

PHYSICS 200B: ELECTROMAGNETISM I

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Lecture 1.

Tuesday, January 7, 2020

Note. This course will have discussion sections! I will not be writing notes for those since they're like homework. Exams will be closed-book but with a formula sheet—two pages, front and back, typed okay. The final exam can be moved with signed consent of all students.

The textbook for this course is Zangwill *Modern Electrodynamics*. The plan is to cover chapters 1-13, mostly electrostatics and magnetostatics (time-independent stuff). Homeworks due Tuesdays apart from the very last one, which is due Thursday.

Most of Chapter 1 of Zangwill is mathematical preliminaries. Chapter 2 is largely a review of Maxwell's equations. There is one important auxiliary to the Maxwell equations, though, and it's the *continuity equation*,

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{j} = 0. \quad (1.1)$$

This equation just says there's stuff (ρ) and the stuff can flow in a way defined by the vector field \mathbf{j} . The divergence $\nabla \cdot \mathbf{j}$ tells us how much charge is flowing out of a point, on average.

To review, the first two Maxwell's equations are the following:

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad (1.2)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (1.3)$$

The next one we might guess is

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j}, \quad (1.4)$$

that current flow sources magnetic fields. This equation can't be quite right, because if we take the divergence, the divergence of a curl always vanishes, so

$$0 = \nabla \cdot (\nabla \times \mathbf{B}) = \mu_0 \nabla \cdot \mathbf{j}, \quad (1.5)$$

which by the continuity equation says that $\frac{\partial \rho}{\partial t} = 0$ everywhere. That seems nonphysical, so let us amend the equation by adding a \mathbf{j}_D term, called the *displacement current*. That is,

$$0 = \mathbf{j}_D + \mu_0 \left(-\frac{\partial \rho}{\partial t} \right) = -\mu_0 \epsilon_0 \nabla \cdot \frac{\partial \mathbf{E}}{\partial t} + \mathbf{j}_D. \quad (1.6)$$

This *defines* the displacement current as

$$\mu_0 \epsilon_0 \nabla \cdot \frac{\partial \mathbf{E}}{\partial t} = \mathbf{j}_D, \quad (1.7)$$

and since we recall that $\mu_0 \epsilon_0 = \frac{1}{c^2}$, we can rewrite what we recognize as Ampère's law as

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}. \quad (1.8)$$

The last Maxwell equation is Faraday's law,

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}. \quad (1.9)$$

These are Maxwell's equations in vacuum, and they can be modified to describe fields in materials with some little tweaks.

There's also a "glitch" in Zangwill's exposition. In the text, Zangwill mentions that Maxwell wrote down 12 equations prior to the development of vector notation (relating each of the components), but in fact he wrote down *eight*. Why eight? Each of the curl equations is a vector equation (three components), but each of the divergence equations is only one (a scalar equation). Hence $2 \times 3 + 2 \times 1 = 8$.

Altogether, we have the differential forms of Maxwell's equations,

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad (1.10)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (1.11)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (1.12)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}. \quad (1.13)$$

We should also be familiar with the integral forms of the Maxwell equations,

$$\int \mathbf{E} \cdot d\mathbf{S} = \frac{1}{\epsilon_0} Q_{\text{enc}} \quad (1.14)$$

$$\int \mathbf{B} \cdot d\mathbf{S} = 0 \quad (1.15)$$

$$\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int \mathbf{B} \cdot d\mathbf{S} \quad (1.16)$$

$$\oint \mathbf{B} \cdot d\mathbf{L} = \mu_0 I_{\text{enc}} + \frac{1}{c^2} \frac{\partial}{\partial t} \int \mathbf{E} \cdot d\mathbf{S}. \quad (1.17)$$

If we have matter, then the laws need to be adapted because generically, charges and magnetic dipoles reorient themselves based on the applied fields. Materials have electric and magnetic polarizabilities. It's useful to define the total charge as a sum

$$\rho = \rho_f - \nabla \cdot \mathbf{P}, \quad (1.18)$$

where \mathbf{P} is the *polarization vector*. That is, we can put some charge ρ_f on a material, but in general when there's a background applied field, the charges will redistribute themselves. We know this as the fact that charges in a dielectric generically rearrange themselves to oppose the applied field. Recall that \mathbf{P} points from negative to positive charge. Thus a positive divergence of \mathbf{P} acts like a local negative charge.

We can do the same for magnetism, though it's a bit messier.

$$\mathbf{j} = \mathbf{j}_f + \frac{\partial \mathbf{P}}{\partial t} + \nabla \times \mathbf{M}, \quad (1.19)$$

where \mathbf{M} is the *magnetization vector*, which we think of as little magnetic dipoles or eddy currents orienting themselves to minimize their energy. This one depends on the current due to free charge $\mathbf{j}_f = \frac{\partial \rho_f}{\partial t}$, the rate of change of the bound charge from polarization, and the curl of the magnetization.

This leads us to define auxiliary fields:

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} = \epsilon \mathbf{E} \quad (1.20)$$

$$\mathbf{H} = \frac{1}{\mu_0} \mathbf{B} - \mathbf{M} = \frac{1}{\mu} \mathbf{B}. \quad (1.21)$$

For the electric field, the sign conventions (whether to add or subtract \mathbf{p} make sense. It's very natural for the polarization pointing from $-$ to $+$ to add to an effective field \mathbf{D} . But for the magnetic field, it could go either way. Magnets near superconductors induce a magnetization that perfectly cancels the applied field, whereas in ferromagnets like iron, the magnetization is in the same direction as the applied field. We just have to pick a convention and stick to it.

