

2016 / 9 / 19 (Sat) (0).

$$PTH = (i\sigma_y \nu_x K) \left(\epsilon_0(\vec{k}) \sigma_0 \tau_x \nu_0 + \epsilon'(\vec{k}) \sigma_0 \tau_0 \nu_0 + \epsilon_{id}(\vec{k}) \sigma_z \tau_y \nu_0 \right. \\ \left. + t_c \tau_x \sigma_0 \nu_x + t'_c \tau_y \sigma_z \nu_x \right)$$

$$= \epsilon_0(\vec{k}) i\sigma_y \nu_0 \tau_x + \epsilon'(\vec{k}) i\sigma_y \nu_x \tau_0 + \epsilon_{id}(-\sigma_x)(-\tau_y) \nu_x \\ + t_c \tau_x i\sigma_y + t'_c (-\tau_y)(-\sigma_x)$$

$$HPT = \left(\epsilon_0(\vec{k}) \sigma_0 \tau_x \nu_0 + \epsilon'(\vec{k}) \sigma_0 \tau_0 \nu_0 + \epsilon_{id}(\vec{k}) \sigma_z \tau_y \nu_0 \right. \\ \left. + t_c \tau_x \sigma_0 \nu_x + t'_c \tau_y \sigma_z \nu_x \right) (i\sigma_y \nu_x K)$$

$$= \left(\epsilon_0(\vec{k}) i\sigma_y \tau_x \nu_x + \epsilon'(\vec{k}) i\sigma_y \tau_0 \nu_x + \epsilon_{id}(\vec{k}) \sigma_x \tau_y \nu_x \right. \\ \left. + t_c \tau_x i\sigma_y + t'_c \tau_y \sigma_x \right)$$

$$[H, PT] = 0.$$

$$G_x H = (i\sigma_x) \left(\epsilon_0(\vec{k}) \sigma_0 \tau_x \nu_0 + \epsilon'(\vec{k}) \sigma_0 \tau_0 \nu_0 + \epsilon_{id}(\vec{k}) \sigma_z \tau_y \nu_0 \right. \\ \left. + t_c \tau_x \sigma_0 \nu_x + t'_c \tau_y \sigma_z \nu_x \right)$$

$$HG_x = \left(\epsilon_0(\vec{k}) \sigma_0 \tau_x \nu_0 + \epsilon'(\vec{k}) \sigma_0 \tau_0 \nu_0 + \epsilon_{id}(\vec{k}) \sigma_z \tau_y \nu_0 \right. \\ \left. + t_c \tau_x \sigma_0 \nu_x + t'_c \tau_y \sigma_z \nu_x \right) (i\sigma_x)$$

2016 / 9 / 19 (2) (1).

$$|J_z = \frac{1}{2}\rangle = \frac{1}{\sqrt{3}} \left(|d_{yz} \downarrow\rangle + i |d_{zx} \downarrow\rangle + |d_{xy} \uparrow\rangle \right)$$

$$PT |J_z = \frac{1}{2}\rangle = \frac{1}{\sqrt{3}} \left(PT |d_{yz} \downarrow, A\rangle - i PT |d_{zx} \downarrow, A\rangle + PT |d_{xy} \uparrow, A\rangle \right)$$

$$= \frac{1}{\sqrt{3}} \left(|d_{yz} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^*$$

$$- i |d_{zx} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^*$$

$$- |d_{xy} \downarrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right)$$

$$P: (x, y, t) \rightarrow (-x+\frac{1}{2}, -y+\frac{1}{2}, t) \times \nu_x \tau_x$$

$$T: (x, y, t) \rightarrow (x, y, -t) \times i \sigma_y K$$

$$G_x: (x, y, t) \rightarrow (-x+\frac{1}{2}, +y+\frac{1}{2}, t) \times i \sigma_x \tau_x$$

$$G_y: (x, y, t) \rightarrow (x+\frac{1}{2}, -y+\frac{1}{2}, t) \times i \sigma_y \tau_x$$

$$S_x = G_y P: (x, y, t) \xrightarrow{P} (-x+\frac{1}{2}, -y+\frac{1}{2}, t) \times \nu_x \tau_x \xrightarrow{G_y} (-x+\frac{1}{2}, y, t) \times i \sigma_y \nu_x$$

$$M_z: (x, y, t) \rightarrow (x+\frac{1}{2}, y+\frac{1}{2}, t) \times i \sigma_z \nu_x \tau_x$$

$$PT: (x, y, t) \rightarrow (-x+\frac{1}{2}, -y+\frac{1}{2}, -t) \times i \sigma_y \nu_x \tau_x K.$$

