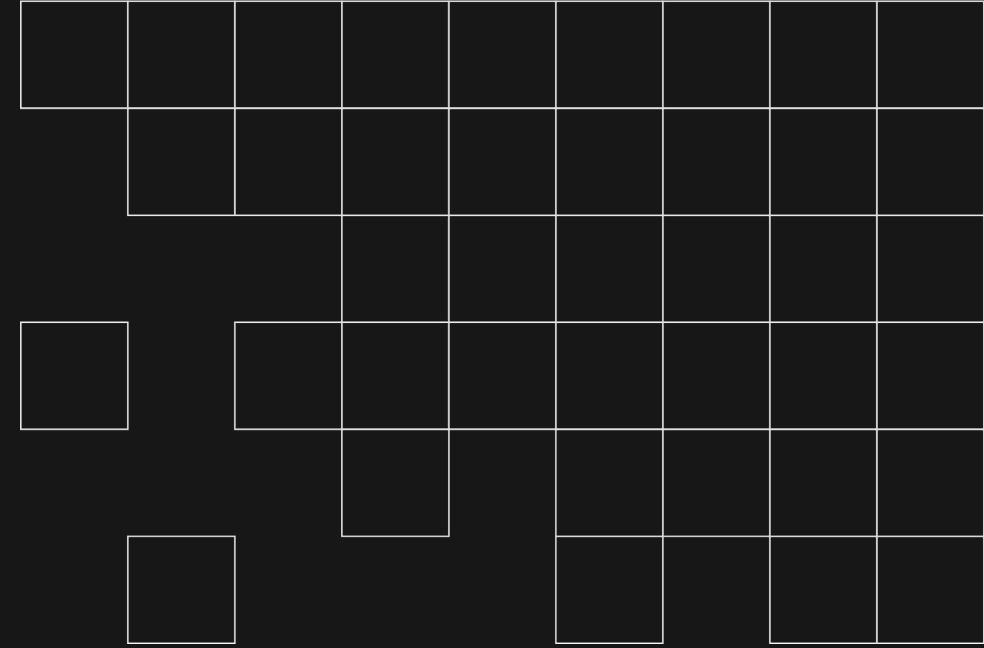


Lanczos Algorithm for Qiskit Dynamics

Mentor – Mirko Amico, IBM

Mentee – R K Rupesh, University of Hyderabad



$$|\psi(t)\rangle = e^{-iHt} |\psi(0)\rangle$$

- Local Hamiltonians describing qubit systems are sparse

$$H = \begin{pmatrix} 0 & 0 & \alpha & \beta \\ 0 & d_0 & 0 & 0 \\ \alpha^* & 0 & 0 & 0 \\ \beta^* & 0 & 0 & d_1 \end{pmatrix}$$

- Calculating time evolution requires exponentiating the Hamiltonian

$$|\psi(t)\rangle = e^{-iHt} |\psi_0\rangle$$

- This can be done by diagonalizing H

$$e^{-iHt} = S^\dagger e^{-iDt} S$$

- Time evolution requires only sparse matrix – vector multiplication

$$\begin{aligned} |\psi(t)\rangle &= e^{-iHt} |\psi_0\rangle \\ &= \sum_n \frac{(-it)^n}{n!} H^n |\psi_0\rangle \\ &= \sum_n \frac{(-it)^n}{n!} |u_n\rangle \end{aligned}$$

- $|u_0\rangle = |\psi\rangle$ $|u_1\rangle = H|u_0\rangle$ $|u_2\rangle = H|u_1\rangle$

Why Lanczos (Krylov Subspace)

- $K_r = \{|\psi\rangle, A|\psi\rangle, A^2|\psi\rangle, A^3|\psi\rangle \dots A^{k-1}|\psi\rangle\}$ Is the krylov subspace for a given matrix A and vector $|\psi\rangle$ of order k
- One can construct a basis $\{|\phi_i\rangle\}$ for this subspace using Gram-Schmidt

$$|\tilde{\phi}_{k-1}\rangle = |u_{k-1}\rangle - \sum_i \langle \phi_i | u_{k-1} \rangle |\phi_i\rangle$$

$$|\phi_{k-1}\rangle = \frac{|\tilde{\phi}_{k-1}\rangle}{\langle \tilde{\phi}_{k-1} | \tilde{\phi}_{k-1} \rangle}$$

Why Lanczos (Krylov Subspace)

- One can construct an orthogonal matrix $Q_{n,k}$ With $|\phi_i\rangle$ as the columns such that

