# 上节课回顾



#### 经典理论

$$\frac{d\vec{v}}{dt} = -\frac{1}{\rho}\nabla p + \vec{g} - 2\vec{\Omega} \times \vec{v} + \vec{F}$$

$$\frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \vec{V})$$

$$P\alpha = RT$$

$$Q = Cp\frac{dT}{dt} - \alpha \frac{dp}{dt}$$

$$\frac{\partial \rho q}{\partial t} = -\nabla \cdot (\rho \vec{Vq}) + \rho (E - C)$$

#### 最新研究成果



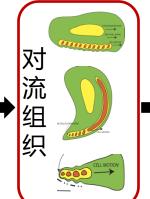
#### 实际应用



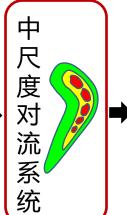




对流触发



超 级 对流单体









强 对流天气 初始场





预报场

的数值模 拟

# 课程材料



1. 请查看课程网站,上完每一章后将上传相应材料(安排、课件、作业)

https://qiuyang50.github.io/\_pages/mesoscale\_2024fall/



2. 请加入课程微信群(通知、交流), 群内请注明真实姓名





# 第一章 中尺度分析基础

# 主要内容



## 1.1 什么是中尺度

- 1.2 中尺度基本方程组
- 1.3 扰动气压
- 1.4 基本工具

Skew-T

Hodograph

Radar基础

# 天气和天气系统

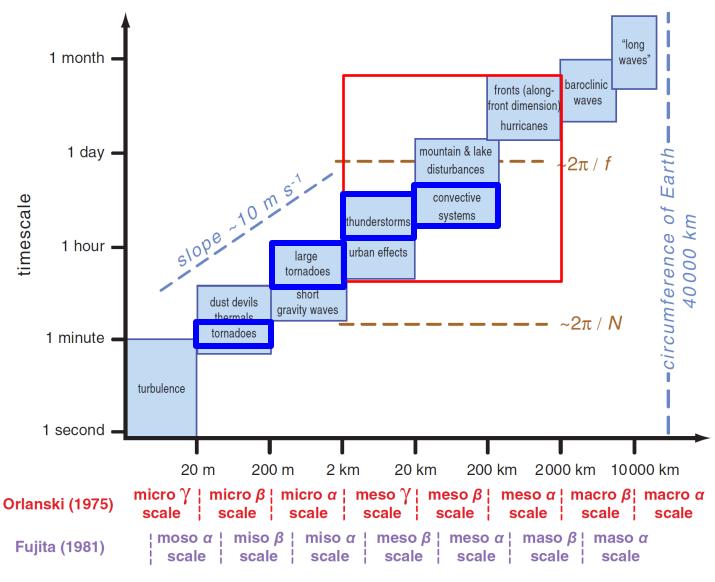


**天气**:某一个地区距离地表较近的大气层在短时间内的具体状态。大气中气象要素的空间分布可表现为各种瞬息万变的天气现象。

**天气系统:**引起各种天气变化和分布的高压、低压和高压脊、低压槽等具有典型特征的大气运动系统。

# 什么是中尺度?

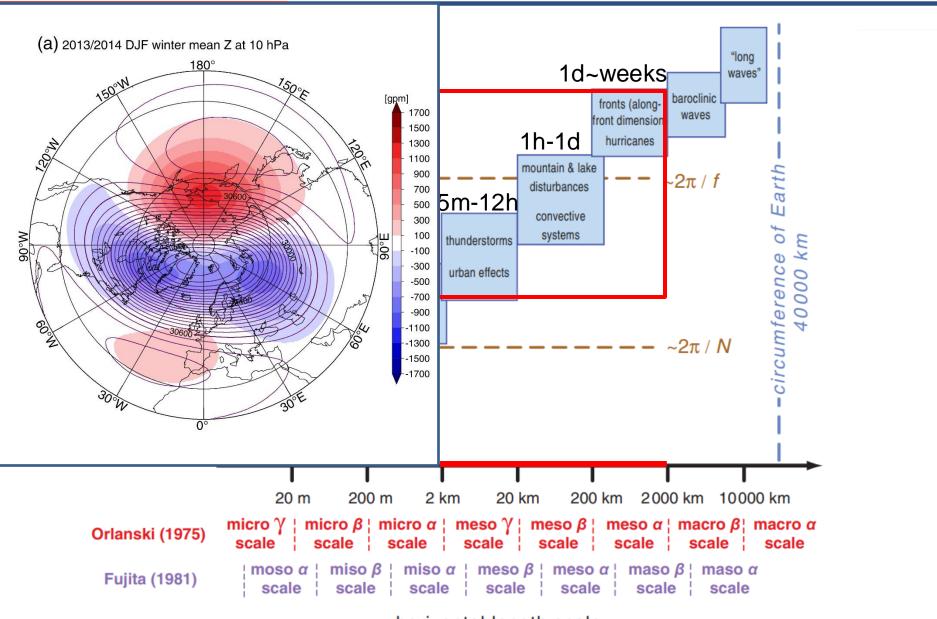




(MR2010)

