Qiskit Mentorship Program

Midterm checkpoint

Project: Good first issues on Retworkx

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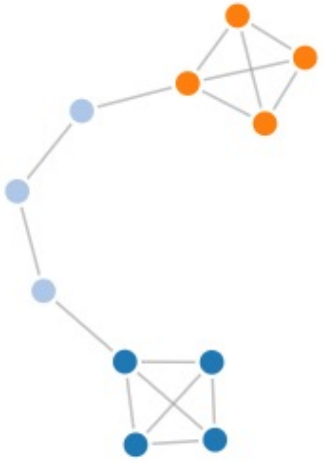
Presenter: Chris (Jielun) Chen

Disclaimer: this is an individual presentation; the speaker does not represent the whole team.

NetworkX

Network Analysis in Python

NetworkX is a Python package for the creation, manipulation, and study of the structure, dynamics, and functions of complex networks.



networkx in Rust → retworkx

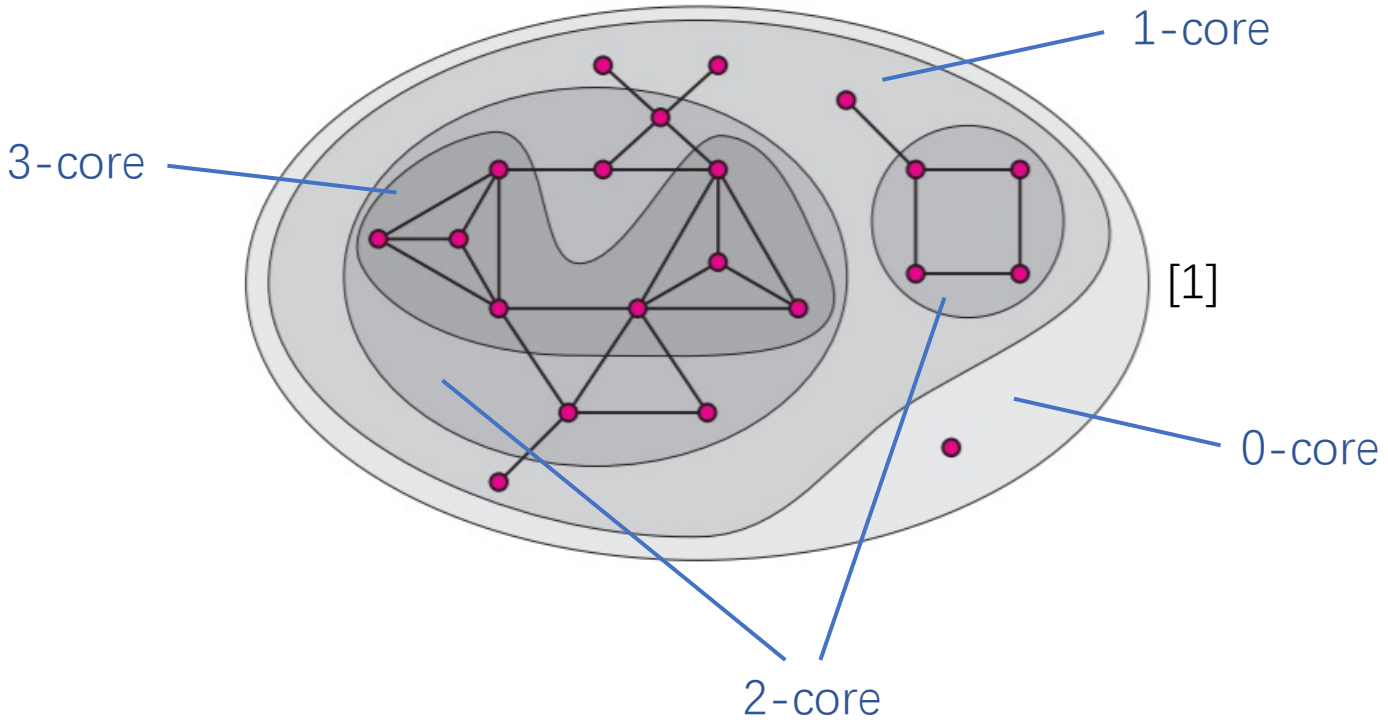
All graph usage in qiskit!