The Maxwell equations in materials take on kind of a nice form:

$$\nabla \cdot \mathbf{D} = \rho_f \quad (1.22)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (1.23)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (1.24)$$

$$\nabla \times \mathbf{H} = \mathbf{j}_f + \frac{\partial \mathbf{D}}{\partial t}. \quad (1.25)$$

Helmholtz theorem The Helmholtz theorem says that if we specify the divergence and curl of a function everywhere, then the function is uniquely defined up to adding functions which have zero divergence and zero curl. Such functions are called *harmonic functions*, which we'll see more later, and whether or not we should add them corresponds to fitting boundary conditions.

We can actually write the electric field explicitly in terms of the divergence and curl:

$$\mathbf{E}(\mathbf{r}) = -\underbrace{\nabla \int d^3 r' \frac{\nabla' \cdot \mathbf{E}(\mathbf{r}')}{4\pi|\mathbf{r} - \mathbf{r}'|}}_{\text{curl}=0} + \underbrace{\nabla \times \int d^3 r' \frac{\nabla' \times \mathbf{E}(\mathbf{r}')}{4\pi|\mathbf{r} - \mathbf{r}'|}}_{\text{div}=0}. \quad (1.26)$$

The second term is actually zero if there is no time dependence, from Faraday's law. If we apply Gauss's law to rewrite $\nabla' \cdot \mathbf{E}$, we recognize what remains as

$$\mathbf{E}(\mathbf{r}) = -\nabla \phi(\mathbf{r}) = -\nabla \int d^3 r' \frac{\rho(\mathbf{r}')}{4\pi\epsilon_0|\mathbf{r} - \mathbf{r}'|} = \frac{1}{4\pi\epsilon_0} \int d^3 r' \frac{\rho(\mathbf{r}')(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}. \quad (1.27)$$

We've recovered Coulomb's law, just written in a more vectorial language.

Let's consider the force on a charge distribution ρ^* due to the field from a distribution ρ . That is,

$$\mathbf{F}(\rho, \rho^*) = \int d^3 r \rho^*(\mathbf{r}) \mathbf{E}(\mathbf{r}) \quad (1.28)$$

$$= \frac{1}{4\pi\epsilon_0} \int d^3 r \int d^3 r' \frac{\rho^*(\mathbf{r}) \rho(\mathbf{r}') (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}. \quad (1.29)$$

But we notice that we can exchange \mathbf{r} and \mathbf{r}' at the cost of picking up a sign flip:

$$\mathbf{F}(\rho, \rho^*) = -\mathbf{F}(\rho^*, \rho). \quad (1.30)$$

If we set $\rho = \rho^*$, then $\mathbf{F}(\rho, \rho) = 0$, which tells us that a charge distribution cannot exert a net force on itself.

Finally, let's introduce potentials. The electric field in electrostatics can be written as the gradient of the scalar potential,

$$\mathbf{E} = -\nabla \phi, \quad (1.31)$$

so that

$$\frac{\rho}{\epsilon_0} = \nabla \cdot \mathbf{E} = -\nabla \cdot \nabla \phi = -\nabla^2 \phi. \quad (1.32)$$

The equation

$$\nabla^2 \phi = -\frac{\rho}{\epsilon_0} \quad (1.33)$$

is hopefully familiar to us as Poisson's equation, and the homogeneous case ($\rho = 0$) is

$$\nabla^2 \phi = 0, \quad (1.34)$$

which is Laplace's equation.

Lecture 2.

Thursday, January 9, 2020

Today we'll start our discussion with Gauss's law, moving rapidly into chapter 3 of Zangwill. Gauss's law lets us calculate electric fields rapidly for situations with high amounts of symmetry. Basically, we can solve systems with spherical symmetry, cylindrical symmetry, and translational plane symmetry. It doesn't get us too far but it's a lot better than Coulomb's law volume integrals.

As we know, Gauss's law (differential form) states

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}, \quad (2.1)$$

or in integral form

$$\oint_S \mathbf{E} \cdot d\mathbf{A} = \int_V \nabla \cdot \mathbf{E} d^3r = \int_V \frac{\rho}{\epsilon_0} d^3r = \frac{Q_{\text{enc}}}{\epsilon_0}. \quad (2.2)$$

The simplest example is for the point charge. For a single positive charge $q > 0$, we can reason that the field must point radially outwards and it is constant at surfaces of constant R , so that

$$\oint_S \mathbf{E} \cdot d\mathbf{Q} = |E| 4\pi R^2 = \frac{q}{\epsilon_0}, \quad (2.3)$$

which yields

$$\mathbf{E} = \frac{1}{4\pi R^2 \epsilon_0} \hat{\mathbf{r}}. \quad (2.4)$$

Gauss's law also gives us a nice result (sometimes known as Newton's shell theorem), which says that the electric field due to a spherically symmetric shell of charge *inside* that shell ($r < R$) is zero.

