ACM/ICPC 代码模板库

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目录

1 比赛配置

1.1 代码库校验和

```
01b4 # 代码库校验用于检查代码库录入是否正确，忽略
       每行的空白字符和注释(//)
44f9 # 使用方法: python checksum.py < 1001.cpp
4de6 # 输出: 每一行代码及其校验和(md5)
c502 import re, sys, hashlib
427e
b41f def digest_line(s):
d74e   return hashlib.md5(re.sub(r'\s|//.*',
         '', s)).hexdigest()[-4:]
427e
f7db for line in sys.stdin.read().strip().
       split("\n"):
f335   print digest_line(line), line
```

1.2 vimrc

```
3ff1 color evening
7db5 set number
7232 set cindent
427e
427e
427e
6cb2 function HomeBind(offset)
7d5c   let cursor=getpos('.')
bda7   let s0=getline(line('.'))
1903   let s1=substitute(s0, "^\\s\\+", "",
         "")
7f8d   let x=len(s0)-len(s1)+1
2b1d   if col('.') == x-a:offset
0437     let x=1
400b   endif
d7af   call setpos('.', [cursor[0], cursor[1],
         x, cursor[3]])
f298 endfunction
1a4a imap <silent> <Home> <Esc>:call HomeBind
       (1)<cr>i
73c9 nmap <silent> <Home> :call HomeBind(0)<cr
       >
b506 vmap <silent> <Home> <Esc>:call HomeBind
       (1)<cr>
```

1.3 代码库校验和

```
01b4 # 代码库校验用于检查代码库录入是否正确，忽略
       每行的空白字符和注释(///)
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def digest_line(s):                                  b41f
  return hashlib.md5(re.sub(r'\s|//.*', '          d74e
    ', s)).hexdigest()[-4:]
                                                     427e
for line in sys.stdin.read().strip().                f7db
  split("\n"):
  print digest_line(line), line                      f335
```

1.4 vim 配置文件

```
# vimrc 配置文件                                     44ed
set nocompatible                                     914c
set number                                           7db5
set ruler                                            57b2
set showcmd                                          9832
set autoindent                                       e416
set cindent                                          7232
set smartindent                                      740c
set shiftwidth=4                                     5913
```

1.5 外挂

```
// 调栈空间                                          427e
const int N_MAX = 10000000;                          08e0
static int stack[N_MAX * 5], bak;                    772b
asm __volatile__                                     68df
  (                                                  bbf4
    "movl %%esp, %0;"                                4d52
    "movl %1, %%esp;":                               22d3
    "=g"(bak):                                       7f26
    "g"(stack + N_MAX * 5 - 1):                      5bf1
  );                                                 fe62
                                                     427e
// IO 外挂                                           427e
#define BUFSIZE 20000000                             6540
char buf[BUFSIZE], *pt = buf;                        eb51
#define scan(t) \                                    45da
{ \                                                  c2a7
  t = 0; \                                           f000
  while (!((*pt) >= '0' && (*pt) <= '9'))            2760
     pt ++; \
  while (((*pt) >= '0' && (*pt) <= '9'))             7181
    t = t * 10 + (*(pt ++)) - '0'; \
}                                                    95cf
                                                     427e
 int main()                                          299c
{                                                    4506
 fread(buf, 1, BUFSIZE, stdin);                      486b
scan(N);                                             0756
}                                                    95cf
                                                     427e
// C++ 编译器(VS) 调栈空间                           427e
#pragma comment(linker,"/STACK                       85cb
  :102400000,102400000")
```

2 二维计算几何

2.1 定义

```
652e  #define eps 1e-8
c1b0  #define fabs(x) ((x) > 0? (x): -(x))
0102  #define zero(x) (fabs(x) < eps)
12d8  #define _sign(x) ((x)>eps?1:((x)<-eps
        ?2:0))
dca2  #define sqr(x) ((x)*(x))
418f  #define MAXN 1000
8d0a  #define offset 10000
13f1  const double pi=acos(-1);
427e
427e
427e  // 点的定义
9704  struct point{
082e    int index;
98c9    double ang;
d0aa    double x, y;
52a2    point(){x = 0;y = 0;}
df98    point(double sx, double sy){
e87b      x = sx;
d22b      y = sy;
95cf    }
4f13    void read(){
dab2      scanf("%lf %lf ", &x, &y);
95cf    }
a7a6    bool operator <(const point &b)const{
73b2      if (b.x == x) return y < b.y;
66d1      return x < b.x;
95cf    }
7b0b    point operator - (const point &b)const
          {
f32c      point a;
d53d      a.x = x - b.x;
5365      a.y = y - b.y;
5ffd      return a;
95cf    }
e254    point operator + (const point &b)const{
f32c      point a;
7683      a.x = x + b.x;
70a0      a.y = y + b.y;
5ffd      return a;
95cf    }
14f6    point operator / (const double &c)const
          {
f32c      point a;
225c      a.x = x / c;
414d      a.y = y / c;
5ffd      return a;
95cf    }
d466    point operator * (const double &c)const
          {
f32c      point a;
7aa6      a.x = x * c;
9a5c      a.y = y * c;
5ffd      return a;
95cf    }
12ba    bool operator == (const point &p) const
          {
e89b      return zero(x - p.x)&&zero(y - p.y);
95cf    }
daed    friend ostream& operator << (ostream &
          out, const point &a);
329b  };
f71b  typedef const point CP;
05c6  ostream& operator << (ostream &out, const
        point &a){
df9c    out<<a.x<<' '<<a.y;
d324    return out;
95cf  }
eb7f  bool cmp(const point &p1, const point &p2
        ){
84df    return p1.ang < p2.ang;
95cf  }
427e
427e  // 线定义, 使用< 进行极角排序之前需要对所有
        线段调用getang 函数
bda3  struct line{
98c9    double ang;
a334    point a, b;line(){};
5ae1    line(const point &p1, const point &p2){
0fa8      a = p1;
ce41      b = p2;
95cf    }
cfb1    bool operator < (const line &y)const{
8e85      if (zero(ang - y.ang))
37ec        return (xmult(a, y.b, y.a) < 0);
3b83      return ang < y.ang;
95cf    }
1d99    void getang(){
f061      ang = atan2(b.y - a.y, b.x - a.x);
95cf    }
4c7b    friend ostream& operator << (ostream &
          out, const line &a);
329b  };
cdd9  ostream& operator << (ostream &out, const
        line &a){
1d6a    out<<a.a<<' '<<a.b<<' '<<a.ang;
d324    return out;
95cf  }
a5b5  typedef const line CL;
427e  // 圆定义
2f47  struct circle{
0c09    double r;
```

```
67a8   point c;
c0ad   circle(){};
614e   circle(const point &p, double x){
c23d     c = p;
d0c6     x = r;
95cf   }
a9b1   friend ostream& operator << (ostream &
         out, const circle &a);
329b };
b802 ostream& operator << (ostream &out, const
        circle &a){
d469   out<<a.c<<' '<<a.r;
d324   return out;
95cf }
e519 typedef const circle CC;
```

2.2 定义

```
652e #define eps 1e-8
c1b0 #define fabs(x) ((x) > 0? (x): -(x))
0102 #define zero(x) (fabs(x) < eps)
12d8 #define _sign(x) ((x)>eps?1:((x)<-eps
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418f #define MAXN 1000
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95cf   }
a7a6   bool operator <(const point &b)const{
73b2     if (b.x == x) return y < b.y;
66d1     return x < b.x;
95cf   }
7b0b   point operator - (const point &b)const
         {
f32c     point a;
d53d     a.x = x - b.x;
5365     a.y = y - b.y;
5ffd     return a;
95cf   }
e254   point operator + (const point &b)const{
f32c     point a;
7683     a.x = x + b.x;
70a0     a.y = y + b.y;
5ffd     return a;
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14f6   point operator / (const double &c)const
         {
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5ffd     return a;
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5ffd     return a;
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e89b     return zero(x - p.x)&&zero(y - p.y);
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         out, const point &a);
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05c6 ostream& operator << (ostream &out, const
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df9c   out<<a.x<<' '<<a.y;
d324   return out;
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eb7f bool cmp(const point &p1, const point &p2
       ){
84df   return p1.ang < p2.ang;
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ce41     b = p2;
95cf   }
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8e85     if (zero(ang - y.ang))
37ec       return (xmult(a, y.b, y.a) < 0);
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4c7b   friend ostream& operator << (ostream &
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```

```
cdd9 ostream& operator << (ostream &out, const
       line &a){
1d6a   out<<a.a<<' '<<a.b<<' '<<a.ang;
d324   return out;
95cf }
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427e // 圆定义
2f47 struct circle{
0c09   double r;
67a8   point c;
c0ad   circle(){};
614e   circle(const point &p, double x){
c23d     c = p;
d0c6     x = r;
95cf   }
a9b1   friend ostream& operator << (ostream &
         out, const circle &a);
329b };
b802 ostream& operator << (ostream &out, const
       circle &a){
d469   out<<a.c<<' '<<a.r;
d324   return out;
95cf }
```

2.3 点与线

```
427e // 计算cross product (P1-P0)x(P2-P0)
9060 double xmult(CP &p1,CP &p2,CP &p0){
a01c   return (p1.x-p0.x)*(p2.y-p0.y)-(p2.x-p0
         .x)*(p1.y-p0.y);
95cf }
26f9 double xmult(double x1,double y1,double
       x2,double y2,double x0,double y0){
c71e   return (x1-x0)*(y2-y0)-(x2-x0)*(y1-y0);
95cf }
0209 double xmult(CP &v1, CP &v2){
12a3   return v1.x * v2.y - v2.x * v1.y;
95cf }
427e
427e // 计算dot product (P1-P0).(P2-P0)
dbb2 double dmult(CP &p1,CP &p2,CP &p0){
6b50   return (p1.x-p0.x)*(p2.x-p0.x)+(p1.y-p0
         .y)*(p2.y-p0.y);
95cf }
8c06 double dmult(double x1,double y1,double
       x2,double y2,double x0,double y0){
4103   return (x1-x0)*(x2-x0)+(y1-y0)*(y2-y0);
95cf }
cb7a double dmult(CP &v1, CP &v2){
d871   return v1.x * v2.x + v1.y * v2.y;
95cf }
427e
427e // 计算向量v 的长度
bd72 double len(CP &v){
  return sqrt((v.x * v.x) + (v.y * v.y));  7c36
}                                          95cf
                                           427e
// 两点距离                                427e
double dis(CP &p1,CP &p2){                 21ca
  return sqrt((p1.x-p2.x)*(p1.x-p2.x)+(p1  b08a
    .y-p2.y)*(p1.y-p2.y));
}                                          95cf
double dis(double x1,double y1,double x2,  8046
  double y2){
  return sqrt((x1-x2)*(x1-x2)+(y1-y2)*(y1  9f44
    -y2));
}                                          95cf
double dis2(CP &p1,CP &p2){                1627
  return (p1.x-p2.x)*(p1.x-p2.x)+(p1.y-p2  3eaf
    .y)*(p1.y-p2.y);
}                                          95cf
double dis2(double x1,double y1,double x2  a880
  ,double y2){
  return (x1-x2)*(x1-x2)+(y1-y2)*(y1-y2);  5819
}                                          95cf
                                           427e
// 判三点共线                              427e
int dots_inline(CP &p1,CP &p2,CP &p3){     68d7
  return zero(xmult(p1,p2,p3));            20b6
}                                          95cf
int dots_inline(double x1,double y1,       a6a7
  double x2,double y2,double x3,double y3
  ){
  return zero(xmult(x1,y1,x2,y2,x3,y3));   fc4c
}                                          95cf
                                           427e
// 判点是否在线段上, 包括端点              427e
int dot_online_in(CP &p,CL &l){            23f7
  return zero(xmult(p,l.a,l.b))&&(l.a.x-p  d7f1
    .x)*(l.b.x-p.x)<eps&&(l.a.y-p.y)*(l.b
    .y-p.y)<eps;
}                                          95cf
int dot_online_in(CP &p,CP &l1,CP &l2){    a66d
  return zero(xmult(p,l1,l2))&&(l1.x-p.x)  9f13
    *(l2.x-p.x)<eps&&(l1.y-p.y)*(l2.y-p.y
    )<eps;
}                                          95cf
int dot_online_in(double x,double y,       86fb
  double x1,double y1,double x2,double y2
  ){
  return zero(xmult(x,y,x1,y1,x2,y2))&&(   5e8a
    x1-x)*(x2-x)<eps&&(y1-y)*(y2-y)<eps;
}                                          95cf
                                           427e
// 判点是否在线段上不包括端点,             427e
int dot_online_ex(CP &p,CL &l){            84f5
  return dot_online_in(p,l)&&(!zero(p.x-l  289e
```

```
        .a.x)||!zero(p.y-l.a.y))&&(!zero(p.x-
        l.b.x)||!zero(p.y-l.b.y));
95cf  }
a73f  int dot_online_ex(CP &p,CP &l1,CP &l2){
82af    return dot_online_in(p,l1,l2)&&(!zero(p
          .x-l1.x)||!zero(p.y-l1.y))&&(!zero(p.
          x-l2.x)||!zero(p.y-l2.y));
95cf  }
0181  int dot_online_ex(double x,double y,
        double x1,double y1,double x2,double y2
        ){
58c5    return dot_online_in(x,y,x1,y1,x2,y2)
          &&(!zero(x-x1)||!zero(y-y1))&&(!zero(
          x-x2)||!zero(y-y2));
95cf  }
427e
427e  // 判两点在线段同侧, 点在线段上返回0
ea31  int same_side(CP &p1,CP &p2,CL &l){
d345    return xmult(l.a,p1,l.b)*xmult(l.a,p2,l
          .b)>eps;
95cf  }
8a3c  int same_side(CP &p1,CP &p2,CP &l1,CP &l2
        ){
14cc    return xmult(l1,p1,l2)*xmult(l1,p2,l2)>
          eps;
95cf  }
427e
427e  // 判两点在线段异侧, 点在线段上返回0
b5f2  int opposite_side(CP &p1,CP &p2,CL &l){
95bc    return xmult(l.a,p1,l.b)*xmult(l.a,p2,l
          .b)<-eps;
95cf  }
d050  int opposite_side(CP &p1,CP &p2,CP &l1,CP
         &l2){
de06    return xmult(l1,p1,l2)*xmult(l1,p2,l2)
          <-eps;
95cf  }
427e
427e  // 判两直线平行
efdb  int parallel(CL &u,CL &v){
92d6    return zero((u.a.x-u.b.x)*(v.a.y-v.b.y)
          -(v.a.x-v.b.x)*(u.a.y-u.b.y));
95cf  }
3419  int parallel(CP &u1,CP &u2,CP &v1,CP &v2)
        {
4806    return zero((u1.x-u2.x)*(v1.y-v2.y)-(v1
          .x-v2.x)*(u1.y-u2.y));
95cf  }
427e
427e  // 判两直线垂直
7e98  int perpendicular(CL &u,CL &v){
980d    return zero((u.a.x-u.b.x)*(v.a.x-v.b.x)
          +(u.a.y-u.b.y)*(v.a.y-v.b.y));
95cf  }
518c  int perpendicular(CP &u1,CP &u2,CP &v1,CP
         &v2){
6143    return zero((u1.x-u2.x)*(v1.x-v2.x)+(u1
          .y-u2.y)*(v1.y-v2.y));
95cf  }
427e
427e  // 判两线段相交, 包括端点和部分重合
779d  int intersect_in(CL &u,CL &v){
e887    if (!dots_inline(u.a,u.b,v.a)||!
          dots_inline(u.a,u.b,v.b))
d666      return !same_side(u.a,u.b,v)&&!
            same_side(v.a,v.b,u);
efeb    return dot_online_in(u.a,v)||
          dot_online_in(u.b,v)||dot_online_in(v
          .a,u)||dot_online_in(v.b,u);
95cf  }
2882  int intersect_in(CP &u1,CP &u2,CP &v1,CP
        &v2){
8fcb    if (!dots_inline(u1,u2,v1)||!
          dots_inline(u1,u2,v2))
4b79      return !same_side(u1,u2,v1,v2)&&!
            same_side(v1,v2,u1,u2);
cc40    return dot_online_in(u1,v1,v2)||
          dot_online_in(u2,v1,v2)||
          dot_online_in(v1,u1,u2)||
          dot_online_in(v2,u1,u2);
95cf  }
427e
427e  // 判两线段相交, 不包括端点和部分重合
cc64  int intersect_ex(CL &u,CL &v){
bedb    return opposite_side(u.a,u.b,v)&&
          opposite_side(v.a,v.b,u);
95cf  }
5c8b  int intersect_ex(CP &u1,CP &u2,CP &v1,CP
        &v2){
70ea    return opposite_side(u1,u2,v1,v2)&&
          opposite_side(v1,v2,u1,u2);
95cf  }
427e
427e  // 计算两直线交点, 注意事先判断直线是否平行!
427e  // 线段交点请另外判线段相交, 同时还是要判断
        是否平行
afec  point intersection(CL &u,CL &v){
39f9    point ret=u.a;
273a    double t=((u.a.x-v.a.x)*(v.a.y-v.b.y)-(
          u.a.y-v.a.y)*(v.a.x-v.b.x))
9cb3        /((u.a.x-u.b.x)*(v.a.y-v.b.y)-(u.a.
              y-u.b.y)*(v.a.x-v.b.x));
1143    ret.x+=(u.b.x-u.a.x)*t;
12e9    ret.y+=(u.b.y-u.a.y)*t;
ee0f    return ret;
95cf  }
```

```
fbb7 point intersection(CP &u1,CP &u2,CP &v1,
       CP &v2){
f0a0   point ret=u1;
a7db   double t=((u1.x-v1.x)*(v1.y-v2.y)-(u1.y
         -v1.y)*(v1.x-v2.x))
16f0       /((u1.x-u2.x)*(v1.y-v2.y)-(u1.y-u2.
             y)*(v1.x-v2.x));
a1f8   ret.x+=(u2.x-u1.x)*t;
fa1b   ret.y+=(u2.y-u1.y)*t;
ee0f   return ret;
95cf }
427e // 求给定线段的中垂线
1cc5 line pbline(CL &l){
671e   line ret;ret.a = (l.a + l.b) / 2;
d118   double a = l.b.x - l.a.x, b = l.b.y - l
         .a.y;
a2fc   double c = (l.a.y - l.b.y) * ret.a.y +
         (l.a.x - l.b.x) * ret.a.x;
c99e   if (!zero(a)){
03b7     ret.b.y = 0;ret.b.x = -c / a;
effa     if (zero(dis(ret.a, ret.b))){
dca4       ret.b.y = 1e10;ret.b.x = - (c - b *
             ret.b.y) / a;
95cf     }
8e2e   }else{
08d6     ret.b.x = 0.0;ret.b.y = -c / b;
effa     if (zero(dis(ret.a, ret.b))){
3b6b       ret.b.x = 1e10;ret.b.y = -(c - a *
             ret.b.x) / b;
95cf     }
95cf   }
ee0f   return ret;
95cf }
427e
427e // 点到直线上的最近点
27b7 point ptoline(CP &p,CL &l){
1960   point t=p;
c7d0   t.x+=l.a.y-l.b.y,t.y+=l.b.x-l.a.x;
2f7b   return intersection(p,t,l.a,l.b);
95cf }
b7a1 point ptoline(CP &p,CP &l1,CP &l2){
1960   point t=p;
e925   t.x+=l1.y-l2.y,t.y+=l2.x-l1.x;
60f2   return intersection(p,t,l1,l2);
95cf }
427e
427e // 点到直线距离
a82a double disptoline(CP &p,CL &l){
9546   return fabs(xmult(p,l.a,l.b))/dis(l.a,l
         .b);
95cf }
e8c8 double disptoline(CP &p,CP &l1,CP &l2){
ccfa   return fabs(xmult(p,l1,l2))/dis(l1,l2);
95cf }
83c9 double disptoline(double x,double y,
       double x1,double y1,double x2,double y2
       ){
d1a4   return fabs(xmult(x,y,x1,y1,x2,y2))/dis
         (x1,y1,x2,y2);
95cf }
427e
427e // 点到线段上的最近点
59a9 point ptoseg(CP &p,CL &l){
1960   point t=p;
c7d0   t.x+=l.a.y-l.b.y,t.y+=l.b.x-l.a.x;
c788   if (xmult(l.a,t,p)*xmult(l.b,t,p)>eps)
4763     return dis(p,l.a)<dis(p,l.b)?l.a:l.b;
2f7b   return intersection(p,t,l.a,l.b);
95cf }
0e5b point ptoseg(CP &p,CP &l1,CP &l2){
1960   point t=p;
e925   t.x+=l1.y-l2.y,t.y+=l2.x-l1.x;
b478   if (xmult(l1,t,p)*xmult(l2,t,p)>eps)
9083     return dis(p,l1)<dis(p,l2)?l1:l2;
60f2   return intersection(p,t,l1,l2);
95cf }
427e
427e // 点到线段距离
d9a8 double disptoseg(CP &p,CL &l){
1960   point t=p;
c7d0   t.x+=l.a.y-l.b.y,t.y+=l.b.x-l.a.x;
c788   if (xmult(l.a,t,p)*xmult(l.b,t,p)>eps)
9b41     return dis(p,l.a)<dis(p,l.b)?dis(p,l.
           a):dis(p,l.b);
9546   return fabs(xmult(p,l.a,l.b))/dis(l.a,l
         .b);
95cf }
0b5b double disptoseg(CP &p,CP &l1,CP &l2){
1960   point t=p;
e925   t.x+=l1.y-l2.y,t.y+=l2.x-l1.x;
b478   if (xmult(l1,t,p)*xmult(l2,t,p)>eps)
234b     return dis(p,l1)<dis(p,l2)?dis(p,l1):
           dis(p,l2);
ccfa   return fabs(xmult(p,l1,l2))/dis(l1,l2);
95cf }
427e
427e // 线段到线段距离, 事先判断相交情况
d24d double dissegtoseg(CL &l1, CL &l2){
37e7   return min(min(disptoseg(l1.a, l2),
         disptoseg(l1.b, l2)), min(disptoseg(
         l2.a, l1), disptoseg(l2.b, l1)));
95cf }
d0fd double dissegtoseg(CP &l1a, CP &l1b, CP &
       l2a, CP &l2b){
c92c   return min(min(disptoseg(l1a, l2a, l2b)
         , disptoseg(l1b, l2a, l2b)), min(
```

```
        disptoseg(l2a, l1a, l1b), disptoseg(
        l2b, l1a, l1b)));
95cf  }
427e
427e  // 矢量V 以P 为顶点逆时针旋转angle 并放
        大scale 倍
546e  point rotate(point v,point p,double angle
        ,double scale){
15e2    point ret=p;
cee4    v.x-=p.x,v.y-=p.y;
2350    p.x=scale*cos(angle);
6a5a    p.y=scale*sin(angle);
2bf2    ret.x+=v.x*p.x-v.y*p.y;
0ad4    ret.y+=v.x*p.y+v.y*p.x;
ee0f    return ret;
95cf  }
427e
427e  // p 在新坐标系O(I,e1,e2) 中的坐标
f6d4  point rotate(CP &p, CP &I, CP &e1, CP &e2
        ){
22ef    point p2;
495d    p2.x = I.x + e1.x * p.x + e1.y * p.y;
84f1    p2.y = I.y + e2.x * p.x + e2.y * p.y;
7a0c    return p2;
427e
95cf  }
427e
427e  //p 点绕原点按逆时针旋转angle
3f0e  point rotate(CP &p, double angle){
3e07    point e1, e2, I;
1f1c    e1.x = cos(angle);e1.y = -sin(angle);
ed21    e2.x = -e1.y;e2.y = e1.x;
085d    I.x = 0;I.y = 0;
e586    return rotate(p, I, e1, e2);
95cf  }
427e
427e  // 返回值[0, 4), 正比向量v1 到向量v2 的顺时
        针旋转角度
452a  double angle(CP &v1, CP &v2){
94c9    double cosa = dmult(v1, v2) / len(v1) /
           len(v2);cosa = 1 - cosa;
53df    if (xmult(v1, v2) < 0) cosa = 4 - cosa;
          return cosa;
95cf  }
8cb3  double angle(CP &v1, CP &a, CP &b){
ce1f    return angle(v1, b - a);
95cf  }
427e  // 向量a-c 到b-c 的顺时针度数
aab2  double angle(CP &a, CP &b, CP &c){
427e    //return angle(a - b, b - c);
76a4    double cosa = dmult(a, b, c) / dis(a, c
          ) / dis(b, c);cosa = 1 - cosa;
c807    if (xmult(a, b, c) < 0) cosa = 4 - cosa
          ;return cosa;
95cf  }
```

2.4 三角形

```
427e  // 外心
878f  point circumcenter(CP &a,CP &b,CP &c){
7173    line u,v;
2ecf    u.a.x=(a.x+b.x)/2;
5a23    u.a.y=(a.y+b.y)/2;
ee31    u.b.x=u.a.x-a.y+b.y;
77b1    u.b.y=u.a.y+a.x-b.x;
5396    v.a.x=(a.x+c.x)/2;
8492    v.a.y=(a.y+c.y)/2;
abe9    v.b.x=v.a.x-a.y+c.y;
63ff    v.b.y=v.a.y+a.x-c.x;
ed5d    return intersection(u,v);
95cf  }
427e
427e  // 内心
6bd8  point incenter(CP &a,CP &b,CP &c){
7173    line u,v;
1a7c    double m,n;
2aec    u.a=a;
cd0a    m=atan2(b.y-a.y,b.x-a.x);
4211    n=atan2(c.y-a.y,c.x-a.x);
af8c    u.b.x=u.a.x+cos((m+n)/2);
b80b    u.b.y=u.a.y+sin((m+n)/2);
93b1    v.a=b;
da57    m=atan2(a.y-b.y,a.x-b.x);
0a23    n=atan2(c.y-b.y,c.x-b.x);
3d04    v.b.x=v.a.x+cos((m+n)/2);
b99c    v.b.y=v.a.y+sin((m+n)/2);
ed5d    return intersection(u,v);
95cf  }
427e
427e  // 垂心
8ae2  point perpencenter(CP &a,CP &b,CP &c){
7173    line u,v;
1ecd    u.a=c;
ee31    u.b.x=u.a.x-a.y+b.y;
77b1    u.b.y=u.a.y+a.x-b.x;
93b1    v.a=b;
abe9    v.b.x=v.a.x-a.y+c.y;
63ff    v.b.y=v.a.y+a.x-c.x;
ed5d    return intersection(u,v);
95cf  }
427e
427e  // 重心
427e  // 到三角形三顶点距离的平方和最小的点
427e  // 三角形内到三边距离之积最大的点
81bd  point barycenter(CP &a,CP &b,CP &c){
7173    line u,v;
2ecf    u.a.x=(a.x+b.x)/2;
```

```
5a23    u.a.y=(a.y+b.y)/2;
fad0    u.b=c;
5396    v.a.x=(a.x+c.x)/2;
8492    v.a.y=(a.y+c.y)/2;
f28e    v.b=b;
ed5d    return intersection(u,v);
95cf  }
427e
427e  // 费马点
427e  // 到三角形三顶点距离之和最小的点
b0a9  point fermentpoint(CP &a,CP &b,CP &c){
03f5    point u,v;
c4d2    double step=fabs(a.x)+fabs(a.y)+fabs(b.
          x)+fabs(b.y)+fabs(c.x)+fabs(c.y);
c8ed    int i,j,k;
1eb8    u.x=(a.x+b.x+c.x)/3;
9137    u.y=(a.y+b.y+c.y)/3;
7bf1    while (step>1e-10)
0fcc      for (k=0;k<10;step/=2,k++)
13ea        for (i=-1;i<=1;i++)
9366          for (j=-1;j<=1;j++){
6701            v.x=u.x+step*i;
61f3            v.y=u.y+step*j;
7b0c            if (dis(u,a)+dis(u,b)+dis(u,c)>
                  dis(v,a)+dis(v,b)+dis(v,c))
c013              u=v;
95cf          }
81b0    return u;
95cf  }
```

2.5 多边形

