and DDRs, one needs to be careful not to disturb the state of other bits of the register.
- For example, the following code attempts to set pin 2 of PORTD

```
1 DDRD |= 0b00000100;
```

- Unfortunately, this code also clears all other bits of PORTD
- Bit twiddling allows not to set all 8 bits in register PORT without regard for the directions of each individual pin, i.e. all the bits stored in DDR
- For example, the above example could be best solved as follows

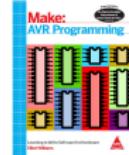
```
1 DDRD = DDRD | (1<<2);
2 /*which can also be written as*/
3 DDRD |= (1<<2);
```

- Please read "Programming 101 - By Eric Weddington"<sup>5</sup> for more details.

<sup>5</sup><https://www.avrfreaks.net/forum/tut-c-bit-manipulation-aka-programming-101?page=all>

## Reading material

- Bit manipulation (AKA "Programming 101")<sup>1</sup>
- Chap 4 of Williamson, E. (2014). Make: Avr programming. Maker Media<sup>2</sup>.
- AVR Bit Manipulation in C<sup>3</sup>
- Bitwise Operations in Embedded Programming<sup>4</sup>



<sup>1</sup><https://www.avrfreaks.net/forum/tut-c-bit-manipulation-aka-programming-101?page=all>  
<sup>2</sup><https://appzine.best/hardware/avr/5.html>  
<sup>3</sup><http://www.rjhcoding.com/avr-bit-manip.php>  
<sup>4</sup><https://binaryupdates.com/bitwise-operations-in-embedded-programming/>

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### Bit Shifting

- Bit shifting—a bitwise operator that allows to move (to the left or right) the order of one or several bits
- Bit-shifting is very fast and required fewer CPU operations compared to arithmetic (e.g., multiplication and division) operations.
- Bit shifting uses Bitwise Operators<sup>6</sup>

Operator	Name	Example	Result
&	Bitwise AND	6 & 3	2
	Bitwise OR	10   10	10
^	Bitwise XOR	2^2	0
~	Bitwise 1's complement	~9	-10
<<	Left-Shift	10<<2	40
>>	Right-Shift	10>>2	2

FIG 1. Example of Bitwise operations

<sup>6</sup>[https://en.wikipedia.org/wiki/Bitwise\\_operation](https://en.wikipedia.org/wiki/Bitwise_operation)

## Bit Shifting

There are three main types of shifts:

- Left Shifts—When shifting left, the most-significant bit is lost, and a 0 bit is inserted on the other end.
  - The left shift operator is usually written as <<

```
1 (0010 << 1)=0100 /* (2<<1)=4 */
2 (0010 << 2)=1000 /* (2<<2)=8 */
```

- Right Shifts—When shifting right with an arithmetic right shift, the least-significant bit is lost and the most-significant bit is copied.
  - The right shift operator is usually written as >>

```
1 (1011 >> 1)=1101 /* (11>>1)=5 */
2 (1011 >> 3)=0001 /* (11>>3)=1 */
```

- Logical Right Shifts—When shifting right with a logical right shift, the least-significant bit is lost and a 00 is inserted on the other end.

```
1 (1011 >>> 1)=0101
2 (1011 >>> 3)=0001
```

## Setting Bits with the OR operator

Consider the diodes in Figure 4 and Figure 7

- How would you turn on LED1 while other LEDs are turned off?

```
1 /*set the pin as an
   output*/
2 DDRB |= (1<<PBO);
3 /*set the bit PBO as
   high*/
4 PORTB |=(1<<PBO);
```

- How would you turn on only LED2 and LED3 and leave out other LEDs in their previous state?

```
1 PORTB |= (1<< PB1) |
  (1<< PB2);
```

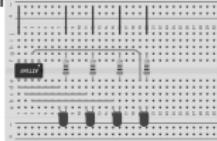


FIG 2



FIG 3

## Controlling Memory-Mapped I/O Registers Using Bit Operations

### Clearing a bit with AND and NOT operators

- How to turn OFF LED 1 only

```
1 /*Set PBO to low/
  PORTB &= ~(1<<PBO);
```

- How would you turn OFF only LED2 and LED3 and leave out other LEDs in their previous state?

```
1 PORTB &= ~( (1<<PB1) |
  (1<< PB2));
```

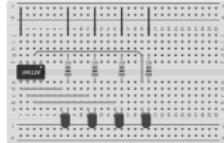


FIG 4

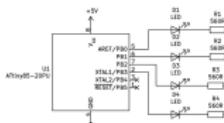


FIG 5

NOTE: There is a NOT outside the parentheses in order to have two zeros

# Toggling Bits with XOR operator

- How to toggle OFF LED 1 only

```
1 PORTB ^= (1<<PBO);
```

- How to toggle only LED2 and LED3 and leave out other LEDs in their previous state?

```
1 PORTB ^= ((1<<PB1) | (1<<PB2));
```

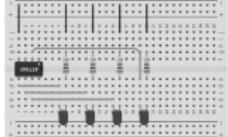


FIG 6

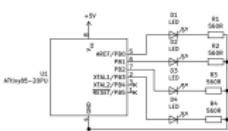


FIG 7

Noted:

- Don't forget to set direction of pins first! else, the pin will not be set
- Remember if pins are configured as inputs (DDR<sub>B</sub> bit is 0) then the corresponding

# Testing a Bit

- Suppose we need to know if the switch *S1* is pressed
- We use the PIN register to know the content of the PORT

```
1 int status=(PINB & (1<<PB0));
2 if(status){
3   // If the switch is pressed
4 }
```

- You can also check multiple switches

```
1 int status=PINB& ((1<<PB4) | (1<<PB5))
2 if(status){
3   //If any of the switches is
4     pressed
5 }
```

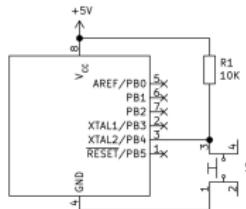


FIG 8

# AVR bit twiddling

TAB 1. Important bit-twiddling operations.

Operation	Implementation in C	Implication
Set a bit	PORTB  = (1<<PB1)	Bit PB1 is set to 1 [other pins are left unchanged]
Clear bit	PORTB &= ~ (1<<PB1)	Bit PB1 is set to 0 [other pins are left unchanged]
Toggle a bit	PORTB ^= (1<<PB1)	If Bit PB1 was 1, it is toggled to 0. Otherwise, it is set to 1 [other pins are left unchanged]
Read a value bit	uint8_t bit = PORTB & (1<< PB1)	Read and put the value of bit PB1 of PORTB into the variable bit. This is used to read switches.

## Important readings:

- Please read the document—which is uploaded on the course website—entitled 'AVR Bit Twiddling' to better understand this important topic.
- You should also read "Bit manipulation" by Eric Weddington<sup>8</sup>

<sup>8</sup><https://www.avrfreaks.net/forum/tut-c-bit-manipulation-aka-programming-101?page=all>

# Special bit twiddling AVR functions

One can use the `_BV(x)` macro defined in `avr/sfr_defs.h` which is included through `avr/io.h` as `#define _BV(x) (1<<x)`

```
DDR0 &= ~_BV(0); //set PORTD pin0 to zero as
input
PORTD |= _BV(0); //Enable pull up;
DDR0 |= _BV(1); //set PORTD pin1 to one as output
PORTD |= _BV(1); //led ON
while (1) {
  if (bit_is_clear(PIND, 0)) {
    //if button is pressed
    while (1) {
      PORTD &= ~_BV(1); //turn the led OFF
      //LED OFF while Button is pressed
      loop_until_bit_is_set(PIND, 0);
      PORTD |= _BV(1); //turn the led ON
    }
  }
}
```

# Software Delay Functions

AVR GCC compiler's util/delay.h defines the \_delay\_ms(double ms) function

- Requires # include <util/delay.h>
- F\_CPU preprocessor symbol should be defined as MCPU frequency in Hz using #define or passed through the -D compiler option
  - In code: #define F\_CPU 8000000UL //8 MHz clock
  - Command line option: -D F\_CPU=8000000UL
- The maximum delay is calculated as

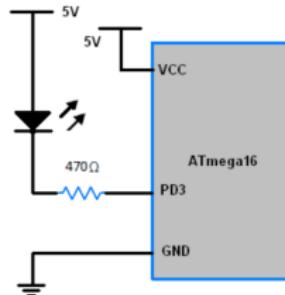
$$delay = \frac{4294967.295 \cdot 10^6}{F\_CPU} \quad (1)$$

- Thus, for an 8MHz clock, the maximum delay would be

$$delay = \frac{4294967.295 \cdot 10^6}{8 \cdot 10^6} = 536871ms \quad (2)$$

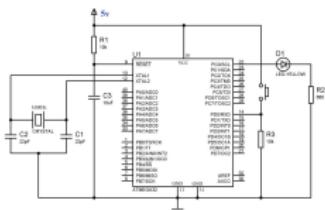
# Example: blink an LED

```
#define F_CPU 8000000UL
#include <avr/io.h>
#include <util/delay.h>
int main(void)
{
    //Set all pins of DDR3 as output
    DDRD = DDRO | (1<<3);
    while(1)
    {
        //Turn on the LED by making pin PD3 high
        PORTD = PORTD | (1<<3);
        //Wait one second
        _delay_ms(1000);
        //Turn off the LED by making pin PD3 low
        PORTD = PORTD & ~(1<<3);
        _delay_ms(1000);
    }
    return 0;
}
```



# Example: Reading switch

```
#include <avr/io.h>
#include <util/delay.h>
int main(void)
{
    //Set PC0 as Output
    DDRC |= (1 << PC0);
    //Set PD0 as an input
    DDRD &= ~(1 << PD0);
    while (1)
    {
        //Turns OFF LED
        PORTC &= ~(1 << PC0);
        //If switch is pressed
        if (PIND & (1 << PD0) == 1) {
            //Turns ON LED for one second
            PORTC |= (1 << PC0);
            _delay_ms(1000);
        }
    }
}
```



The end