We can also do Gauss's law for an infinite plane by drawing a Gaussian pillbox, say, extending a height h above and below the plane. Rotational symmetry lets us reason that the field can only point in the normal direction to the plane, while reflection symmetry says its magnitude is the same equal distances above and below the plane. It follows that

$$\oint_S \mathbf{E} \cdot d\mathbf{A} = \frac{1}{\epsilon_0} \sigma A, \quad (2.5)$$

where A is the area of the face of the Gaussian pillbox. Since the field is normal to the plane and the faces of the pillbox are oriented outwards, we have

$$\oint_S \mathbf{E} \cdot d\mathbf{A} = 2E(h)A, \quad (2.6)$$

so that

$$\mathbf{E}(h) = \begin{cases} \frac{\sigma}{2\epsilon_0} \hat{\mathbf{z}} & z > 0 \\ -\frac{\sigma}{2\epsilon_0} \hat{\mathbf{z}} & z < 0. \end{cases} \quad (2.7)$$

The reason there is no h dependence is because the infinite plane is scale-invariant. If we rescale all the coordinates, the infinite plane still looks like an infinite plane. This result isn't necessarily useful to us because real life is filled with infinite planes of charge, or even because the problem is exactly solvable; rather, it's because any reasonably smooth (in the mathematical sense) surface looks locally flat, which means that near the surface, we have essentially the field from an infinite plane.

By the same Gaussian pillbox arguments, we find that E_{\parallel} is continuous at surfaces of charge, while E_{\perp} is discontinuous by $\frac{\sigma}{\epsilon_0}$. How should we calculate the force on a little surface of charge, given that the electric field is discontinuous above and below the field? Well, we can just take the average. This seems physically reasonable, but we can justify it. Remember the discontinuity comes from the charge at the surface itself,

and as we showed last time, charges cannot exert forces on themselves. So if we average above and below the surface, we will basically average away the contribution of the charged surface itself and get the right answer.

We can also state Earnshaw's theorem— in a closed region with no charge, any extrema of the potential must be on the boundary. For suppose there was a local maximum of the potential in the interior. The gradient of the potential vanishes at that point, and a little bit away we can draw a Gaussian surface it is pointing towards that point everywhere. It follows that the \mathbf{E} -field points away everywhere, so our integral $\oint_S \mathbf{E} \cdot d\mathbf{A} > 0$, which violates our assumption that there was no charge in the region.¹ This tells us that we cannot make an electrostatic cage; no charge distribution can hold itself in a static configuration under Coulomb interactions alone. Earnshaw's theorem has told us that any charge dropped in a region with no other charge will move to the edges of that region, since it cannot sit at an extremum.

Potential and potential energy For our purposes, we will follow Zangwill and denote potential energy by V and electrostatic potential by φ . We say the potential energy changes as

$$\delta V = -\mathbf{F} \cdot d\mathbf{s} \quad (2.8)$$

for small displacements, i.e.

$$\mathbf{F} = -\nabla V. \quad (2.9)$$

In addition, when forces are due only to electric fields, then

$$\mathbf{F} = q\mathbf{E} = -q\nabla\varphi \implies V = q\varphi. \quad (2.10)$$

Hence the electrostatic potential is the energy per charge.

Let's now prove Green's reciprocity relation for the potential energy. That is, suppose there are two charge distributions ρ_1, ρ_2 . The energy of ρ_2 in the potential φ_1 created by ρ_1 is

$$V = \int d^3r \rho_2(\mathbf{r}) \varphi_1(\mathbf{r}), \quad (2.11)$$

such that

$$\delta V = \int d^3r [\rho_2(\mathbf{r} - \delta\mathbf{s}) - \rho_2(\mathbf{r})] \varphi_1(\mathbf{r}). \quad (2.12)$$

The minus sign comes from that active/passive transformation jazz. If the distribution is moved by $\delta\mathbf{s}$, then looking at the "same" point in space \mathbf{r} for the new distribution is equivalent to looking at the original distribution at a point $\mathbf{r} - \delta\mathbf{s}$.

We can now Taylor expand as $\delta\mathbf{s}$ gets small, such that

$$\delta V \approx -\delta\mathbf{s} \cdot \int d^3r (\nabla \rho_2(\mathbf{r})) \varphi_1(\mathbf{r}) = -\delta\mathbf{s} \cdot \int d^3r (\nabla(\rho_2 \varphi_1) - \rho_2 \nabla \varphi_1), \quad (2.13)$$

after a product rule manipulation (basically an integration by parts). Now this first term is a total derivative, so it vanishes as we take our integration region d^3r to be all space. What's left is

$$\delta V = -\delta\mathbf{s} \cdot \int d^3r \rho_2(\mathbf{r}) \mathbf{E}_1(\mathbf{r}). \quad (2.14)$$

Let us rewrite this energy in a different way:

$$V = \int d^3r \rho_2(\mathbf{r}) \varphi_1(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int d^3r \int d^3r' \rho_2(\mathbf{r}) \frac{\rho_1(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|}. \quad (2.15)$$

But notice that this integral is manifestly symmetric in \mathbf{r} and \mathbf{r}' (i.e. $|\mathbf{r} - \mathbf{r}'| = |\mathbf{r}' - \mathbf{r}|$). This certainly converges, so we can switch the order of integration and do the d^3r integral first to find

$$V = \int d^3r \rho_2(\mathbf{r}) \varphi_1(\mathbf{r}) = \int d^3r' \rho_1(\mathbf{r}') \varphi_2(\mathbf{r}'). \quad (2.16)$$

This relation means that the energy in an electrostatic charge distribution doesn't depend on how we build it, only on the final geometry.

Consider the following example.

¹One can also argue this directly from the form of Laplace's equation.