```
427e  // 判定凸多边形, 顶点按顺时针或逆时针给
        出, 允许相邻边共线
7a16  int is_convex(int n,point* p){
53c4    int i,s[3]={1,1,1};
cb40    for (i=0;i<n&&s[1]|s[2];i++)
1a26      s[_sign(xmult(p[(i+1)%n],p[(i+2)%n],p
            [i]))]=0;
e8ad    return s[1]|s[2];
95cf  }
427e
427e  // 判定凸多边形, 顶点按顺时针或逆时针给
        出, 不允许相邻边共线
eba7  int is_convex_v2(int n,point* p){
53c4    int i,s[3]={1,1,1};
ae7f    for (i=0;i<n&&s[0]&&s[1]|s[2];i++)
1a26      s[_sign(xmult(p[(i+1)%n],p[(i+2)%n],p
            [i]))]=0;
e92f    return s[0]&&s[1]|s[2];
95cf  }
427e
427e  // 判点在凸多边形内或多边形边上, 顶点按顺时
        针或逆时针给出
ea98  int inside_convex(CP &q,int n,point* p){
53c4    int i,s[3]={1,1,1};
cb40    for (i=0;i<n&&s[1]|s[2];i++)
8fa5      s[_sign(xmult(p[(i+1)%n],q,p[i]))]=0;
e8ad    return s[1]|s[2];
95cf  }
427e
427e  // 判点在凸多边形内, 顶点按顺时针或逆时针给
        出, 在多边形边上返回0
9e0e  int inside_convex_v2(CP &q,int n,point* p
        ){
53c4    int i,s[3]={1,1,1};
ae7f    for (i=0;i<n&&s[0]&&s[1]|s[2];i++)
8fa5      s[_sign(xmult(p[(i+1)%n],q,p[i]))]=0;
e92f    return s[0]&&s[1]|s[2];
95cf  }
427e
427e  // 判点在任意多边形内顶点按顺时针或逆时针给
        出,
427e  // on_edge 表示点在多边形边上时的返回
        值,offset 为多边形坐标上限
78bd  int inside_polygon(CP &q,int n,point* p,
        int on_edge=1){
af1a    point q2;
1adf    int i=0,count;
22c1    while (i<n)
ea47      for (count=i=0,q2.x=rand()+offset,q2.
            y=rand()+offset;i<n;i++)
960c        if (zero(xmult(q,p[i],p[(i+1)%n]))
              &&(p[i].x-q.x)*(p[(i+1)%n].x-q.x)
              <eps&&(p[i].y-q.y)*(p[(i+1)%n].y-
              q.y)<eps)
163a          return on_edge;
19b2        else if (zero(xmult(q,q2,p[i])))
6173          break;
f875        else if (xmult(q,p[i],q2)*xmult(q,p
              [(i+1)%n],q2)<-eps&&xmult(p[i],q,
              p[(i+1)%n])*xmult(p[i],q2,p[(i+1)
              %n])<-eps)
45d2          count++;
9103    return count&1;
95cf  }
427e
427e  // 判线段在任意多边形内, 顶点按顺时针或逆时
        针给出, 与边界相交返回1
2e50  int inside_polygon(CP &l1,CP &l2,int n,
        point* p){
b779    point t[MAXN],tt;
ff68    int i,j,k=0;
535b    if (!inside_polygon(l1,n,p)||!
          inside_polygon(l2,n,p))
7021      return 0;
2dbf    for (i=0;i<n;i++)
```

```
6a8f      if (opposite_side(l1,l2,p[i],p[(i+1)%
            n])&&opposite_side(p[i],p[(i+1)%n],
            l1,l2))
7021        return 0;
d6e2      else if (dot_online_in(l1,p[i],p[(i
            +1)%n]))
29be        t[k++]=l1;
cbea      else if (dot_online_in(l2,p[i],p[(i
            +1)%n]))
3d75        t[k++]=l2;
1abb      else if (dot_online_in(p[i],l1,l2))
8b2e        t[k++]=p[i];
a83a    for (i=0;i<k;i++)
e784      for (j=i+1;j<k;j++){
2874        tt.x=(t[i].x+t[j].x)/2;
abed        tt.y=(t[i].y+t[j].y)/2;
4b25        if (!inside_polygon(tt,n,p))
7021          return 0;
95cf      }
7459    return 1;
95cf  }
427e
427e  // 多边形重心
3a12  point barycenter(int n,point* p){
54ec    point ret,t;
3444    double t1=0,t2;
a0f7    int i;
5b97    ret.x=ret.y=0;
440f    for (i=1;i<n-1;i++)
4241      if (fabs(t2=xmult(p[0],p[i],p[i+1]))>
            eps){
c812        t=barycenter(p[0],p[i],p[i+1]);
0f3e        ret.x+=t.x*t2;
531e        ret.y+=t.y*t2;
1ea2        t1+=t2;
95cf      }
63aa    if (fabs(t1)>eps)
a16e      ret.x/=t1,ret.y/=t1;
ee0f    return ret;
95cf  }
427e
427e  // 将多边形沿l1,l2 确定的直线切割在side 侧
        切割
427e  // 保证l1,l2,side 不共线
3a0f  void polygon_cut(int& n,point* p,CP &l1,
        CP &l2,CP &side){
7368    point pp[100];
9894    int m=0,i;
ee09    for (i=0;i<n;i++){
2f5d      if (same_side(p[i],side,l1,l2))
33c3        pp[m++]=p[i];
226e      if (!same_side(p[i],p[(i+1)%n],l1,l2)
            &&!(zero(xmult(p[i],l1,l2))&&zero(
            xmult(p[(i+1)%n],l1,l2))))
4119        pp[m++]=intersection(p[i],p[(i+1)%n
              ],l1,l2);
95cf    }
dea9    for (n=i=0;i<m;i++)
08e5      if (!i||!zero(pp[i].x-pp[i-1].x)||!
            zero(pp[i].y-pp[i-1].y))
0d6a        p[n++]=pp[i];
f09f    if (zero(p[n-1].x-p[0].x)&&zero(p[n-1].
          y-p[0].y))
61b6      n--;
4046    if (n<3)
91c9      n=0;
95cf  }
427e
427e  // 求平行于v 的所有射线中，穿过的凸包中最左
        边的点的坐标
427e  // 凸包点按顺时针给出
e405  point vector_throw_convex(int n, point *
        convex, CP &v){
9c56    int s = 0;double as = angle(v, convex[s
          ], convex[(s + 1) % n]);
c116    int t = n - 1;double at = angle(v,
          convex[t], convex[(t + 1) % n]);
bed9    while (s < t){
a934      if (as >= at){s = t;break;}int mid =
            (s + t + 1) / 2;
ef17      double amid = angle(v, convex[mid],
            convex[(mid + 1) % n]);
b31e      if (amid <= as){s = mid;as = amid;}
8674      else{t = mid - 1;at = angle(v, convex
            [t], convex[(t + 1) % n]);}
95cf    }
605e    return convex[(s + 1) % n];
95cf  }
427e
427e
427e  // 求直线l1 是否穿过凸包, 凸包按顺时针给出，
        返回是否穿过
427e  // p 储存凸包内l1 共线的某点
18a9  bool line_throw_convex(int n, point *
        convex, CL &l, point &p){
91c3    point p1 = vector_throw_convex(n,
          convex, l.a - l.b);
a453    point p2 = vector_throw_convex(n,
          convex, l.b - l.a);
f6ad    line l2(p1, p2);p = intersection(l, l2)
          ;
56e0    if (dot_online_in(p, l2)) return true;
          return false;
95cf  }
427e
427e  // 求射线是否穿过凸包, 凸包按顺时针给出，返
```

```
      回是否穿过
427e  // p 储存凸包内l1 共线的某点
162c  bool ray_throw_convex(int n, point *
        convex, CL &l, point &p){
ab11    if (line_throw_convex(n, convex, l, p))
          {
ff30      if (dmult(p, l.b, l.a) >= -eps)
            return true;return false;
95cf    }
438e    return false;
95cf  }
427e
427e  // 求凸包直径, 输入要求顺时针输入凸包, 没有
        共线的点
9c74  double convex_diameter(int n, point *con)
        {
571d    int q=1;double ans=0;
9c16    for(int p=0;p<n;++p)
4506    {
f1dc      while(xmult(con[(p+1)%n],con[(q+1)%n
            ],con[p])<xmult(con[(p+1)%n],con[q
            ],con[p]))
78df        q=(q+1)%n;
605a      ans=max(ans,max(dis(con[p],con[q]),
            dis(con[(p+1)%n],con[(q+1)%n])));
95cf    }
4206    return ans;
95cf  }
427e
427e  // 求凸包最小截面, 输入要求顺时针输入凸包
2bc8  double convex_min_section(int n, point *
        con){
987e    int q=1;double ans=1000000000;
9c16    for(int p=0;p<n;++p)
4506    {
f1dc      while(xmult(con[(p+1)%n],con[(q+1)%n
            ],con[p])<xmult(con[(p+1)%n],con[q
            ],con[p]))
78df        q=(q+1)%n;
adf5      ans=min(ans,disptoline(con[q], con[p
            ], con[p + 1]));
95cf    }
4206    return ans;
95cf  }
ff80  double convex_min_section2(int n, point *
        con){
c166    double l1 = 1000000000;
6c2f    for (int i = 0; i < n; ++i){
3cec      point a = con[i] - con[(i + 1) % n];
5394      point b = vector_throw_convex(n, con,
            a);
746a      l1 = min(l1, disptoline(b, con[i],
            con[i + 1]));
        }                                       95cf
        return l1;                              66fb
      }                                         95cf
                                                427e
      // 求两个不包含的凸包的最短距离, 逆时针输入   427e
        背包
      double convex_min_dis(int n, point *a,    27ad
        int m, point *b){
        int p1 = 0, p2 = 0;                     4ab2
        double ans = 1<<30;                     5db6
        for (int i = 0; i < n; ++i)             85c3
          if (a[i].y < a[p1].y) p1 = i;         6f87
        for (int i = 0; i < m; ++i)             e725
          if (b[i].y > b[p2].y) p2 = i;         ca57
        for (int i = 0; i < n; ++i){            6c2f
          double t = xmult(b[(p2 + 1) % m], a[  ff12
            p1], a[(p1 + 1) % n]);
          t -= xmult(b[p2], a[p1], a[(p1 + 1) %  474d
             n]);
          //cout<<p1<<' '<<p2<<' '<<t<<endl;    427e
          if (_sign(t) == 1){                   2c1f
            ans = min(ans, disptoseg(a[p1], b[  c706
              p2], b[(p2 + 1) % m]));
            p2 = (p2 + 1) % m;                  8d05
            --i;                                215f
          }else if (_sign(t) == 2){             09a7
            ans = min(ans, disptoseg(b[p2], a[  1c6e
              p1], a[(p1 + 1) % n]));
            p1 = (p1 + 1) % n;                  c583
          }else{                                8e2e
            ans = min(ans, dissegtoseg(a[p1], a 50f3
              [(p1 + 1) % n], b[p2], b[(p2 + 1)
               % m]));
            p1 = (p1 + 1) % n;                  c583
            p2 = (p2 + 1) % m;                  8d05
          }                                     95cf
        }                                       95cf
        return ans;                             4206
      }                                         95cf
                                                427e
      // 求多边形中最长的线段, 的长度, 线段储存   427e
        在 l 中
      double inside_polygon_max(int n,point* p, 25a1
         line &l){
        double len = 0;                         e5cd
        for (int i = 0; i < n; ++i)             85c3
          for (int j = i + 1; j < n; ++j){      dd26
            vector<point> points;               374e
            points.clear();                     5603
            points.push_back(p[i]);             aaca
            points.push_back(p[j]);             3329
            for (int a = 0; a < n; ++a)         1aaa
              for (int b = a + 1; b < n; ++b){  231a
```

```
dbc2            if (a == i) continue;
3695            if (parallel(p[i], p[j], p[a],
                  p[b]))
b333              continue;
f9ae            point p1 = intersection(p[i], p
                  [j], p[a], p[b]);
cb8b            if (dmult(p[a], p[b], p1) <= 0)
                  {
a62b              points.push_back(p1);
95cf            }
95cf          }
52c1        sort(points.begin(), points.end());
427e
bd55        int s = 0;
2927        for (int k = 0; k < points.size() -
               1; ++k){
d563          if (zero(dis(points[k], points[k
                + 1]))) continue;
8ac5          point p1;
1667          p1 = (points[k] + points[k + 1])
                / 2;
8984          if (inside_polygon(p1, n, p))
                continue;
154a          double d = dis(points[s], points[
                k + 1]);
db17          if (len < d){
aaed            len = d;
bff1            l.a = points[s];
71e0            l.b = points[k + 1];
95cf          }
69cc          s = k + 1;
95cf        }
5be3        double d = dis(points[s], points[
              points.size() - 1]);
db17        if (len < d){
aaed          len = d;
bff1          l.a = points[s];
352a          l.b = points[points.size() - 1];
95cf        }
95cf      }
1891    return len;
95cf  }
427e
427e  // 判断点知否在半平面内, 平面位于向量左侧
917a  bool phplaneout(CL &l, CP &p){
45ae    return xmult(p, l.b, l.a) > eps;
95cf  }
427e
427e  // 求半平面交, 平面位于向量左侧
e484  int halfpanelcross(int n, line *lines,
        point *p){
a0f7    int i;
85c3    for (int i = 0; i < n; ++i)
          lines[i].getang();                    4d87
      sort(lines, lines + n);                   efa0
      int m = 1;                                dcba
      for (int i = 1; i < n; ++i)               bc29
        if (!zero(lines[i].ang - lines[i -      fa79
          1].ang))
          lines[m++] = lines[i];                aa88
      n = m;                                    7852
      int bot = 0, top = 1;                     dad4
      for (int i = 2; i < n; ++i){              a007
        if ((parallel(lines[top], lines[top -   f9fe
           1])||parallel(lines[bot], lines[
          bot + 1])))
          return 0;                             7021
        while ((bot < top)&&(xmult(             ba77
          intersection(lines[top], lines[top
          - 1]), lines[i].b, lines[i].a) >
          eps))
          --top;                                f959
        while ((bot < top)&&(xmult(             c049
          intersection(lines[bot], lines[bot
          + 1]), lines[i].b, lines[i].a) >
          eps))
          ++bot;                                5425
        ++top;                                  c56b
        lines[top] = lines[i];                  973c
      }                                         95cf
      while ((bot < top)&&(xmult(intersection   f6dc
        (lines[top], lines[top - 1]), lines[
        bot].b, lines[bot].a) > eps))
        --top;                                  f959
      while ((bot < top)&&(xmult(intersection   1b45
        (lines[bot], lines[bot + 1]), lines[
        top].b, lines[top].a) > eps))
        ++bot;                                  5425
      if (top <= bot + 1) return 0;             580b
      n = 0;                                    91c9
      for (int i = bot; i < top; ++i)           9c73
        p[n++] = intersection(lines[i], lines   dfe9
          [i + 1]);
      if (bot < top + 1)                        a1f8
        p[n++] = intersection(lines[bot],       f5bc
          lines[top]);
      return n;                                 c757
    }                                           95cf
                                                427e
    // 算法顺时针构造包含所有共线点的凸          427e
      包graham,O(nlogn)
    point p1,p2;                                cc70
    int graham_cp(const void* a,const void* b   91cb
      ){
      double ret=xmult(*((point*)a),*((point    43a2
        *)b),p1);
```

```
6307    return zero(ret)?(xmult(*((point*)a)
          ,*((point*)b),p2)>0?1:-1):(ret
          >0?1:-1);
95cf  }
a709  void _graham(int n,point* p,int& s,point*
        ch){
6e7d    int i,k=0;
396d    for (p1=p2=p[0],i=1;i<n;p2.x+=p[i].x,p2
          .y+=p[i].y,i++)
b2ba      if (p1.y-p[i].y>eps||(zero(p1.y-p[i].
            y)&&p1.x>p[i].x))
6d56        p1=p[k=i];
6584    p2.x/=n,p2.y/=n;
fc86    p[k]=p[0],p[0]=p1;
427e    //cout<<n<<endl;
725f    qsort(p+1,n-1,sizeof(point),graham_cp);
427e    //cout<<n<<endl;
501c    for (ch[0]=p[0],ch[1]=p[1],ch[2]=p[2],s
          =i=3;i<n;ch[s++]=p[i++])
1eaf      for (;s>2&&xmult(ch[s-2],p[i],ch[s
            -1])<-eps;s--);
95cf  }
427e
427e  // 构造凸包接口函数, 传入原始点集大小n, 点
        集p(p 原有顺序被打乱!)
427e  // 返回凸包大小, 凸包的点在convex 中
427e  // 参数maxsize 为1 包含共线点, 为0 不包含共
        线点, 缺省为1
427e  // 参数clockwise 为1 顺时针构造, 为0 逆时针
        构造, 缺省为1
427e  // 在输入仅有若干共线点时算法不稳定, 可能有
        此类情况请另行处理!
427e  // 不能去掉点集中重合的点
046c  int graham(int n,point* p,point* convex,
        int maxsize=1,int dir=1){
b7cd    point* temp=new point[n];
dee3    int s,i;
7ec2    _graham(n,p,s,temp);
79fb    for (convex[0]=temp[0],n=1,i=(dir?1:(s
          -1));dir?(i<s):i;i+=(dir?1:-1)){
cecf      if (maxsize||!zero(xmult(temp[i-1],
            temp[i],temp[(i+1)%s])))
02e5        convex[n++]=temp[i];
95cf      }
8562    delete []temp;
c757    return n;
95cf  }求入射边
427e
427e  //关于边的折射角，不考虑全反射，折射率为uvr
0ab4  line refraction(CL &u, CL &v, CP &p,
        double r){
57f5    line v2;
57f9    v2.a = p;
6bd4    v2.b.x = v.b.y - v.a.y + p.x;
99c4    v2.b.y = v.a.x - v.b.x + p.y;
efc1    if (dmult(v2.b - v2.a, u.b - u.a) < 0)
          swap(v2.a, v2.b);
10cd    double alpha = xmult(v2.b - v2.a, u.b -
           u.a) / len(v2.b - v2.a) / len(u.b -
          u.a);
d9eb    alpha = asin(alpha / r) + atan2(v2.b.y
          - v2.a.y, v2.b.x - v2.a.x);
57f9    v2.a = p;
2a97    v2.b.x = 10 * cos(alpha) + v2.a.x;
33d7    v2.b.y = 10 * sin(alpha) + v2.a.y;
9d48    return v2;
95cf  }求入射边
427e
427e  //关于凸包折射两次的情况，出射角保存在中，折
        射率为vvr如果不相交，返回
427e  //，false 不考虑镜面反射和入射到凸包角上的情
        况
0c20  bool refreaction(int n, point p[], line &
        v, double r){
4e58    int index = -1;
c9aa    line l[n];
8ac5    point p1;
6c2f    for (int i = 0; i < n; ++i){
bd2f      l[i].a = p[i];
ab75      l[i].b = p[(i + 1) % n];
95cf    }
6c2f    for (int i = 0; i < n; ++i){
8cf8      if (parallel(v, l[i])) continue;
fada      point p2 = intersection(v, l[i]);
a36f      if (dmult(l[i].a, l[i].b, p2) >= 0)
            continue;
6446      if (dmult(p2, v.b, v.a) <= 0)
            continue;
fe41      if ((index == -1)||(dis2(p2, v.a) <
            dis2(p1, v.a))){
8d74        index = i;
3524        p1 = p2;
95cf      }
95cf    }
38b6    if (index == -1) return 0;
2817    swap(l[0], l[index]);
5df5    v = refraction(v, l[0], p1, r);
17c3    index = -1;
2892    for (int i = 1; i < n; ++i){
8cf8      if (parallel(v, l[i])) continue;
fada      point p2 = intersection(v, l[i]);
a36f      if (dmult(l[i].a, l[i].b, p2) >= 0)
            continue;
6446      if (dmult(p2, v.b, v.a) <= 0)
            continue;
fe41      if ((index == -1)||(dis2(p2, v.a) <
```

```
        dis2(p1, v.a))){
8d74      index = i;
3524      p1 = p2;
95cf    }
95cf  }
087b  swap(l[1], l[index]);
01a2  v = refraction(v, l[1], p1, 1 / r);
3361  return true;
95cf }
```

2.6 面积

```
427e // 计算三角形面积, 输入三顶点
ab5f double area_triangle(CP &p1,CP &p2,CP &p3
       ){
f8a3   return fabs(xmult(p1,p2,p3))/2;
95cf }
243e double area_triangle(double x1,double y1,
       double x2,double y2,double x3,double y3
       ){
1953   return fabs(xmult(x1,y1,x2,y2,x3,y3))
         /2;
95cf }
427e
427e // 计算三角形面积, 输入三边长
7fb2 double area_triangle(double a,double b,
       double c){
f36a   double s=(a+b+c)/2;
7a86   return sqrt(s*(s-a)*(s-b)*(s-c));
95cf }
427e
427e // 计算多边形面积, 顶点按顺时针或逆时针给出
427e // 顺时针的时候，面积为负，逆时针的时候面积为
       正
2ed4 double area_polygon(int n,point* p){
0934   double s1=0,s2=0;
a0f7   int i;
2dbf   for (i=0;i<n;i++)
e3ae     s1+=p[(i+1)%n].y*p[i].x,s2+=p[(i+1)%n
           ].y*p[(i+2)%n].x;
1109   return (s1-s2)/2;
95cf }
```

2.7 球面

```
427e // 计算圆心角lat 表示纬度,-90<=w<=90,lng 表
       示经度
427e // 返回两点所在大圆劣弧对应圆心
       角,0<=angle<=pi
8176 double angle(double lng1,double lat1,
       double lng2,double lat2){
533a   double dlng=fabs(lng1-lng2)*pi/180;
88a6   while (dlng>=pi+pi)
a612     dlng-=pi+pi;
d991   if (dlng>pi)
ea50     dlng=pi+pi-dlng;
6a31   lat1*=pi/180,lat2*=pi/180;
dc31   return acos(cos(lat1)*cos(lat2)*cos(
         dlng)+sin(lat1)*sin(lat2));
95cf }
427e
427e // 计算距离,r 为球半径
3a23 double line_dist(double r,double lng1,
       double lat1,double lng2,double lat2){
533a   double dlng=fabs(lng1-lng2)*pi/180;
88a6   while (dlng>=pi+pi)
a612     dlng-=pi+pi;
d991   if (dlng>pi)
ea50     dlng=pi+pi-dlng;
6a31   lat1*=pi/180,lat2*=pi/180;
24df   return r*sqrt(2-2*(cos(lat1)*cos(lat2)*
         cos(dlng)+sin(lat1)*sin(lat2)));
95cf }
427e
427e // 计算球面距离,r 为球半径
1bec inline double sphere_dist(double r,double
       lng1,double lat1,double lng2,double
       lat2){
5db0   return r*angle(lng1,lat1,lng2,lat2);
95cf }
```

2.8 圆

```
427e // 判直线和圆相交, 包括相切
128f int intersect_line_circle(CP &c,double r,
       CP &l1,CP &l2){
c721   return disptoline(c,l1,l2)<r+eps;
95cf }
641a int intersect_line_circle(CC &c,CP &l1,CP
       &l2){
e25b   return disptoline(c.c,l1,l2)<c.r+eps;
95cf }
427e
427e // 判线段和圆相交, 包括端点和相切
a4a8 int intersect_seg_circle(CP &c,double r,
       CP &l1,CP &l2){
7ace   double t1=dis(c,l1)-r,t2=dis(c,l2)-r;
481d   point t=c;
6bfd   if (t1<eps||t2<eps)
b703     return t1>-eps||t2>-eps;
524a   t.x+=l1.y-l2.y;
9773   t.y+=l2.x-l1.x;
7706   return xmult(l1,c,t)*xmult(l2,c,t)<eps
         &&disptoline(c,l1,l2)-r<eps;
95cf }
e3cf int intersect_seg_circle(CC &c,CP &l1,CP
       &l2){
63c9   double t1=dis(c.c,l1)-c.r,t2=dis(c.c,l2
```

```
        )-c.r;
3bc7    point t=c.c;
6bfd    if (t1<eps||t2<eps)
b703      return t1>-eps||t2>-eps;
524a    t.x+=l1.y-l2.y;
9773    t.y+=l2.x-l1.x;
78b0    return xmult(l1,c.c,t)*xmult(l2,c.c,t)<
          eps&&disptoline(c.c,l1,l2)-c.r<eps;
95cf  }
427e  // 判圆和圆相交, 包括相切
e4fa  int intersect_circle_circle(CP &c1,double
         r1,CP &c2,double r2){
9676    return dis(c1,c2)<r1+r2+eps&&dis(c1,c2)
          >fabs(r1-r2)-eps;
95cf  }
da9a  int intersect_circle_circle(CC &c1,CC &c2
        ){
14e2    return dis(c1.c,c2.c)<c1.r+c2.r+eps&&
          dis(c1.c,c2.c)>fabs(c1.r-c2.r)-eps;
95cf  }
427e
427e  // 计算圆上到点p 最近点, 如p 与圆心重合, 返
        回p 本身
f391  point dot_to_circle(CP &c,double r,CP &p)
        {
03f5    point u,v;
82e2    if (dis(p,c)<eps)
e149      return p;
6b5b    u.x=c.x+r*fabs(c.x-p.x)/dis(c,p);
e0a3    u.y=c.y+r*fabs(c.y-p.y)/dis(c,p)*((c.x-
          p.x)*(c.y-p.y)<0?-1:1);
8ae0    v.x=c.x-r*fabs(c.x-p.x)/dis(c,p);
81cd    v.y=c.y-r*fabs(c.y-p.y)/dis(c,p)*((c.x-
          p.x)*(c.y-p.y)<0?-1:1);
ceec    return dis(u,p)<dis(v,p)?u:v;
95cf  }
521e  point dot_to_circle(CC &c,CP &p){
03f5    point u,v;
3905    if (dis(p,c.c)<eps)
e149      return p;
525f    u.x=c.c.x+c.r*fabs(c.c.x-p.x)/dis(c.c,p
          );
0882    u.y=c.c.y+c.r*fabs(c.c.y-p.y)/dis(c.c,p
          )*((c.c.x-p.x)*(c.c.y-p.y)<0?-1:1);
2d9f    v.x=c.c.x-c.r*fabs(c.c.x-p.x)/dis(c.c,p
          );
fc50    v.y=c.c.y-c.r*fabs(c.c.y-p.y)/dis(c.c,p
          )*((c.c.x-p.x)*(c.c.y-p.y)<0?-1:1);
ceec    return dis(u,p)<dis(v,p)?u:v;
95cf  }
427e
427e  // 计算直线与圆的交点, 保证直线与圆有交点
427e  // 计算线段与圆的交点可用这个函数后判点是否在
        线段上
c8d1  void intersection_line_circle(CP &c,
        double r,CP &l1,CP &l2,point& p1,point&
         p2){
e36e    point p=c;
3337    double t;
e339    p.x+=l1.y-l2.y;
4399    p.y+=l2.x-l1.x;
1b68    p=intersection(p,c,l1,l2);
d753    t=sqrt(r*r-dis(p,c)*dis(p,c))/dis(l1,l2
          );
f468    p1.x=p.x+(l2.x-l1.x)*t;
7618    p1.y=p.y+(l2.y-l1.y)*t;
d8a7    p2.x=p.x-(l2.x-l1.x)*t;
24fc    p2.y=p.y-(l2.y-l1.y)*t;
95cf  }
c26e  void intersection_line_circle(CC &c,CP &
        l1,CP &l2,point& p1,point& p2){
92cd    point p=c.c;
3337    double t;
e339    p.x+=l1.y-l2.y;
4399    p.y+=l2.x-l1.x;
c608    p=intersection(p,c.c,l1,l2);
3855    t=sqrt(c.r*c.r-dis(p,c.c)*dis(p,c.c))/
          dis(l1,l2);
f468    p1.x=p.x+(l2.x-l1.x)*t;
7618    p1.y=p.y+(l2.y-l1.y)*t;
d8a7    p2.x=p.x-(l2.x-l1.x)*t;
24fc    p2.y=p.y-(l2.y-l1.y)*t;
95cf  }
427e
427e  // 计算圆与圆的交点, 保证圆与圆有交点圆心不
        重合,
0999  void intersection_circle_circle(CP &c1,
        double r1,CP &c2,double r2,point& p1,
        point& p2){
03f5    point u,v;
3337    double t;
b814    t=(1+(r1*r1-r2*r2)/dis(c1,c2)/dis(c1,c2
          ))/2;
fcc3    u.x=c1.x+(c2.x-c1.x)*t;
3c66    u.y=c1.y+(c2.y-c1.y)*t;
20b2    v.x=u.x+c1.y-c2.y;
c44e    v.y=u.y-c1.x+c2.x;
bb81    intersection_line_circle(c1,r1,u,v,p1,
          p2);
95cf  }
8068  void intersection_circle_circle(CC &c1,CC
         &c2,point& p1,point& p2){
03f5    point u,v;
3337    double t;
ad39    t=(1+(c1.r*c1.r-c2.r*c2.r)/dis(c1.c,c2.
          c)/dis(c1.c,c2.c))/2;
```