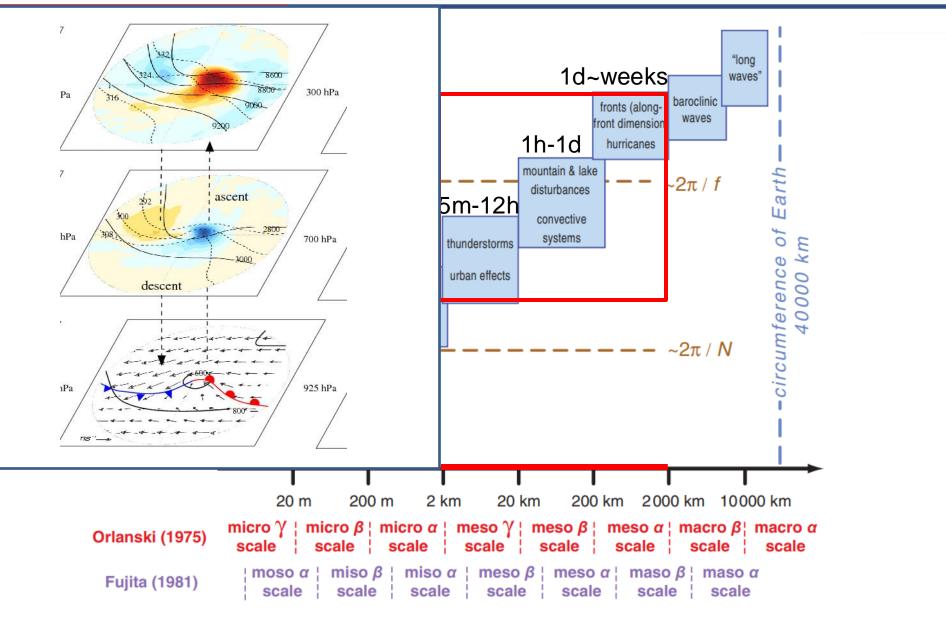
# 尺度分类: 大尺度驻波





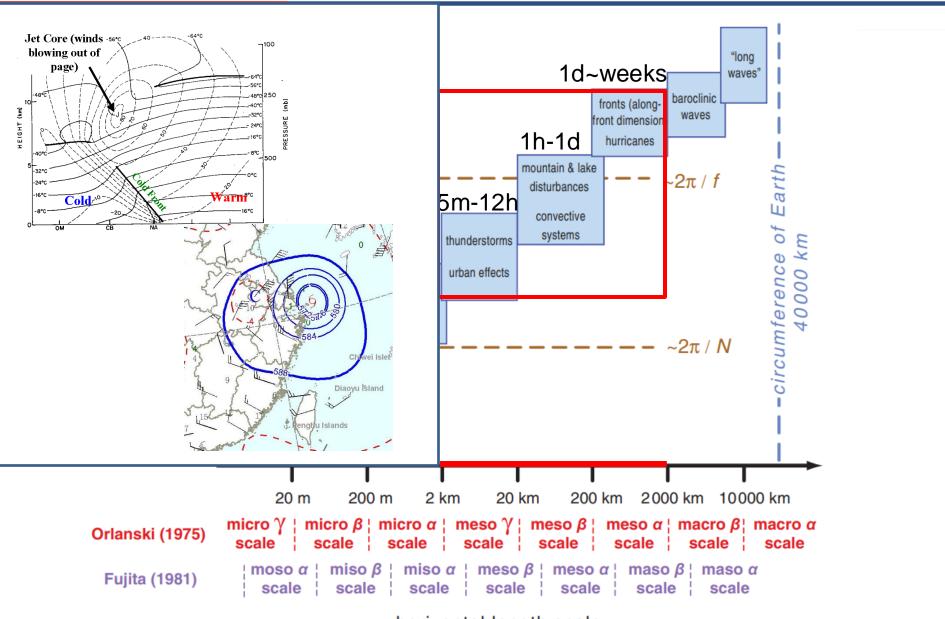
# 尺度分类: 中尺度锋面





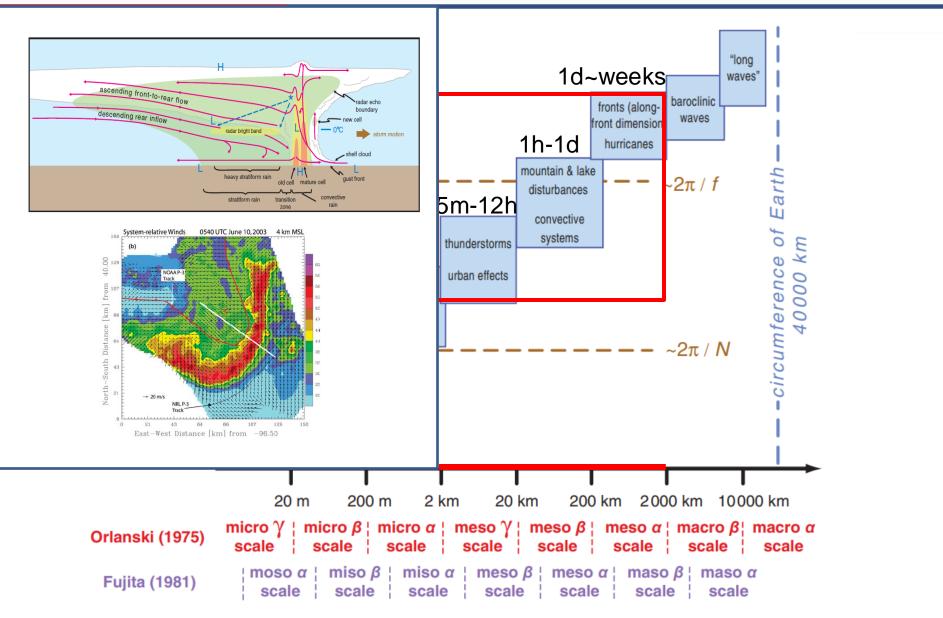
## 尺度分类: 台风





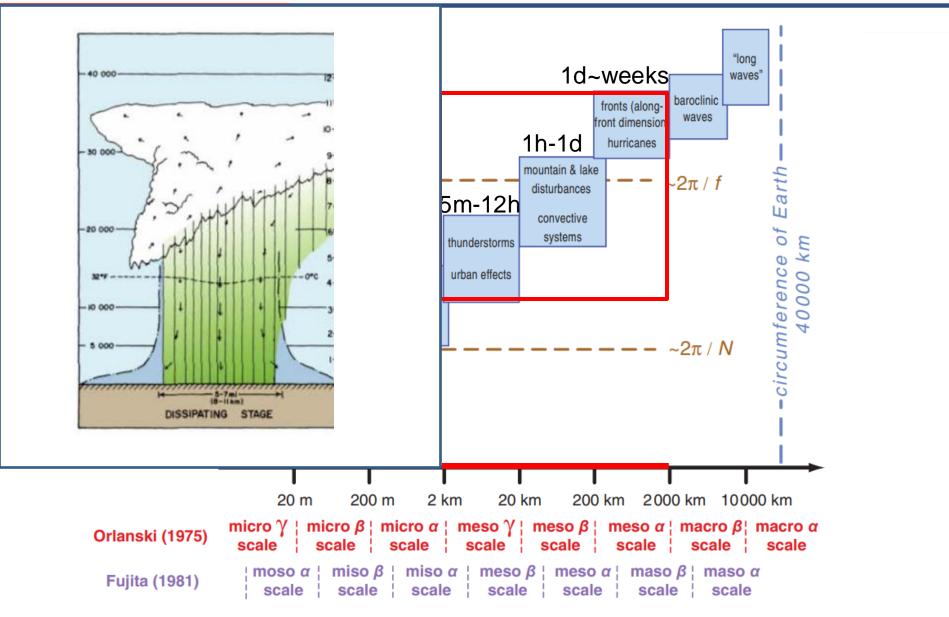
# 尺度分类: 飑线





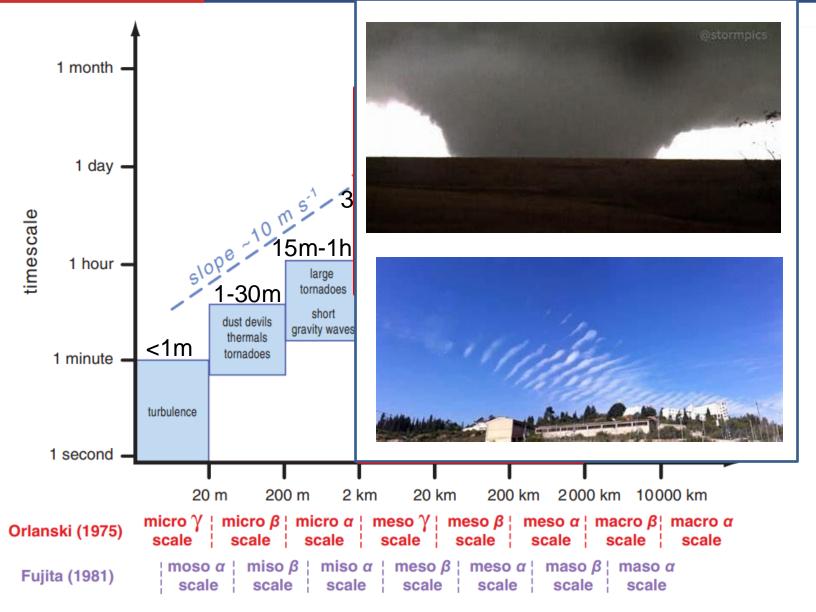
# 尺度分类: 雷暴





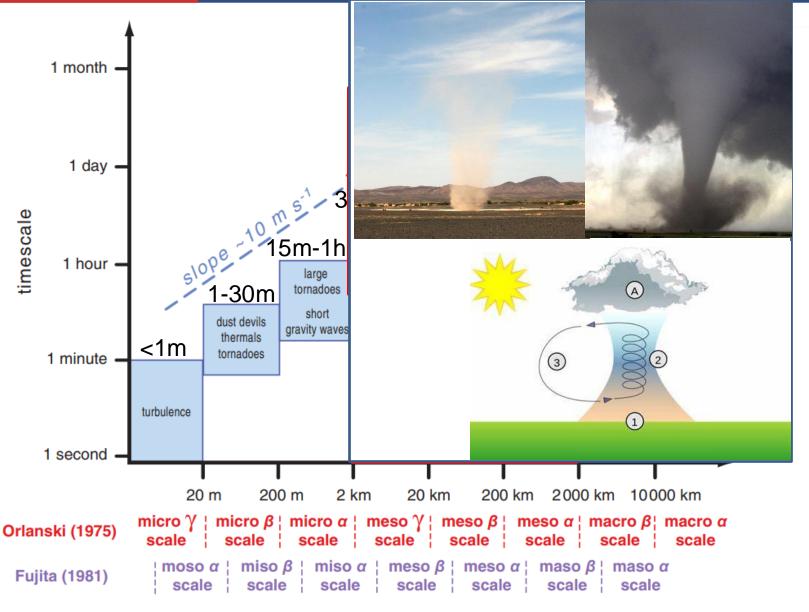