Example 2.17. Suppose we have a spherical region of radius R centered on the origin with no charge inside. As it turns out, the potential at the center is the average potential on the surface:²

$$\varphi(0) = \frac{1}{4\pi R^2} \int dS \varphi(\mathbf{r}). \quad (2.18)$$

Can we use Green's reciprocity relation to find this result? Take

$$\varphi_1 = \varphi, \quad \rho_1 = \rho; \quad \rho_2(\mathbf{r}) = \frac{q}{4\pi R^2} \delta(r - R). \quad (2.19)$$

Then

$$\varphi_2 = \begin{cases} \frac{q}{4\pi\epsilon_0 r} & r \geq R, \\ \frac{q}{4\pi\epsilon_0 R} & r \leq R. \end{cases} \quad (2.20)$$

It follows that

$$\int d^3r \frac{q}{4\pi R^2} \delta(r - R) \varphi(\mathbf{r}) = \int d^3r \rho(\mathbf{r}) \varphi_2(\mathbf{r}) = \int_R^\infty r^2 dr \int d\Omega \rho(\mathbf{r}) \frac{q}{4\pi\epsilon_0 r}. \quad (2.21)$$

But this last expression up the the factor of q is exactly the integral we would use to compute the potential at the origin. That is,

$$\int_R^\infty r^2 dr \int d\Omega \rho(\mathbf{r}) \frac{q}{4\pi\epsilon_0 r} = q\varphi(\mathbf{r} = 0). \quad (2.22)$$

Meanwhile, the LHS says that we just integrate

$$\int d^3r \frac{q}{4\pi R^2} \delta(r - R) \varphi(\mathbf{r}) = \frac{q}{4\pi R^2} \int dS \varphi(\mathbf{r}). \quad (2.23)$$

Cancelling the factors of q , we have exactly the desired result. The potential at the center of the sphere is equal to the average potential on its surface.

We can write the potential energy of a charge distribution as

$$U_E = \frac{1}{4\pi\epsilon_0} \sum_{j=1}^N \sum_{i>j}^N \frac{q_i q_j}{|\mathbf{r}_i - \mathbf{r}_j|} \quad (2.24)$$

or for continuous distributions,

$$U_E = \frac{1}{8\pi\epsilon_0} \int d^3r \int d^3r' \frac{\rho(\mathbf{r})\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} = \frac{1}{2} \int d^3r \rho(\mathbf{r}) \varphi(\mathbf{r}) \quad (2.25)$$

Note that for all-positive or all-negative distributions of charges, these formulae make it clear that the energy of assembling the distribution is positive-definite. The answer is somewhat less clear when we have a mix of charges. Let's manipulate this result to see what happens.

$$\begin{aligned} U_E &= \frac{1}{2} \int d^3r \rho(\mathbf{r}) \varphi(\mathbf{r}) \\ &= \frac{1}{2} \int d^3r \epsilon_0 \nabla \cdot \mathbf{E} \varphi(\mathbf{r}) \\ &= \frac{\epsilon_0}{2} \int d^3r (\nabla \cdot (\mathbf{E} \varphi) - \mathbf{E} \cdot (\nabla \varphi)) \\ &\rightarrow \frac{\epsilon_0}{2} \int d^3r |\mathbf{E}|^2 \end{aligned}$$

where the last step is taking the limit as the region of integration becomes all space, and the total derivative term goes away.

So U_E for continuous distributions defined in this way is *positive-definite*. How does this square with our idea that we could just bring one positive and one negative charge together? Well, it takes energy to assemble the charges in the first place. In fact, one can check that the energy of a point charge is divergent since it's a finite amount of charge squished into a single point of space. Part of the energy in this expression (summing up the energy in the E-field) comes from actually assembling the charge distribution, and we'll get some practice with this on the homework.

²Again, this is a property of Laplace's equation. For a good reference on this, see Evans *Partial Differential Equations*, section 2.2.2.

Tuesday, January 14, 2020

Multipole expansion Today we're moving into Chapter 4 of Zangwill, on multipoles. Multipoles are a way of thinking about the field of a charge distribution far away from that distribution. For instance, if there is a net charge in that distribution, far away we have a field that decays as $1/r^2$, like the field of a point charge.

Suppose we have a charge distribution $\rho(\mathbf{r}')$ contained entirely within a sphere of radius R . That is, $\rho(\mathbf{r}') = 0$ for $|\mathbf{r}'| > R$. Then we can look at a point \mathbf{r} outside the sphere with $|\mathbf{r}| > R$. Well, our potential is just given by

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int d^3r' \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|}, \quad (3.1)$$

and we'd like to expand the denominator when $|\mathbf{r}| \gg |\mathbf{r}'|$. Our expansion looks like

$$\frac{1}{|\mathbf{r} - \mathbf{r}'|} \approx \frac{1}{r} - \mathbf{r}' \cdot \nabla \frac{1}{r} + \frac{1}{2} (\mathbf{r}' \cdot \nabla)^2 \frac{1}{r} - \dots \quad (3.2)$$

If we're being careful we should really expand in r'/r as a small parameter. The derivatives are all with respect to unprimed coordinates, and then the \mathbf{r}' determines which direction we're looking. This is much better in index notation. With the Einstein summation convention (i.e. sum over repeated indices), this becomes

$$\frac{1}{|\mathbf{r} - \mathbf{r}'|} \approx \frac{1}{r} - r'_i \nabla_i \frac{1}{r} + \frac{1}{2} r'_i r'_j \nabla_i \nabla_j \frac{1}{r} + \dots \quad (3.3)$$