```
8414    u.x=c1.c.x+(c2.c.x-c1.c.x)*t;
b2d6    u.y=c1.c.y+(c2.c.y-c1.c.y)*t;
4218    v.x=u.x+c1.c.y-c2.c.y;
4b8b    v.y=u.y-c1.c.x+c2.c.x;
30f9    intersection_line_circle(c1.c,c1.r,u,v,
          p1,p2);
95cf  }
427e
427e  // 判断圆在多边形内, 顶点按顺时针或逆时针给
        出,offset 为多边形坐标上限
9451  bool inside_circle_polygon(CP &c, double
        r, int n, point * polygon){
d1de    if (!inside_polygon(c, n, polygon, 1))
438e      return false;
85c3    for (int i = 0; i < n; ++i)
b348      if (disptoline(c,polygon[i], polygon
            [(i + 1) % n]) < r)
438e        return false;
3361    return true;
95cf  }
0dc3  bool inside_circle_polygon(CC &c, int n,
        point * polygon){
a224    if (!inside_polygon(c.c, n, polygon, 1)
          )
438e      return false;
85c3    for (int i = 0; i < n; ++i)
a14b      if (disptoline(c.c,polygon[i],
            polygon[(i + 1) % n]) < c.r)
438e        return false;
3361    return true;
95cf  }
427e
427e  // 判断多边形在圆内, 包括圆上
5c07  bool inside_polygon_circle(CP &c, double
        r, int n, point *polygon){
85c3    for (int i = 0; i < n; ++i)
1b91      if (dis2(c, polygon[i]) >= r * r)
438e        return false;
3361    return true;
95cf  }
6a80  bool inside_polygon_circle(CC &c, int n,
        point *polygon){
85c3    for (int i = 0; i < n; ++i)
5c9f      if (dis2(c.c, polygon[i]) >= c.r * c.
            r)
438e        return false;
3361    return true;
95cf  }
427e
427e  // 求圆外一点与圆的切线, 返回两个切点
218e  void tangent_point_circle(CP &c, double r
        , CP &p, point &a, point &b){
00e3    double d = dis(c, p);
        double angp = acos(r / d);                0e20
        double ango = atan2(p.y - c.y, p.x - c.   736d
          x);
        a.x = c.x + r * cos(ango + angp);         0150
        a.y = c.y + r * sin(ango + angp);         fc8b
        b.x = c.x + r * cos(ango - angp);         8b80
        b.y = c.y + r * sin(ango - angp);         0c1e
      }                                           95cf
      void tangent_point_circle(CC &c, CP &p,     6800
        point &a, point &b){
        double d = dis(c.c, p);                   ad5f
        double angp = acos(c.r / d);              5c2a
        double ango = atan2(p.y - c.c.y, p.x -    5922
          c.c.x);
        a.x = c.c.x + c.r * cos(ango + angp);     e086
        a.y = c.c.y + c.r * sin(ango + angp);     a8d8
        b.x = c.c.x + c.r * cos(ango - angp);     b6f5
        b.y = c.c.y + c.r * sin(ango - angp);     aa9f
      }                                           95cf
                                                  427e
      // 求内切圆, 返回两个切线                   427e
      void incut_circle_circle(CP &c1,double r1   0d4d
        ,CP &c2,double r2,line& l1,line& l2){
        double d = sqrt(dis2(c1, c2) - sqr(r1 +   b709
          r2));
        point p1, p2;                             cc70
        intersection_circle_circle(c1, r1 + r2,   d070
          c2, d, p1, p2);
        l1.a = (p1 * r1 + c1 * r2) / (r1 + r2);   6042
        l1.b = l1.a + (c2 - p1);                  6bb3
        l2.a = (p2 * r1 + c1 * r2) / (r1 + r2);   4a4c
        l2.b = l2.a + (c2 - p2);                  ea2d
      }求原点原语扇形的夹角                      95cf
                                                  427e
      //                                          427e
      double area_circle_angle(CP &p1, CP &p2,    5ad0
        CP &c, double r){
        double alpha = fabs(atan2(p1.y - c.y,     db38
          p1.x - c.x) - atan2(p2.y - c.y, p2.x
          - c.x));
        if (alpha > pi) alpha = 2 * pi - alpha;   9617
        return alpha / 2 * r * r;                 25ea
      }                                           95cf
                                                  427e
      // 求三角形的的外接圆                       427e
      void  circleoftri(CP &a, CP &b, CP &c,      6ff9
        circle &tmp){
        tmp.c = circumcenter(a,b,c);              d028
        tmp.r = dis(a, tmp.c);                    cdd7
      }                                           95cf
                                                  427e
      // 求包含n 个给定点的的最小圆， n <= 3      427e
      void min_circle_reduce(int n, point *p,     8504
```

```
    circle &tmp){
427e  //cout<<n<<endl;
7707  if (n == 0) tmp.r = -2;
a7ed  else if (n == 1){
c330    tmp.c = p[0];
0541    tmp.r = 0;
02a8  }else if (n == 2){
fa16    tmp.r = dis(p[0], p[1]) / 2;
8222    tmp.c = (p[0] + p[1]) / 2;
119b  }else if (n == 3)
87a4    circleoftri(p[0], p[1], p[2], tmp);
95cf }
427e
e0ae void min_circle(int n, point *p, int m,
    point *down, circle &c){
427e
425e  min_circle_reduce(m, down, c);
1ae8  if (m == 3) return;
6c2f  for (int i = 0; i < n; ++i){
427e    //cout<<i<<"  "<<n<<endl;
427e    //cout<<dis(p[i], c.c)<<' '<<c.r<<
          endl;
899e    if (dis(p[i], c.c) > c.r){
427e      //cout<<m<<"yes"<<endl;
03c5      down[m] = p[i];
85d9      min_circle(i, p, m + 1, down, c);
fe45      point tmp = p[i];
f1bb      for (int j = i; j >= 1; --j)
a042        p[j] = p[j - 1];
9161      p[0] = tmp;
95cf    }
95cf  }
95cf }
427e
427e // 求包含n 个给定点的最小圆
71a8 void min_circle(int n, point *p, circle &
    c){
ab81  point down[3];
9fff  min_circle(n, p, 0,down,c);
95cf }求圆和三角形
427e
427e //{c p1 p2的相交面积}
4c91 double area_triangle_circle(CP &c, double
     r, CP &p1, CP &p2){
8059  double x = xmult(p2, c, p1);
3230  int flag = ((x)>eps?1:((x)<-eps?-1:0));
1be0  if (flag == 0) return 0;
c3b3  double r2 = sqr(r);
6c66  double s = 0, l1 = dis2(p1, c), l2 =
      dis2(p2, c);
64ce  if ((l1 <= r2)&&(l2 <= r2))
f56c    return area_triangle(p2, c, p1) *
          flag;
1e19  if ((l1 > r2)&&(l2 > r2)){
98ff    point p3, p4;
fbb4    s = area_circle_angle(p2, p1, c, r);
a4ed    if (disptoseg(c, p1, p2) < r){
4917      intersection_line_circle(c, r, p1,
            p2, p3, p4);
7d00      if (dis2(p3, p1) > dis2(p4, p1))
            swap(p3, p4);
a289      s -= area_circle_angle(p3, p4, c, r
            ) - area_triangle(p3, c, p4);
95cf      }
c890    return s * flag;
95cf  }
bcd6  if (l1 < l2){
98ff    point p3, p4;
4917    intersection_line_circle(c, r, p1, p2
          , p3, p4);
912e    if (dmult(p3, p2, p1) <= 0) p3 = p4;
f0b8    s = area_triangle(p1, p3, c) +
          area_circle_angle(p3, p2, c, r);
c890    return s * flag;
8e2e  }else{
98ff    point p3, p4;
4917    intersection_line_circle(c, r, p1, p2
          , p3, p4);
f453    if (dmult(p3, p1, p2) <= 0) p3 = p4;
8ee3    s = area_triangle(p2, p3, c) +
          area_circle_angle(p3, p1, c, r);
c890    return s * flag;
95cf  }
95cf }求圆和多边形的相交面积
427e
427e //
baa7 double area_polygon_circle(int n, point p
    [], CP &c, double r){
753f  double ans = 0;
85c3  for (int i = 0; i < n; ++i)
3b9b    ans += area_triangle_circle(c, r, p[i
          ], p[(i + 1) % n]);
80ec  return fabs(ans);
95cf }
```

2.9 网格

```
058c #define abs(x) ((x)>0?(x):-(x))
29c0 struct point{int x,y;};
427e
0d5b int gcd(int a,int b){
5fd6   return b?gcd(b,a%b):a;
95cf }
427e
427e // 多边形上的网格点个数
bd90 int grid_onedge(int n,point* p){
54c1   int i,ret=0;
```

```
2dbf    for (i=0;i<n;i++)
b3cc      ret+=gcd(abs(p[i].x-p[(i+1)%n].x),abs
            (p[i].y-p[(i+1)%n].y));
ee0f    return ret;
95cf  }
427e
427e  // 多边形内的网格点个数
b273  int grid_inside(int n,point* p){
54c1    int i,ret=0;
2dbf    for (i=0;i<n;i++)
0639      ret+=p[(i+1)%n].y*(p[i].x-p[(i+2)%n].
            x);
0ba0    return (abs(ret)-grid_onedge(n,p))/2+1;
95cf  }
```

2.10 区域中点集个数

```
427e  // 求p1 中任意三点切割的七个区域的p1 点集的
        个数, 要求三点不共线
427e  // 求xy 到xz 角度里点的个数
cfb5  int pointinang(int x, int y, int z, int m
        , int f[][MAXN], int index[][MAXN]){
3c28    if (index[x][z] < index[x][y]) return m
           + f[x][z] - f[x][y] + 1;
03df    return f[x][z] - f[x][y] - 1;
95cf  }
427e
427e  // 求三角形xyz 中的点的个数, 输入总的点的个
        数,
427e  //f[x][y] 表示x 为中心ang 比y 小的点的个数
427e  //h[x][y] 表示xy 左边的点的个数
427e  //index[x][y] 表示x 为中心极角排序后的序
e42a  int pointintri(point p[], int x, int y,
        int z, int m, int f[][MAXN], int h[][
        MAXN], int index[][MAXN]){
283b    if (xmult(p[z], p[y], p[x]) > 0) swap(y
          , z);
53ef    int a = h[x][z] + h[y][x] + h[z][y];
5a59    a += pointinang(x, y, z, m, f, index);
f5d7    a += pointinang(y, z, x, m, f, index);
150c    a += pointinang(z, x, y, m, f, index);
fd8e    a -= 2 * m;
5ffd    return a;
95cf  }
427e
427e  // 求p1 任意三点划分的区域的点的个数, 要求三
        点不共线
427e  //f[x][y] 表示x 为中心ang 比y 小的点的个数
427e  //h[x][y] 表示xy 左边的点的个数
427e  //index[x][y] 表示x 为中心极角排序后的序
614b  void pointinarea(int n, point p1[], int f
        [][MAXN], int h[][MAXN], int index[][
        MAXN]){
60da    point p[2 * MAXN];
```

```
  for (int i = 0; i < n; ++i){                    6c2f
    int cnt = 0;                                  8abb
    for (int j = 0; j < n; ++j)                   fde8
      if (i != j){                                4a23
        p[cnt] = p1[j];                           ca58
        p[cnt].index = j;                         28c2
        p[cnt++].ang = atan2(p1[j].y - p1         2f66
          [i].y, p1[j].x - p1[i].x);
      }                                           95cf
    sort(p, p + cnt, cmp);                        b073
    for (int j = 0; j < cnt; ++j){                07de
      p[j + cnt] = p[j];                          fcfa
      p[j + cnt].ang += 2 * pi;                   ceb9
    }                                             95cf
    for (int k = 0, j = 0, mine = 0, l =          07b3
      0; k < cnt; ++k){
      while (p[j].ang - p[k].ang < pi){           9b9c
        ++mine;                                   ae6d
        ++j;                                      917f
      }                                           95cf
      --mine;                                     5021
      h[i][p[k].index] = mine;                    ca69
      f[i][p[k].index] = l;                       c92b
      index[i][p[k].index] = k;                   e5d0
      ++l;                                        713f
    }                                             95cf
  }                                               95cf
}                                                 95cf
                                                  427e
                                                  427e
// 求p1 中任意三点切割的七个区域的p2 点集的        427e
  个数, 要求三点不共线
// 求xy 到xz 角度里点的个数                       427e
int pointinang2(int x, int y, int z, int        251e
  m, int f[][MAXN], int index[][MAXN]){
  if (index[x][z] < index[x][y]) return m       35b8
     + f[x][z] - f[x][y];
  return f[x][z] - f[x][y];                       bd1e
}                                                 95cf
                                                  427e
// 求三角形xyz 中的点的个数, 输入总的点的个       427e
  数,
//f[x][y] 表示x 为中心ang 比y 小的点的个数       427e
//h[x][y] 表示xy 左边的点的个数                  427e
//index[x][y] 表示x 为中心极角排序后的序         427e
int pointintri2(point p[], int x, int y,        73ff
  int z, int m, int f[][MAXN], int h[][
  MAXN], int index[][MAXN]){
  if (xmult(p[z], p[y], p[x]) > 0) swap(y       283b
    , z);
  int a = h[x][z] + h[y][x] + h[z][y];           53ef
  a += pointinang2(x, y, z, m, f, index);        2851
  a += pointinang2(y, z, x, m, f, index);        61bc
```

```
164e    a += pointinang2(z, x, y, m, f, index);
fd8e    a -= 2 * m;
5ffd    return a;
95cf  }
427e
427e  // 求p1 任意三点划分的区域的p2 点的个数, 要
        求三点不共线
427e  //f[x][y] 表示x 为中心ang 比y 小的点的个数
427e  //h[x][y] 表示xy 左边的点的个数
427e  //index[x][y] 表示x 为中心极角排序后的序
3cbd  void pointinarea2(int n, point p1[], int
        m, point p2[], int f[][MAXN], int h[][
        MAXN], int index[][MAXN]){
9941    point p[2 * (MAXN + MAXM)];
6c2f    for (int i = 0; i < n; ++i){
8abb      int cnt = 0;
fde8      for (int j = 0; j < n; ++j)
4a23        if (i != j){
ca58          p[cnt] = p1[j];
28c2          p[cnt].index = j;
2f66          p[cnt++].ang = atan2(p1[j].y - p1
                [i].y, p1[j].x - p1[i].x);
95cf        }
6613      for (int j = 0; j < m; ++j){
acb5          p[cnt] = p2[j];
6d16          p[cnt].index = n + j;
3745          p[cnt++].ang = atan2(p2[j].y - p1
                [i].y, p2[j].x - p1[i].x);
95cf        }
b073      sort(p, p + cnt, cmp);
07de      for (int j = 0; j < cnt; ++j){
fcfa        p[j + cnt] = p[j];
ceb9        p[j + cnt].ang += 2 * pi;
95cf      }
07b3      for (int k = 0, j = 0, mine = 0, l =
            0; k < cnt; ++k){
9b9c        while (p[j].ang - p[k].ang < pi){
8ddd          if (p[j].index >= n) ++mine;
917f          ++j;
95cf        }
85b2        if (p[k].index < n){
ca69          h[i][p[k].index] = mine;
c92b          f[i][p[k].index] = l;
e5d0          index[i][p[k].index] = k;
95cf        }
2410        if (p[k].index >= n){
5021          --mine;
713f          ++l;
95cf        }
95cf      }
95cf    }
95cf  }
```

3 三维计算几何

3.1 定义

```
#define eps 1e-8                                652e
#define fabs(x) ((x) > 0? (x): -(x))            c1b0
#define zero(x) (fabs(x) < eps)                 0102
#define sqr(x) ((x)*(x))                        dca2
#define _sign(x) ((x)>eps?1:((x)<-eps           12d8
  ?2:0))
const double pi = acos(-1);                     13f1
                                                427e
// 点的定义                                     427e
struct point3{                                  b6b2
  double x, y, z;                               9d7e
  point3(){x = 0;y = 0;z = 0;}                  6c19
  point3(double sx, double sy, double sz)       18ee
    {
    x = sx;                                     e87b
    y = sy;                                     d22b
    z = sz;                                     826b
    }                                           95cf
  bool operator <(const point3 &b)const{        548e
    if (b.x == x){                              1737
      if (y == b.y) return z < b.z;             e65c
      return y < b.y;                           326b
    }                                           95cf
    return x < b.x;                             66d1
  }                                             95cf
  point3 operator - (const point3 &b)           bb9f
    const {
    point3 a;                                   d6bc
    a.x = x - b.x;                              d53d
    a.y = y - b.y;                              5365
    a.z = z - b.z;                              eb85
    return a;                                   5ffd
  }                                             95cf
  point3 operator + (const point3 &b)           c055
    const{
    point3 a;                                   d6bc
    a.x = x + b.x;                              7683
    a.y = y + b.y;                              70a0
    a.z = z + b.z;                              ee56
    return a;                                   5ffd
  }                                             95cf
  point3 operator / (const double &c)           1731
    const{
    point3 a;                                   d6bc
    a.x = x / c;                                225c
    a.y = y / c;                                414d
    a.z = z / c;                                155b
    return a;                                   5ffd
  }                                             95cf
```

```
4f46   point3 operator * (const double &c)
         const{
d6bc     point3 a;
7aa6     a.x = x * c;
9a5c     a.y = y * c;
f068     a.z = z * c;
5ffd     return a;
95cf   }
412f   bool operator == (const point3 &p)
         const {
84cf     return zero(x - p.x)&&zero(y - p.y)&&
           zero(z - p.z);
95cf   }
c712   friend ostream& operator << (ostream &
         out, const point3 &a);
329b };
1da1 ostream& operator << (ostream &out, const
       point3 &a){
5d5d   out<<a.x<<' '<<a.y<<' '<<a.z;
d324   return out;
95cf }
427e
427e // 边定义
3cfc struct line3{
2f60   point3 a, b;
2f79   line3(){};
64c6   line3(const point3 &p1, const point3 &
         p2){
0fa8     a = p1;
ce41     b = p2;
95cf   }
e69c   friend ostream& operator << (ostream &
         out, const line3 &a);
329b };
0e98 ostream& operator << (ostream &out, const
       line3 &a){
ad81   out<<a.a<<' '<<a.b<<' ';
d324   return out;
95cf }
427e
427e // 面定义
a1a2 struct plane3{point3 a,b,c;};
```

3.2 点线面

```
427e // 计算cross product U x V
c4b1 point3 xmult(const point3 &u, const
       point3 &v){
92b5   point3 ret;
97a6   ret.x = u.y * v.z - v.y * u.z;
55e0   ret.y = u.z * v.x - u.x * v.z;
cf98   ret.z = u.x * v.y - u.y * v.x;
ee0f   return ret;
95cf }
                                          427e
// 计算dot product U . V                  427e
double dmult(const point3 &u, const       f42e
  point3 &v){
  return u.x * v.x + u.y * v.y + u.z * v.  49f2
    z;
}                                         95cf
                                          427e
// 取平面法向量                           427e
point3 pvec(const plane3 &s){             388c
  return xmult(s.a - s.b, s.b - s.c);     07d5
}                                         95cf
point3 pvec(const point3 &s1, const       afb0
  point3 &s2, const point3 &s3){
  return xmult(s1 - s2, s2 - s3);         fd86
}                                         95cf
                                          427e
// 两点距离, 单参数取向量大小             427e
double dis(const point3 &p1, const point3 9e30
   &p2){
  return sqrt(sqr(p1.x - p2.x) + sqr(p1.y fafb
     - p2.y) + sqr(p1.z - p2.z));
}                                         95cf
double dis2(const point3 &p1, const       be8b
  point3 &p2){
  return sqr(p1.x - p2.x) + sqr(p1.y - p2 5cdd
    .y) + sqr(p1.z - p2.z);
}                                         95cf
                                          427e
// 向量大小                               427e
double len(const point3 &p){              81ce
  return sqrt(sqr(p.x) + sqr(p.y) + sqr(p 2aa8
    .z));
}                                         95cf
                                          427e
// 判三点共线                             427e
int dots_inline(const point3 &p1, const   d4bb
  point3 &p2,const point3 &p3){
  return len(xmult(p1 - p2, p2 - p3)) <   f368
    eps;
}                                         95cf
                                          427e
// 判四点共面                             427e
int dots_onplane(const point3 &a, const   2e86
  point3 &b, const point3 &c, const
  point3 &d){
  return zero(dmult(pvec(a, b, c), d - a) 03fd
    );
}                                         95cf
                                          427e
// 判点是否在线段上, 包括端点和共线       427e
int dot_online_in(const point3 &p, const  e21b
  line3 &l){
```

```
5cd9    return zero(len(xmult(p - l.a, p - l.b)
          ))&&
7c2a      (l.a.x - p.x) * (l.b.x - p.x) < eps&&
0643      (l.a.y - p.y) * (l.b.y - p.y) < eps&&
4305      (l.a.z - p.z) * (l.b.z - p.z) < eps;
95cf  }
ac26  int dot_online_in(const point3 &p, const
        point3 &l1, const point3 &l2){
2feb    return zero(len(xmult(p - l1,p - l2)))
          &&
0a0b      (l1.x - p.x) * (l2.x - p.x) < eps&&
6f88      (l1.y - p.y) * (l2.y - p.y) < eps&&
51be      (l1.z - p.z) * (l2.z - p.z) < eps;
95cf  }
427e
427e  // 判点是否在线段上, 不包括端点
bd50  int dot_online_ex(const point3 &p, const
        line3 &l){
02c3    return dot_online_in(p, l) && (!(p == l
          .a))&&(!(p == l.b));
95cf  }
f8de  int dot_online_ex(const point3 &p, const
        point3 &l1, const point3 &l2){
35c7    return dot_online_in(p, l1, l2) && (!(p
           == l1))&&(!(p == l2));
95cf  }
427e
427e  // 判点是否在空间三角形上, 包括边界, 三点共
        线无意义
9b58  int dot_inplane_in(const point3 &p, const
         plane3 &s){
de8c    return zero(len(xmult(s.a - s.b, s.a -
          s.c)) - len(xmult(p - s.a, p - s.b))-
febf      len(xmult(p - s.b, p - s.c)) - len(
            xmult(p - s.c, p - s.a)));
95cf  }
e9f4  int dot_inplane_in(const point3 &p, const
         point3 &s1, const point3 &s2, const
        point3 &s3){
cc89    return zero(len(xmult(s1 - s2, s1 - s3)
          ) - len(xmult(p - s1, p - s2))-
daa7      len(xmult(p - s2, p - s3)) - len(
            xmult(p - s3, p - s1)));
95cf  }
427e
427e  // 判点是否在空间三角形上, 不包括边界, 三点
        共线无意义
6d33  int dot_inplane_ex(const point3 &p, const
         plane3 &s){
ac70    return dot_inplane_in(p, s) && len(
          xmult(p - s.a, p - s.b)) > eps &&
1c47      len(xmult(p - s.b, p - s.c)) > eps &&
f1de      len(xmult(p - s.c, p - s.a)) > eps;
}                                                95cf
int dot_inplane_ex(const point3 &p, const        bcde
   point3 &s1, const point3 &s2, const
  point3 &s3){
  return dot_inplane_in(p, s1, s2, s3) &&        3430
     len(xmult(p - s1, p - s2)) > eps &&
    len(xmult(p - s2, p - s3)) > eps &&          505b
    len(xmult(p - s3, p - s1)) > eps;            f5c1
}                                                95cf
                                                 427e
// 判两点在线段同侧, 点在线段上返回0, 不共面      427e
  无意义
int same_side(const point3 &p1, const            7ef7
  point3 &p2, const line3 &l){
  return dmult(xmult(l.a - l.b, p1 - l.b)        d86a
    , xmult(l.a - l.b, p2 - l.b)) > eps;
}                                                95cf
int same_side(const point3 &p1, const            0410
  point3 &p2,const point3 &l1, const
  point3 &l2){
  return dmult(xmult(l1 - l2, p1 - l2),          0b72
    xmult(l1 - l2, p2 - l2)) > eps;
}                                                95cf
                                                 427e
// 判两点在线段异侧, 点在线段上返回0, 不共面      427e
  无意义
int opposite_side(const point3 &p1, const        9477
   point3 &p2, const line3 &l){
  return dmult(xmult(l.a - l.b, p1 - l.b)        faa2
    , xmult(l.a - l.b, p2 - l.b)) < -eps;
}                                                95cf
int opposite_side(const point3 &p1, const        76a6
   point3 &p2,const point3 &l1, const
  point3 &l2){
  return dmult(xmult(l1 - l2, p1 - l2),          4ffb
    xmult(l1 - l2, p2 - l2)) < -eps;
}                                                95cf
                                                 427e
// 判两点在平面同侧, 点在平面上返回0             427e
int same_side(const point3 &p1, const            3b4b
  point3 &p2, const plane3 &s){
  return dmult(pvec(s), p1 - s.a) * dmult        e2bb
    (pvec(s), p2 - s.a) > eps;
}                                                95cf
int same_side(const point3 &p1, const            7b77
  point3 &p2, const point3 &s1, const
  point3 &s2, const point3 &s3){
  return dmult(pvec(s1,s2,s3), p1 - s1) *        94f6
     dmult(pvec(s1,s2,s3), p2 - s1) > eps
    ;
}                                                95cf
                                                 427e
// 判两点在平面异侧, 点在平面上返回0             427e
```