# 尺度分类: 大龙卷、重力波





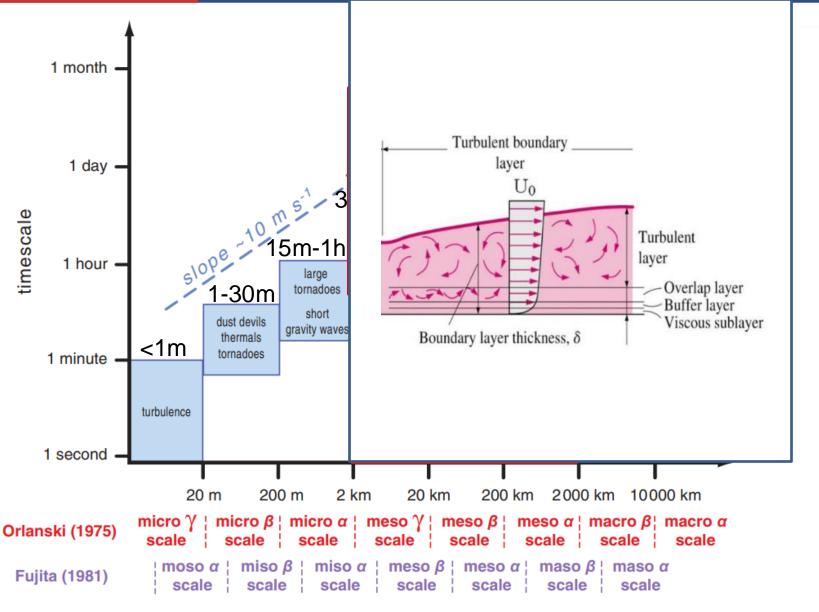
# 尺度分类: 龙卷





## 尺度分类:湍流





# 按尺度划分



小尺度: 水平范围2km以下, 生命期为几分钟到几小时.

updraft scale

 $2\pi/N$ 

中尺度:水平范围2~2000km,生命期为几小时到几天。

大尺度:水平范围2000km以上,生命期为几天到十几天。

NH/f  $2\pi/f$ 

天气尺度: 200~2000km 生命期为一天到几天 (台风、锋面、 气旋、反气旋等),

人们有时把等于或大于天气尺度的天气系统统称为大尺度天气 系统.