If we plug this expansion back into the expression for the potential, we get

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \left\{ \underbrace{\left[\int d^3r' \rho(\mathbf{r}') \right]}_{\text{monopole}=Q} \frac{1}{r} - \underbrace{\left[\int d^3r' \rho(\mathbf{r}') r'_i \right]}_{\text{dipole}=\mathbf{p}} \partial_i \frac{1}{r} + \underbrace{\left[\frac{1}{2} \int d^3r' \rho(\mathbf{r}') r'_i r'_j \right]}_{\text{quadrupole}=Q_{ij}} \nabla_i \nabla_j \frac{1}{r} + \dots \right\} \quad (3.4)$$

A note on tensors. Tensors are like collections of numbers that have special properties under coordinate transformations. A rank 1 tensor is just a vector; we need only one number to label which component we are looking at. So if we write a vector $\mathbf{v} = (a, b, c)$ then we can also write its components v_i such that $v_1 = a, v_2 = b, v_3 = c$.

Similarly matrices are rank two tensors—we need two index labels to say which element we are looking at. That is, a 3×3 matrix requires two index labels to pick out an element, a row and a column. We can guess what a rank three tensor looks like, i.e. some sort of cube of numbers. After rank three it's best to just think of these in the abstract. However, not any collection of numbers is a tensor. Each row and column of a matrix must transform like a vector.

Note that many of the complications of working with tensors (e.g. where do you put the indices, up or down?) will drop out when we work in flat Cartesian coordinates.

Can we study the limiting behavior of this expansions? Sure, if we perform some dimensional analysis. We took our charge to be confined to a sphere of radius R ; the monopole moment is independent of R , while the dipole and quadrupole components scale as

$$p_i \sim QR, \quad Q_{ij} \sim QR^2. \quad (3.5)$$

Derivatives with respect to the \mathbf{r} unprimed coordinates act like $1/r$, so our approximation looks like

$$\varphi(r) \sim \frac{1}{4\pi\epsilon_0} \left[\frac{Q}{r} - \frac{QR}{r^2} + \frac{QR^2}{r^3} + \dots \right]. \quad (3.6)$$

If we work out the derivatives, we get

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \left\{ \frac{Q}{r} + \frac{p_i r_i}{r^3} + Q_{ij} \frac{3r_i r_j - r^2 \delta_{ij}}{r^5} + \dots \right\} \quad (3.7)$$

Let us find the field of the dipole term far away.

$$\mathbf{E} = -\nabla \varphi_{\text{dipole}} \quad (3.8)$$

$$= -\frac{1}{4\pi\epsilon_0} \nabla \left(\frac{\mathbf{p} \cdot \mathbf{r}}{r^3} \right). \quad (3.9)$$

We will write this vector in terms of its components. Note that $\partial_i r = \partial_i \sqrt{x^2 + y^2 + z^2} = \frac{r_i}{\sqrt{x^2 + y^2 + z^2}} = r_i/r$. Then

$$\begin{aligned} E_i &= -\frac{1}{4\pi\epsilon_0} \partial_i \left(\frac{p_j r_j}{r^3} \right) \\ &= -\frac{1}{4\pi\epsilon_0} \left[p_j \frac{\delta_{ij}}{r^3} - \frac{3p_j r_j}{r^4} \partial_i r \right] \\ &= -\frac{1}{4\pi\epsilon_0} \left[p_j \frac{\delta_{ij}}{r^3} - \frac{3p_j r_j r_i}{r^5} \right] \\ &= \frac{1}{4\pi\epsilon_0} \left[\frac{\mathbf{p} \cdot \mathbf{r}}{r^5} r_i - \frac{p_i}{r^3} \right]. \end{aligned}$$

Equating these as vectors gives

$$\mathbf{E} = \frac{1}{4\pi\epsilon_0} \left[\frac{3\mathbf{p} \cdot \hat{\mathbf{r}}}{r^3} \hat{\mathbf{r}} - \frac{\mathbf{p}}{r^3} \right]. \quad (3.10)$$

One can model a physical dipole as two charges, one $+q$ and one $-q$, separated by a distance a and connected by a rigid “rod” of some sort. Then the dipole moment is qa . One can imagine shrinking this dipole down by keeping the product qa fixed while taking $a \rightarrow 0$. In a sense, a dipole is like a derivative of a delta function.

In constant electric fields, there is no net force on a dipole since each of the charges experiences an equal and opposite force. (In general there will be a torque.) It's only when the field is changing that we experience a net force, so we may think of dipoles as sensitive to gradients in the field.

The quadrupole The quadrupole moment was defined as

$$Q_{ij} = \frac{1}{2} \int d^3r' (\rho(\mathbf{r}') r'_i r'_j), \quad (3.11)$$

and from this expression we see that $Q_{ij} = Q_{ji}$, e.g. $Q_{12} = Q_{21}$, and so on. It is symmetric, and hence in 3 dimensions there are 6 independent components. If we choose our axes really well, we can diagonalize the quadrupole tensor and just compute three components.

We can also define the *traceless quadrupole tensor* as

$$\Theta_{ij} = 3Q_{ij} - Q_{kk} \delta_{ij}. \quad (3.12)$$

That is, if we take the trace of this, then we get

$$\Theta_{ii} = 3Q_{ii} - Q_{kk} \delta_{ii} = 3Q_{ii} - Q_{kk}(3) = 0, \quad (3.13)$$

since the trace of the Kronecker delta in 3 dimensions is 3. (More generally, it is the dimension of the space in d dimensions.) This will have *five* independent components, since we have imposed one algebraic constraint on the six components (that the trace vanishes).