```
9512 int opposite_side(const point3 &p1, const
       point3 &p2, const plane3 &s){
fe1f   return dmult(pvec(s), p1 - s.a) * dmult
         (pvec(s), p2 - s.a) < -eps;
95cf }
05f5 int opposite_side(const point3 &p1, const
       point3 &p2, const point3 &s1, const
       point3 &s2, const point3 &s3){
9067   return dmult(pvec(s1,s2,s3), p1 - s1) *
         dmult(pvec(s1,s2,s3), p2 - s1) < -
         eps;
95cf }
427e
427e // 判两直线平行
490a int parallel(const line3 &u, const line3
       &v){
1ac2   return len(xmult(u.a - u.b, v.a - v.b))
         < eps;
95cf }
7409 int parallel(const point3 &u1, const
       point3 &u2, const point3 &v1, const
       point3 &v2){
8751   return len(xmult(u1 - u2, v1 - v2)) <
         eps;
95cf }
427e
427e // 判两平面平行
3062 int parallel(const plane3 &u, const
       plane3 &v){
c6ae   return len(xmult(pvec(u) , pvec(v))) <
         eps;
95cf }
7d09 int parallel(const point3 &u1, const
       point3 &u2, const point3 &u3, const
       point3 &v1,point3 v2,point3 v3){
ef70   return len(xmult(pvec(u1, u2, u3), pvec
         (v1, v2, v3))) < eps;
95cf }
427e
427e // 判直线与平面平行
454a int parallel(const line3 &l, const plane3
       &s){
31d4   return zero(dmult(l.a - l.b, pvec(s)));
95cf }
06d0 int parallel(const point3 &l1, const
       point3 &l2, const point3 &s1, const
       point3 &s2, const point3 &s3){
d311   return zero(dmult(l1 - l2, pvec(s1, s2,
         s3)));
95cf }
427e
427e // 判两直线垂直
b98a int perpendicular(const line3 &u, const
       line3 &v){
85bf   return zero(dmult(u.a - u.b, v.a - v.b)
         );
95cf }
b77b int perpendicular(const point3 &u1, const
       point3 &u2, const point3 &v1, const
       point3 &v2){
4547   return zero(dmult(u1 - u2, v1 - v2));
95cf }
427e
427e // 判两平面垂直
0e75 int perpendicular(const plane3 &u, const
       plane3 &v){
da40   return zero(dmult(pvec(u), pvec(v)));
95cf }
75f2 int perpendicular(const point3 &u1, const
       point3 &u2, const point3 &u3, const
       point3 &v1, const point3 &v2, const
       point3 &v3){
8919   return zero(dmult(pvec(u1, u2, u3),
         pvec(v1, v2, v3)));
95cf }
427e
427e // 判直线与平面平行
16f9 int perpendicular(const line3 &l, const
       plane3 &s){
ff31   return len(xmult(l.a - l.b, pvec(s))) <
         eps;
95cf }
d6d3 int perpendicular(const point3 &l1, const
       point3 &l2, const point3 &s1, const
       point3 &s2, const point3 &s3){
d501   return len(xmult(l1 - l2, pvec(s1, s2,
         s3))) < eps;
95cf }
427e
427e // 判两线段相交, 包括端点和部分重合
dfe1 int intersect_in(const line3 &u, const
       line3 &v){
5163   if (!dots_onplane(u.a, u.b, v.a, v.b))
7021     return 0;
e887   if (!dots_inline(u.a,u.b,v.a)||!
         dots_inline(u.a,u.b,v.b))
d666     return !same_side(u.a,u.b,v)&&!
           same_side(v.a,v.b,u);
efeb   return dot_online_in(u.a,v)||
         dot_online_in(u.b,v)||dot_online_in(v
         .a,u)||dot_online_in(v.b,u);
95cf }
2b77 int intersect_in(const point3 &u1, const
       point3 &u2, const point3 &v1, const
       point3 &v2){
cedb   if (!dots_onplane(u1, u2, v1, v2))
```

```
7021      return 0;
8fcb    if (!dots_inline(u1,u2,v1)||!
          dots_inline(u1,u2,v2))
4b79      return !same_side(u1,u2,v1,v2)&&!
            same_side(v1,v2,u1,u2);
cc40    return dot_online_in(u1,v1,v2)||
          dot_online_in(u2,v1,v2)||
          dot_online_in(v1,u1,u2)||
          dot_online_in(v2,u1,u2);
95cf  }
427e
427e  // 判两线段相交, 不包括端点和部分重合
ea94  int intersect_ex(const line3 &u, const
        line3 &v){
6c51    return dots_onplane(u.a,u.b,v.a,v.b)&&
          opposite_side(u.a,u.b,v)&&
          opposite_side(v.a,v.b,u);
95cf  }
aa4a  int intersect_ex(const point3 &u1, const
        point3 &u2, const point3 &v1, const
        point3 &v2){
6424    return dots_onplane(u1,u2,v1,v2)&&
          opposite_side(u1,u2,v1,v2)&&
          opposite_side(v1,v2,u1,u2);
95cf  }
427e
427e  // 判线段与空间三角形相交, 包括交于边界
        和( 部分) 包含
4e75  int intersect_in(const line3 &l, const
        plane3 &s){
8378    return !same_side(l.a,l.b,s)&&!
          same_side(s.a,s.b,l.a,l.b,s.c)&&
153b      !same_side(s.b,s.c,l.a,l.b,s.a)&&!
            same_side(s.c,s.a,l.a,l.b,s.b);
95cf  }
e9ac  int intersect_in(const point3 &l1, const
        point3 &l2, const point3 &s1, const
        point3 &s2, const point3 &s3){
3c9d    return !same_side(l1,l2,s1,s2,s3)&&!
          same_side(s1,s2,l1,l2,s3)&&
89da      !same_side(s2,s3,l1,l2,s1)&&!
            same_side(s3,s1,l1,l2,s2);
95cf  }
427e
427e  // 判线段与空间三角形相交, 不包括交于边界
        和( 部分) 包含
2571  int intersect_ex(const line3 &l, const
        plane3 &s){
02e8    return opposite_side(l.a,l.b,s)&&
          opposite_side(s.a,s.b,l.a,l.b,s.c)&&
f9f7      opposite_side(s.b,s.c,l.a,l.b,s.a)&&
            opposite_side(s.c,s.a,l.a,l.b,s.b);
95cf  }
```

```
ebd9  int intersect_ex(const point3 &l1, const
        point3 &l2, const point3 &s1, const
        point3 &s2, const point3 &s3){
3e15    return opposite_side(l1,l2,s1,s2,s3)&&
          opposite_side(s1,s2,l1,l2,s3)&&
ebb0      opposite_side(s2,s3,l1,l2,s1)&&
            opposite_side(s3,s1,l1,l2,s2);
95cf  }
427e
427e  // 计算两直线交点, 注意事先判断直线是否共面
        和平行 !
427e  // 线段交点请另外判线段相交同时还是要判断是否
        平行 ( !)
58cf  point3 intersection(const line3 &u, const
        line3 &v){
87cc    point3 ret=u.a;
273a    double t=((u.a.x-v.a.x)*(v.a.y-v.b.y)-(
          u.a.y-v.a.y)*(v.a.x-v.b.x))
9cb3        /((u.a.x-u.b.x)*(v.a.y-v.b.y)-(u.a.
              y-u.b.y)*(v.a.x-v.b.x));
1143    ret.x+=(u.b.x-u.a.x)*t;
12e9    ret.y+=(u.b.y-u.a.y)*t;
1037    ret.z+=(u.b.z-u.a.z)*t;
ee0f    return ret;
95cf  }
b3fa  point3 intersection(const point3 &u1,
        const point3 &u2, const point3 &v1,
        const point3 &v2){
1fef    point3 ret=u1;
a7db    double t=((u1.x-v1.x)*(v1.y-v2.y)-(u1.y
          -v1.y)*(v1.x-v2.x))
16f0        /((u1.x-u2.x)*(v1.y-v2.y)-(u1.y-u2.
              y)*(v1.x-v2.x));
a1f8    ret.x+=(u2.x-u1.x)*t;
fa1b    ret.y+=(u2.y-u1.y)*t;
d408    ret.z+=(u2.z-u1.z)*t;
ee0f    return ret;
95cf  }
427e
427e  // 计算直线与平面交点, 注意事先判断是否平
        行, 并保证三点不共线!
427e  // 线段和空间三角形交点请另外判断
1f8f  point3 intersection(const line3 &l, const
        plane3 &s){
a582    point3 ret=pvec(s);
f84a    double t=(ret.x*(s.a.x-l.a.x)+ret.y*(s.
          a.y-l.a.y)+ret.z*(s.a.z-l.a.z))/
7e59      (ret.x*(l.b.x-l.a.x)+ret.y*(l.b.y-l.a
            .y)+ret.z*(l.b.z-l.a.z));
6247    ret.x=l.a.x+(l.b.x-l.a.x)*t;
6934    ret.y=l.a.y+(l.b.y-l.a.y)*t;
706b    ret.z=l.a.z+(l.b.z-l.a.z)*t;
ee0f    return ret;
```

```
95cf  }
2ec4  point3 intersection(const point3 &l1,
        const point3 &l2, const point3 &s1,
        const point3 &s2, const point3 &s3){
2f24    point3 ret=pvec(s1,s2,s3);
38b0    double t=(ret.x*(s1.x-l1.x)+ret.y*(s1.y
          -l1.y)+ret.z*(s1.z-l1.z))/
e0f5      (ret.x*(l2.x-l1.x)+ret.y*(l2.y-l1.y)+
            ret.z*(l2.z-l1.z));
6302    ret.x=l1.x+(l2.x-l1.x)*t;
9cd9    ret.y=l1.y+(l2.y-l1.y)*t;
29b2    ret.z=l1.z+(l2.z-l1.z)*t;
ee0f    return ret;
95cf  }
427e
427e  // 计算两平面交线, 注意事先判断是否平行, 并
        保证三点不共线 !
69e4  line3 intersection(const plane3 &u, const
         plane3 &v){
57af    line3 ret;
7b9a    ret.a=parallel(v.a,v.b,u.a,u.b,u.c)?
          intersection(v.b,v.c,u.a,u.b,u.c):
          intersection(v.a,v.b,u.a,u.b,u.c);
033e    ret.b=parallel(v.c,v.a,u.a,u.b,u.c)?
          intersection(v.b,v.c,u.a,u.b,u.c):
          intersection(v.c,v.a,u.a,u.b,u.c);
ee0f    return ret;
95cf  }
68d7  line3 intersection(const point3 &u1,
        const point3 &u2, const point3 &u3,
        const point3 &v1, const point3 &v2,
        const point3 &v3){
57af    line3 ret;
0075    ret.a=parallel(v1,v2,u1,u2,u3)?
          intersection(v2,v3,u1,u2,u3):
          intersection(v1,v2,u1,u2,u3);
2a2b    ret.b=parallel(v3,v1,u1,u2,u3)?
          intersection(v2,v3,u1,u2,u3):
          intersection(v3,v1,u1,u2,u3);
ee0f    return ret;
95cf  }
427e
427e  // 点到直线距离
3696  double ptoline(const point3 &p, const
        line3 &l){
eddb    return len(xmult(p - l.a, l.b - l.a))/
          dis(l.a,l.b);
95cf  }
c402  double ptoline(const point3 &p, const
        point3 &l1, const point3 &l2){
c833    return len(xmult(p - l1, l2 - l1))/dis(
          l1,l2);
95cf  }
```

```
427e
427e  // 点到平面距离
427e  double ptoplane(const point3 &p, const
7ed7    plane3 &s){
b87b    return fabs(dmult(pvec(s), p - s.a))/
          len(pvec(s));
95cf  }
33d1  double ptoplane(const point3 &p, const
        point3 &s1, const point3 &s2, const
        point3 &s3){
3cea    return fabs(dmult(pvec(s1,s2,s3), p -
          s1))/len(pvec(s1,s2,s3));
95cf  }
427e
427e  // 直线到直线距离
eaed  double linetoline(const line3 &u, const
        line3 &v){
79e9    point3 n=xmult(u.a - u.b, v.a - v.b);
2a04    return fabs(dmult(u.a - v.a,n))/len(n);
95cf  }
c288  double linetoline(const point3 &u1, const
         point3 &u2, const point3 &v1, const
        point3 &v2){
a9a1    point3 n=xmult(u1 - u2, v1 - v2);
04de    return fabs(dmult(u1 - v1,n))/len(n);
95cf  }
427e
427e  // 两直线夹角cos 值
7010  double angle_cos(const line3 &u, const
        line3 &v){
0567    return dmult(u.a - u.b, v.a - v.b)/len(
          u.a - u.b)/len(v.a - v.b);
95cf  }
a590  double angle_cos(const point3 &u1, const
        point3 &u2, const point3 &v1, const
        point3 &v2){
b4cf    return dmult(u1 - u2, v1 - v2)/len(u1 -
           u2)/len(v1 - v2);
95cf  }
427e
427e  // 两平面夹角cos 值
5766  double angle_cos(const plane3 &u, const
        plane3 &v){
8688    return dmult(pvec(u),pvec(v))/len(pvec(
          u))/len(pvec(v));
95cf  }
2053  double angle_cos(const point3 &u1, const
        point3 &u2, const point3 &u3, const
        point3 &v1, const point3 &v2, const
        point3 &v3){
a583    return dmult(pvec(u1,u2,u3),pvec(v1,v2,
          v3))/len(pvec(u1,u2,u3))/len(pvec(v1,
          v2,v3));
```

```
95cf }
427e
427e // 直线平面夹角sin 值
9344 double angle_sin(const line3 &l, const
       plane3 &s){
2177   return dmult(l.a - l.b,pvec(s))/len(l.a
         - l.b)/len(pvec(s));
95cf }
e36a double angle_sin(const point3 &l1,const
       point3 &l2, const point3 &s1, const
       point3 &s2, const point3 &s3){
14dc   return dmult(l1 - l2,pvec(s1,s2,s3))/
         len(l1 - l2)/len(pvec(s1,s2,s3));
95cf }
```

3.3 面积

```
427e // 求三角形有向表面积，输入三个顶点
0f35 double area_triangle(const plane3 &p){
c025   return len(xmult(p.b - p.a, p.c - p.a))
         /2;
95cf }
78b2 double area_triangle(const point3 &p1,
       const point3 &p2, const point3 &p3){
aa2a   return len(xmult(p2 - p1, p3 - p1))/2;
95cf }
6e8b double area_triangle(const point3 &p2,
       const point3 &p3){
c28a   return len(xmult(p2, p3))/2;
95cf }
427e // 求多边形有向表面积，输入三个顶点
2eca double area_polygon(int n,point3* p){
99ec   double s;
85c3   for (int i = 0;i < n; ++i)
d161     s += len(xmult(p[i], p[(i + 1) % n]))
           / 2;
fe09   return s;
95cf }
```

3.4 体积

```
427e // 求四面体有向体积，输入四个点
ef35 double volume_tetrahedron(const point3 &
       p1, const point3 &p2, const point3 &p3,
        const point3 &p4){
c2f2   return dmult(xmult(p1 - p4, p2 - p4),
         p3 - p4) / 6;
95cf }
b1cf double volume_tetrahedron(const point3 &
       p1, const point3 &p2, const point3 &p3)
       {
74cc   return dmult(xmult(p1, p2), p3) / 6;
95cf }
```

```
double volume_tetrahedron(const plane3 &p  2cde
  ){
  return dmult(xmult(p.a, p.b), p.c) / 6;  9493
}                                          95cf
// 求多面体有向体积                        427e
double volume_polygon(int n, plane3 *      0532
  polygon){
  double c = 0;                            0ea9
  for (int i = 0; i < n; ++i)              85c3
    c += volume_tetrahedron(polygon[i]);   8088
  return c;                                14df
}                                          95cf
```

3.5 重心

```
// 三角形重心                              427e
point3 barycenter(const point3 &a, const  4ce9
  point3 &b, const point3 &c){
  return a + b + c / 3;                    85a3
}                                          95cf
// 四面体重心                              427e
point3 barycenter(const point3 &a, const  6485
  point3 &b, const point3 &c, const
  point3 &d){
  return (a + b) + (c + d) / 4;            3cb1
}                                          95cf
// 多面体重心                              427e
point3 barycenter(int n, plane3 *polygon)  0a46
  {
  point3 c;                                a1fc
  double v = 0;                            b0c2
  for (int i = 0; i < n; ++i){             6c2f
    double j = volume_tetrahedron(polygon  e51b
      [i]);
    v += j;                                58e1
    c = c + (polygon[i].a + polygon[i].b   32b4
      + polygon[i].c) * j;
    }                                      95cf
  return c / (4 * v);                      432b
}                                          95cf
```

3.6 凸包

```
//a–b–右手定则指向凸包外面c               427e
const int MAXN = 500;                      ce3a
const int MAXM = 250000;                   9400
struct NODE{                               f8d9
  int p[4], next, out;                     f5a3
  point3 f;                                7f4c
}s[MAXM];                                  4cef
int edge[MAXN][MAXN];                      91d4
int tot;                                   8164
int next(int x){                           0019
  if (s[x].next == x) return x;            d010
```

```
901a    return s[x].next = next(s[x].next);
95cf  }
f01b  void add(int a, int b, int c, point3 *p){
582f    s[tot].p[0] = a;
661d    s[tot].p[1] = b;
50e3    s[tot].p[2] = c;
c4b1    s[tot].p[3] = a;
202c    s[tot].f = xmult(p[b] - p[a], p[c] - p[
          a]);
7fb3    s[tot].out = false;
100b    for (int i = 0; i < 3; ++i)
1e79      edge[s[tot].p[i]][s[tot].p[i + 1]] =
            tot;
ac2d    ++tot;
95cf  }
c1c6  void add(int a, int b, int c, int d,
        point3 *p){
05a3    point3 f = xmult(p[b] - p[a], p[c] - p[
          a]);
40d9    if (dmult(f, p[d] - p[a]) > 0) add(a, c
          , b, p);
3c28    else add(a, b, c, p);
95cf  }
427e
427e  // 主程序输入顶点个数，点集，返回面，
427e  // 要求不是所有点共面
4db6  int get_convex(int n, point3* p, plane3*
        convex){
d712    for (int i = 0; i < MAXM; ++i)
06de      s[i].next = i;
b7ad    tot = 0;
37f3    for (int i = 3; i < n; ++i)
79d4      if (!dots_onplane(p[0], p[1], p[2], p
            [i])){
3d14        swap(p[i], p[3]);
6173        break;
95cf      }
ea37    add(0, 1, 2, 3, p);
97fe    add(2, 3, 0, 1, p);
0393    add(3, 1, 0, 2, p);
cee5    add(3, 1, 2, 0, p);
7384    for (int i = 4; i < n; ++i){
e569      for (int j = next(0); j < tot; j =
            next(j + 1))
da36        s[j].out = dmult(s[j].f, p[i] - p[s
              [j].p[0]]) > 0;
21b5      int c = tot;
e569      for (int j = next(0); j < tot; j =
            next(j + 1))
9413        if (s[j].out){
9004          for (int k = 0; k < 3; ++k)
bda5            if (!s[edge[s[j].p[k + 1]][s[j
                  ].p[k]]].out)
1807              add(s[j].p[k], s[j].p[k + 1],
                    i, p);
68c3        s[j].next = j + 1;
95cf      }
95cf    }
576f    int i, j;
d4d9    for (i = 0, j = next(0); j < tot; ++i,
          j = next(j + 1)){
82ac      convex[i].a = p[s[j].p[0]];
c1d7      convex[i].b = p[s[j].p[1]];
f7bf      convex[i].c = p[s[j].p[2]];
95cf    }
ffec    return i;
95cf  }
```

4 数论

4.1 头文件

```
427e  // independent
e0a5  #include<iostream>
54ff  #include<algorithm>
c928  #include<cmath>
59b9  #include<cstdio>
59b9  #include<cstdio>
8c52  #include<map>
6326  #include<set>
09f7  #include<vector>
ef2f  #include<cstring>
2349  #include<string>
421c  using namespace std;
5cad  typedef long long LL;
1f2c  typedef unsigned int UI;
b773  typedef unsigned long long ULL;
4d7e  const LL mod=1000000007;
```

4.2 基础

```
427e  // independent
427e  // fast multiplication
3f6b  LL FM(LL a,LL t,LL mod)
4506  {
af5c    a%=mod;
b56a    LL ans=1, mid=a;
4c1b    while(t){
06fb      if(t&1) ans*=mid,ans%=mod;
3ea9      mid*=mid;mid%=mod;
2f01      t>>=1;
95cf    }
4206    return ans;
95cf  }
427e  // gcd
c2e9  LL gcd(LL a,LL b)
```

```
4506 {
55d6   if (a<b){LL c=a;a=b;b=c;}
c56f   while (b!=0)
4506   {
28f6     LL c=a;a=b;b=c%b;
95cf   }
5ffd   return a;
95cf }
80eb LL lcm(LL a,LL b){
2dcf   LL g=gcd(a,b);
bda5   return a/g*b;
95cf }
427e // return gcd(a,b),a*x+b*y=g;
8534 LL ext_gcd(LL a,LL b,LL &x,LL &y)
4506 {
7d1a   if(b == 0){x = 1;y = 0;return a;}
e9fa   LL g = ext_gcd(b, a % b, x, y);
166e   LL t = x;x = y,y=t-a/b*y;
05da   return g;
95cf }
```

4.3 线性筛法

```
427e // independent
62a8 const int MAXN=10000000;
1858 int cprime[MAXN],used=0;
8a94 char p[MAXN];
0919 void prime_(){
ff7c    memset(p,0,sizeof p);
3099    for(int i=2;i<MAXN;i++){
f677      if(!p[i])  cprime[used]=i,used++;
97c2      for(int j=0;j<used;j++){
c98f        if(i*cprime[j]>MAXN) break;
ece6        p[i*cprime[j]]=true;
0f27        if(i%cprime[j]==0)break;
95cf      }
95cf    }
95cf }
```

4.4 线性同余方程

```
427e // depend on 基础：ext_gcd
427e
427e // 求一元线性同余方程： a*x = b mod m 的所
       有解（在同余系中）存于 ,数组ans 解的个数
       存在,中len
c8bd bool cong_eq(LL a,LL b,LL m,LL ans[],LL &
       len)
4506 {
2f15    LL g,x,y;
6b0f    g=ext_gcd(a,m,x,y);
1bd9    if(b%g) return false;
2800    LL base=((b/g*x)%m+m)%m;
62c8    len=g;
89a5    for(int i=0;i<len;i++) ans[i]=(base+i
          *(m/len))%m;
3361    return true;
95cf }
```

4.5 中国剩余定理

```
427e // depend on 基础：ext_gcd
427e
427e // 中国剩余定理解特殊线性方程组，
        x= a[i] mod b[i其中], b[i两两互质，
       共]个方程r
7300 LL china(LL a[], LL b[], int r){
afa3   LL M=1;
8fa0   LL i,Mi,x0,y0,d,ans=0;
38d2   for(i=0;i<r;i++){
b024     M*=b[i];
95cf   }
38d2   for(i=0;i<r;i++){
13d5     Mi=M/b[i];
e90f     ext_gcd(Mi,b[i],x0,y0);
e55d     ans=(ans+Mi*x0*a[i])%M;
95cf   }
361d   if(ans<0) ans+=M;
4206   return ans;
95cf }
```

4.6 离散对数

```
427e // independent
427e // 求解形如  a^x= bmod MOD 的方程，，，已
       知abMOD
427e
ee1f const int maxn = 65535;
4609 struct hash{
db04   int a,b,next;
cbde }Hash[maxn << 1];
ab55 int flg[maxn];
3ce9 int top,idx;
4921 void ins(int a,int b){
2e3c   int k = b & maxn;
fcdc   if(flg[k] != idx){
29f2     flg[k] = idx;
81a6     Hash[k].next = -1;
c3b7     Hash[k].a = a;
e19e     Hash[k].b = b;
4f2d     return ;
95cf   }
fd3e   while(Hash[k].next != -1){
e55c     if(Hash[k].b == b) return ;
5551     k = Hash[k].next;
95cf   }
f7e2   Hash[k].next = ++ top;
8c95   Hash[top].next = -1;
```

```
d291    Hash[top].a = a;
ad12    Hash[top].b = b;
95cf  }
99f4  int find(int b){
2e3c    int k = b & maxn;
a4dc    if(flg[k] != idx) return -1;
9030    while(k != -1){
b35f      if(Hash[k].b == b) return Hash[k].a;
5551      k = Hash[k].next;
95cf    }
fb5e    return -1;
95cf  }
427e
e8bb  int gcd(int a,int b){return b?gcd(b,a%b):
        a;}
5e78  int ext_gcd(int a,int b,int& x,int& y){
0c60    int t,ret;
a0bb    if (!b){x=1,y=0;return a;}
4d23    ret=ext_gcd(b,a%b,x,y);
0eb3    t=x,x=y,y=t-a/b*y;
ee0f    return ret;
95cf  }
427e
49b5  int pow_mod(LL a,int b,int c)
4506  {
8fef    LL ret=1%c;a%=c;
7c06    while(b)
4506    {
6f75      if(b&1)
6bc0      ret=ret*a%c;
3386      a=a*a%c;
ca1f      b>>=1;
f959    }return ret;
95cf  }
3be4  int Inval(int a,int b,int n){
9853    int x,y,e;
38ce    ext_gcd(a,n,x,y);
4c93    e=(LL)x*b%n;
4e9d    return e<0?e+n:e;
95cf  }
c5f3  int BabyStep(int A,int B,int C){
856b    top = maxn; ++ idx;
c05a    LL buf=1%C,D=buf,K;
36c9    int i,d=0,tmp;
9f59    for(i=0;i<=100;buf=buf*A%C,++i)if(buf==
          B)return i;
87dc    while((tmp=gcd(A,C))!=1){
9506      if(B%tmp)return -1;
fb15      ++d;
6f10      C/=tmp;
e3f3      B/=tmp;
b8d3      D=D*A/tmp%C;
95cf    }
fea4    int M=(int)ceil(sqrt((double)C));
2662    for(buf=1%C,i=0;i<=M;buf=buf*A%C,++i)
          ins(i,buf);
21a3    for(i=0,K=pow_mod((LL)A,M,C);i<=M;D=D*K
          %C,++i){
5d4e      tmp=Inval((int)D,B,C);int w ;
b3d8      if(tmp>0&&(w = find(tmp)) != -1)
            return i*M+w+d;
95cf    }
fb5e    return -1;
95cf  }
427e
427e
427e
3117  int main(){
1e17    int A,B,C;
2072    while(scanf("%d%d%d",&A,&C,&B)!=EOF,A
          || B || C){
1fc4      B %= C;
1719      int tmp=BabyStep(A,B,C);
6a67      if(tmp<0)puts("No Solution");else
            printf("%d\n",tmp);
95cf    }
7021    return 0;
95cf  }
```

4.7 MillerRabin

```
427e  // depend on 基础:  multiMod
44b6  bool witness ( LL s , LL n ) {
c625    LL u = n - 1 ;
2f70    int t = 0 ;
01e0    while ( ( u & 1 ) == 0 ) u >>= 1 , t ++
          ;
427e
de44    LL x = FM ( s , u , n ) ;
3c2f    while ( t -- ) {
6da3      LL tmp = x ;
7216      x = multiMod ( x , x , n ) ;
89ce      if ( x == 1 ) {
a72c        if ( tmp == n - 1 || tmp == 1  )
              return false ;//may be prime
fe75        else return true ;//composite
95cf      }
95cf    }
3361    return true ; //composite
95cf  }
427e
2daf  bool millerRabin ( LL n , const int times
        = 3 ) {
89e8    if ( n == 2 ) return true ;
62ac    if ( ( n & 1 ) == 0 || n < 2 ) return
          false ;
d8c4    int i = times ;
```

```
148a    while ( i -- ) {
2e40      LL s = rand ( ) % ( n - 1 ) + 1 ;
6474      if ( witness ( s , n ) ) return false
             ;
95cf    }
3361    return true ;
95cf  }
```

4.8 PollardRho

```
427e  // depend on 基础：，multiModFM
5bc3  LL multiMod ( LL a , LL b , LL n ) {
dcd8    a %= n ;
37f2    b %= n ;
9f3a    LL s = 0 ;
ca22    while( b ) {
90a9      if( b & 1 ) {
4134        s += a ;
f497        if( s >= n ) s -= n ;
95cf      }
80ab      a <<= 1 ; b >>= 1 ;
082b      if(a >= n ) a -= n ;
95cf    }
fe09    return  s ;
95cf  }
427e
9285  LL FM ( LL s , LL u , LL n ) {
c7db    s %= n ;
eb30    LL tmp = 1 ;
7ce6    while ( u ) {
5ab5      if ( u & 1 ) tmp = multiMod ( tmp , s
             , n ) ;
5085      s = multiMod ( s , s , n ) ;
517f      u >>= 1 ;
95cf    }
fe6e    return tmp ;
95cf  }
427e
44b6  bool witness ( LL s , LL n ) {
c625    LL u = n - 1 ;
2f70    int t = 0 ;
01e0    while ( ( u & 1 ) == 0 ) u >>= 1 , t ++
           ;
427e
de44    LL x = FM ( s , u , n ) ;
3c2f    while ( t -- ) {
6da3      LL tmp = x ;
7216      x = multiMod ( x , x , n ) ;
89ce      if ( x == 1 ) {
a72c        if ( tmp == n - 1 || tmp == 1  )
              return false ;//may be prime
fe75        else return true ;//composite
95cf      }
95cf    }
    return true ; //composite                3361
  }                                           95cf
                                              427e
  bool millerRabin ( LL n , const int times   2daf
     = 3 ) {
    if ( n == 2 ) return true ;               89e8
    if ( ( n & 1 ) == 0 || n < 2 ) return     62ac
      false ;
    int i = times ;                           d8c4
    while ( i -- ) {                          148a
      LL s = rand ( ) % ( n - 1 ) + 1 ;       2e40
      if ( witness ( s , n ) ) return false   6474
         ;
    }                                         95cf
    return true ;                             3361
  }                                           95cf
  LL gcd ( LL a , LL b ) {                    4990
    if ( b == 0 ) return a ;                  22aa
    return gcd ( b , a % b ) ;                7b09
  }                                           95cf
  LL pollard_rho ( LL n ) {                   32db
    LL x , y , k , d  ;                       61ac
    x = y = rand ( ) % n ;                    2cce
    k = 2 ;                                   7924
    int i = 1 ;                               0d80
    int c =rand ( ) % n ;                     25c7
                                              427e
    while ( true ) {                          1026
      i ++ ;                                  a42b
      x = ( multiMod ( x , x , n ) + c ) %    a98e
        n ;
      if ( y == x ) return 1 ;//restart       abe5
      else if ( y > x ) d = gcd ( y - x , n   397a
         ) ;
      else d = gcd ( x - y , n ) ;            f73d
      if ( d != 1 && d != n - 1 ) return d    6dad
        ;
      else {                                  037f
        if ( i == k ) {                       679a
          y = x ;                             88e9
          k <<= 1 ;                           453c
        }                                     95cf
      }                                       95cf
    }                                         95cf
  }存放分解出的质因子                         95cf
  //                                          427e
  LL factors [ 54 ] ;初始化为                 a6bf
  //0                                         427e
  int cnt ;                                   9f58
                                              427e
  void split ( LL n ) {//n != 1               10b4
    if ( millerRabin ( n ) ) factors [ cnt    0494
      ++ ] = n ;
```