# 中尺度的特殊性



## a. 基本方程组最接近于原始方程

大尺度:  $\frac{dw}{dt}$ ,  $\overrightarrow{v_a} \cdot \nabla \alpha$  可以忽略

小尺度: 科氏力, 甚至水平气压梯度力可以忽略

## b. 运动受多种不稳定性控制

大尺度: 斜压不稳定

中尺度: 静力不稳定,对称不稳定,正压不稳定 (Kelvin-Helmholtz不稳定)

小尺度: 静力不稳定

## c. 时间尺度

大尺度: 惯性震荡  $(\frac{2\pi}{f} \sim 17 \text{ h})$ 

小尺度: 纯浮力震荡  $\left(\frac{2\pi}{N} \sim 10 \text{ min}\right)$ 

$$\begin{cases} \frac{du}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv \\ \frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial y} - fu \\ \frac{dw}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + g \\ \frac{d\rho}{dt} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0 \\ p = \rho RT \\ \frac{d\theta}{dt} = -\frac{\theta}{C_n T} \frac{dQ}{dt} \end{cases}$$

# 对称不稳定

惯性不稳定的判据(水平判据):

$$M = u_g - fy$$
 绝对动量(此处定义和第5章差负号)  $\frac{\partial M}{\partial y} > 0$  不稳定  $\frac{\partial M}{\partial y} < 0$  稳定

干对流不稳定的判据(垂直判据):

$$N^2 = \frac{g}{\theta_0} \frac{\partial \theta_0}{\partial z} = \frac{g}{T_0} (\Gamma_d - \Gamma)$$

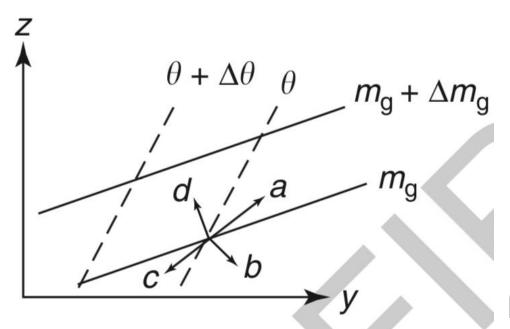
现考虑在y-z平面上的运动,如果运动可以沿着倾斜的方向,则稳定度判据有何不同?

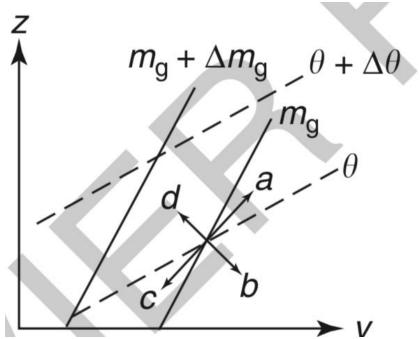
#### $\theta$ 等值线和 $M_g$ 等值线夹角为正: 对称不稳定

沿着a,c方向, 对流不稳定且惯性不稳定

$$\theta$$
等值线和 $M_g$ 等值线夹角为负:  
对称稳定

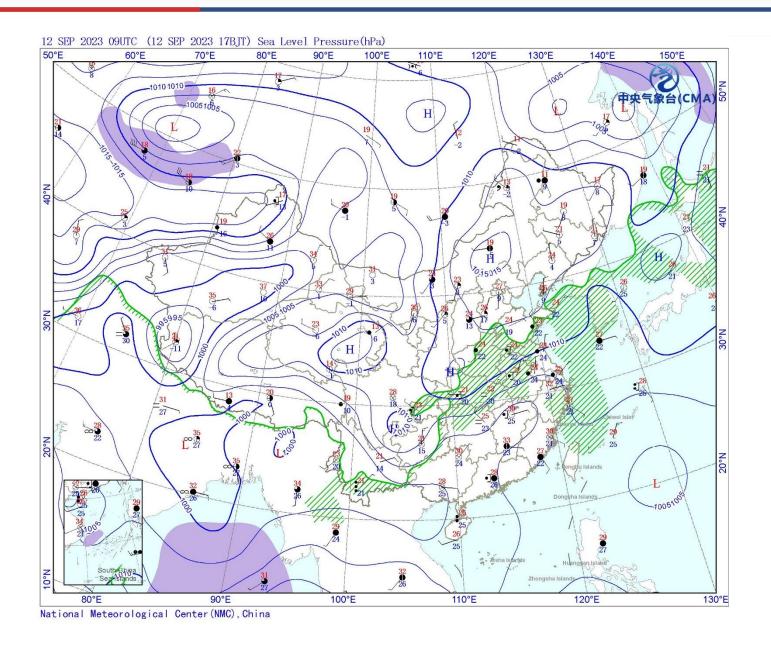
$$\frac{\delta\theta}{\delta z}|_{s} < 0 \qquad \frac{\delta m_{g}}{\delta y}|_{s} > 0$$





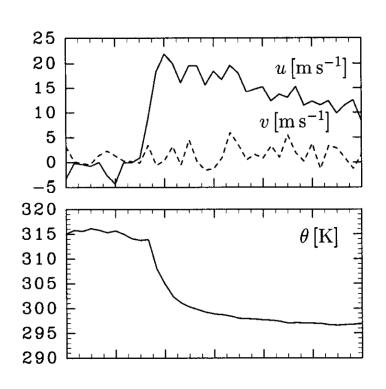
# 大尺度的气压变化





# 中尺度的气压变化





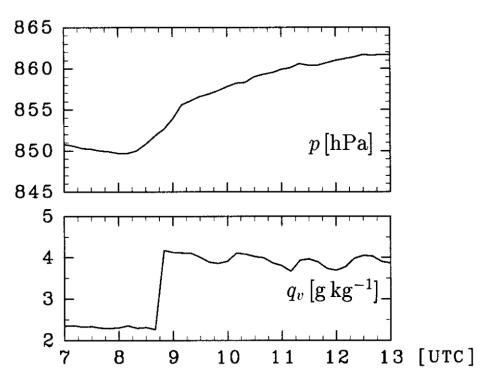


FIG. 6. Time series of surface variables observed at Minqin AWS during the squall line passage. Wind components u and v indicate parallel and normal to the squall line motion (from  $304^{\circ}$ ), respectively. The arrival of the gust front is at about 0840 UTC.