Why is this useful? Well, we can rewrite the quadrupole potential as

$$\varphi_{\text{quad}}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} Q_{ij} \frac{3r_i r_j - \delta_{ij} r^2}{5} = \frac{1}{4\pi\epsilon_0} \Theta_{ij} \frac{r_i r_j}{r^5}. \quad (3.14)$$

If we ever need to go to higher orders, this trace-free condition becomes really useful, since we can take the trace with respect to any pair of indices, e.g. by setting $Q_{iij} = 0$ or $Q_{ijj} = 0$.

We can write the potential as

$$\frac{Q}{r} + \frac{\mathbf{p} \cdot \hat{\mathbf{r}}}{r^2} + Q_{ij} \frac{3\cos\theta_i \cos\theta_j - \delta_{ij}}{r^3}. \quad (3.15)$$

If we start writing out the expansion terms in spherical coordinates, we find that these are secretly (maybe not so secretly) Legendre and associated Legendre polynomials.

The reason for this is that our potential far away can be built out of solutions to Laplace's equation $\nabla^2\varphi = 0$, since there is no charge there. In 204A, we considered separable solutions to Laplace's equation in spherical coordinates, which we wrote as

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \sum_{m=-l}^l \frac{A_{lm}}{r^{l+1}} Y_{lm}(\theta, \phi). \quad (3.16)$$

It's perhaps not so surprising that the spherical harmonics arise like this. Moreover, if we think about how many A_{lm} we get for fixed l , there are $2l + 1$ choices for m . That is, the quadrupole moment, which corresponds to $l = 2$, really should have five independent components.³

For $l = 3$, we expect $2l + 1 = 7$ components. From the Cartesian perspective, there are a priori $3 \times 3 \times 3 = 27$ components. However, $Q_{ijk} = Q_{jik}$ and so on. Hence we get some different sets of components.

There's

$$Q_{111}, Q_{222}, Q_{333} \quad (3.17)$$

which are unaffected by the symmetry and all independent. There's also sets where all three indices are distinct, e.g.

$$Q_{123}, \quad (3.18)$$

and there are six of these (like Q_{213}), all related to this one by the symmetry. Then there are ones with two identical indices, like

$$Q_{122}, Q_{133}, Q_{112}, Q_{113}, Q_{233}, Q_{223} \quad (3.19)$$

Each of these is related to two other components by symmetry, e.g. $Q_{122} = Q_{212} = Q_{221}$, for a total of $3 \times 6 = 18$ components with two indices the same. Hence $3 + 6 + 18 = 27$.

All the other components are related to the ones we have listed by symmetry, so there are $3 + 1 + 6 = 10$ components. Moreover, if we impose three constraints on the traces

$$T_{iik} = 0, T_{iji} = 0, T_{ijj} = 0, \quad (3.20)$$

then we get $10 - 3 = 7$, which is exactly the right number of components as given by the spherical harmonic coefficients A_{2m} .

Lecture 4.

Thursday, January 16, 2020

It's very useful to note that we can expand angular dependence from the Legendre polynomials P_l in terms of spherical harmonics, i.e.

$$P_l(\hat{\mathbf{r}} \cdot \hat{\mathbf{r}}') = \frac{4\pi}{2l+1} \sum_{m=-l}^l Y_{lm}^*(\theta', \phi') Y_{lm}(\theta, \phi). \quad (4.1)$$

That is, we can express an arbitrary angular dependence in terms of spherical harmonics. For instance,

$$f(\theta, \phi; \theta', \phi') = \sum_{l'=0}^{\infty} \sum_{m=-l'}^{l'} A_{l'm}(\theta', \phi') Y_{l'm}(\theta, \phi), \quad (4.2)$$

where we treat the $A_{l'm}$ as coefficients which depend on "fixing" some choice of θ', ϕ' . That is, $A_{l'm}$ is like picking a choice of coordinates, and in particular choosing f to be the Legendre polynomial $f(\theta, \phi; \theta', \phi') = P_l(\theta, \phi; \theta', \phi')$ tells us that

$$P_l(\theta, \phi; \theta', \phi') = \sum_{m=-l}^l A_{lm}(\theta', \phi') Y_{lm}(\theta, \phi), \quad (4.3)$$

where

$$A_{lm}(\theta', \phi') = \frac{4\pi}{2l+1} Y_{lm}^*(\theta', \phi'). \quad (4.4)$$

³There's also a second solution to Laplace's equation scaling as r^l , but those solutions diverge as $r \rightarrow \infty$, so they represent interior rather than exterior solutions.

That is, the only terms in the sum (4.2) we need are for $l' = l$.

The spherical harmonics Y_{lm} are polynomials in x, y, z of degree l . All terms in a given spherical harmonic either have even degree or odd degree. Moreover, we can make all terms have degree l by inserting $x^2 + y^2 + z^2$ s, since this is equal to $r^2 = 1$ on the unit sphere. For instance,

$$P_2 = \frac{3}{2}z^2 - \frac{1}{2} = \frac{3}{2}z^2 - \frac{1}{2}(x^2 + y^2 + z^2) = z^2 - \frac{1}{2}x^2 - \frac{1}{2}y^2. \quad (4.5)$$

Hence we can always increase the power of a term by 2. Similarly Y_{3m} will contain terms like

$$x^3, y^3, z^3, xyx, xxy, yxx, \dots,$$

and this sort of counting argument is exactly analogous to our multipole expansion and how elements of the tensor were related by symmetry. Then the $x^2 + y^2 + z^2 = 1$ constraint gives us our trace constraints.