```
037f   else {
3942     LL p ;
a69f     do {
9a67       p = pollard_rho ( n ) ;
1ce0     }while ( p == n || p == 1 );
83ef     split ( p ) ;
0573     split ( n / p ) ;
95cf   }
95cf }
```

4.9 矩阵基础

```
427e // independent
cffb struct Matrix{int m[MAXN][MAXN],l,r;
d184   Matrix(int w){
d0d9     l=r=w;
6b09     memset(m,0,sizeof m);
95cf   }
b54c   Matrix(){l=r=0;memset(m,0,sizeof m);}
329b };
427e // a.r = b.l
0a3f Matrix operator * (Matrix a,Matrix b){
c97f   Matrix c;
3fe0   memset(c.m,0,sizeof c.m);
7272   c.l=a.l,c.r=b.r;
91ca   for(int i=0;i<a.l;i++){
6363     for(int j=0;j<b.r;j++){
d081       for(int k=0;k<a.r;k++){
78c3         c.m[i][j]+=a.m[i][k]*b.m[k][j];
427e //         c.m[i][j]%=mod取余;//
95cf       }
95cf     }
95cf   }
14df   return c;
95cf }
427e
427e // a.l == b.l && a.r == b.r
ece1 Matrix operator + (Matrix a,Matrix b){
c97f   Matrix c;
b567   c.l=a.l;c.r=a.r;
91ca   for(int i=0;i<a.l;i++){
c58d     for(int j=0;j<a.r;j++){
c4cc       c.m[i][j]=a.m[i][j]+b.m[i][j];
bd48       c.m[i][j]%=mod;
95cf     }
95cf   }
14df   return c;
95cf }
5eb9 Matrix FM(Matrix a,int t)
4506 {
d2a0   Matrix ans;ans.l=ans.r=a.l;
782d   for(int i=0;i<a.l;i++)ans.m[i][i]=1;
6880   Matrix mid=a;
4c1b   while(t){
e385     if(t&1) ans=ans*mid;
c1cb     mid=mid*mid;
2f01     t>>=1;
95cf   }
4206   return ans;
95cf }
```

4.10 高斯消元

```
427e // independent
fb02 #define MAXN 100
c1b0 #define fabs(x) ((x)>0?(x):-(x))
b76f #define eps 1e-10列主元
427e
427e //消去求解gaussa[][]x[]=b[]返回是否有唯一解
       若有解在
427e //,b中[]
f2e9 int gauss_cpivot(int n,double a[][MAXN],
       double b[]){
c75e   int i,j,k,row;
ea2e   double maxp,t;
ab8e   for (k=0;k<n;k++){
a1ed     for (maxp=0,i=k;i<n;i++)
8dd1       if (fabs(a[i][k])>fabs(maxp))
f0ed         maxp=a[row=i][k];
ff5d     if (fabs(maxp)<eps)
7021       return 0;
7dcf     if (row!=k){
0dff       for (j=k;j<n;j++)
b70f         t=a[k][j],a[k][j]=a[row][j],a[row
               ][j]=t;
243a       t=b[k],b[k]=b[row],b[row]=t;
95cf     }
1ff9     for (j=k+1;j<n;j++){
8e4d       a[k][j]/=maxp;
34eb       for (i=k+1;i<n;i++)
56e2         a[i][j]-=a[i][k]*a[k][j];
95cf     }
4cd8     b[k]/=maxp;
34eb     for (i=k+1;i<n;i++)
5fe8       b[i]-=b[k]*a[i][k];
95cf   }
e913   for (i=n-1;i>=0;i--)
cd1d     for (j=i+1;j<n;j++)
2139       b[i]-=a[i][j]*b[j];
7459   return 1;
95cf }
```

5 数据结构

5.1 SplayTree

```
59b9 #include<cstdio>
```

```
ef2f  #include<cstring>
bffa  #include<cstdlib>
427e
421c  using namespace std;
427e
1c79  #define MAXN 40010
06a1  #define INF 1ll<<62
5da6  #define MAX(a,b) ((a)>(b)?(a):(b))
11d0  struct SplayTree{
427e
f7cd    struct SplayNode{
b275      SplayNode *f,*C[2];
427e      //int s,ml,mr,max,tot,sz;
440f      long long s,c,sz;
427e      //bool rev,same;
b01b    } S[MAXN],*root,*null,*tr;
427e
4a30    int sz;
427e
88f1    void init()
4506    {
bd30      for (int i=0;i<=sz;i++) S[i].s=S[i].c
            =S[i].sz=0;
1bb9      sz=0;
47f6      null=NewNode(null,-INF);
ab2e      null->s=0;
f607      null->f=null;
c969      null->sz=0;
e3e8      null->C[0]=null->C[1]=null;
b6b3      root=NewNode(null,-INF);
0e03      root->C[1]=NewNode(root,INF);
2753      update(root->C[1]);
d657      update(root);
95cf    }
427e
b77a    SplayNode * NewNode( SplayNode *f, long
           long s){
dbed      SplayNode *ts;
40e5      ts=S+ ++sz;
2d59      ts->f=f;
bc22      ts->c=0;
577f      ts->C[0]=ts->C[1]=null;
ca6f      ts->s=s;
427e      //ts->tot=ts->max=ts->ml=ts->mr=ts->s
            ;
fdcf      ts->sz=1;
427e      //ts->rev=ts->same=0;
dd0c      return ts;
95cf    }
427e
9356    SplayTree(){
47f6      null=NewNode(null,-INF);
ab2e      null->s=0;
          null->f=null;                          f607
          null->sz=0;                            c969
          null->C[0]=null->C[1]=null;            e3e8
          root=NewNode(null,-INF);               b6b3
          root->C[1]=NewNode(root,INF);          0e03
          update(root->C[1]);                    2753
          update(root);                          d657
        }                                        95cf
                                                 427e
        void update( SplayNode * x){             886d
          x->sz=x->C[0]->sz+x->C[1]->sz+1+x->c;  fa89
          /*x->tot=x->C[0]->tot+x->C[1]->tot+x   180a
            ->s;
          x->max=MAX(x->s,x->C[0]->max);         b048
          x->max=MAX(x->max,x->C[1]->max);       935a
          x->max=MAX(x->max,x->C[0]->mr+x->s);   3392
          x->max=MAX(x->max,x->C[1]->ml+x->s);   9a2e
          x->max=MAX(x->max,x->C[0]->mr+x->s+x   8176
            ->C[1]->ml);
          x->ml=MAX(x->C[0]->ml,x->C[0]->tot+x   0181
            ->s);
          x->ml=MAX(x->ml,x->C[0]->tot+x->s+x->  7a57
            C[1]->ml);
          x->mr=MAX(x->C[1]->mr,x->C[1]->tot+x   77d1
            ->s);
          x->mr=MAX(x->mr,x->C[1]->tot+x->s+x->  a71b
            C[0]->mr);*/
        }                                        95cf
                                                 427e
        /*void labledown( SplayNode *x){         1455
          SplayNode *ts;                         dbed
          int tmp;                               6eb3
          if (x==null||!(x->same||x->rev))       45c9
            return ;
          if (x->same){                          d66a
            x->C[1]->same=x->C[0]->same=1;       d26a
            x->C[1]->s=x->C[0]->s=x->s;          e573
            x->tot=x->s*x->sz;                   3058
            x->max=x->ml=x->mr=x->tot;           37f3
            if (x->s<0)                          89b1
              x->max=x->ml=x->mr=x->s;           be32
          }                                      95cf
          if (x->rev){                           e2e3
            tmp=x->ml;x->ml=x->mr;x->mr=tmp;     f24b
            ts=x->C[1];x->C[1]=x->C[0];x->C[0]=  ef88
              ts;
            x->C[1]->rev=!x->C[1]->rev;x->C      001e
              [0]->rev=!x->C[0]->rev;
          }                                      95cf
          x->same=x->rev=0;                      925b
        }*/                                      fe38
                                                 427e
        void route( SplayNode *k1, int c){       965e
```

```
487c      SplayNode *k2=k1->f;
427e      //labledown(k2->C[!c]);labledown(k1->
            C[0]);labledown(k1->C[1]);
427e
18d3      k2->C[c]=k1->C[!c];
390f      k2->C[c]->f=k2;
8b3f      k1->f=k2->f;
70ea      if (k2->f->C[0]==k2) k2->f->C[0]=k1;
561f      else k2->f->C[1]=k1;
6439      k2->f=k1;
b627      k1->C[!c]=k2;
c05b      update(k2);//update(k1);
0e39      if (root==k2) root=k1;
95cf    }
427e
5237    SplayNode * rank( int k){
56b2      SplayNode *ts=root;
6eb3      int tmp;
1d6c      while (k){
427e        //labledown(ts);
188b        tmp=ts->C[0]->sz;
f57e        if (k<=tmp) ts=ts->C[0];
17be        else if (k<=tmp+ts->c+1) break;
f19e        else k-=tmp+ts->c+1,ts=ts->C[1];
95cf      }
dd0c      return ts;
95cf    }
427e
ce71    /*void select( int s, int r){
46d4      rank(s,null);rank(r,root);
fe38    }*/
427e
58b9    void splay( SplayNode *x, SplayNode *s)
          {
961d      if (x==null) return ;
66e8      update(x);
427e      //labledown(x);
ea33      while (x->f!=s){
b6c4        if (x->f->f==s){
2f96          if (x->f->C[0]==x)
5c86            route(x,0);
649a          else
f931            route(x,1);
1112        } else if (x->f->f->C[0]==x->f){
2f96          if (x->f->C[0]==x)
3252            route(x->f,0),route(x,0);
649a          else
b8c5            route(x,1),route(x,0);
8e2e        } else {
717f          if (x->f->C[1]==x)
eb10            route(x->f,1),route(x,1);
649a          else
142a            route(x,0),route(x,1);
95cf        }
95cf      }
66e8      update(x);
95cf    }
427e
519b    void ins( long long k)
4506    {
3cd1      SplayNode *ts=root,*ls=null;
8d36      while (ts!=null){
427e        //labledown(ts);
17d7        ls=ts;
4be3        if (k==ts->s)
4506        {
ebae          ts->c++;
841d          update(ts);
530f          splay(ts,null);
4f2d          return ;
95cf        }
35a1        else if (k<ts->s) ts=ts->C[0];
b87e        else ts=ts->C[1];
95cf      }
4efc      if (k<ls->s)
4506      {
7728        ls->C[0]=NewNode(ls,k);
96ed        update(ls->C[0]);update(ls);
4b8a        splay(ls->C[0],null);
d268      } else
4506      {
703f        ls->C[1]=NewNode(ls,k);
9628        update(ls->C[1]);update(ls);
758e        splay(ls->C[1],null);
95cf      }
95cf    }
427e
427e    //value k
6bd3    void remove( long long k)
4506    {
3cd1      SplayNode *ts=root,*ls=null;
8d36      while (ts!=null){
427e        //labledown(ts);
17d7        ls=ts;
4be3        if (k==ts->s)
4506        {
c447          if (ts->c==0)
4506          {
530f            splay(ts,null);
77f9            splay(rank(ts->C[0]->sz),root);
646e            root=ts->C[0];
d16b            root->f=null;
469b            root->C[1]=ts->C[1];
1105            ts->C[1]->f=root;
d657            update(root);
3f99          } else ts->c--,update(ts),splay(
```

```
            ts,null);
4f2d          return ;
95cf        }
35a1        else if (k<ts->s) ts=ts->C[0];
b87e        else ts=ts->C[1];
95cf      }
4f2d      return ;//not find
95cf    }
427e
427e    //rank k
0909    void del( int k)
4506    {
d827      splay(rank(k+1),null);
79ab      splay(rank(root->C[0]->sz),root);
56b2      SplayNode *ts=root;
646e      root=ts->C[0];
d16b      root->f=null;
469b      root->C[1]=ts->C[1];
1105      ts->C[1]->f=root;
d657      update(root);
95cf    }
427e
d16f    int find( int k)
4506    {
d827      splay(rank(k+1),null);
1ff2      return root->s;
95cf    }
427e
8c3f    int find_v( int k)
4506    {
56b2      SplayNode *ts=root;
8d36      while (ts!=null){
427e        //labledown(ts);
4be3        if (k==ts->s)
4506        {
530f          splay(ts,null);
7459          return 1;
95cf        }
35a1        else if (k<ts->s) ts=ts->C[0];
b87e        else ts=ts->C[1];
95cf      }
7021      return 0;
95cf    }
427e
4a3d    bool empty()
4506    {
c635      return !(root->sz-2>0);
95cf    }
eb81  } T;
427e
427e
59b9  #include<cstdio>
ef2f  #include<cstring>
```

```
#include<cstdlib>                                bffa
#include<algorithm>                              54ff
#include<queue>                                  acb9
                                                 427e
using namespace std;                             421c
                                                 427e
priority_queue<int> MinNumber;                   baf7
                                                 427e
#define MAXN 300010                              b47b
#define INF 1ll<<62                              06a1
#define MAX(a,b) ((a)>(b)?(a):(b))               5da6
                                                 427e
                                                 427e
                                                 427e
struct SplayNode{                                f7cd
  SplayNode *f,*C[2];                            b275
  //int s,ml,mr,max,tot,sz;                      427e
  long long s,c,sz,tot;                          880b
  int neg,pos,sta;                               9673
  //bool rev,same;                               427e
};                                               329b
                                                 427e
int N,st,it;                                     e929
char s[100];                                     6c85
SplayNode *A[MAXN],*B[MAXN];                     437d
                                                 427e
                                                 427e
struct SplayTree{                                11d0
                                                 427e
  int sz;                                        4a30
  SplayNode S[MAXN],*root,*null,*tr;             ea48
                                                 427e
  void init()                                    88f1
  {                                              4506
    for (int i=0;i<=sz;i++) S[i].s=S[i].c        bd30
      =S[i].sz=0;
    sz=0;                                        1bb9
    null=NewNode(null,-INF);                     47f6
    null->s=0;                                   ab2e
    null->tot=0;                                 6b1f
    null->neg=null->pos=0;                       0380
    null->f=null;                                f607
    null->sz=0;                                  c969
    null->C[0]=null->C[1]=null;                  e3e8
    root=NewNode(null,0);                        8259
    root->C[1]=NewNode(root,0);                  6a6a
    root->neg=root->pos=root->C[1]->neg=         a562
      root->C[0]->pos=root->sta=root->C
      [1]->sta=0;
    update(root->C[1]);                          2753
    update(root);                                d657
  }                                              95cf
                                                 427e
```

```
b77a  SplayNode * NewNode( SplayNode *f, long
        long s){
dbed    SplayNode *ts;
40e5    ts=S+ ++sz;
2d59    ts->f=f;
577f    ts->C[0]=ts->C[1]=null;
ca6f    ts->s=s;
2d6b    ts->tot=s;
bd5a    ts->neg=s<0?1:0;
ac50    ts->pos=s>0?1:0;
b142    ts->sta=s>0?1:-1;
fdcf    ts->sz=1;
dd0c    return ts;
95cf  }
427e
9356  SplayTree(){
47f6    null=NewNode(null,-INF);
ab2e    null->s=0;
f607    null->f=null;
c969    null->sz=0;
e3e8    null->C[0]=null->C[1]=null;
8259    root=NewNode(null,0);
6a6a    root->C[1]=NewNode(root,0);
2753    update(root->C[1]);
d657    update(root);
95cf  }
427e
886d  void update( SplayNode * x){
fa89    x->sz=x->C[0]->sz+x->C[1]->sz+1+x->c;
7619    x->tot=x->C[0]->tot+x->C[1]->tot+x->s
          ;
9fe9    x->neg=x->C[0]->neg+x->C[1]->neg+(x->
          sta==-1?1:0);
fb82    x->pos=x->C[0]->pos+x->C[1]->pos+(x->
          sta==1?1:0);
95cf  }
427e
965e  void route( SplayNode *k1, int c){
487c    SplayNode *k2=k1->f;
427e    //labledown(k2->C[!c]);labledown(k1->
          C[0]);labledown(k1->C[1]);
427e
18d3    k2->C[c]=k1->C[!c];
390f    k2->C[c]->f=k2;
8b3f    k1->f=k2->f;
70ea    if (k2->f->C[0]==k2) k2->f->C[0]=k1;
561f    else k2->f->C[1]=k1;
6439    k2->f=k1;
b627    k1->C[!c]=k2;
f5eb    update(k2);update(k1);
0e39    if (root==k2) root=k1;
95cf  }
427e
```

```
5237  SplayNode * rank( int k){
56b2    SplayNode *ts=root;
6eb3    int tmp;
1d6c    while (k){
427e  //        labledown(ts);
188b      tmp=ts->C[0]->sz;
f57e      if (k<=tmp) ts=ts->C[0];
f1b2      else if (k<=tmp+1) break;
fefe      else k-=tmp+1,ts=ts->C[1];
95cf    }
dd0c    return ts;
95cf  }
427e
427e
f257  long long query( SplayNode *l,
        SplayNode *r)
4506  {
da8a    splay(l,null);splay(r,root);
7602    return root->C[1]->C[0]->tot+root->s+
          root->C[1]->s;
95cf  }
427e
58b9  void splay( SplayNode *x, SplayNode *s)
        {
961d    if (x==null) return ;
66e8    update(x);
427e    //labledown(x);
ea33    while (x->f!=s){
b6c4      if (x->f->f==s){
2f96        if (x->f->C[0]==x)
5c86          route(x,0);
649a        else
f931          route(x,1);
1112      } else if (x->f->f->C[0]==x->f){
2f96        if (x->f->C[0]==x)
3252          route(x->f,0),route(x,0);
649a        else
b8c5          route(x,1),route(x,0);
8e2e      } else {
717f        if (x->f->C[1]==x)
eb10          route(x->f,1),route(x,1);
649a        else
142a          route(x,0),route(x,1);
95cf      }
95cf    }
66e8      update(x);
95cf  }
427e
427e  //rank k
aae1  void del( SplayNode *ss)
4506  {
fc5e    splay(ss,null);
79ab    splay(rank(root->C[0]->sz),root);
```

```
56b2      SplayNode *ts=root;
646e      root=ts->C[0];
d16b      root->f=null;
469b      root->C[1]=ts->C[1];
1105      ts->C[1]->f=root;
d657      update(root);
95cf    }
427e
0edf    void ins( int k, int s)
4506    {
d827      splay(rank(k+1),null);
427e      //splay(rank(k),root);
e7e2      SplayNode *ts=NewNode(root,s);
7235      root->C[0]->f=ts;
3fe8      ts->C[0]=root->C[0];
d5f0      root->C[0]=ts;
f9af      A[s]=ts;
530f      splay(ts,null);
95cf    }
a228    void find( int t)
4506    {
af72      SplayNode *ts=root,*ls;
eb9a      while (ts!=null)
4506      {
17d7        ls=ts;
eec3        if (ts->C[1]->neg>=t) ts=ts->C[1];
20e3        else if (ts->C[1]->neg+(ts->sta
              <0?1:0)==t) break;
3c94        else t-=ts->C[1]->neg+(ts->sta
              <0?1:0),ts=ts->C[0];
95cf      }
8740      if (ts==null)splay(ls,null);
9bfe      else splay(ts,null);
95cf    }
df17    void insins( int k, int s)
4506    {
9131      int t=root->C[1]->pos;
b7b0      find(t);
ee3d      SplayNode *ts=NewNode(root,-s);
7235      root->C[0]->f=ts;
3fe8      ts->C[0]=root->C[0];
d5f0      root->C[0]=ts;
ebf4      B[s]=ts;
530f      splay(ts,null);
95cf    }
eb81  } T;
427e
0edf  void ins( int k, int s)
4506  {
b69b    T.ins(k,s);
0a72    T.insins(k,s);
95cf  }
427e
```

```
427e
int main()                                  299c
{                                           4506
  int cases=0;                              1008
  while (scanf("%d\n",&N)!=EOF)             b889
  {                                         4506
    T.init();                               db73
    while (MinNumber.size()) MinNumber.     19f9
      pop();
    int nown=0,t;                           6b7c
    printf("Case #%d:\n",++cases);          524a
    while (N--)                             720b
    {                                       4506
      scanf("%s %d\n",s,&t);                860a
      if (s[0]=='i')                        b81b
      {                                     4506
        t++;                                5006
        if (MinNumber.empty()) it=++nown;   7309
        else it=-MinNumber.top(),           c2a0
          MinNumber.pop();
        ins(t,it);                          a3af
      } else if (s[0]=='r')                 603e
      {                                     4506
        MinNumber.push(-t);                 3834
        T.del(A[t]);                        bf62
        T.del(B[t]);                        bb40
      } else if (s[0]=='q')                 b72a
      {                                     4506
        printf("%I64d\n",T.query(A[t],B[t   0016
          ]));
      }                                     95cf
    }                                       95cf
  }                                         95cf
}                                           95cf
```

5.2 SplayTree

```
#include<cstdio>                            59b9
#include<cstring>                           ef2f
#include<cstdlib>                           bffa
                                            427e
using namespace std;                        421c
                                            427e
#define MAXN 40010                          1c79
#define INF 1ll<<62                         06a1
#define MAX(a,b) ((a)>(b)?(a):(b))          5da6
struct SplayTree{                           11d0
                                            427e
  struct SplayNode{                         f7cd
    SplayNode *f,*C[2];                     b275
    //int s,ml,mr,max,tot,sz;               427e
    long long s,c,sz;                       440f
    //bool rev,same;                        427e
  } S[MAXN],*root,*null,*tr;                b01b
```

```
427e
4a30  int sz;
427e
88f1  void init()
4506  {
bd30    for (int i=0;i<=sz;i++) S[i].s=S[i].c
          =S[i].sz=0;
1bb9    sz=0;
47f6    null=NewNode(null,-INF);
ab2e    null->s=0;
f607    null->f=null;
c969    null->sz=0;
e3e8    null->C[0]=null->C[1]=null;
b6b3    root=NewNode(null,-INF);
0e03    root->C[1]=NewNode(root,INF);
2753    update(root->C[1]);
d657    update(root);
95cf  }
427e
b77a  SplayNode * NewNode( SplayNode *f, long
        long s){
dbed    SplayNode *ts;
40e5    ts=S+ ++sz;
2d59    ts->f=f;
bc22    ts->c=0;
577f    ts->C[0]=ts->C[1]=null;
ca6f    ts->s=s;
427e    //ts->tot=ts->max=ts->ml=ts->mr=ts->s
          ;
fdcf    ts->sz=1;
427e    //ts->rev=ts->same=0;
dd0c    return ts;
95cf  }
427e
9356  SplayTree(){
47f6    null=NewNode(null,-INF);
ab2e    null->s=0;
f607    null->f=null;
c969    null->sz=0;
e3e8    null->C[0]=null->C[1]=null;
b6b3    root=NewNode(null,-INF);
0e03    root->C[1]=NewNode(root,INF);
2753    update(root->C[1]);
d657    update(root);
95cf  }
427e
886d  void update( SplayNode * x){
fa89    x->sz=x->C[0]->sz+x->C[1]->sz+1+x->c;
180a    /*x->tot=x->C[0]->tot+x->C[1]->tot+x
          ->s;
b048    x->max=MAX(x->s,x->C[0]->max);
935a    x->max=MAX(x->max,x->C[1]->max);
3392    x->max=MAX(x->max,x->C[0]->mr+x->s);
9a2e    x->max=MAX(x->max,x->C[1]->ml+x->s);
8176    x->max=MAX(x->max,x->C[0]->mr+x->s+x
          ->C[1]->ml);
0181    x->ml=MAX(x->C[0]->ml,x->C[0]->tot+x
          ->s);
7a57    x->ml=MAX(x->ml,x->C[0]->tot+x->s+x->
          C[1]->ml);
77d1    x->mr=MAX(x->C[1]->mr,x->C[1]->tot+x
          ->s);
a71b    x->mr=MAX(x->mr,x->C[1]->tot+x->s+x->
          C[0]->mr);*/
95cf  }
427e
1455  /*void labledown( SplayNode *x){
dbed    SplayNode *ts;
6eb3    int tmp;
45c9    if (x==null||!(x->same||x->rev))
          return ;
d66a    if (x->same){
d26a      x->C[1]->same=x->C[0]->same=1;
e573      x->C[1]->s=x->C[0]->s=x->s;
3058      x->tot=x->s*x->sz;
37f3      x->max=x->ml=x->mr=x->tot;
89b1      if (x->s<0)
be32        x->max=x->ml=x->mr=x->s;
95cf    }
e2e3    if (x->rev){
f24b      tmp=x->ml;x->ml=x->mr;x->mr=tmp;
ef88      ts=x->C[1];x->C[1]=x->C[0];x->C[0]=
            ts;
001e      x->C[1]->rev=!x->C[1]->rev;x->C
            [0]->rev=!x->C[0]->rev;
95cf    }
925b    x->same=x->rev=0;
fe38  }*/
427e
965e  void route( SplayNode *k1, int c){
487c    SplayNode *k2=k1->f;
427e    //labledown(k2->C[!c]);labledown(k1->
          C[0]);labledown(k1->C[1]);
427e
18d3    k2->C[c]=k1->C[!c];
390f    k2->C[c]->f=k2;
8b3f    k1->f=k2->f;
70ea    if (k2->f->C[0]==k2) k2->f->C[0]=k1;
561f    else k2->f->C[1]=k1;
6439    k2->f=k1;
b627    k1->C[!c]=k2;
c05b    update(k2);//update(k1);
0e39    if (root==k2) root=k1;
95cf  }
427e
5237  SplayNode * rank( int k){
```