(TAKEMI, 1999, MWR)



$$\frac{du}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv + F_u \tag{E1.1}$$

#### 大尺度

O 
$$(fv)$$
 10<sup>-4</sup> s<sup>-1</sup> . 10 m s<sup>-1</sup>  $\sim 10^{-3}$  m s<sup>-2</sup>

$$O\left(-\frac{1}{\rho}\frac{\partial p}{\partial x}\right)$$

$$\frac{1}{1 \text{ kg. m}^{-3}} \cdot \frac{10 \text{ mb}}{1000 \text{ km}}$$

$$= \frac{1}{1 \text{ kg.m}^{-3}} \cdot \frac{10^3 \text{kg·m}}{\text{s}^{-2} \text{m}^2 10^6 \text{m}}$$

$$= 10^{-3} \text{ m} \cdot \text{s}^{-2}$$

#### 中尺度

$$\sim 10^{-3} \ m \ s^{-2}$$

$$\frac{1}{1 \text{ kg. m}^{-3}} \cdot \frac{10 \text{ mb}}{10 \text{ km}}$$

$$= \frac{1}{1 \text{ kg.m}^{-3}} \cdot \frac{10^3 \text{kg·m}}{\text{s}^{-2} \text{m}^2 10^4 \text{m}}$$

$$= 10^{-1} \text{ m} \cdot \text{s}^{-2}$$



### 大尺度

$$\Rightarrow \frac{du}{dt}$$
 很小
$$v = v_a + v_g$$

$$fv_a = fv - fv_g = fv - \frac{1}{\rho} \frac{\partial p}{\partial x}$$

⇒ 非地转风很小 为准地转平衡

$$R_0 = \frac{\text{U}}{fL}$$
 
$$\frac{10 \text{ m} \cdot \text{s}^{-1}}{10^{-4} \text{s}^{-1} \cdot 10^6 \text{ m}}$$
$$= 10^{-1} \ll 1$$

#### 中尺度

加速度和非地转风都很大 地转、准地转、梯度风平 衡近似都不适用

$$\frac{10 \text{ m} \cdot \text{s}^{-1}}{10^{-4} \text{s}^{-1} \cdot 10^{4} \text{ m}}$$
$$= 10 \ge 1$$



$$\frac{dw}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + 2\Omega u \cos \phi - g + F_w \qquad (E1.2)$$

$$= -\frac{1}{\rho} \frac{\partial p}{\partial z} - g$$

如果 
$$\frac{dw}{dt}$$
 可以忽略,  $-\frac{1}{\rho}\frac{\partial p}{\partial z} = g$  为静力平衡

- >是不是所有的中尺度天气系统都不满足静力平衡?
- >天气尺度呢?

#### 静力平衡需要满足什么条件?

$$\frac{dw}{dt}$$
 与  $-\frac{1}{\rho}\frac{\partial p}{\partial z}$  尺度比较



$$\frac{dw}{dt}$$
 与  $-\frac{1}{\rho}\frac{\partial p}{\partial z}$  尺度比较

参考大气: 定常, 水平均匀, 满足静力平衡

$$p = \bar{p}(z) + p'(x, y, z, t)$$

$$\rho = \bar{\rho}(z) + \rho'(x, y, z, t)$$

$$\frac{\partial \bar{p}}{\partial z} = -\bar{\rho}g$$

$$\frac{dw}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial z} - g \implies \rho \frac{dw}{dt} = -\frac{\partial p}{\partial z} - \rho g$$

$$\rho \frac{dw}{dt} = -\frac{\partial \bar{p}}{\partial z} - \frac{\partial p'}{\partial z} - \bar{\rho} g - \rho' g$$

$$= -\frac{\partial p'}{\partial z} - \rho' g$$



$$\frac{dw}{dt}$$
 与  $-\frac{1}{\rho}\frac{\partial p}{\partial z}$  尺度比较

$$\rho \frac{dw}{dt} = -\frac{\partial p'}{\partial z} - \rho' g \implies \frac{dw}{dt} = -\frac{1}{\rho} \frac{\partial p'}{\partial z} - \frac{\rho'}{\rho} g$$
 (E1.3)

估计
$$O(\frac{dw}{dt})/O(-\frac{1}{\rho}\frac{\partial p'}{\partial z})$$
 需要知道  $O(w)$  和  $O(\frac{p'}{\rho})$ 

假定o
$$(\frac{\partial w}{\partial z})$$
~ o $(\frac{\partial u}{\partial x})$ 

$$\frac{W}{H} \sim \frac{U}{L} \implies \frac{H}{W} \sim \frac{L}{U} \implies T_Z \sim T_h \tag{E1.4}$$

## 垂直平流时间尺度 水平平流时间尺度

$$\Rightarrow$$
 W  $\sim \frac{\text{UH}}{\text{L}}$  (E1.5)  $\Rightarrow$  O $(\frac{dw}{dt}) \sim \frac{\text{UH}}{\text{LT}_z}$ 