We could also make a transformation $x \rightarrow x' \cos \alpha + y' \sin \alpha, y \rightarrow -x' \sin \alpha + y' \cos \alpha$, and we see that under such rotations, the orders of the terms in Y_{lm} don't change. It follows that rotations don't mix Y_{lm} s between different orders l .

Let's now make an argument from completeness using a 2D delta function defined on the surface of a sphere. We'll write it in terms of unit vectors rather than angles to avoid prefactors of the sphere area. Hence we shall assert that the delta function can be expanded in this way,

$$\delta(\hat{\mathbf{v}} - \hat{\mathbf{w}}) = \sum_{l=0}^{\infty} \sum_{m=-l}^l c_{lm}(\hat{\mathbf{w}}) Y_{lm}(\hat{\mathbf{v}}) \quad (4.6)$$

where $Y_{lm}(\hat{\mathbf{v}})$ indicates the spherical harmonic as a function of the angular coordinates of $\hat{\mathbf{v}}$. The (as yet undetermined) coefficients c_{lm} depend on $\hat{\mathbf{w}}$, just as $A_{l'm'}$ depended on θ', ϕ' .

Now we observe that by the orthonormality of the spherical harmonics,

$$\int d\Omega_v \sum_{l=0}^{\infty} \sum_m c_{lm} Y_{lm}(\hat{\mathbf{v}}) Y_{l'm'}^*(\hat{\mathbf{v}}) = c_{lm} \delta_{ll'} \delta_{mm'} = c_{l'm'}(\hat{\mathbf{w}}). \quad (4.7)$$

But this is equivalent to

$$\int d\Omega_v \left(\sum_{l=0}^{\infty} \sum_m c_{lm} Y_{lm}(\hat{\mathbf{v}}) \right) Y_{l'm'}^*(\hat{\mathbf{v}}) = \int d\Omega_v \delta(\hat{\mathbf{v}} - \hat{\mathbf{w}}) Y_{l'm'}^*(\hat{\mathbf{v}}) Y_{l'm'}^*(\hat{\mathbf{v}}) = Y_{l'm'}^*(\hat{\mathbf{w}}) \quad (4.8)$$

It follows that

$$c_{lm}(\hat{\mathbf{w}}) = Y_{lm}^*(\hat{\mathbf{w}}), \quad (4.9)$$

so

$$\delta(\hat{\mathbf{v}} - \hat{\mathbf{w}}) = \sum_{l=0}^{\infty} \sum_{m=-l}^l Y_{lm}(\hat{\mathbf{v}}) Y_{lm}^*(\hat{\mathbf{w}}). \quad (4.10)$$

If we choose $\hat{\mathbf{w}} = \hat{\mathbf{z}}$, i.e. we fix $\hat{\mathbf{w}}$ to point along the z axis, then we have *cylindrical* symmetry, not just spherical. But only the $m = 0$ spherical harmonics have cylindrical symmetry, so in fact

$$\delta(\hat{\mathbf{v}} - \hat{\mathbf{z}}) = \sum_{l=0}^{\infty} Y_{l0}(\hat{\mathbf{v}}) Y_{l0}^*(\hat{\mathbf{z}}). \quad (4.11)$$

Moreover, note that $P_l(\cos \theta = 0) = 1$,

$$Y_{l0} = \sqrt{\frac{2l+1}{4\pi}} P_l, \quad (4.12)$$

so it follows that

$$\delta(\hat{\mathbf{v}} - \hat{\mathbf{z}}) = \sum_{l=0}^{\infty} \frac{2l+1}{4\pi} P_l(\hat{\mathbf{v}} \cdot \hat{\mathbf{z}}). \quad (4.13)$$

It follows that since the LHS of this expression depends only on the difference $\hat{\mathbf{v}} - \hat{\mathbf{z}}$ and the RHS depends only on the dot product $\hat{\mathbf{v}} \cdot \hat{\mathbf{z}}$, this difference is independent of rotating our choice of coordinates, which means that in fact

$$\delta(\hat{\mathbf{v}} - \hat{\mathbf{w}}) = \sum_{l=0}^{\infty} \frac{2l+1}{4\pi} P_l(\hat{\mathbf{v}} \cdot \hat{\mathbf{w}}). \quad (4.14)$$

Equating the boxed equations and taking this order by order in l , we find precisely that

$$P_l(\hat{\mathbf{r}} \cdot \hat{\mathbf{r}}') = \frac{4\pi}{2l+1} \sum_{m=-l}^l Y_{lm}^*(\theta', \phi') Y_{lm}(\theta, \phi), \quad (4.15)$$

which is none other than Eqn. (4.1).

