

### Generative Zero-Shot Learning for Semantic Segmentation of 3D Point Clouds

Poster presentation - 3DV 2021

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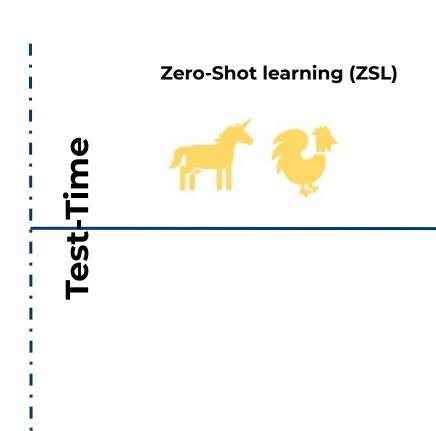


#### **Zero-Shot learning**

Training







VALEO RESERVED

#### **Zero-Shot learning**

## **Frainin**g





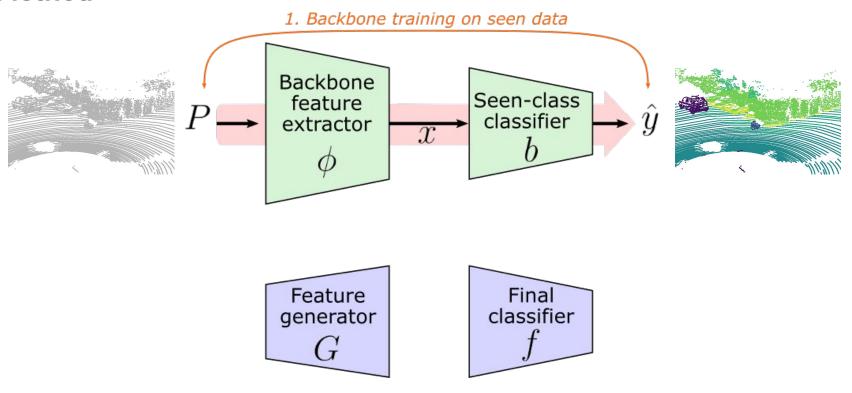
# **Zero-Shot learning (ZSL)**

**Generalized Zero-Shot learning (GZSL)** 

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VALEO RESERVED Valeo

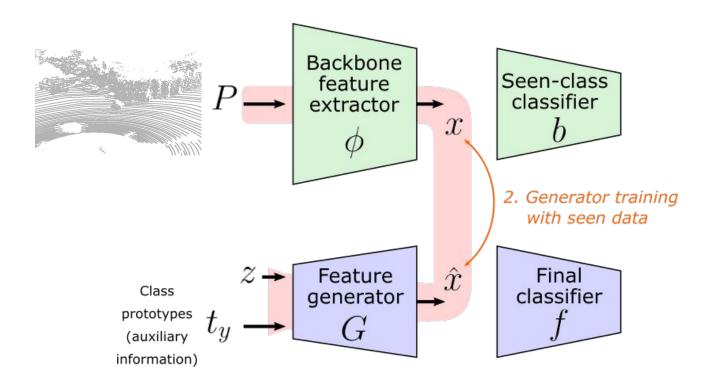
#### Method<sup>1)</sup>



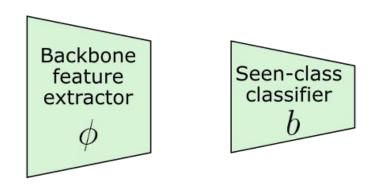
1) Adapted from:

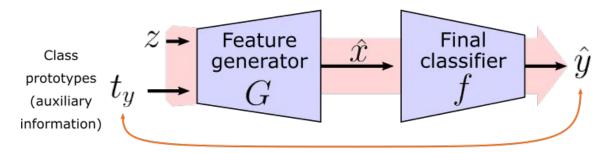
Bucher et al. Generating visual representations for zero-shot classification. ICCV, 2017. Bucher et al. Zero-shot semantic segmentation. NeurIPS, 2019.