(E1.6)



$$O\left(-\frac{1}{\rho}\frac{\partial p'}{\partial z}\right) \sim \frac{p'}{\rho H}$$
 首先分析  $\frac{p'}{\rho}$ 

$$\frac{du}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv \approx -\frac{1}{\rho} \frac{\partial p}{\partial x} \approx -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x} - \frac{1}{\rho} \frac{\partial p'}{\partial x} \approx -\frac{1}{\rho} \frac{\partial p'}{\partial x}$$

$$10^{-1} \quad 10^{-3}$$

$$O(\frac{du}{dt}) \sim O(-\frac{1}{\rho} \frac{\partial p'}{\partial x})$$

$$\frac{\mathrm{U}}{\mathrm{T}_{h}} \sim \frac{p'}{\rho \mathrm{L}} \quad \Longrightarrow \quad \frac{p'}{\rho} \sim \frac{\mathrm{UL}}{\mathrm{T}_{h}} \tag{E1.8}$$

$$O\left(-\frac{1}{O}\frac{\partial p'}{\partial z}\right) \sim \frac{UL}{HT_h}$$
 (E1.9)



$$T_z \sim T_h$$

$$O\left(\frac{dw}{dt}\right)/O\left(-\frac{1}{\rho}\frac{\partial p'}{\partial z}\right) \sim \frac{UH}{LT_z}/\frac{UL}{HT_h} \sim \frac{WH}{LT_z} \cdot \frac{HT_h}{WL} \sim \left(\frac{H}{L}\right)^2$$

Aspect ratio

如果 
$$\frac{H}{L} \ll 1$$
,  $\frac{dw}{dt}$  可以忽略  $\Rightarrow$  静力平衡

大尺度 
$$\frac{H}{L} \sim \frac{10 \text{ km}}{1000 \text{ km}} \sim 10^{-2} \ll 1$$
,满足静力平衡

中尺度 
$$\frac{H}{L} \sim \frac{10 \text{ km}}{10 \text{ km}} \sim 1$$
, 不满足静力平衡

并不是所有的中尺度系统都不满足静力平衡

比如: 冷池 
$$\frac{H}{L} \sim \frac{2 \text{ km}}{20 \text{ km}} \sim 0.1$$

# 主要内容



- 1.1 什么是中尺度天气系统
- 1.2 中尺度基本方程组
- 1.3 扰动气压
- 1.4 基本工具

Skew-T

Hodograph

Radar基础

## 简化原始方程



#### 简单起见,不考虑摩擦和科氏力的垂直分量

$$\int \frac{du}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv$$

$$\frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial y} - fu$$

$$\frac{dw}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + g$$

$$\frac{\partial p}{\partial t} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + g$$

- 该方程不适合讨论中小尺度天气, 因为方程中包含大、中、小各种尺 度和声波,需要简化。
- 通过做合理假定,使方程中的某些 项线性化,也可以使问题简化。

$$\frac{d\rho}{dt} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$p = \rho RT$$

$$\frac{d\theta}{dt} = -\frac{\theta}{C_p T} \frac{dQ}{dt}$$

其他形式

$$\frac{dp}{dt} - C_s^2 \frac{d\rho}{dt} = \frac{dQ}{dt} \qquad c_s^2 = \gamma RT$$

$$C_v \frac{dT}{dt} + p \frac{d\alpha}{dt} = \frac{dQ}{dt} \qquad \gamma = \frac{C_p}{C_v}$$

# Boussinesq近似



$$\rho = \rho_0 + \delta \rho(x, y, z, t)$$

#### **Summary of Boussinesq Equations**

The simple Boussinesq equations are, for an inviscid fluid:

momentum equations:  $\frac{\mathrm{D}\boldsymbol{v}}{\mathrm{D}t} + \boldsymbol{f} \times \boldsymbol{v} = -\nabla \phi + b\mathbf{k}, \quad (B.1)$ 

mass conservation:  $\nabla \cdot \boldsymbol{v} = 0$ , (B.2)

buoyancy equation:  $\frac{\mathrm{D}b}{\mathrm{D}t} = \dot{b}. \tag{B.3}$ 

## Anelastic近似



#### 针对中尺度做简化处理:

- (1) 尺度分离  $f = \bar{f} + f'$   $\bar{f}$  为大尺度参考量 f' 为偏离 $\bar{f}$  的中尺度扰动。
- (2) 假定大尺度的时间变化远慢于中尺度扰动的时间变化。  $\left|\frac{\partial \bar{f}}{\partial t}\right| \ll \left|\frac{\partial f'}{\partial t}\right|$



定常

(3) 假定大尺度的水平梯度远小于中尺度扰动的水平梯度。

$$\left| \frac{\partial \bar{f}}{\partial x} \right| \ll \left| \frac{\partial f'}{\partial x} \right|, \quad \left| \frac{\partial \bar{f}}{\partial y} \right| \ll \left| \frac{\partial f'}{\partial y} \right|$$

- (4) 假定天气尺度参考量  $\bar{f}$  远大于中尺度扰动量 f'。  $\left|\frac{f'}{\bar{f}}\right| \ll 1$
- (5) 大尺度背景满足静力平衡。  $\frac{\partial p}{\partial z} = -\bar{\rho}g$

## Anelastic近似



$$p = \bar{p}(z) + p'(x, y, z, t) \qquad \theta = \bar{\theta}(z) + \theta'(x, y, z, t)$$

$$\rho = \bar{\rho}(z) + \rho'(x, y, z, t) \qquad T = \bar{T}(z) + T'(x, y, z, t)$$

静态假定:  $\bar{u}=0$ ,  $\bar{v}=0$ ,  $\bar{w}=0$ , 速度仅为扰动速度, 简单起见, 省略', 记为u, v, w

## 运动方程



$$\frac{du}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv$$

$$\frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial y} - fu$$

$$\frac{du}{dt} = -\frac{1}{\bar{\rho} + \rho'} \frac{\partial (\bar{p} + p')}{\partial x} + fv$$

$$= -\frac{1}{\bar{\rho} + \rho'} \frac{\partial p'}{\partial x} + fv$$

$$\frac{du}{dt} \approx -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial x} + fv$$

$$\frac{dv}{dt} \approx -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial y} - fu$$