Back to the physics. Recall that Coulomb's law gives us scalar potentials as

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int d^3r' \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|}. \quad (4.16)$$

There's a nice expansion we can use for this inverse separation:

$$\frac{1}{|\mathbf{r} - \mathbf{r}'|} = \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{r'}{r}\right)^l P_l(\hat{\mathbf{r}} \cdot \hat{\mathbf{r}}'), \quad r' < r. \quad (4.17)$$

This is really a very sensible way to *define* the Legendre polynomials. The RHS is an expansion in increasing powers of $1/r$, and purely on dimensional grounds, the RHS must have dimensions of $1/\text{distance}$, which means that increasing powers of $1/r$ must be accompanied by powers of r' . That is, we need powers of r'/r . Plugging in our expansion (4.1) we have

$$\frac{1}{|\mathbf{r} - \mathbf{r}'|} = \frac{1}{r} \sum_{l=0}^{\infty} \sum_{m=-l}^l \frac{4\pi}{2l+1} \left(\frac{r'}{r}\right)^l Y_{lm}(\theta, \phi) Y_{lm}^*(\theta', \phi'). \quad (4.18)$$

Last time, we saw that

$$\varphi(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \sum_{m=-l}^l A_{lm} \frac{Y_{lm}(\theta, \phi)}{r^{l+1}} \implies A_{lm} = \int d^3r' \frac{4\pi}{2l+1} r'^l Y_{lm}^*(\theta', \phi') \rho(\mathbf{r}'). \quad (4.19)$$

The interior solution for Laplace's equation (i.e. the one that doesn't diverge as $r \rightarrow 0$) just replaces $\frac{r'^l}{r^{l+1}} \rightarrow \frac{r^l}{(r')^{l+1}}$, and then the A_{lm} s are modified.

Conductors For our purposes, we will use the terms conductors and metals interchangeably. The charge carriers in a conductor reorganize themselves to respond to external applied fields. Specifically, they configure themselves so that the electric field inside is zero (equivalently, this minimizes the energy in the field). Thus $\mathbf{E} = 0$ inside. On the surface, the electric field is perpendicular to the surface. If this weren't the case, the charge would reshuffle to cancel this.⁴ To sum up,

$$\mathbf{E} = 0 \text{ inside}, \quad (4.20)$$

$$E_{\parallel} = 0 \text{ on surface}. \quad (4.21)$$

It follows from Gauss's law and the definition of potential that

$$\rho = 0, \quad \varphi = \text{constant inside}. \quad (4.22)$$

Let's work out the classic example of a neutral conducting sphere in a constant applied field E_0 . See Fig. 1. The total field in the sphere is therefore the sum of the applied field and the induced field from the rearranged charges in the sphere.

That is, if the applied field is

$$\mathbf{E}_0 = E_0 \hat{\mathbf{z}}, \quad (4.23)$$

then the self-field inside must be $-\mathbf{E}_0 \hat{\mathbf{z}}$. The potential from the induced charge is⁵

$$\varphi_{\text{self}}(r < R, \theta) = E_0 z = E_0 r \cos \theta. \quad (4.24)$$

A priori, the self-field outside is then

$$\varphi_{\text{self}}(r > R, \theta) = \frac{1}{4\pi\epsilon_0} \left[\frac{A_0}{r} + \frac{A_1}{r^2} P_1(\cos \theta) + \frac{A_2}{r^3} P_2(\cos \theta) + \dots \right] \quad (4.25)$$

⁴At least in the absence of an external magnetic field.

⁵This is clearly not constant! Nor should it be. The total potential is constant, and it is the sum of this induced potential and the potential sourcing the applied field.

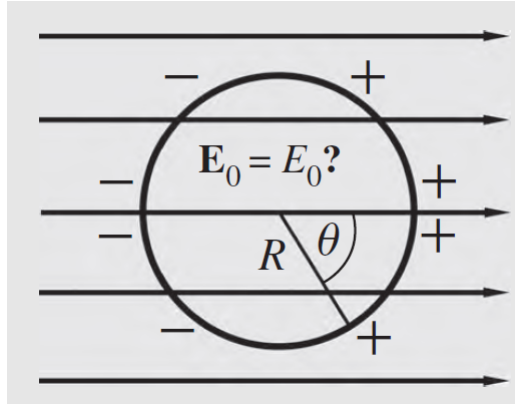


FIGURE 1. Zangwill Fig. 5.2.

We can now use matching conditions. The potential is continuous, so if we take $r = R$ and set φ_{self} inside equal to φ_{self} outside, then

$$E_0 R \cos \theta = \frac{1}{4\pi\epsilon_0} \frac{A_1}{R^2} \cos \theta. \quad (4.26)$$

By the orthogonality of the Legendre polynomials, we can just match order by order in P_l , and if we solve for $A_1/4\pi\epsilon_0$, then

$$\varphi_{\text{self}}(r \geq R, \theta) = E_0 R^3 \frac{\cos \theta}{r^2}. \quad (4.27)$$

This is *exactly* the field of a dipole. The quantity $\mathbf{p} = 4\pi R^3 \epsilon_0 \mathbf{E}$ is the dipole moment of this sphere, where $\alpha = 4\pi R^3$ is called the polarizability. In general, more complicated shapes will have a vanishing monopole moment but some of higher multipole moments.

Suppose now we have some strangely-shaped conductor with a cavity machined out of it, and we place a small (say, positive) charge inside the cavity. Well, what happens to the charge in the conductor? Clearly the inside surface of the cavity must rearrange itself to cancel the field within the conductor. That takes some net negative charge on the inside surface. That is, negative charge accumulates to shield the interior. That charge had to come from somewhere, though. There must be a net positive charge on the exterior surface which rearranges itself in some energetically favorable way. The neat thing is that the solution on the exterior surface doesn't depend at all on the shape of the cavity, or where the charge is placed inside. This is what we mean by shielding. Our conductor hides the details of the interior and reveals only the net charge contained within.