```
56b2    SplayNode *ts=root;
6eb3    int tmp;
1d6c    while (k){
427e      //labledown(ts);
188b      tmp=ts->C[0]->sz;
f57e      if (k<=tmp) ts=ts->C[0];
17be      else if (k<=tmp+ts->c+1) break;
f19e      else k-=tmp+ts->c+1,ts=ts->C[1];
95cf    }
dd0c    return ts;
95cf  }
427e
ce71  /*void select( int s, int r){
46d4    rank(s,null);rank(r,root);
fe38  }*/
427e
58b9  void splay( SplayNode *x, SplayNode *s)
        {
961d    if (x==null) return ;
66e8    update(x);
427e    //labledown(x);
ea33    while (x->f!=s){
b6c4      if (x->f->f==s){
2f96        if (x->f->C[0]==x)
5c86          route(x,0);
649a        else
f931          route(x,1);
1112      } else if (x->f->f->C[0]==x->f){
2f96        if (x->f->C[0]==x)
3252          route(x->f,0),route(x,0);
649a        else
b8c5          route(x,1),route(x,0);
8e2e      } else {
717f        if (x->f->C[1]==x)
eb10          route(x->f,1),route(x,1);
649a        else
142a          route(x,0),route(x,1);
95cf      }
95cf    }
66e8        update(x);
95cf  }
427e
519b  void ins( long long k)
4506  {
3cd1    SplayNode *ts=root,*ls=null;
8d36    while (ts!=null){
427e      //labledown(ts);
17d7      ls=ts;
4be3      if (k==ts->s)
4506      {
ebae        ts->c++;
841d        update(ts);
530f        splay(ts,null);
4f2d        return ;
95cf      }
35a1      else if (k<ts->s) ts=ts->C[0];
b87e      else ts=ts->C[1];
95cf    }
4efc    if (k<ls->s)
4506    {
7728      ls->C[0]=NewNode(ls,k);
96ed      update(ls->C[0]);update(ls);
4b8a      splay(ls->C[0],null);
d268    } else
4506    {
703f      ls->C[1]=NewNode(ls,k);
9628      update(ls->C[1]);update(ls);
758e      splay(ls->C[1],null);
95cf    }
95cf  }
427e
427e  //value k
6bd3  void remove( long long k)
4506  {
3cd1    SplayNode *ts=root,*ls=null;
8d36    while (ts!=null){
427e      //labledown(ts);
17d7      ls=ts;
4be3      if (k==ts->s)
4506      {
c447        if (ts->c==0)
4506        {
530f          splay(ts,null);
77f9          splay(rank(ts->C[0]->sz),root);
646e          root=ts->C[0];
d16b          root->f=null;
469b          root->C[1]=ts->C[1];
1105          ts->C[1]->f=root;
d657          update(root);
3f99        } else ts->c--,update(ts),splay(
              ts,null);
4f2d        return ;
95cf      }
35a1      else if (k<ts->s) ts=ts->C[0];
b87e      else ts=ts->C[1];
95cf    }
4f2d    return ;//not find
95cf  }
427e
427e  //rank k
0909  void del( int k)
4506  {
d827    splay(rank(k+1),null);
79ab    splay(rank(root->C[0]->sz),root);
56b2    SplayNode *ts=root;
646e    root=ts->C[0];
```

```
d16b      root->f=null;
469b      root->C[1]=ts->C[1];
1105      ts->C[1]->f=root;
d657      update(root);
95cf    }
427e
d16f    int find( int k)
4506    {
d827      splay(rank(k+1),null);
1ff2      return root->s;
95cf    }
427e
8c3f    int find_v( int k)
4506    {
56b2      SplayNode *ts=root;
8d36      while (ts!=null){
427e        //labledown(ts);
4be3        if (k==ts->s)
4506        {
530f          splay(ts,null);
7459          return 1;
95cf        }
35a1        else if (k<ts->s) ts=ts->C[0];
b87e        else ts=ts->C[1];
95cf      }
7021      return 0;
95cf    }
427e
4a3d    bool empty()
4506    {
c635      return !(root->sz-2>0);
95cf    }
eb81  } T;
```

5.3 kdtree

```
0193  const int inf = 1000000000;
f877  #define sqr(x) (((long long)(x))*(x))
7829  const int MAXN = 500000;
427e  //MAXM 维度数
d975  const int MAXM = 2;
427e  // 必须手动设置点的度数 degree
5f09  struct POINT{
a5e8    int x[MAXM], lx[MAXM], rx[MAXM];
082e    int index;
7864    int degree;
aa08    POINT(){
3b30      for (int i = 0; i < MAXM; ++i){
8339        lx[i] = 0;
58a4        rx[i] = inf;
95cf      }
329b    };
9bba    long long dis(const POINT &a){
889f      long long ans = 0;
b02e      for (int i = 0; i < degree; ++i)
d902        ans += sqr(x[i] - a.x[i]);
4206      return ans;
95cf    }
c188  }p[MAXN];
427e  //comindex 是首先比较的维度必须在比较之前赋
        值
6343  int cmpindex;
f78e  bool cmp(const POINT &a, const POINT &b){
ceb8    for (int i = 0; i < a.degree; ++i){
6055      int j = (i + cmpindex) % a.degree;
2abf      if (a.x[j] != b.x[j])
d66a        return a.x[j] < b.x[j];
95cf    }
438e    return false;
95cf  }
427e  //degree 首先被比较的维度
f8d9  struct NODE{
38a5    POINT p;
6f63    int left, right, father;
a55b    int number, degree, flag;
c024    void init(const POINT &a, int d){
0c52      p = a;
009e      left = -1;
5e06      right = -1;
fae0      degree = d;
b556      number = 1;
3a4a      flag = false;
95cf    }
96c3  }node[MAXN];
6ee4  int nodesize;
427e  // 储存结果
eea1  struct CYL{
38a5    POINT p;
eae0    long long r;
2db0    bool operator < (const CYL &a)const{
c9e2      return r < a.r;
95cf    }
329b  };
427e  // 求出v 节点下的所有点到顶点p 的距离
4e6c  void searchr(int v, const POINT &p,
        priority_queue<CYL> &pq, int k){
d043    if (v == -1) return;
0109    CYL c;
add6    c.p = node[v].p;
ffe7    c.r = c.p.dis(p);
b544    pq.push(c);
e49b    while (pq.size() > k) pq.pop();
5ceb    searchr(node[v].left, p, pq, k);
6d98    searchr(node[v].right, p, pq, k);
95cf  }
427e  // 贪心地返回点数接近k 的节点
48d3  int searchknode(int v, const POINT &p,
```

```
    int k){
1cc2  if ((v == -1)||(node[v].number < k))
        return -1;
d02f  cmpindex = node[v].degree;
ff78  if (cmp(p, node[v].p)){
e7b8    if ((node[v].left != -1)&&(node[node[
          v].left].number >= k))
006e      return searchknode(node[v].left, p,
            k);
8e2e  }else{
5fcc    if ((node[v].right != -1)&&(node[node
          [v].right].number >= k))
527c      return searchknode(node[v].right, p
            , k);
95cf  }
aa78  return v;
95cf }
427e // 检查某区域是否可能有k 小的点
3ef1 bool check(POINT &root, const POINT &p,
    priority_queue<CYL> &pq){
d3df  POINT c;
ad9e  c.degree = p.degree;
af4d  for (int i = 0; i < p.degree; ++i){
2451    if ((root.lx[i] <= p.x[i])&&(p.x[i]
          <= root.rx[i])){
91b7      c.x[i] = p.x[i];
b333      continue;
95cf    }
b3f8    if (p.x[i] < root.lx[i]) c.x[i] =
          root.lx[i];
0817    else c.x[i] = root.rx[i];
95cf  }
0f33  if (c.dis(p) < pq.top().r) return true;
438e  return false;
95cf }
427e // 寻找距离最近的k 个点
0fb3 void findk(int v, const POINT &p, int k,
    priority_queue<CYL> &pq){
5dd1  if (node[v].flag){
e213    node[v].flag = false;
4f2d    return;
95cf  }
af9c  long long d = node[v].p.dis(p);
0b50  if (d < pq.top().r){
0109    CYL c;
add6    c.p = node[v].p;
895b    c.r = d;
b544    pq.push(c);
4e19    pq.pop();
95cf  }
f7cb  if ((node[v].left != -1)&&check(node[
        node[v].left].p, p, pq))
2836    findk(node[v].left, p, k, pq);
    if ((node[v].right != -1)&&check(node[   f1f4
      node[v].right].p, p, pq))
    findk(node[v].right, p, k, pq);          5846
}                                            95cf
//KNN 算法，输入KD-tree 的根，返回与 p 最相   427e
  邻的k 个点
//ans 中保证点到的距离依次递增p               427e
void KNN(const POINT &p, int k, POINT ans    4d4d
  []){
  priority_queue<CYL> pq;                    b335
  int v = searchknode(0, p, k);              3c91
  //cout<<v<<endl;                           427e
  node[v].flag = true;                       13c5
  searchr(v, p, pq, k);                      c275
  while(pq.size() > k){                      aa47
    pq.pop();                                4e19
  }                                          95cf
  cnt = 0;                                   8766
  findk(0, p, k, pq);                        07c2
  node[v].flag = false;                      e213
  int n = pq.size();                         9bd2
  for (int i = 0; i < k; ++i){               130b
    ans[i] = pq.top().p;                     bcd6
    pq.pop();                                4e19
  }                                          95cf
  reverse(ans, ans + k);                     2741
}                                            95cf
// 设置每个区域的界                          427e
void boundset(int v){                        007d
  if (v == -1) return;                       d043
  if (node[v].left != -1){                   1c34
    for (int i = 0; i < node[v].p.degree;    788a
       ++i){
      node[node[v].left].p.rx[i] = node[v    4cd0
        ].p.rx[i];
      node[node[v].left].p.lx[i] = node[v    01cc
        ].p.lx[i];
    }                                        95cf
    node[node[v].left].father = v;           1cf1
    node[node[v].left].p.rx[node[v].         2de3
      degree] = node[v].p.x[node[v].
      degree];
    boundset(node[v].left);                  9123
  }                                          95cf
  if (node[v].right != -1){                  3d5d
    for (int i = 0; i < node[v].p.degree;    788a
       ++i){
      node[node[v].right].p.rx[i] = node[    9cb6
        v].p.rx[i];
      node[node[v].right].p.lx[i] = node[    1388
        v].p.lx[i];
    }                                        95cf
    node[node[v].right].father = v;          51dc
```

```
910e      node[node[v].right].p.lx[node[v].
            degree] = node[v].p.x[node[v].
            degree];
33ad      boundset(node[v].right);
95cf    }
95cf  }
427e
427e  // 根据p 中的[s, t) 点建立Kd-TREE ,
427e  //p 中的顺序会被破坏
427e  //degree 是首先比较的维度
d02f  int buildtree(int s, int t, int degree,
        POINT p[], begin = 1){
fb76    if (begin) nodesize = 0;
636f    if (s == t) return -1;
34f1    else if(t - s == 1){
e0a6      node[nodesize].init(p[s], degree);
11a5      return nodesize++;
95cf    }
910c    cmpindex = degree;
4aed    sort(p + s, p + t, cmp);
a7b0    int mid = (s + t - 1) >> 1;
7b7e    int v = nodesize;
8ce7    node[nodesize++].init(p[mid], degree);
ac44    node[v].left = buildtree(s, mid, (
          degree + 1) % p[mid].degree, p, 0);
b4f2    node[v].right = buildtree(mid + 1, t, (
          degree + 1) % p[mid].degree, p, 0);
6a2a    node[v].number = t - s;
e8ae    if (!v){
74a5      node[0].father = -1;
0176      boundset(0);
95cf    }
aa78    return v;
95cf  }
```

5.4 后缀数组

```
e0a5  #include<iostream>
59b9  #include<cstdio>
09f7  #include<vector>
ef2f  #include<cstring>
2349  #include<string>
421c  using namespace std;
f7d6  const int maxn=10000;
1779  #define F(x) ((x)/3+((x)%3==1?0:tb))
2358  #define G(x) ((x)<tb?(x)*3+1:((x)-tb)
        *3+2)值得注意的
        是，
427e
427e  //数组rank 与数组互逆 sa ，所以可以根据sa 在
        （）时间内求出 Onrank以下为倍增算法实现
427e  //  （） Onlogn
427e  //r 为字符串数组  ,sa 为结果S 的n 个后缀从
        小到大进行排序之后把排好序的后缀的开头位置
        顺序，也就是字典序次放入
      //sa 中                                    427e
                                                 427e
      int wa[maxn],wb[maxn],wv[maxn],ws_[maxn];  2278
      int cmp(int *r,int a,int b,int l)          3aa5
      {                                          4506
        return r[a]==r[b]&&r[a+l]==r[b+l];       e543
      }                                          95cf
      //是数组的长度，即（）nrstrlenr,m 为语言集的  427e
        最大编号
      void da(int *r,int *sa,int n,int m)        cdcb
      {                                          4506
         int i,j,p,*x=wa,*y=wb,*t;               8fa8
         for(i=0;i<m;i++) ws_[i]=0;              c934
         for(i=0;i<n;i++) ws_[x[i]=r[i]]++;      e6d3
         for(i=1;i<m;i++) ws_[i]+=ws_[i-1];      2d9a
         for(i=n-1;i>=0;i--) sa[--ws_[x[i]]]=i;  5b0a
                                                 427e
         for(j=1,p=1;p<n;j*=2,m=p)               efbc
         {                                       4506
          for(p=0,i=n-j;i<n;i++) y[p++]=i;       5b7b
          for(i=0;i<n;i++) if(sa[i]>=j) y[p++]=  dc1c
            sa[i]-j;
          for(i=0;i<n;i++) wv[i]=x[y[i]];        792f
          for(i=0;i<m;i++) ws_[i]=0;             c934
          for(i=0;i<n;i++) ws_[wv[i]]++;         f297
          for(i=1;i<m;i++) ws_[i]+=ws_[i-1];     2d9a
          for(i=n-1;i>=0;i--) sa[--ws_[wv[i]]]=  e91d
            y[i];
          for(t=x,x=y,y=t,p=1,x[sa[0]]=0,i=1;i<  0b94
            n;i++)
           x[sa[i]]=cmp(y,sa[i-1],sa[i],j)?p-1:  fef3
             p++;
         }                                       95cf
      }                                          95cf
      /*int wa[maxn],wb[maxn],wv[maxn],ws[maxn   8a3e
        ];
      int cmp(int *r,int a,int b,int l)          3aa5
      {return r[a]==r[b]&&r[a+l]==r[b+l];}        9692
      void da(int *r,int *sa,int n,int m)        cdcb
      {                                          4506
        int i,j,p,*x=wa,*y=wb,*t;                8fa8
        for(i=0;i<m;i++) ws[i]=0;                4f37
        for(i=0;i<n;i++) ws[x[i]=r[i]]++;        960c
        for(i=1;i<m;i++) ws[i]+=ws[i-1];         be11
        for(i=n-1;i>=0;i--) sa[--ws[x[i]]]=i;    5f6d
        for(j=1,p=1;p<n;j*=2,m=p)                efbc
        {                                        4506
          for(p=0,i=n-j;i<n;i++) y[p++]=i;       5b7b
          for(i=0;i<n;i++) if(sa[i]>=j) y[p++]=  dc1c
            sa[i]-j;
          for(i=0;i<n;i++) wv[i]=x[y[i]];        792f
          for(i=0;i<m;i++) ws[i]=0;              4f37
```

```
7f78     for(i=0;i<n;i++) ws[wv[i]]++;
be11     for(i=1;i<m;i++) ws[i]+=ws[i-1];
f3a2     for(i=n-1;i>=0;i--) sa[--ws[wv[i]]]=y
           [i];
0b94     for(t=x,x=y,y=t,p=1,x[sa[0]]=0,i=1;i<
           n;i++)
fef3     x[sa[i]]=cmp(y,sa[i-1],sa[i],j)?p-1:p
           ++;
95cf   }
fe38 }*/以下是
427e //算法DC3  O(n)
427e //r 数组和sa 数组的大小都要是3*n下面的三行都
       是必须的。。为了避免名冲突
427e //
427e //#define F(x) ((x)/3+((x)%3==1?0:tb))
427e //#define G(x) ((x)<tb?(x)*3+1:((x)-tb)
       *3+2)
427e //int wa[maxn],wb[maxn],wv[maxn],ws_[maxn
       ];
9750 int c0(int *r,int a,int b)
4506 {
d7f5   return r[a]==r[b]&&r[a+1]==r[b+1]&&r[a
         +2]==r[b+2];
95cf }
6829 int c12(int k,int *r,int a,int b)
1258 {  if(k==2) return r[a]<r[b]||r[a]==r[b
       ]&&c12(1,r,a+1,b+1);
8b9e    else return r[a]<r[b]||r[a]==r[b]&&wv[
          a+1]<wv[b+1];
95cf }
8df6 void sort_sa(int *r,int *a,int *b,int n,
       int m)
4506 {
a0f7    int i;
0fed    for(i=0;i<n;i++) wv[i]=r[a[i]];
c934    for(i=0;i<m;i++) ws_[i]=0;
f297    for(i=0;i<n;i++) ws_[wv[i]]++;
2d9a    for(i=1;i<m;i++) ws_[i]+=ws_[i-1];
1285    for(i=n-1;i>=0;i--) b[--ws_[wv[i]]]=a[
          i];
4f2d    return;
95cf }
81ce void dc3(int *r,int *sa,int n,int m)
4506 {
455d    int i,j,*rn=r+n,*san=sa+n,ta=0,tb=(n
          +1)/3,tbc=0,p;
825e    r[n]=r[n+1]=0;
b6f1    for(i=0;i<n;i++) if(i%3!=0) wa[tbc++]=
          i;
427e
7371    sort_sa(r+2,wa,wb,tbc,m);
06a6    sort_sa(r+1,wb,wa,tbc,m);
79ea    sort_sa(r,wa,wb,tbc,m);
427e
64aa    for(p=1,rn[F(wb[0])]=0,i=1;i<tbc;i++)
16b5    rn[F(wb[i])]=c0(r,wb[i-1],wb[i])?p-1:p
          ++;
427e
778a    if(p<tbc) dc3(rn,san,tbc,p);
6879    else for(i=0;i<tbc;i++) san[rn[i]]=i;
427e
37b9    for(i=0;i<tbc;i++) if(san[i]<tb) wb[ta
          ++]=san[i]*3;
427e
6cbc    if(n%3==1) wb[ta++]=n-1;
427e
0fde    sort_sa(r,wb,wa,ta,m);
427e
e658    for(i=0;i<tbc;i++) wv[wb[i]=G(san[i])
          ]=i;
79d3    for(i=0,j=0,p=0;i<ta && j<tbc;p++)
427e
1a17    sa[p]=c12(wb[j]%3,r,wa[i],wb[j])?wa[i
          ++]:wb[j++];
427e
d05f    for(;i<ta;p++) sa[p]=wa[i++];
b151    for(;j<tbc;p++) sa[p]=wb[j++];
427e
95cf }
427e
427e //height 数组：定义height[i]=suffix(sa[i
       -1])和suffix(sa[i])的最长公共前缀算法如
       下，复杂度
427e //（）On一个重要的结论：
427e //suffix(j) 和suffix(k) 的最长公共前缀
       为height[rank[j]+1],
427e //height[rank[j]+2], height[rank[j]+3],
       … ,height[rank[k中的最小值。]]待排序的字
       符串放在
427e
427e //r 数组中，从r到[0]r[n，长度为-1]，且最大值
       小n于
427e //。为了函数操作的方便，约定除mr[n外所有
       的-1]r[i都大于]0, r[n。-1]=0函数结束后，
       结果放在
427e //sa 数组中，从sa到[0]sa[n。-1]
8039 int rank[maxn],height[maxn];
4772 void calheight(int *r,int *sa,int n)
4506 {
ff68    int i,j,k=0;
3748    for(i=1;i<=n;i++) rank[sa[i]]=i;
d007    for(i=0;i<n;height[rank[i++]]=k)
3e0a    for(k?k--:0,j=sa[rank[i]-1];r[i+k]==r[
          j+k];k++);
4f2d    return;
95cf }
```

```
427e
4fe3 char str[100];
5731 int  r[100];
01f2 int  sa[100];
299c int main()
4506 {
582c   while(cin>>str){
8d4d     int L=strlen(str);
e2ff     for(int i=0;i<L;i++)r[i]=str[i]-'0';
f411     for(int i=0;i<L;i++)sa[i]=i;
8426     r[L]=0;
f76f     da(r,sa,L+1,200);
7bae     cout<<"haha\n";
790a     for(int i=0;i<L;i++)
0c37       cout<<sa[i]<<' ';cout<<endl;
5271     calheight(r,sa,L);
790a     for(int i=0;i<L;i++)
8560       cout<<height[i]<<' ';cout<<endl;
95cf   }
95cf }
```

5.5 线段树区间修改

```
59b9 #include <cstdio>
427e
5963 struct IT
4506 {
ff6f   #define MN 1048577*2
d788   long long F[MN],D[MN];
d7af   int N;
651e   long long C,Ans;
ecbf   int ll,rr;
f365   void upd( int k, int l, int r)
4506   {
2d0d     if (D[k])
4506     {
1111       F[k]+=D[k]*((long long)r-l+1);
1f3f       if (k<N) D[k<<1]+=D[k],D[(k<<1)
             +1]+=D[k];
eef5       D[k]=0;
95cf     }
95cf   }
69ea   void find( int k, int l, int r)
4506   {
eed2     upd(k,l,r);
30f7     if (r<ll||l>rr) return ;
456c     if (ll<=l&&rr>=r)
4506     {
a619       Ans+=F[k];
4f2d       return ;
95cf     }
8f58     find(k<<1,l,(l+r)>>1);
b2c9     find((k<<1)+1,((l+r)>>1)+1,r);
95cf   }
  void Add( int k, int l, int r)                25be
  {                                             4506
    upd(k,l,r);                                 eed2
    if (r<ll||l>rr) return ;                    30f7
    if (ll<=l&&rr>=r)                           456c
    {                                           4506
      D[k]+=C;                                  f1c1
      upd(k,l,r);                               eed2
      return ;                                  4f2d
    }                                           95cf
    Add(k<<1,l,(l+r)>>1);                       817a
    Add((k<<1)+1,((l+r)>>1)+1,r);               3afb
    F[k]=F[k<<1]+F[(k<<1)+1];                   7514
  }                                             95cf
  void init( int NN)                            4d16
  {                                             4506
    for (N=1;N<NN;N<<=1);                       2944
    for (int i=1;i<=NN;i++) scanf("%I64d        b3f6
      ",&F[i+N-1]);
    for (int i=N-1;i;i--) F[i]=F[i<<1]+F        7991
      [(i<<1)+1];
  }                                             95cf
  long long search( int _l, int _r)             a363
  {                                             4506
    ll=_l;rr=_r;                                a0c0
    Ans=0;                                      ea34
    find(1,1,N);                                cc62
    return Ans;                                 ba71
  }                                             95cf
  void add( int _l, int _r, long long c)        893e
  {                                             4506
    ll=_l;rr=_r;C=c;                            62cd
    Add(1,1,N);                                 31fd
  }                                             95cf
} T;                                            eb81
                                                427e
int N,M,a,b,c;                                  12d2
                                                427e
int main()                                      299c
{                                               4506
  scanf("%d%d",&N,&M);                          a82c
  T.init(N);                                    d49b
  for (int i=1;i<=M;i++)                        a874
  {                                             4506
    scanf("%d%d%d",&a,&b,&c);                   677b
    T.Add(a,b,c);                               3069
    printf("%lld\n",T.search(i,N));             c396
  }                                             95cf
}                                               95cf
```

5.6 AhoCorasick

```
#include<iostream>                              e0a5
#include<cstring>                               ef2f
```

```
59b9 #include<cstdio>
c928 #include<cmath>
09f7 #include<vector>
acb9 #include<queue>
54ff #include<algorithm>
421c using namespace std;
427e //const int inf=INT_MAX;
427e //int maxInt   =   0x7FFFFFFF;//   32
       bit
427e //long  maxLong  =   0x7FFFFFFFFFFFFFFF;
       // 64   bit
c115 #define ll long long
5841 const int inf= 0x7FFFFFFF;
b43a const char atcg[]="ATCG";
94ec const int kind=4;
35b8 int n,m;
586b char in[105];
cbdf struct ahocorasick{
5520   static const int undef=0;//初始化tag
df17   static const int maxn=1<<10;
8c42   static const int charset子节点个数=4;//
4022   int end;
2e34   int tag[maxn],fail[maxn],trie[maxn][
         charset];
5d53   void init(){
59e7     tag[0]=undef;
196d     fill(trie[0],trie[0]+charset,-1);
feb8     end=1;
95cf   }
f53c   void add(int m,const char *s,int t)插入
         状态为{//t
ff1e     int p=0,index;
356f     for(int i=0;i<m;i++){
c273       index=strchr(atcg,s[i])-atcg;
9c09       if(trie[p][index]==-1){
5e5e         tag[end]=undef;
f543         fill(trie[end],trie[end]+charset
               ,-1);
bc80         trie[p][index]=end++;
95cf       }
79dc       p=trie[p][index];
95cf     }
7b5e     tag[p]|=t;
95cf   }
2114   void build(){
dfc8     queue<int>bfs;
a7a6     fail[0]=0;
6830     for(int i=0;i<charset;i++){
131c       if(trie[0][i]!=-1){
9b4d         fail[trie[0][i]]=0;
79f5         bfs.push(trie[0][i]);
95cf       }
649a       else
6c43         trie[0][i]=0;
95cf     }
88bb     while(!bfs.empty()){
e42e       int p=bfs.front();
38ff       tag[p]|=tag[fail[p]];
1a76       bfs.pop();
6830       for(int i=0;i<charset;i++){
9f81         if(trie[p][i]!=-1){
076e           fail[trie[p][i]]=trie[fail[p]][
                 i];
659d           bfs.push(trie[p][i]);
95cf         }
649a         else
7720           trie[p][i]=trie[fail[p]][i];
95cf       }
95cf     }
95cf   }
0244 }ac;
7af7 bool dp[2][1<<11][1<<11];
1abe int sum[1<<11];
dfbc int w[101];
3117 int main(){
8b27   int i,j,k,t,cur,pre;
178e   while(scanf("%d%d",&n,&m)+1){
c5bc     ac.init();
ee09     for(i=0;i<n;i++){
137a       scanf("%s %d",in,&w[i]);
aa86       ac.add(strlen(in),in,1<<i);
95cf     }
b345     ac.build();
7a1a     memset(sum,0,sizeof(sum));
bbfc     for(i=0;i<(1<<10);i++)
9e25     for(j=0;j<n;j++){
5f0a       if(i&(1<<j))
c3c1       sum[i]+=w[j];
95cf     }
3663     memset(dp,false,sizeof(dp));
4b53     cur=0,pre=1;
8fc2     dp[cur][0][0]=true;
494a     for(i=0;i<m;i++){
f70a       swap(cur,pre);
f281       memset(dp[cur],false,sizeof(dp[cur
             ]));
3ddf       for(int j=0;j<ac.end;j++)
24ec         for(k=0;k<4;k++){
9e0a           int nxt=ac.trie[j][k];
f4b4           for(t=0;t<(1<<n);t++)
f9e8           dp[cur][nxt][t|ac.tag[nxt]] |=
                 dp[pre][j][t];
95cf         }
95cf     }
1aea     int ans=-1;
4d5d     for(i=0;i<(1<<n);i++)
```

```
5ad9        for(j=0;j<ac.end;j++){
1daa          if(dp[cur][j][i]){
7968            ans=max(ans,sum[i]);
95cf          }
95cf        }
3214      if(ans<0)puts("No Rabbit after
            2012!");
e0fa      else cout<<ans<<endl;
95cf    }
95cf  }
```

5.7 kmp

```
e0a5  #include<iostream>
59b9  #include<cstdio>
8c52  #include<map>
6326  #include<set>
ef2f  #include<cstring>
2349  #include<string>
421c  using namespace std;
427e
427e  //extended kmp
427e  //nxt[] & ext[] should be clarify out of
        the function
99b8  void ExtendKmp(char s[],int ls,char t[],
        int lt)
4506  {
c8ed    int i,j,k;
3f1e    int Len,L;
427e
27ef    j=0;
8a9f    while(t[j+1]==t[j]&&j+1<lt) j++;
6a3e    nxt[1]=j,k=1;
427e
7588    for(i=2;i<lt;i++){
c163      Len=k+nxt[k],L=nxt[i-k];
0c66      if(Len>L+i) nxt[i]=L;
037f      else{
00d5        j=Len-i>0?Len-i:0;
e0db        while(t[i+j]==t[j]&&i+j<lt) j++;
a782        nxt[i]=j,k=i;
95cf      }
95cf    }
27ef    j=0;
70fe    while(s[j]==t[j]&&j<lt&&j<ls) j++;
bd73    ext[0]=j,k=0;
427e
bf8b    for(i=1;i<ls;i++){
8241      Len=k+ext[k],L=nxt[i-k];
93ba      if(Len>L+i) ext[i]=L;
037f      else{
00d5         j=Len-i>0?Len-i:0;
d6e6         while(s[i+j]==t[j]&&i+j<ls&&j<lt)
               j++;
8df1       ext[i]=j,k=i;
95cf     }
95cf   }
95cf  }
427e
427e  //kmp
427e
2ab8  void get_ne(char* p,int *nex)
4506  {
6b27      int i=0;int j=-1;
9d06      nex[0]=-1;
26de      int L=strlen(p);
f044      while(i<L)
4506      {
84ee          if(j==-1||p[i]==p[j])
4506          {
b209            i++;j++;
f023            nex[i]=j;
95cf          }
649a          else
8051            j=nex[j];
427e
95cf      }
95cf  }
```

5.8 Palindromic