# 运动方程



垂直运动方程

$$\frac{dw}{dt} = -\frac{1}{\bar{\rho} + \rho'} \left( \frac{\partial \bar{p}}{\partial z} + \frac{\partial p'}{\partial z} \right) - g$$

$$= -\frac{1}{\bar{\rho} + \rho'} \left( -\bar{\rho}g + \frac{\partial p'}{\partial z} \right) - g$$

$$= -\frac{1}{\bar{\rho} + \rho'} \frac{\partial p'}{\partial z} + \left( \frac{\bar{\rho}}{\bar{\rho} + \rho'} - 1 \right) g$$

$$= -\frac{1}{\bar{\rho} + \rho'} \frac{\partial p'}{\partial z} - \frac{\rho'}{\bar{\rho} + \rho'} g$$

$$\approx -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial z} - \frac{\rho'}{\bar{\rho}} g$$

由密度扰动引起的浮力



$$\frac{\partial \rho}{\partial t} = -\left(u\frac{\partial \rho}{\partial x} + v\frac{\partial \rho}{\partial y} + w\frac{\partial \rho}{\partial z}\right) - \rho\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$

比容 
$$\frac{\partial \alpha}{\partial t} = -\left(u\frac{\partial \alpha}{\partial x} + v\frac{\partial \alpha}{\partial y} + w\frac{\partial \alpha}{\partial z}\right) + \alpha\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$
  
 $\Rightarrow \alpha = \bar{\alpha}(z) + \alpha'(x, y, z, t)$ 

$$\frac{\partial \overline{\alpha}}{\partial t} + \frac{\partial \alpha'}{\partial t} = -\left(u\frac{\partial \alpha'}{\partial x} + v\frac{\partial \alpha'}{\partial y} + w\frac{\partial \alpha'}{\partial z} + u\frac{\partial \overline{\alpha}}{\partial x} + v\frac{\partial \overline{\alpha}}{\partial y} + w\frac{\partial \overline{\alpha}}{\partial z}\right) + \overline{\alpha}(1 + \frac{\alpha'}{\overline{\alpha}}) \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$

根据 (2) - (4) 的假定



$$\frac{\partial \alpha'}{\partial t} \approx -\left[\left(u\frac{\partial \alpha'}{\partial x} + v\frac{\partial \alpha'}{\partial y} + w\frac{\partial \alpha'}{\partial z}\right) + w\frac{\partial \overline{\alpha}}{\partial z}\right] + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$

特征尺度: x,  $y\sim L$ ,  $z\sim H$ , u,  $v\sim U$ ,  $t\sim \frac{L}{U}$ ,  $w\sim \frac{UH}{L}$ 

假定:  $\frac{\partial w}{\partial z} \sim \frac{\partial u}{\partial x} \sim \frac{\mathsf{U}}{\mathsf{L}}$ 

下面把每一项与 $\alpha \frac{\partial w}{\partial z}$ 相比

$$\left| \frac{\partial \alpha'}{\partial t} \right| / \left| \overline{\alpha} \frac{\partial w}{\partial z} \right| \sim \frac{\alpha'}{\overline{\alpha}} \cdot \frac{\mathsf{U}}{\mathsf{L}} \cdot \frac{\mathsf{L}}{\mathsf{U}} = \frac{\alpha'}{\overline{\alpha}} \ll 1$$

$$\left| u \frac{\partial \alpha'}{\partial x} \right| / \left| \overline{\alpha} \frac{\partial w}{\partial z} \right| \sim \frac{\alpha'}{\overline{\alpha}} \cdot \frac{\mathsf{U}}{\mathsf{L}} \cdot \frac{\mathsf{L}}{\mathsf{U}} = \frac{\alpha'}{\overline{\alpha}} \ll 1$$



$$\frac{\partial \omega}{\partial t} \approx -\left[\left(u\frac{\partial \alpha'}{\partial x} + v\frac{\partial \alpha'}{\partial y} + w\frac{\partial \alpha'}{\partial z}\right) + w\frac{\partial \overline{\alpha}}{\partial z}\right] + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$

$$\left|v\frac{\partial\alpha'}{\partial\nu}\right|/\left|\overline{\alpha}\frac{\partial w}{\partial z}\right|\sim\frac{\alpha'}{\overline{\alpha}}\cdot\frac{\mathsf{U}}{\mathsf{L}}\cdot\frac{\mathsf{L}}{\mathsf{U}}=\frac{\alpha'}{\overline{\alpha}}\ll 1$$

$$\left|w\frac{\partial\alpha'}{\partial z}\right|/\left|\overline{\alpha}\frac{\partial w}{\partial z}\right| \sim \frac{\mathsf{UH}}{\mathsf{L}} \cdot \frac{\alpha'}{\mathsf{H}} \cdot \frac{1}{\overline{\alpha}} \cdot \frac{\mathsf{L}}{\mathsf{U}} = \frac{\alpha'}{\overline{\alpha}} \ll 1 \qquad \forall \exists \exists \alpha', \ \alpha' \approx \partial\alpha'$$

$$\left|w\frac{\partial \overline{\alpha}}{\partial z}\right| / \left|\overline{\alpha}\frac{\partial w}{\partial z}\right| \sim \frac{\mathsf{UH}}{\mathsf{L}} \cdot \frac{\mathsf{L}}{\mathsf{U}} / \left|\frac{1}{\overline{\alpha}}\frac{\partial \overline{\alpha}}{\partial z}\right|^{-1} = \mathsf{H} / \left|\frac{1}{\overline{\alpha}}\frac{\partial \overline{\alpha}}{\partial z}\right|^{-1} = \frac{\mathsf{H}}{\mathsf{H}_{\alpha}}$$

对于 $\bar{\alpha}$ ,  $\bar{\alpha} \neq \partial \bar{\alpha}$ , 对于不同的H,  $\partial \bar{\alpha}$ 不一样

标高: 大气密度减小到起始密度的1/e 时的高度增量  $H_{\alpha} \sim \begin{vmatrix} 1 \partial \overline{\alpha} \\ \overline{\overline{\alpha}} \frac{\partial \overline{z}}{\partial z} \end{vmatrix}^{-1}$ 



$$\frac{\partial u}{\partial t} \approx -\left[\left(u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z}\right) + w\frac{\partial \overline{u}}{\partial z}\right] + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial y} + \frac{\partial w}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial z} + \frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial z} + \frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{\partial u}{\partial z}\right) + \overline{\alpha}\left(\frac{$$