#### Method



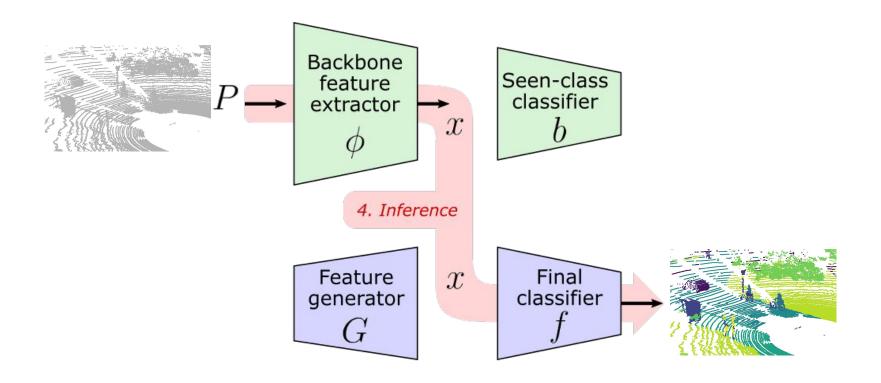
#### Method





3. Classifier training on generated unseen data (+ seen for GZSL)

#### Method



#### **Bias problem GZSL**

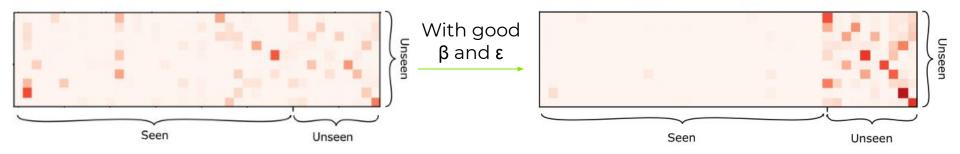
Confusion matrix for unseen classes (GZSL on Modelnet40)



#### Bias problem and reduction

Additional bias reduction techniques

- Class-dependant weighting: Loss for unseen classes is weighted (factor  $\beta > 1$ ) in classifier training.
- Calibrated Stacking<sup>1)</sup>: Subtracting a small value ε from the seen-class score (after softmax) at test time.



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#### **Visualisations SemanticKITTI**

4 unseen, 15 seen classes

Predicted



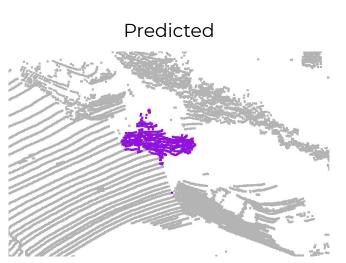
Unseen Class Bicyclist

Ground-Truth

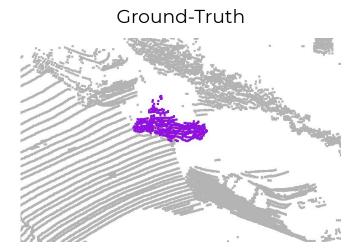


#### **Visualisations SemanticKITTI**

4 unseen, 15 seen classes

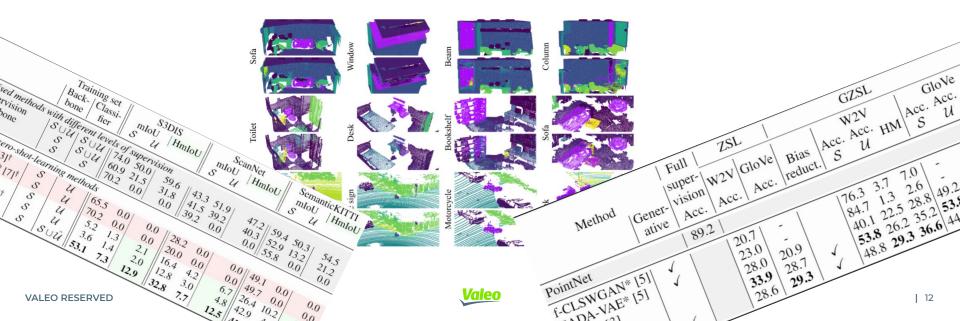


Unseen Class Motorcycle



#### Interested?

- Zero shot learning for 3D point clouds with generative approach:
  - 1. GZSL in **Classification** with additional bias reduction
  - 2. GZSL for **Semantic Segmentation** with 3D PCs on 3 datasets (SemanticKITTI, S3DIS, ScanNet)
- Usage of image-based class prototypes information





SMART TECHNOLOGY FOR SMARTER MOBILITY