Why Rust

- 1. Memory safety
  - Does not permit null pointers, dangling pointers, or data races
  - Data values can be initialized only through a fixed set of forms
- 2. Memory management
  - Ownership
  - Low-level control
  - No need for garbage collection
- 3. High performance
  - Speed on par with C++; much faster than Python
  - Low-risk parallel computation

Merged issue: **k-core** of a graph

A **k-core** is a maximal subgraph that contains nodes of degree k or more. For directed graphs, the degree is in_degree + out_degree.



[1] Batagelj, Vladimir & Zaveršnik, Matjaž. (2003). An O(m) Algorithm for Cores Decomposition of Networks. CoRR. cs.DS/0310049.

Merged issue: **k-core** of a graph

rayon::slice::ParallelSliceMut

```
node_vec.par_sort_by_key(|k| degree_map.get(k));
```

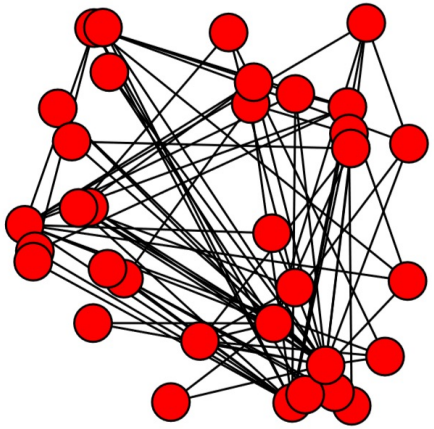
Algorithm 1: *The Cores Algorithm for Simple Undirected Graphs* [1]

```
01  procedure cores(var g: graph; var deg: tableVert);
02  var
03     n, d, md, i, start, num: integer;
04     v, u, w, du, pu, pw: integer;
05     vert, pos: tableVert;
06     bin: tableDeg;
07  begin
08     n := size(g);  md := 0;
09     for v := 1 to n do begin
10        d := 0;  for u in Neighbors(g, v) do inc(d);
11        deg[v] := d;  if d > md then md := d;
12     end;
13     for d := 0 to md do bin[d] := 0;
14     for v := 1 to n do inc(bin[deg[v]]);
15     start := 1;
16     for d := 0 to md do begin
17        num := bin[d];
18        bin[d] := start;
19        inc(start, num);
20     end;
21     for v := 1 to n do begin
22        pos[v] := bin[deg[v]];
23        vert[pos[v]] := v;
24        inc(bin[deg[v]]);
25     end;
26     for d := md downto 1 do bin[d] := bin[d-1];
27     bin[0] := 1;
28     for i := 1 to n do begin
29        v := vert[i];
30        for u in Neighbors(g, v) do begin
31           if deg[u] > deg[v] then begin
32              du := deg[u];   pu := pos[u];
33              pw := bin[du];  w := vert[pw];
34              if u <> w then begin
35                 pos[u] := pw;  vert[pu] := w;
36                 pos[w] := pu;  vert[pw] := u;
37              end;
38              inc(bin[du]);  dec(deg[u]);
39           end;
40        end;
41     end;
42  end;
```

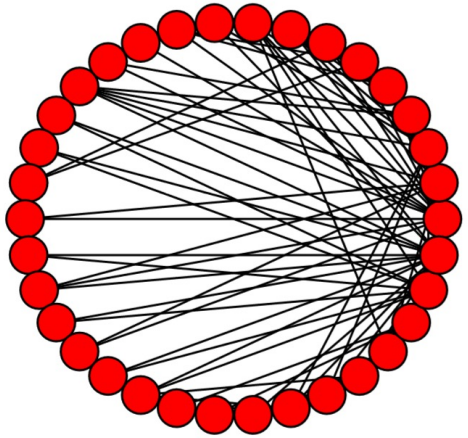
[1] Batagelj, Vladimir & Zaveršnik, Matjaž. (2003). An O(m) Algorithm for Cores Decomposition of Networks. CoRR. cs.DS/0310049.