2016/9/19 (Eq) (2).

$$G_x PT |J_z = \frac{1}{2}\rangle = \frac{1}{\sqrt{3}} \left(G_x |d_{yz} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right. \\ \left. - i G_x |d_{zx} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right. \\ \left. - \underset{G_x}{\sqrt{2}} |d_{xy} \downarrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right)$$

$$= \frac{1}{\sqrt{3}} \left(+i |d_{yz} \uparrow, A, \nu=2, x, -y+1, -t\rangle^* \right. \\ \left. - |d_{zx} \uparrow, A, \nu=2, x, -y+1, -t\rangle^* \right. \\ \left. + i |d_{xy} \downarrow, A, \nu=2, x, -y+1, -t\rangle^* \right)$$

$$G_x |J_z = \frac{1}{2}\rangle = \frac{1}{\sqrt{3}} \left(G_x |d_{yz} \downarrow\rangle + i G_x |d_{zx} \downarrow\rangle + G_x |d_{xy} \uparrow\rangle \right) \\ = \frac{1}{\sqrt{3}} \left(i |d_{yz} \downarrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right. \\ \left. + |d_{zx} \downarrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right. \\ \left. - i |d_{xy} \uparrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right)$$

$$PT G_x |J_z = \frac{1}{2}\rangle = \frac{1}{\sqrt{3}} \left(-i PT |d_{yz} \downarrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right. \\ \left. + PT |d_{zx} \downarrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right. \\ \left. + i PT |d_{xy} \uparrow, B, \nu=1, -x+\frac{1}{2}, y+\frac{1}{2}, t\rangle \right)$$

$$= \frac{1}{\sqrt{3}} \left(-i |d_{yz} \uparrow, A, \nu=2, x, -y, -t\rangle^* \right. \\ \left. + |d_{zx} \uparrow, A, \nu=2, x, -y, -t\rangle^* \right. \\ \left. - i |d_{xy} \downarrow, A, \nu=2, x, -y, -t\rangle^* \right)$$

$G_x PT |J_z = \frac{1}{2}\rangle$
 $= -e^{iky} PT G_x |J_z = \frac{1}{2}\rangle$

2016/9/19 P2 (3).

$$\begin{aligned}
 S_x P_T |J_z = \frac{1}{2}\rangle &= \frac{1}{\sqrt{3}} \left(S_x |d_{yz} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right. \\
 &\quad - i S_x |d_{zx} \uparrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \\
 &\quad \left. - S_x |d_{xy} \downarrow, B, \nu=2, -x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right) \\
 &= \frac{1}{\sqrt{3}} \left(- |d_{yz} \downarrow, B, \nu=1, x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right. \\
 &\quad - i |d_{zx} \downarrow, B, \nu=1, x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \\
 &\quad \left. + |d_{xy} \uparrow, B, \nu=1, x+\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right)
 \end{aligned}$$

$$\begin{aligned}
 S_x |J_z = \frac{1}{2}\rangle &= \frac{1}{\sqrt{3}} \left(|d_{yz} \uparrow, A, \nu=2, -x+1, y, t\rangle \right. \\
 &\quad - i |d_{zx} \uparrow, A, \nu=2, -x+1, y, t\rangle \\
 &\quad \left. + |d_{xy} \downarrow, A, \nu=2, -x+1, y, t\rangle \right)
 \end{aligned}$$

$$\begin{aligned}
 P_T S_x |J_x = \frac{1}{2}\rangle &= \frac{1}{\sqrt{3}} \left(P_T |d_{yz} \uparrow, A, \nu=2, -x+1, y, t\rangle \right. \\
 &\quad + i P_T |d_{zx} \uparrow, A, \nu=2, -x+1, y, t\rangle \\
 &\quad \left. + P_T |d_{xy} \downarrow, A, \nu=2, -x+1, y, t\rangle \right)
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{\sqrt{3}} \left(- |d_{yz} \downarrow, B, \nu=1, x-\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right. \\
 &\quad - i |d_{zx} \downarrow, B, \nu=1, x-\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \\
 &\quad \left. + |d_{xy} \uparrow, B, \nu=1, x-\frac{1}{2}, -y+\frac{1}{2}, -t\rangle^* \right)
 \end{aligned}$$

$$S_x P_T |J_z = \frac{1}{2}\rangle = e^{-ik_x} P_T S_x |J_z = \frac{1}{2}\rangle$$

At $k_x = \pi$

$$S_x P_T = - P_T S_x$$