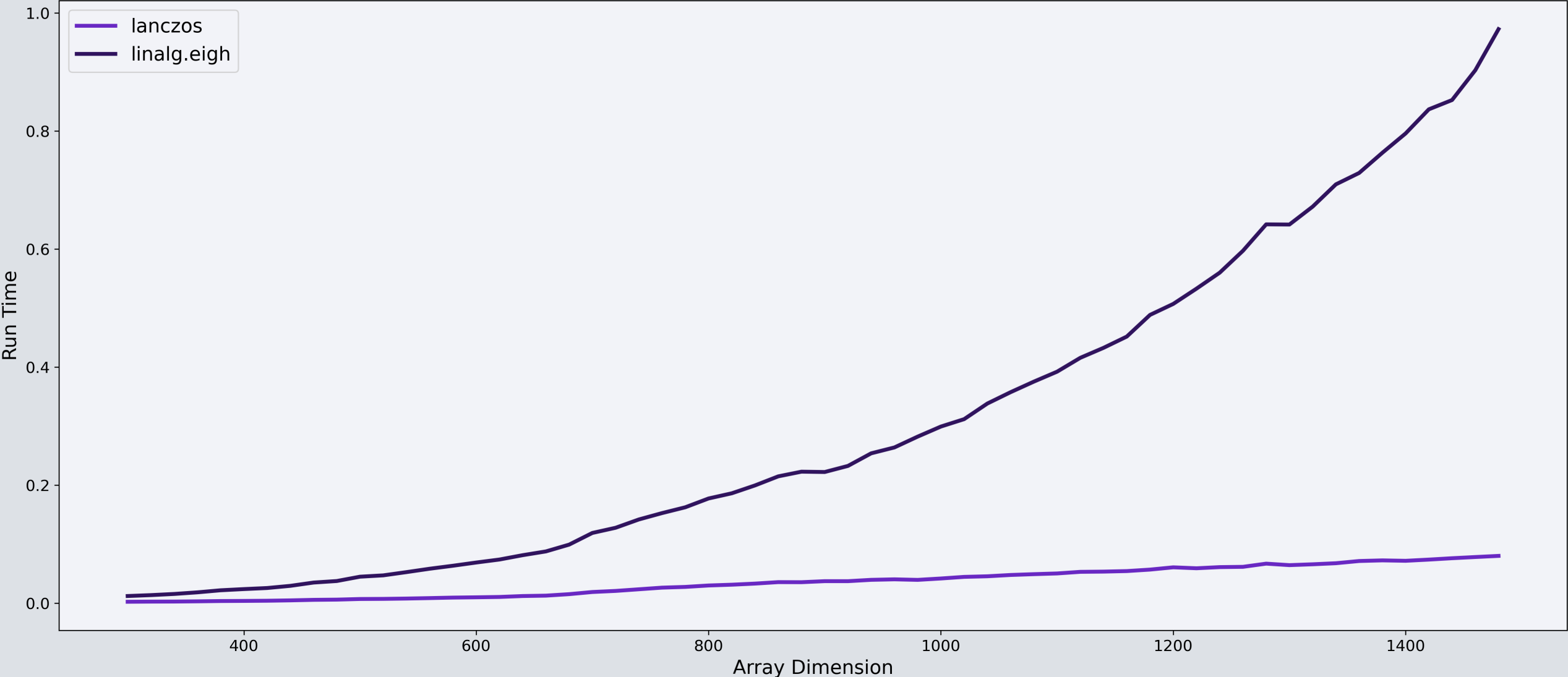
$$T_{k,k} = Q_{k,n}^\dagger H_{n,n} Q_{n,k}$$

- Where T is a Tridiagonal matrix
- Diagonalizing this Tridiagonal matrix is a lot faster since typically, $k \ll n$
- The Eigen-vectors of T is then an approximation of the lowest k Eigen vectors of H
- Therefore, we have $V_n = Q_{n,k} V_k$ where V_k are the eigenvectors of T

Lanczos vs NumPy

(ground state calculation)

$\langle RunTime \rangle_{100}$ vs Array Dimension



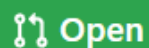
- Once we have the basis vectors and the Tridiagonal projection, we have the equation

$$H_{n,n} = Q_{n,k} T_{k,k} Q_{k,n}^\dagger$$

- Thus, the time evolution unitary becomes
- $e^{-iHt} = e^{-iQTQ^\dagger t} = Qe^{-iTt}Q^\dagger = QVe^{-i\text{diag}(T)t}V^\dagger Q^\dagger$
- If we had chosen the initial vector of the Lanczos iteration to be same as the initial state which we want to evolve, then the rows of Q (other than first) are orthogonal to $|\psi_i\rangle$

- If we had chosen the initial vector of the Lanczos iteration to be same as the initial state which we want to evolve, then the rows of Q (other than first) are orthogonal to $|\psi_i\rangle$
- $$\begin{aligned} e^{-iHt} &= QV_k e^{-i\text{diag}(T)t} V_k^\dagger Q^\dagger |\psi_i\rangle \\ &= QV_k e^{-i\text{diag}(T)t} V_k^\dagger \delta_{0,k} \\ &= QV_k e^{-i\text{diag}(T)t} V_0^\dagger = QV_k \exp(-iE_T t) |\psi_i\rangle \end{aligned}$$
- This increases the accuracy of the simulation since we aren't affected by loss of orthogonality.

Implementing Lanczos algorithm as a new solver method #109



rupeshknn wants to merge 27 commits into `Qiskit:main` from `rupeshknn:lanczos`



Conversation 1



Commits 27



Checks 0



Files changed 5



rupeshknn commented 3 days ago • edited



Summary

Lanczos algorithm is an approximate diagonalisation method. It is implemented as an LMDE method and is a considerable speedup compared to `scipy.expm`

Details and comments

This PR adds a new fixed-step solver method `lanczos_diag`. This method only works with hermitian generators and works best in sparse evaluation mode. A follow up with a Jax implementation of the same is in progress.

Thank You



R K Rupesh

MSc Physics, University of Hyderabad

Gachibowli, India

GitHub: github.com/rupeshknn/lanczos-QD