如果 
$$\frac{H}{H_{\alpha}} \ll 1$$
,  $\bar{\alpha} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$  或  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$ 

$$\nabla \cdot \overrightarrow{\boldsymbol{v}} = 0$$

运动的垂直尺度远小于大气密度标高的情况下的不可压缩近似,或Boussinesq近似,为浅对流连续方程,滤掉了声波 ( $\frac{\partial \rho'}{\partial t} = 0$ )



$$\frac{\partial u}{\partial t} \approx -\left[\left(u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z}\right) + w\frac{\partial \overline{u}}{\partial z}\right] + \overline{u}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)$$
如果  $\frac{H}{H}$  《1不成立,则有:  $-w\frac{\partial \overline{u}}{\partial z} + \overline{u}\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) = 0$ 

$$w\frac{\partial\overline{\rho}}{\partial z} + \overline{\rho}(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) = 0$$

$$u\frac{\partial\overline{\rho}}{\partial x} + v\frac{\partial\overline{\rho}}{\partial y} + w\frac{\partial\overline{\rho}}{\partial z} + \overline{\rho}(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) = 0$$

$$\frac{\partial u\overline{\rho}}{\partial x} + \frac{\partial v\overline{\rho}}{\partial y} + \frac{\partial w\overline{\rho}}{\partial z} = 0$$

$$abla \cdot \overline{\rho} \overrightarrow{\boldsymbol{v}} = 0$$
 滞弹性近似 (Anelastic Approximation)

# 状态方程



$$p = \rho RT \implies \bar{p} + p' = (\bar{\rho} + \rho')R(\bar{T} + T')$$

$$\bar{p}(1+\frac{p'}{\bar{p}})=\bar{\rho}(1+\frac{\rho'}{\bar{\rho}})R\bar{T}(1+\frac{T'}{\bar{T}})$$

两边取对数

$$\ln \bar{p} + \ln(1 + \frac{p'}{\bar{p}}) = \ln \bar{p} + \ln\left(1 + \frac{\rho'}{\bar{p}}\right) + \ln \bar{R}\bar{T} + \ln\left(1 + \frac{T'}{\bar{T}}\right)$$

由于 
$$\ln \bar{p} = \ln \bar{\rho} + \ln R\bar{T}$$

$$\Rightarrow \ln(1 + \frac{p'}{\bar{p}}) = \ln(1 + \frac{\rho'}{\bar{p}}) + \ln(1 + \frac{T'}{\bar{T}})$$

# 状态方程



由于 
$$\begin{cases} \ln(1 + \frac{p'}{\bar{p}}) \approx \frac{p'}{\bar{p}} \\ \ln(1 + \frac{\rho'}{\bar{\rho}}) \approx \frac{\rho'}{\bar{\rho}} \end{cases} \implies \frac{p'}{\bar{p}} \approx \frac{\rho'}{\bar{\rho}} + \frac{T'}{\bar{T}}$$
 
$$\ln(1 + \frac{T'}{\bar{T}}) \approx \frac{T'}{\bar{T}}$$

观测证明,大多数中小尺度系统均满足  $\frac{p'}{\bar{n}} \ll \frac{T'}{\bar{T}}$ 

$$\rightarrow -\frac{\rho'}{\bar{\rho}} \approx \frac{T'}{\bar{T}} \quad \overline{z} = \overline{$$

# 热力学方程



$$\frac{1}{T}\frac{dQ}{dt} = c_{p}\frac{d\ln\theta}{dt}$$

绝热条件下 
$$\frac{d \ln \theta}{dt} = 0$$
,  $\Rightarrow \theta = \bar{\theta} + \theta'$ 

$$\Rightarrow \frac{d \ln(\bar{\theta} + \theta')}{dt} = 0$$

$$\frac{1}{\bar{\theta} + \theta'} \frac{d(\bar{\theta} + \theta')}{dt} = 0$$

$$\frac{1}{\bar{\theta}}(\frac{d\bar{\theta}}{dt} + \frac{d\theta'}{dt}) = 0$$

# 热力学方程



$$\frac{1}{\bar{\theta}}\frac{d\theta'}{dt} + \frac{1}{\bar{\theta}}(\frac{\partial\bar{\theta}}{\partial t} + u\frac{\partial\bar{\theta}}{\partial x} + v\frac{\partial\bar{\theta}}{\partial y} + w\frac{\partial\bar{\theta}}{\partial z}) = 0$$

$$\frac{1}{\bar{\theta}}\frac{d\theta'}{dt} + \frac{w}{\bar{\theta}}\frac{\partial\bar{\theta}}{\partial z} = 0 \implies \frac{d\theta'}{dt} = -w\frac{\partial\bar{\theta}}{\partial z}$$

## 可用于稳定度分析

$$\frac{1}{\bar{\theta}}\frac{d\theta'}{dt} + sw = 0$$

# 中小尺度天气方程组



$$\frac{du}{dt} = -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial x} + fv$$

$$\frac{dv}{dt} = -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial y} - fu$$

$$\frac{dw}{dt} = -\frac{1}{\bar{\rho}} \frac{\partial p'}{\partial z} - \frac{\rho'}{\bar{\rho}} g$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\frac{p'}{\bar{p}} = \frac{\rho'}{\bar{\rho}} + \frac{T'}{\bar{T}} \implies -\frac{\rho'}{\bar{\rho}} \approx \frac{T'}{\bar{T}}$$

$$\frac{d\theta'}{\bar{\rho}} = -\frac{w}{\bar{\rho}} \frac{\partial \bar{\theta}}{\partial z}$$

### 适用于发生在浅层 内的中尺度运动:

积云对流、海陆风 、边界层急流中的 重力波等。

# Anelastic近似方程组



$$\frac{\mathbf{D}\boldsymbol{v}}{\mathbf{D}t} + 2\boldsymbol{\Omega} \times \boldsymbol{v} = \mathbf{k}b_a - \nabla \boldsymbol{\phi}$$

$$\frac{\mathbf{D}b_a}{\mathbf{D}t} = 0$$

$$\nabla \cdot (\tilde{\rho}\boldsymbol{v}) = 0$$