Issue in progress: **graph layouts**

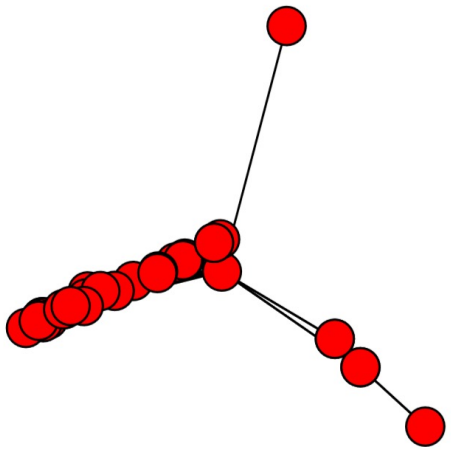
random layout



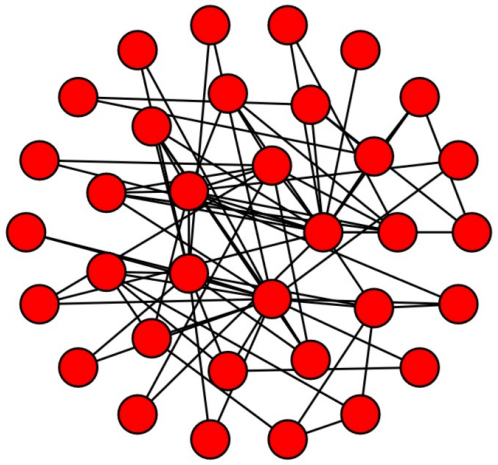
circular layout



spectral layout



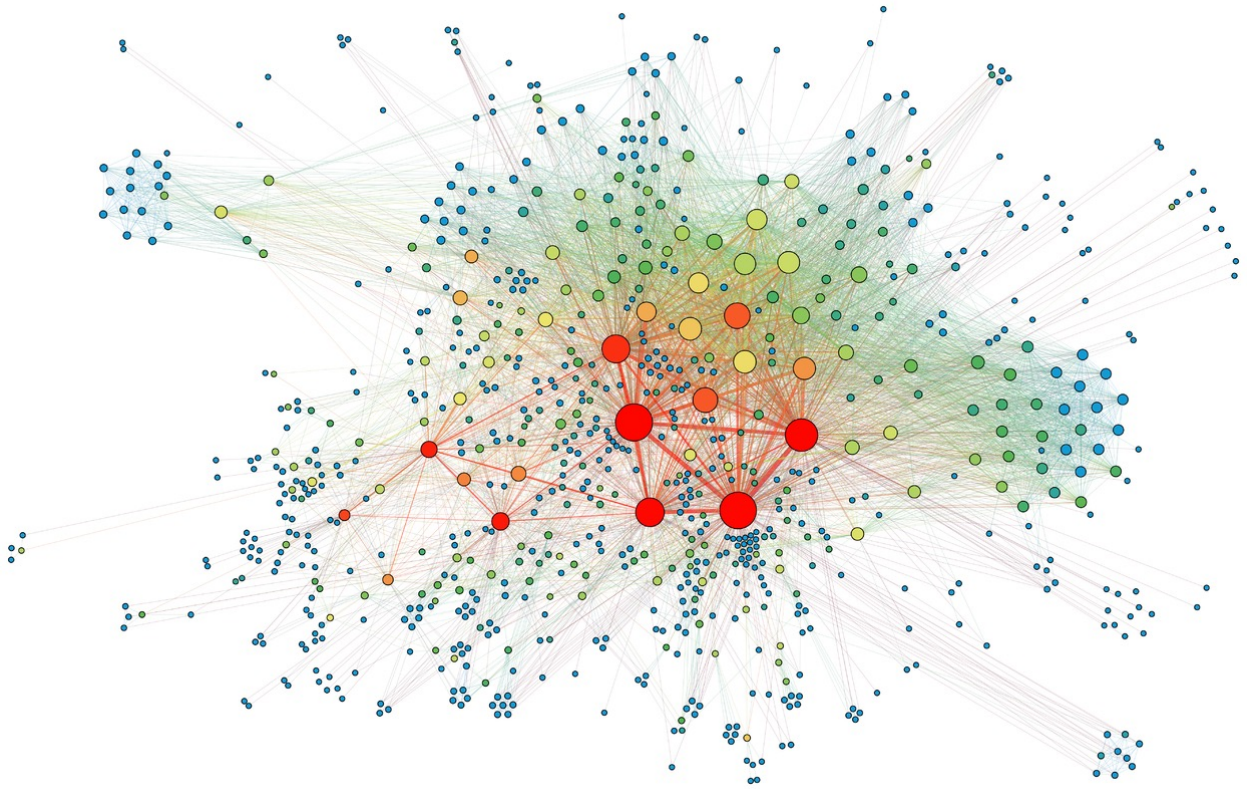
shell layout



Issue in progress: **graph layouts**

The algorithm simulates a force-directed representation of the network treating edges as springs holding nodes close, while treating nodes as repelling objects, sometimes called an anti-gravity force. Simulation continues until the positions are close to an equilibrium.

Fruchterman-Reingold force-directed algorithm.



@georgios-ts is working on the same issue.