```
cce1  void manacher( int* r, int len, int* p )
4506  {
cc69    int i, id, right = 0;
ab12    for( i = 0; i < len; ++i )
4506    {
27c2      if( i < right )
3fb4        p[i] = min(p[2*id-i], right-i);
649a      else
0d63        p[i] = 1;
357d      while( i+p[i] < len && i-p[i] >= 0
3a1f        && r[i+p[i]] == r[i-p[i]] )
0eac        p[i]++;
5bba      if( p[i] + i > right )
4506      {
d237        right = p[i]+i;
d14a        id = i;
95cf      }
95cf    }
95cf  }
```

6 图论

6.1 Hamilton

```
427e  //Hamilton 回路存在条件:
427e  // 每个点的度数超过一半点数
```

```
427e  // 复杂度 N^3 左右
427e  //@
59b9  #include <cstdio>
ef2f  #include <cstring>
427e
4c18  #define MN 201
427e
b7b3  int map[MN][MN];
aa15  int N,M;
53a5  int ans[MN];
427e
90a3  void reverse( int ans[MN], int s, int t)
4506  {
e87d    int temp;
d7ae    while (s<t)
4506    {
cb13      temp=ans[s];
9ace      ans[s]=ans[t];
8ba6      ans[t]=temp;
3c90      s++;t--;
95cf    }
95cf  }
427e
4871  void Hamilton()
4506  {
f392    int s=1,t;
6d29    int ansi=2,i,j,w,temp;
3fe0    bool vis[MN]={false};
87fb    memset(vis,0,sizeof vis);
7790    for (i=1;i<=N;i++)
0ba4      if (map[s][i]) break;
5093    t=i;
6299    vis[s]=vis[t]=1;
ea3a    ans[0]=s;ans[1]=t;
1f75    while (1)
4506    {
1f75      while (1)
4506      {
7790        for (i=1;i<=N;i++)
44dc          if (map[t][i]&&!vis[i])
4506          {
4d1d            ans[ansi++]=i;
1080            vis[i]=1;
5093            t=i;
6173            break;
95cf          }
882c        if (i>N) break;
95cf      }
4fa4      w=ansi-1;
14dc      i=0;
8ed9      reverse(ans,i,w);
02b3      temp=s;
f770      s=t;t=temp;
1f75      while (1)
4506      {
7790        for (i=1;i<=N;i++)
44dc          if (map[t][i]&&!vis[i])
4506          {
5260            ans[ansi++]=i;vis[i]=1;
5093            t=i;
6173            break;
95cf          }
882c        if (i>N) break;
95cf      }
fd5b      if (!map[s][t])
4506      {
110b        for (i=1;i<ansi-2;i++)
2fc4          if (map[ans[i]][t]&&map[s][ans[i
                +1]]) break;
4fa4        w=ansi-1;
a42b        i++;
642b        t=ans[i];
8ed9        reverse(ans,i,w);
95cf      }
34fc      if (ansi==N) return;
5cf5      for (j=1;j<=N;j++)
4506      {
ccf8        if (vis[j]) continue;
110b        for (i=1;i<ansi-2;i++)
2d6a          if (map[ans[i]][j]) break;
2d6a        if (map[ans[i]][j]) break;
95cf      }
7dd0      s=ans[i-1];
9f0e      t=j;
905e      reverse(ans,0,i-1);
b398      reverse(ans,i,ansi-1);
be20      ans[ansi++]=j;
59bb      vis[j]=1;
95cf    }
95cf  }
427e
299c  int main()
4506  {
60b7    while (scanf("%d%d",&N,&M)!=EOF)
4506    {
acaf      memset(map,0,sizeof map);
e635      int a,b;
3e4a      while (M--)
4506      {
a6b8        scanf("%d%d",&a,&b);
69bc        map[a][b]=map[b][a]=1;
95cf      }
427e
16db      Hamilton();
ea0f      for (int i=0;i<N-1;i++) printf("%d ",
            ans[i]);
```

```
8c45      printf("%d\n",ans[N-1]);
07ea      for (int i=0;i<N-1;i++)
6a10        if (!map[ans[i]][ans[(i+1)%N]])
              while (1);
95cf    }
7021    return 0;
95cf  }
```

6.2 HopcraftKarp

```
427e  // HK 解二分图匹配
427e  // 复杂度 O(sqrt(N)*M)
427e  //*@
59b9  #include <cstdio>
ef2f  #include <cstring>
427e
4cbf  #define MN 50001
0889  #define MM 150001
427e
427e
673f  struct E_Node
4506  {
28a5    int v,ne;
f9e1  } E[MM];
427e
7c0e  int R[MN],e_sz;
aa15  int N,M;
427e
d699  void Add( int a, int b)
4506  {
ddad    E[++e_sz].v=b;E[e_sz].ne=R[a];R[a]=e_sz
          ;
95cf  }
427e
88f1  void init()
4506  {
1282    e_sz=0;
ab17    memset(R,0,sizeof R);
95cf  }
427e
427e
8a67  int ans,qsz;
427e
8ec5  int Qu[MN*2],Lx[MN],Ly[MN],Cx[MN],Cy[MN];
427e
e459  bool BFS()
4506  {
c93c    int p,u,v;
f25a    bool flag=0;
1034    qsz=0;
c802    for (int i=1;i<=N;i++)
a0d0      if (Cx[i]==-1) Qu[++qsz]=i,Lx[i]=1;
3fd6    memset(Ly,0xff,sizeof(Ly[0])*(M+1));
aa16    for (int i=1;i<=qsz;i++)
  {                                          4506
    u=Qu[i];                                 1a30
    for (p=R[u];p;p=E[p].ne)                 f05c
    {                                        4506
      v=E[p].v;                              43a3
      if (Ly[v]==-1)                         dc20
      {                                      4506
        Ly[v]=Lx[u]+1;                       a04e
        if (Cy[v]==-1) flag=1;               0d23
        else                                 649a
        {                                    4506
          Qu[++qsz]=Cy[v];                   19cf
          Lx[Cy[v]]=Ly[v]+1;                 a158
        }                                    95cf
      }                                      95cf
      }                                      95cf
  }                                          95cf
  return flag;                               01d8
}                                            95cf
                                             427e
bool Dfs( int k)                             ec04
{                                            4506
  for (int p=R[k];p;p=E[p].ne)               0470
    if (Ly[E[p].v]==Lx[k]+1)                 68e3
    {                                        4506
      Ly[E[p].v]=-1;                         1ef9
      if (Cy[E[p].v]==-1||Dfs(Cy[E[p].v])    7c7e
        )
      {                                      4506
        Cy[E[p].v]=k;                        f491
        Cx[k]=E[p].v;                        e929
        return 1;                            7459
      }                                      95cf
    }                                        95cf
  return 0;                                  7021
}                                            95cf
                                             427e
                                             427e
     Add(a,b);                               7b71
                                             427e
    ans=0;                                   7360
    memset(Cx,0xff,(N+1)*sizeof(Cx[0]));     f3ef
    memset(Cy,0xff,(M+1)*(sizeof(Cy[0])))    4390
      ;
    while (BFS())                            6ab9
    {                                        4506
      for (int i=N;i;i--)                    3c73
        if (Cx[i]==-1&&Dfs(i)) ans++;        3ed3
    }                                        95cf
    printf("%d\n",ans);                      53b1
}                                            95cf
```

6.3 HopcraftKarp

```
427e  // HK 解二分图匹配复杂度
427e  // O(sqrt(N)*M)
427e  //*@
59b9  #include <cstdio>
ef2f  #include <cstring>
427e
4cbf  #define MN 50001
0889  #define MM 150001
427e
427e
673f  struct E_Node
4506  {
28a5    int v,ne;
f9e1  } E[MM];
427e
7c0e  int R[MN],e_sz;
aa15  int N,M;
427e
d699  void Add( int a, int b)
4506  {
ddad    E[++e_sz].v=b;E[e_sz].ne=R[a];R[a]=e_sz
          ;
95cf  }
427e
88f1  void init()
4506  {
1282    e_sz=0;
ab17    memset(R,0,sizeof R);
95cf  }
427e
427e
8a67  int ans,qsz;
427e
8ec5  int Qu[MN*2],Lx[MN],Ly[MN],Cx[MN],Cy[MN];
427e
e459  bool BFS()
4506  {
c93c    int p,u,v;
f25a    bool flag=0;
1034    qsz=0;
c802    for (int i=1;i<=N;i++)
a0d0      if (Cx[i]==-1) Qu[++qsz]=i,Lx[i]=1;
3fd6    memset(Ly,0xff,sizeof(Ly[0])*(M+1));
aa16    for (int i=1;i<=qsz;i++)
4506    {
1a30      u=Qu[i];
f05c      for (p=R[u];p;p=E[p].ne)
4506      {
43a3        v=E[p].v;
dc20        if (Ly[v]==-1)
4506        {
a04e          Ly[v]=Lx[u]+1;
0d23          if (Cy[v]==-1) flag=1;
649a          else
4506          {
19cf            Qu[++qsz]=Cy[v];
a158            Lx[Cy[v]]=Ly[v]+1;
95cf          }
95cf        }
95cf        }
95cf    }
01d8    return flag;
95cf  }
427e
ec04  bool Dfs( int k)
4506  {
0470    for (int p=R[k];p;p=E[p].ne)
68e3      if (Ly[E[p].v]==Lx[k]+1)
4506      {
1ef9        Ly[E[p].v]=-1;
7c7e        if (Cy[E[p].v]==-1||Dfs(Cy[E[p].v])
              )
4506        {
f491          Cy[E[p].v]=k;
e929          Cx[k]=E[p].v;
7459          return 1;
95cf        }
95cf      }
7021    return 0;
95cf  }
427e
427e
7b71      Add(a,b);
427e
7360    ans=0;
f3ef    memset(Cx,0xff,(N+1)*sizeof(Cx[0]));
4390    memset(Cy,0xff,(M+1)*(sizeof(Cy[0])))
          ;
6ab9    while (BFS())
4506    {
3c73      for (int i=N;i;i--)
3ed3        if (Cx[i]==-1&&Dfs(i)) ans++;
95cf    }
53b1    printf("%d\n",ans);
95cf  }
```

6.4 Hungary

```
427e  // 匈牙利算法解二分图匹配
427e  // 一般小于 NM
427e  //*@
e219  bool Vis[MN];
bf70  int Link[MN];
2a22  int Cache[MN];
2fd8  int Csz;
427e
b96a  bool find( int k)
```

```
4506 {
0470   for (int p=R[k];p;p=E[p].ne)
4d33     if (!Vis[E[p].v])
4506     {
39cb       Vis[E[p].v]=1;
6bbc       Cache[++Csz]=E[p].v;
f267       if (!Link[E[p].v])
4506       {
17ae         Link[E[p].v]=k;
3361         return true;
95cf       }
fc61       if (find(Link[E[p].v]))
4506       {
17ae         Link[E[p].v]=k;
3361         return true;
95cf       }
95cf     }
438e   return false;
95cf }
427e
f531     memset(Link,0,sizeof Link);
c802     for (int i=1;i<=N;i++)
4506     {
73c9       for (int k=1;k<=Csz;k++)
c926         Vis[Cache[k]]=0;
19e8         Csz=0;
8f54         if (find(cc(i,j))) ans++;
95cf     }
```

6.5 KM

```
427e //KM
427e // 二分图最佳匹配
427e // 点数不等时添加虚拟点，与所有点的边权为 0
427e // 点数不等时不能将边权变负，要用 INF 去减
427e //N^3
427e
59b9 #include <cstdio>
ef2f #include <cstring>
427e
1d4b #define MN 301
1cc6 #define INF 0x7fffffff
427e
d7e9 int w[MN][MN];
5897 int lx[MN],ly[MN];
d96c int linky[MN];
9859 int visx[MN],visy[MN];
9012 int slack[MN];
d7af int N;
6097 bool find(int x)
4506 {
28d0   visx[x] = true;
5647   for(int y = 1; y <=N; y++)
4506   {
aab6     if(visy[y])
b333       continue;
44b7     int t = lx[x] + ly[y] - w[x][y];
d790     if(t==0)
4506     {
d2aa       visy[y] = true;
6def       if(linky[y]==-1 || find(linky[y]))
4506       {
b930         linky[y] = x;
3361         return true;
95cf       }
95cf     }
cf8b     else if(slack[y] > t)
52e5       slack[y] = t;
95cf   }
438e   return false;
95cf }
427e
45ef int KM()
4506 {
576f   int i,j;
427e
76e3   memset(linky,-1,sizeof(linky));
b7b2   memset(ly,0,sizeof(ly));
7790   for(i = 1; i <=N; i++)
4506   {
7b3c     lx[i] = -INF;
5cf5     for(j = 1; j <=N; j++)
7f0c       if(w[i][j] > lx[i])
c66c         lx[i] = w[i][j];
95cf   }
427e
67de   for(int x = 1; x <=N; x++)
4506   {
7790     for(i = 1; i <=N; i++)
a6e7       slack[i] = INF;
66e0     while(true)
4506     {
e77f       memset(visx,0,sizeof(visx));
688c       memset(visy,0,sizeof(visy));
3333       if(find(x))
6173         break;
065a       int d = INF;
7790       for(i = 1; i <=N; i++)
4506       {
df80         if(!visy[i] && d > slack[i])
bae8           d = slack[i];
95cf       }
7790       for(i = 1; i <=N; i++)
4506       {
f248         if(visx[i])
529c           lx[i] -= d;
95cf       }
```

```
7790        for(i = 1; i <=N; i++)
4506        {
4427          if(visy[i])
ab77             ly[i] += d;
649a          else
a397            slack[i] -= d;
95cf        }
95cf      }
95cf    }
bf72    int result = 0;
7790    for(i = 1; i <=N; i++)
f7d9    if(linky[i]>-1)
a453      result += w[linky[i]][i];
56b0    return result;
95cf  }
427e
299c  int main()
4506  {
3dda    while (scanf("%d",&N)!=EOF)
4506    {
39be      memset(w,0,sizeof w);
c802      for (int i=1;i<=N;i++)
f595        for (int j=1;j<=N;j++) scanf("%d",&
              w[i][j]);
05c2      printf("%d\n",KM());
95cf    }
95cf  }
```

6.6 lca

```
427e  // 建树和倍增求 lca
427e
427e    //buildtree
427e
727b    int dep[MN],root[MN];
0ae7    int ancestor[MN][logMN];
79ea    void buildtree( int k)
4506    {
0b49      vis[k]=1;
0470      for (int p=R[k];p;p=E[p].ne)
4506      {
f90d        if (vis[E[p].v]) continue;
b082        ancestor[E[p].v][0]=k,dep[E[p].v]=
              dep[k]+1,root[E[p].v]=root[k],
              buildtree(E[p].v);
95cf      }
95cf    }
427e    //lca_init
427e    // 可以处理森林
1b95    void lca_init( int N)
4506    {
5750      memset(ancestor,0,sizeof ancestor);
91c5      for (int i=1;i<=N;i++) vis[i]=0;
c802      for (int i=1;i<=N;i++)
        if (ancestor[i][0]==0) dep[i]=1,      014c
          root[i]=i,buildtree(i);
                                              427e
    for (int k=1;k<=log2(N);k++)              4a2e
      for (int i=1;i<=N;i++)                  c802
        ancestor[i][k]=ancestor[ancestor[     98fc
          i][k-1]][k-1];
  }                                           95cf
                                              427e
  //return lca(a,b)                           427e
  //return -1 if a,b in diffirent tree        427e
  int lca_query( int a, int b, int N)         82b0
  {                                           4506
    int ans=dep[a]+dep[b];                    bb4f
    if (root[a]!=root[b]) return -1;          5801
    if (a==b) return a;                       686e
    if (dep[a]>dep[b]) swap(a,b);             6371
    for (int k=0;k<=log2(N);k++) if ((1<<     798a
      k)&delta) b=ancestor[b][k];
    if (a==b) return a;                       686e
    for (int k=log2(N);k>=0;k--) if (         7b0a
      ancestor[a][k]!=ancestor[b][k]) a=
      ancestor[a][k],b=ancestor[b][k];
    return ancestor[a][0];                    b01a
  }                                           95cf
```

6.7 MaxcostMaxflow

```
// 最小费用路增广 bySPFA                      427e
//*@                                         427e
#include <cstdio>                             59b9
#include <cstring>                            ef2f
#include <queue>                              acb9
                                              427e
using namespace std;                          421c
                                              427e
#define MN 30                                 e8b6
#define MM 100000                             8c3b
#define INF 0x7fffffff                        1cc6
                                              427e
int T,N,M,K;                                  aa81
int Lim[MN],Like[MN][MN],l,cases;             cb35
                                              427e
struct MaxcostMaxflow                         0c77
{                                             4506
  struct E_Node                               673f
  {                                           4506
    int v,f,c,op,ne;                          8253
  } E[MM];                                    f9e1
  int R[MN],sz;                               5586
  int S,T;                                    9bfc
  void Add( int a, int b, int c, int d)       cb15
  {                                           4506
    E[++sz].v=b;E[sz].ne=R[a];R[a]=sz;E[      233c
```

```
        sz].f=c;E[sz].c=d;                                  95cf
    }                                                       d3c6
    void Ins( int a, int b, int c, int d)                   4506
    {                                                       4238
      if (!c) return ;                                      18b4
      Add(a,b,c,d);E[sz].op=sz+1;                           11e8
      Add(b,a,0,-d);E[sz].op=sz-1;                          95cf
    }                                                       7d24
    bool B[MN];                                             0e46
    int D[MN],F[MN];                                        3d1d
    int maxcost,maxflow;                                    88f1
    void init()                                             4506
    {                                                       1bb9
      sz=0;                                                 ab17
      memset(R,0,sizeof R);                                 1fd4
      maxcost=maxflow=0;                                    95cf
    }                                                       aafa
    queue<int> Q;                                           64de
    bool SPFA()                                             4506
    {                                                       3ccf
      int u,m,p;                                            a058
      while (!Q.empty()) Q.pop();                           e753
      Q.push(S);                                            5480
      for (int i=1;i<=T;i++) D[i]=-INF,B[i
        ]=0;                                                eb5f
      D[S]=0;B[S]=1;                                        1b18
      while (!Q.empty())                                    4506
      {                                                     50ae
        u=Q.front();                                        f2f8
        Q.pop();                                            f05c
        for (p=R[u];p;p=E[p].ne)                            94ec
          if (E[p].f&&D[u]+E[p].c>D[E[p].v
            ])                                              4506
          {                                                 32ff
            D[E[p].v]=D[u]+E[p].c;                          6c54
            F[E[p].v]=p;                                    d185
            if (!B[E[p].v])                                 4506
            {                                               fa94
              B[E[p].v]=1;                                  bae3
              if (!Q.empty()&&D[Q.front()]<
                D[E[p].v])                                  4506
              {                                             8b65
                Q.push(Q.front());                          99c8
                Q.front()=E[p].v;                           887e
              } else Q.push(E[p].v);                        95cf
            }                                               95cf
          }                                                 fa2d
        B[u]=0;                                             95cf
      }                                                     d2b6
      if (D[T]==-INF) return 0;                             649a
      else                                                  4506
      {                                                     c088
        u=T;m=INF;                                          870d
        while (u!=S)                                        4506
        {                                                   f593
          m=min(m,E[F[u]].f);                               ace4
          u=E[E[F[u]].op].v;                                95cf
        }                                                   d1e9
        maxflow+=m;                                         8902
        maxcost+=m*D[T];                                    3aaf
        u=T;                                                870d
        while (u!=S)                                        4506
        {                                                   4712
          E[F[u]].f-=m;                                     d9c0
          E[E[F[u]].op].f+=m;                               ace4
          u=E[E[F[u]].op].v;                                95cf
        }                                                   7459
        return 1;                                           95cf
      }                                                     95cf
    }                                                       ff9a
} G;                                                        87e7
/*                                                          664a
    G.S=N+M+1;G.T=G.S+1;                                    69b7
    for (int j=1;j<=M;j++) G.Ins(N+j,G.T
      ,1,0);                                                20d3
    while (G.SPFA());                                       6bcf
    if (G.maxcost+M-G.maxflow>=l) puts("
      YES");                                                9418
    else puts("NO");                                        f2b5
*/
```

6.8 NetworkFlow

```
//Dinic                                                     427e
// 当前弧、多路增广、断层优化                               427e
//*@                                                        427e
#include <cstring>                                          ef2f
#define MN 1000                                             45b5
#define MM 100000                                           8c3b
                                                            427e
struct E_Node                                               673f
{                                                           4506
  int a,b,opp,ne;                                           6221
  int f;                                                    e53b
} E[MM];                                                    f9e1
                                                            427e
int R[MN],e_sz;                                             7c0e
                                                            427e
                                                            427e
                                                            427e
struct s_node{                                              a035
  int v,p;                                                  99ad
} s[MN];                                                    f95b
                                                            427e
                                                            427e
int top,N,M,S,T,ans;                                        df6b
int Q[MN],L[MN];                                            f90e
```

```
4b4a bool hash[MN];
427e
88f1 void init()
4506 {
ab17   memset(R,0,sizeof R);
1282   e_sz=0;
7360   ans=0;
95cf }
427e
0a45 void add( int a, int b, int c){
5242   E[++e_sz].a=a;E[e_sz].b=b;E[e_sz].f=c;
ae1c   E[e_sz].ne=R[a];R[a]=e_sz;
95cf }
427e
e9ba void ins( int a, int b, int c){
00d3   add(a,b,c);
c75f   E[e_sz].opp=e_sz+1;
131a   add(b,a,0);
f992   E[e_sz].opp=e_sz-1;
95cf }
427e
6193 int BFS(){
ad27   int h,t,p;
33f5   memset(L,0,sizeof(L));
879c   Q[h=t=1]=S;
a7f5   L[S]=1;
e2aa   for (;h<=t;h++){
837d     for (p=R[Q[h]];p;p=E[p].ne)
ca1d       if (E[p].f&&(!L[E[p].b])){
713f         L[E[p].b]=L[Q[h]]+1;
3c1d         Q[++t]=E[p].b;
95cf       }
9296     if (L[T]) return L[T];
95cf   }
e010   return L[T];
95cf }
427e
8cef int augmented(){
5dd6   int min=0x7fffffff;
eb8e   int mins;
fb9d   for (int i=1;i<top;i++)
9a8b     if (E[s[i].p].f<min){
6a1b       min=E[s[i].p].f;
7441       mins=i;
95cf     }
c66b   for (int i=1;i<top;i++){
9eb5     E[s[i].p].f-=min;
b362     E[E[s[i].p].opp].f+=min;
95cf   }
2294   ans+=min;
9407   return mins;
95cf }
427e
```

```
9690 void Dinic(){
2f55   bool f;
a591   int *p,*v;
10a0   s[top=1].v=S;s[1].p=0;
d9aa   memset(hash,true,sizeof(hash));
55e4   while (top){
0cc3     v=&s[top].v;
ac2c     p=&s[top].p;
3605     if (*v==T){
454a       top=augmented();
b333       continue;
95cf     }
607d     if (*p)
c70d       *p=E[*p].ne;
649a     else
27e8       *p=R[*v];
3b7e     f=false;
9933     for (;*p;*p=E[*p].ne)
4eeb       if (hash[E[*p].b]&&E[*p].f&&L[*v
             ]+1==L[E[*p].b]){
b97a         s[++top].v=E[*p].b;
5fad         s[top].p=0;
6aed         top++;
69dc         f=true;
6173         break;
95cf       }
d954     if (!f)
cdee       hash[s[top].v]=false;
e9a7     top--;
95cf   }
95cf }
427e
427e //init();
427e //ins(a,b,c);
427e //while (BFS()) Dinic();
```

6.9 SCC

```
427e //SCC by Tarjan
427e // nowc 连通分量个数
427e //*@
59b9 #include<cstdio>
ef2f #include<cstring>
8207 #include<stack>
54ff #include<algorithm>
427e
421c using namespace std;
427e
ab66 #define MN 20001
b120 #define MM 50001
427e
fbb8 int N,M,T;
427e
0c98 struct Graph
```

```
4506 {
a981   struct E_Node{
28a5     int v,ne;
f9e1   } E[MM];
5586   int R[MN],sz;
0d5d   void Add( int a, int b){
1352     E[++sz].v=b;E[sz].ne=R[a];R[a]=sz;
95cf   }
870e   stack<int> S;
7d24   bool B[MN];
b156   int D[MN],L[MN],C[MN],SZ[MN];
85a3   int nowc,nowd;
9372   void Dfs( int k){
0c3d     D[k]=L[k]=++nowd;
d651     B[k]=1;S.push(k);
0470     for (int p=R[k];p;p=E[p].ne)
2f4c       if (B[E[p].v]) L[k]=min(L[k],D[E[p
             ].v]);
8ee9       else if (!D[E[p].v]) Dfs(E[p].v),L[
             k]=min(L[k],L[E[p].v]);
35b1     if (D[k]==L[k]){
3b67       int v;
9c48       nowc++;
a69f       do{
a4a8         v=S.top();
1894         B[v]=0;
c9fd         SZ[nowc]++;
1039         S.pop();
9f0e         C[v]=nowc;
14a1       }while(v!=k);
95cf     }
95cf   }
6e8b   void Rebuild( Graph &GG)
4506   {
2776     GG.init();
c802     for (int i=1;i<=N;i++)
8220       for (int p=R[i];p;p=E[p].ne)
83af         if (C[E[p].v]!=C[i]) GG.Add(C[i],
               C[E[p].v]);
95cf   }
7a60   void SCC(){
c802     for (int i=1;i<=N;i++)
25b5       if (!D[i]) Dfs(i);
95cf   }
88f1   void init()
4506   {
80a6     nowc=nowd=0;
1bb9     sz=0;
a31c     memset(B,0,sizeof B);
ab17     memset(R,0,sizeof R);
d799     memset(D,0,sizeof D);
e11b     memset(SZ,0,sizeof SZ);
95cf   }
} G;                                          ff9a
                                              427e
//G.init();                                   427e
//G.SCC();                                    427e
//G.Rebuild(GG);                              427e
```

6.10 Vconnect

```
#include <cstdio>                             59b9
#include <cstring>                            ef2f
#include <algorithm>                          54ff
#include <set>                                6326
#include <vector>                             09f7
#include <stack>                              8207
#include <cmath>                              c928
                                              427e
using namespace std;                          421c
                                              427e
#define MN 410000                             6c7d
#define MM 2000000                            3c56
#define logMN 19                              5eec
#define pb(x) push_back(x)                    682b
                                              427e
int N,M;                                      aa15
                                              427e
struct Graph                                  0c98
{                                             4506
  struct E_Node                               673f
  {                                           4506
    int a,v,ne;                               a15a
  } E[MM];                                    f9e1
                                              427e
  int R[MN],e_sz;                             7c0e
                                              427e
                                              427e
  void Add( int a, int b, int c=0)            c5de
  {                                           4506
    if (a==b) return;                         e53f
    E[++e_sz].v=b;;E[e_sz].ne=R[a];R[a]=       98b5
      e_sz;E[e_sz].a=a;
  }                                           95cf
                                              427e
  int SZ[MN];                                 4c87
  int O[MM];                                  80ca
                                              427e
  void init()                                 88f1
  {                                           4506
    e_sz=0;                                   1282
    memset(R,0,sizeof R);                     ab17
                                              427e
    //Edge_Connect                            427e
  }                                           95cf
                                              427e
                                              427e
```

```
427e   //Rebuild重构图
427e   //
427e   //E[],R[],N,col[],color
427e   //G
060e   int _col[MN];
427e
6e8b   void Rebuild( Graph &GG)
4506   {
2776     GG.init();
f4f9     for (int i=1;i<=color;i++) GG.cut[i
           ]=0;
c802     for (int i=1;i<=N;i++)
4506     {
9f92       if (cut[i])
4506       {
79b7         GG.cut[col[i]=++color]=1;
8220         for (int p=R[i];p;p=E[p].ne)
2975           GG.Add(col[i],O[p]),GG.Add(O[p
                 ],col[i]);
95cf       }
95cf     }
c5da     for (int i=1;i<=color;i++) GG.SZ[i
           ]=0;
5f3a     for (int i=1;i<=N;i++) GG.SZ[col[i
           ]]++;
95cf   }
427e
427e   //Edge_Connect边双连通分量
427e   //
427e   //E[],R[],N先去除重边
427e   //
427e
024e   bool vis[MN];
6e90   int dfs[MN],low[MN];
79ea   int col[MN];
9ba1   bool vise[MM];
57b2   int color,cc;
50d0   bool cut[MN];
ae27   stack<int> stk;
541b   vector<int> cedge;
427e
9276   int op( int p)
4506   {
29da     if (p&1) return p+1;
ddf2     else return p-1;
95cf   }
427e
b988 int ci,cp;
f0e2   void Cedge()
4506   {
a725     for (ci=0;ci<cedge.size();ci++)
4133       for (cp=R[cedge[ci]];cp;cp=E[cp].ne
             )
8245         if (col[cedge[ci]]==col[E[cp].v])
c7ad           O[cp]=O[op(cp)]=col[cedge[ci]];
95cf   }
427e
f311   int CO[MN];
325b int pp[MN];
d821   void Dfs( int k)
4506   {
0b49     vis[k]=1;
4755     stk.push(k);
139f     low[k]=dfs[k]=++cc;
c399     CO[k]=0;
bf51 #define p pp[k]
3cb5     for (p=R[k];p;p=E[p].ne)
4506     {
044c       if (vise[p])
4506       {
427e // low[k]=min(low[k],dfs[E[p].v]);
b333         continue;
95cf       }
2847       vise[p]=vise[op(p)]=1;
5b6b       if (!vis[E[p].v]) Dfs(E[p].v),CO[k
             ]++,low[k]=min(low[k],low[E[p].v
             ]);
649a       else
4506       {
a333         low[k]=min(low[k],dfs[E[p].v]);
b333         continue;//
95cf       }
1d99       if (dfs[k]==1&&CO[k]>1) cut[k]=1;
4db3       else if (dfs[k]!=1&&dfs[k]<=low[E[p
             ].v]) cut[k]=1;
2020       if (dfs[k]<=low[E[p].v])
4506       {
427e
b786         cedge.clear();
410f         col[k]=++color;
ad56         col[E[p].v]=color;
0e36         cedge.pb(k);
f40f         cedge.pb(E[p].v);
9533         while (stk.top()!=E[p].v)
4506         {
3d2d           col[stk.top()]=color;
ffe2           cedge.pb(stk.top());
75b6           stk.pop();
95cf         }
75b6         stk.pop();
25dc         Cedge();
427e
427e       //stk.pop();
95cf       }
95cf     }
95cf   }
```

```
52c1 #undef p
427e
885f   void Edge_Connect()
4506   {
d235     memset(cut,0,sizeof cut);
77f1     while (stk.size()) stk.pop();
2707     for (int i=0;i<=e_sz;i++) vise[i]=0;
427e
1120     color=cc=0;
c802     for (int i=1;i<=N;i++)
e88f       vis[i]=0,col[i]=0;
c802     for (int i=1;i<=N;i++)
4506     {
395c       cc=0;
07c3       if (!vis[i]) Dfs(i);
56eb /*      if (stk.size())
4506       {
b704         ++color;
7099         while (stk.size())
4506         {
3d2d           col[stk.top()]=color;
75b6           stk.pop();
95cf         }
fe38       }*/
95cf     }
95cf   }
427e
427e   //buildtree建树
427e   //
727b   int dep[MN],root[MN];
0ae7   int ancestor[MN][logMN];
2a08   int F[MN][logMN];
320d   int W[MN][logMN];
f7d7   int P[MN];
bf51 #define p pp[k]
79ea   void buildtree( int k)
4506   {
0b49     vis[k]=1;
3cb5     for (p=R[k];p;p=E[p].ne)
4506     {
f90d       if (vis[E[p].v]) continue;
4522     /*  if (cut[k]&&cut[E[p].v])
4506       {
885d         puts("");
fe38       }*/
427e
3c65       if (cut[k]==1) P[E[p].v]++;
18f1       if (cut[E[p].v]==1) P[k]++;
0854       ancestor[E[p].v][0]=k,F[E[p].v][0]=
             SZ[E[p].v],dep[E[p].v]=dep[k]+1,
             root[E[p].v]=root[k],buildtree(E[
             p].v);
95cf     }
   }
95cf #undef p
52c1   //lca_init
427e   //预处理lca可以处理森林
427e   //
427e   void lca_init( int N)
1b95   {
4506     memset(ancestor,0,sizeof ancestor);
5750     for (int i=1;i<=N;i++) vis[i]=0,P[i
935d       ]=0;
c802     for (int i=1;i<=N;i++)
be65       if (ancestor[i][0]==0) F[i][0]=SZ[i
             ],dep[i]=1,root[i]=i,buildtree(i)
             ;
427e
c802     for (int i=1;i<=N;i++)
4506     {
d611       if (cut[i]) P[i]=0,F[i][0]=1;F[i
             ][0]+=P[i];
95cf     }
4a2e     for (int k=1;k<=log2(N);k++)
c802       for (int i=1;i<=N;i++)
4506       {
98fc         ancestor[i][k]=ancestor[ancestor[
               i][k-1]][k-1];
0630         F[i][k]=F[i][k-1]+F[ancestor[i][k
               -1]][k-1];
95cf       }
95cf   }
427e
427e   //return lca(a,b)
427e   //return -1 if a,b in diffirent tree
82b0   int lca_query(int a, int b, int N)
4506   {
e66e     int ans=0,tans=0,tt=0;
53e6     if (root[a]!=root[b]) return 0;
a9ad     if (a==b) return F[a][0];
6371     if (dep[a]>dep[b]) swap(a,b);
d0b6     int delta=dep[b]-dep[a];
8c70     ans=-delta;
0abf     for (int k=0;k<=log2(N);k++) if ((1<<
           k)&delta) ans+=F[b][k],b=ancestor[b
           ][k];
fdd8     if (a==b) return ans+F[a][0];
8028     for (int k=log2(N);k>=0;k--) if (
           ancestor[a][k]!=ancestor[b][k]) ans
           +=F[a][k]+F[b][k],ans-=1<<(k+1),a=
           ancestor[a][k],b=ancestor[b][k];
0c1e     return ans+F[a][0]+F[b][0]+F[ancestor
           [a][0]][0]-2;
95cf   }
427e
bef6 } G,GG;
```

```
427e
427e
ea31 int cases;
427e
299c int main()
4506 {
e635   int a,b;
60b7   while (scanf("%d%d",&N,&M)!=EOF)
4506   {
1945     G.init();
427e     //Edge.clear();
a874     for (int i=1;i<=M;i++)
4506     {
a6b8       scanf("%d%d",&a,&b);
4bbc       a++;b++;
427e     //  if (Edge.find(make_pair(a,b))!=
           Edge.end()) continue;
03ff       G.Add(a,b);G.Add(b,a);
427e     //  Edge.insert(make_pair(a,b));
427e     //  Edge.insert(make_pair(b,a));
95cf     }
c01f     G.Edge_Connect();
b6c8     G.Rebuild(GG);
e9b6     GG.lca_init(G.color);
427e
9523     int T;
1fd9     scanf("%d",&T);
524a     printf("Case #%d:\n",++cases);
7d0e     while (T--)
4506     {
a6b8       scanf("%d%d",&a,&b);
4bbc       a++;b++;
442b       if (a==b) printf("%d\n",N-1);
eba2       else printf("%d\n",N-GG.lca_query(G
             .col[a],G.col[b],G.color));
95cf     }
885d     puts("");
95cf   }
95cf }
```

6.11 Stoer-Wagne

```
427e // 全局最小割
427e //N^3
427e //@
e0a5 #include <iostream>
59b9 #include <cstdio>
ef2f #include <cstring>
421c using namespace std;
47b3 const int maxn=510;
0541 int map[maxn][maxn];
5c83 int n;
c827 void contract(int x,int y)
4506 {
  int i,j;                                  576f
  for (i=0;i<n;i++)                         2dbf
    if (i!=x) map[x][i]+=map[y][i],map[i    0180
      ][x]+=map[i][y];
  for (i=y+1;i<n;i++) for (j=0;j<n;j++)     ffcb
  {                                         4506
    map[i-1][j]=map[i][j];                  ab88
    map[j][i-1]=map[j][i];                  c988
  }                                         95cf
  n--;                                      61b6
}                                           95cf
int w[maxn],c[maxn];                        78af
int sx,tx;                                  d7dd
int mincut()                                9acc
{                                           4506
  int i,j,k,t;                              74c3
  memset(c,0,sizeof(c));                    7dd1
  c[0]=1;                                   3bab
  for (i=0;i<n;i++) w[i]=map[0][i];         457c
  for (i=1;i+1<n;i++)                       a17f
  {                                         4506
    t=k=-1;                                 901d
    for (j=0;j<n;j++) if (c[j]==0&&w[j]>k   4d7b
      )
     k=w[t=j];                              8647
    c[sx=t]=1;                              d40b
    for (j=0;j<n;j++) w[j]+=map[t][j];      e5e3
  }                                         95cf
  for (i=0;i<n;i++) if (c[i]==0) return w   6bff
    [tx=i];
  }                                         95cf
int main()                                  299c
{                                           4506
  int i,j,k,m;                              e90f
  while (scanf("%d%d",&n,&m)!=EOF)          6853
  {                                         4506
    memset(map,0,sizeof(map));              0ea5
    while (m--)                             c864
    {                                       4506
     scanf("%d%d%d",&i,&j,&k);              0f52
     map[i][j]+=k;                          685d
     map[j][i]+=k;                          24d1
    }                                       95cf
    int mint=999999999;                     575e
    while (n>1)                             65b7
    {                                       4506
     k=mincut();                            2e7a
     if (k<mint) mint=k;                    4efe
     contract(sx,tx);                       d185
    }                                       95cf
    printf("%d\n",mint);                    0f28
  }                                         95cf
  return 0;                                 7021
```

```
95cf  }
```

6.12 度限制生成树

```
e0a5  #include <iostream>
ef0e  #include <fstream>
9581  #include <climits>
acb9  #include <queue>
8c52  #include <map>
ef2f  #include <cstring>
2349  #include <string>
421c  using namespace std;
d8fa  const int maxn = 25;
65a1  struct node
4506  {
7a26    int v, w;
329b  };
a433  struct cmp
4506  {
3d46    bool operator() (const node &a, const
          node &b)
4506    {
1d47      return a.w > b.w; // 是从小到大>.
95cf    }
329b  };
53ee  int n, m, s; // n 个点，m 条边，s 为原
        点. 点为有度数限制的点V0
701e  int num;
4111  int minV0[maxn];
84b0  int total; // 限制的度数.
e8c8  int dist[maxn];
4363  int g[maxn][maxn]; // 用二维数组来记录图。
aede  bool p[maxn];
627b  int pre[maxn];
7680  int max_value[maxn], max_value_v[maxn];
172a  priority_queue <node, vector<node>, cmp>
        Q;
bf86  map <string, int> Map;
9507  int ans;
1e17  void Prim(void);
4a0b  void Solve(void);
d02f  void Cal_max_value(int t);
8a96  int main(void)
4506  {
576f    int i, j;
f661    string name1, name2;
d900    int a, b, w;
769e    map <string, int>::iterator iter;
427e    // 初始化。
d8f6    Map.clear();
f041    Map["Park"] = 0;
deb8    for (i = 0; i <= maxn - 1; i++)
4506    {
f099      dist[i] = INT_MAX;
1a39      pre[i] = -1;
5037      for (j = 0; j <= maxn - 1; j++)
4506      {
b4df        g[i][j] = INT_MAX;
95cf      }
95cf    }
91c9    n = 0;
2eb3    cin >> m;
6988    for (i = 1; i <= m; i++)
4506    {
fad5      cin >> name1 >> name2 >> w;
a3dd      iter = Map.find(name1);
917d      if (iter == Map.end())
4506      { // 说明该结点还不存在.
c93c        n++;
8edc        Map[name1] = n;
95cf      }
fbab      a = Map[name1];
a84b      iter = Map.find(name2);
917d      if (iter == Map.end())
4506      { // 说明该结点还不存在.
c93c        n++;
e2a7        Map[name2] = n;
95cf      }
3878      b = Map[name2];
a996      if (g[a][b] > w)
4506      {
ff0f        g[a][b] = g[b][a] = w;
95cf      }
95cf    }
ff36    cin >> total; // 输入限制的度数.
783a     memset(p, 0, sizeof(p)); num = 0;
1f5c     for (i = 1; i <= n; i++)
4506     {
0dfd       if (!p[i])
4506       {
ed5b         s = i;
303a         num++; minV0[num] = s;
427e        // 求除去限制结点的最小生成树.
af5a        Prim();
95cf       }
95cf     }
7360    ans = 0;
67a2    for (i = 1; i <= n; i++) ans += dist[i
          ];
427e    // 求最小度限制生成树.
ceca    Solve();
d72b    printf("Total miles driven: %d\n", ans)
          ;
7021    return 0;
95cf  }
103f  void Prim(void)
4506  {
```

```
c8ed   int i, j, k;
3495   node mini, temp;
a058   while (!Q.empty()) Q.pop();
c7c1   dist[s] = 0;
a8ed   temp.v = s; temp.w = 0;
6b09   Q.push(temp);
e0e5   for (k = 1; k <= n; k++)
4506   {
1b18     while (!Q.empty())
4506     {
c3cc       mini = Q.top();
f2f8       Q.pop();
6e31       j = mini.v;
6dbf       if (!p[j])
4506       {
cde5         p[j] = 1;
37a1         if (g[0][j] < g[0][minV0[num]])
4506         {
0423           minV0[num] = j;
95cf         }
1f5c         for (i = 1; i <= n; i++)
4506         {
ae84           if (i != j && !p[i] && dist[i]
                 > g[j][i])
4506           {
cf01             dist[i] = g[j][i];
671b             pre[i] = j;
d413             temp.w = dist[i]; temp.v = i;
6b09             Q.push(temp);
95cf           }
95cf         }
6173         break;
95cf       }
95cf     }
95cf   }
95cf }
427e
4abc void Cal_max_value(int t)
4506 {
c8ed   int i, j, k;
bb7c   int Stack[maxn];
22df   int top(-1);
d46a   i = t;
437a   while (pre[i] != 0 && pre[i] != -1)
4506   {
0d63     p[i] = 1;
6a17     Stack[++top] = i;
59b2     i = pre[i];
95cf   }
9047   if (top < 0) return ;
f6a3   j = Stack[top];
abf1   max_value[j] = g[j][pre[j]];
8b10   max_value_v[j] = j;
427e
990e   for (i = top - 1; i >= 0; i--)
4506   {
5cac     j = Stack[i]; k = Stack[i + 1];
74d2     if (max_value[k] > g[j][pre[j]])
4506     {
30b8       max_value[j] = max_value[k];
4b3f       max_value_v[j] = max_value_v[k];
95cf     }
649a     else
4506     {
abf1       max_value[j] = g[j][pre[j]];
8b10       max_value_v[j] = j;
95cf     }
95cf   }
95cf }
a038 void Solve(void)
4506 {
80a8   int i, j, k, l;
9059   int mini, opti_i, opti_maxV;
dc9d .
0e77   for (k = 1; k <= num; k++)
4506   {
9bcf     ans += g[0][minV0[k]];
427e
8d9b     j = minV0[k]; i = pre[j];
c32d     while (i != -1)
4506     {
ae09       l = i;
00ff       i = pre[l];
034d       pre[l] = j;
0ffc       j = l;
95cf     }
ad40     pre[minV0[k]] = 0;
95cf   }
427e
ce2a   memset(p, 0, sizeof(p));
1f5c   for (i = 1; i <= n; i++)
4506   {
0dfd     if (!p[i])
4506     {
5213       Cal_max_value(i);
95cf     }
95cf   }
3f24   for (k = 1; k <= total - num; k++)
4506   {
a722     mini = 0;
1f5c     for (i = 1; i <= n; i++)
4506     {
33ca       if (pre[i] == 0) continue;
427e
9639       if (g[0][i] - max_value[i] < mini)
4506       {
```

```
2a0e        mini = g[0][i] - max_value[i];
8b85        opti_i = i; opti_maxV = max_value_v
              [i];
95cf       }
95cf     }
6bbd     if (mini == 0) break;
dc8c     ans += mini;
427e
adda     pre[opti_maxV] = -1;
f116     j = opti_i; i = pre[j];
c32d     while (i != -1)
4506     {
ae09       l = i;
00ff       i = pre[l];
034d       pre[l] = j;
0ffc       j = l;
95cf     }
3647     pre[opti_i] = 0;
55fa     Cal_max_value(opti_maxV);
95cf   }
95cf }
```

6.13 最小树形图

```
e0a5 #include <iostream>
59b9 #include <cstdio>
ef2f #include <cstring>
c928 #include <cmath>
bfb3 #define MAXN 128
b080 #define MAXM 32768
2f38 #define INF 1e15
421c using namespace std;
4674 double g[MAXN][MAXN];
6849 double res;
35b8 int n, m;
935a double sqr(double x)
4506 {
ef78   return x * x;
95cf }
2d75 double dist(double xa, double ya, double
       xb, double yb)
4506 {
5550   return sqrt(sqr(xa - xb) + sqr(ya - yb)
         );
95cf }
18ce void print_map()
4506 {
2ad4   for (int i = 1; i <= n; ++i)
4506   {
8c5b     for (int j = 1; j <= n; ++j)
03d4       printf("%.2f ", g[i][j]);
00e2     printf("\n");
95cf   }
95cf }
```

```
bool init()                                  28f2
{                                            4506
  if (scanf("%d%d", &n, &m) == EOF)          f547
    return false;
  double x[MAXN], y[MAXN];                   eec6
  int a, b;                                  e635
  for (int i = 1; i <= n; ++i)               2ad4
    scanf("%lf%lf", &x[i], &y[i]);           3c14
  for (int i = 1; i <= n; ++i)               2ad4
    for (int j = 1; j <= n; ++j)             8c5b
      g[i][j] = INF;                         f5a0
  for (int i = 1; i <= m; ++i)               2af5
  {                                          4506
    scanf("%d%d", &a, &b);                   a6b8
    g[a][b] = min(g[a][b], dist(x[a], y[a    3126
      ], x[b], y[b]));
  }                                          95cf
  //print_map();                             427e
  return true;                               3361
}                                            95cf
bool vst[MAXN];                              c753
void dfs(int v)                              8aca
{                                            4506
  vst[v] = true;                             84ad
  for (int i = 1; i <= n; ++i)               2ad4
    if (!vst[i] && g[v][i] != INF) dfs(i)    7532
      ;
}                                            95cf
bool possible(int v)                         1a66
{                                            4506
  memset(vst, false, sizeof(vst));           ddf0
  dfs(v);                                    5f3c
  for (int i = 1; i <= n; ++i)               2ad4
    if (i != v && !vst[i]) return false;     48aa
  return true;                               3361
}                                            95cf
int pre[MAXN];                               fe84
bool del[MAXN];                              992d
void solve(int v)// 根为v                    2656
{                                            4506
  res = 0;                                   f29e
  int num = n;                               b1b7
  memset(del, false, sizeof(del));           cec3
  while(1)                                   1f75
  {                                          4506
    int i;                                   a0f7
    // 更新数组pre                           427e
    for (i = 1; i <= n; ++i)                 0428
    {                                        4506
      if (del[i] || i == v) continue;        50c1
      pre[i] = i;                            86f4
      g[i][i] = INF;                         f900
      for (int j = 1; j <= n; ++j)           8c5b
```

```
4506      {
fff9        if (del[j]) continue;
1f4f        if (g[j][i] < g[pre[i]][i])
671b          pre[i] = j;
95cf      }
95cf    }
0428    for (i = 1; i <= n; ++i)
4506    {
427e      // 找环
50c1      if (del[i] || i == v) continue;
8541      int j = i;
fa64      memset(vst, 0, sizeof(vst));
ee9d      while (!vst[j] && j != v)
4506      {
99c6        vst[j] = true;
b66d        j = pre[j];
95cf      }
24ac      if (j == v) continue;
934c      i = j;
427e      // 更新，有向环缩点res
b0c8      res += g[pre[i]][i];
348f      for(j = pre[i]; j != i; j = pre[j])
4506      {
6ac1        res += g[pre[j]][j];
2280        del[j] = true;
95cf      }
4b26      for(j = 1; j <= n; ++j)
4506      {
fff9        if(del[j]) continue;
a1f5        if(g[j][i] != INF)
48d3          g[j][i] -= g[pre[i]][i];
95cf      }更新缩点以后的有向环和其他点的边权
427e      //
348f      for(j = pre[i]; j != i; j = pre[j])
4506      {
ed11        for(int k = 1; k <= n; ++k)
4506        {
c844          if(del[k])continue;
170a          g[i][k] = min(g[i][k], g[j][k])
                ;
fc80          if(g[k][j] != INF)
664f            g[k][i] = min(g[k][i], g[k][j
                  ] - g[pre[j]][j]);
95cf        }
95cf      }
427e      // 完成缩点
348f      for(j = pre[i]; j != i; j = pre[j])
4506      {
2280        del[j] = true;
95cf      }
6173      break;
95cf    }
427e    // 不存在有向环时，停止循环，得出最终
        值res
      if(i > n){                                6bff
        for(int i = 1; i <= n; ++i)             2ad4
        {                                       4506
          if(del[i] || i == v) continue;        50c1
          res += g[pre[i]][i];                  b0c8
        }                                       95cf
        break;                                  6173
      }                                         95cf
    }                                           95cf
}                                               95cf
int main()                                      299c
{                                               4506
  while (init())                                1f56
  {                                             4506
    if (!possible(1)) printf("poor snoopy       a248
      \n");
    else                                        649a
    {                                           4506
      solve(1);                                 1d60
      printf("%.2f\n", res);                    d6bf
    }                                           95cf
  }                                             95cf
  return 0;                                     7021
}                                               95cf
```

6.14 多重匹配

```
#include <stdio.h>                              1915
const int maxn=100;                             0cbb
int a[maxn],b[maxn],nov_a[maxn],nov_b[          a23c
  maxn];
int w[maxn][maxn];                              bac0
int m,n;                                        4d9b
bool find(int i)                                6271
{                                               4506
  nov_a[i]=0;                                   a274
  for(int p=0;p<n;p++)                          b851
  if(w[i][p]==0&&nov_b[p])                      854a
  {                                             4506
    nov_b[p]=0;                                 5a4d
    if(b[p]>0)                                  226a
    {                                           4506
      b[p]--;                                   aefb
      w[i][p]=1;                                060a
      return true;                              3361
    }                                           95cf
    for(int q=0;q<m;q++)                        2bc2
    if(w[q][p]==1&&nov_a[q])                    1ad5
    {                                           4506
      if(find(q))                               b5be
      {                                         4506
        w[i][p]=1;                              060a
        w[q][p]=0;                              0bb0
```

```
3361          return true;
95cf        }
95cf      }
95cf    }
438e    return false;
95cf  }
653c  bool gao(int i)
4506  {
e4c8    for(int j=0;j<m;j++)nov_a[j]=1;
66c3    for(int j=0;j<n;j++)nov_b[j]=1;
9044    return find(i);
95cf  }
299c  int main()
4506  {
e287    int cas=0;
a41b    while(scanf("%d%d",&m,&n)!=EOF&&(m||n))
4506    {
25fe      for(int i=0;i<m;i++)scanf("%d",&a[i])
            ;
e951      for(int i=0;i<n;i++)scanf("%d",&b[i])
            ;
548e      for(int i=0;i<m;i++)
6bf3      for(int j=0;j<n;j++)
dc5e      w[i][j]=0;
6e7e      bool ans=true;
548e      for(int i=0;i<m;i++)
4506      {
9212        while(a[i]>0&&gao(i))a[i]--;
4fe1        if(a[i]!=0)
4506        {
539e          ans=false;
6173          break;
95cf        }
95cf      }
f5a9      for(int i=0;i<n;i++)
e0ad      if(b[i]>0)ans=false;
548e      for(int i=0;i<m;i++)
6bf3      for(int j=0;j<n;j++)
4b54      if(w[i][j]==1)
4506      {
76a8        b[j]++;
bef5        w[i][j]=-1;
73cd        if(!gao(i))
4506        {
292e          w[i][j]=1;
cd7b          b[j]=0;
95cf        }
427e
95cf      }
6c4d      else w[i][j]=-1;
a27f      cas++;
a3dd      if(cas!=1)printf("\n");
a8ea      if(ans)
4506      {
548e        for(int i=0;i<m;i++)
4506        {
6bf3          for(int j=0;j<n;j++)
a417          if(w[i][j]==1)printf("Y");
8f87          else printf("N");
00e2          printf("\n");
95cf        }
95cf      }
edea      else printf("Impossible\n");
95cf    }
95cf  }
```

7 java 样例

7.1 java 样例

```
84fe  import java.io.*;
93c2  import java.math.BigInteger;
4156  import java.util.*;
788a  public class Main {
e1b6    public static void main(String[] args)
          {
f75d      Scanner cin = new Scanner(new
            BufferedInputStream(System.in));
ac68      while (cin.hasNext()){
93f1        int m = cin.nextInt();
4f78        int n = cin.nextInt();
f3f7        int best = 0;
3c41        BigInteger b[] = new BigInteger[m];
e725        for (int i = 0; i < m; ++i)
734a          b[i] = BigInteger.valueOf(1);
6c2f        for (int i = 0; i < n; ++i){
427e          //BigInteger c = BigInteger.
                valueOf(1);
6613          for (int j = 0; j < m; ++j){
4677            int x = cin.nextInt();
b9b5            BigInteger d = BigInteger.
                  valueOf(x);
0541            b[j] = b[j].multiply(d);
95cf          }
95cf        }
bf14        for (int i = 1; i < m; ++i){
ecee          if (b[best].compareTo(b[i]) <= 0)
                best = i;
95cf        }
004f        System.out.println(best + 1);
427e
95cf      }
95cf    }
427e
95cf  }
```

8 其他

8.1 校赛 Meeting 标程

```
1915 #include <stdio.h>
1fa4 #include <math.h>
427e
842a int u1, v1, u2, v2, u3, v3;
8f9d double x, y, d;
427e
4d45 double f(double u, double v)
4506 {
ec32    double r=0;
e2fe    r+=sqrt((u-u1)*(u-u1)+(v-v1)*(v-v1));
3df7    r+=sqrt((u-u2)*(u-u2)+(v-v2)*(v-v2));
b00a    r+=sqrt((u-u3)*(u-u3)+(v-v3)*(v-v3));
05ee    if(r<d)
4506    {
5c82        d=r;
c0ce        x=u;
583c        y=v;
95cf    }
547e    return r;
95cf }
427e
afdd double f(double u)
4506 {
918b    double L, R, M1, M2;
b4a4    for(L=-1001, R=1001; R-L>1e-6; )
4506    {
3dd0        M1=(L*2+R)/3;
8a02        M2=(L+R*2)/3;
40c0        f(u, M1)<f(u, M2)?(R=M2):(L=M1);
95cf    }
39f8    return f(u, (L+R)/2);
95cf }
427e
299c int main()
4506 {
9523    int T;
918b    double L, R, M1, M2;
427e
ba03    for(scanf("%d", &T); T--; )
4506    {
e322        scanf("%d %d %d %d %d %d", &u1, &v1
              , &u2, &v2, &u3, &v3);
6f5e        for(d=1e100, L=-1001, R=1001; R-L>1
              e-6; )
4506        {
3dd0            M1=(L*2+R)/3;
8a02            M2=(L+R*2)/3;
7091            f(M1)<f(M2)?(R=M2):(L=M1);
95cf        }
a0d8        printf("(%.3lf,%.3lf)\n", x, y);
95cf    }
427e
7021    return 0;
95cf }
```