



Common tasks - Get started with Arm Fast Models

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Guide

Non-Confidential

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1. Overview

This guide describes how to download, license, and install Arm Fast Models, and then run an example system with a simple bare-metal hello world software application.

Arm Fast Models are fast, flexible programmer's view models of Arm IP. Fast Models are used to build virtual prototypes for software development. These prototypes are useful during all phases of a project. Virtual prototypes that are built using Fast Models can evolve incrementally, starting with a basic compute subsystem and growing into a comprehensive model of the target hardware. Fast Models are also a great way to learn the details of software development for the Arm architecture.

Ease of use and flexibility make Fast Models an important tool for software developers. Virtual prototype creators construct system models and provide them to software developers to enable early software development. Fast Models are supported on both Linux (Red Hat Enterprise Linux and Ubuntu) and Windows. The supported operating system versions change over time so please check the [Fast Models User Guide on Arm Developer](#) for the currently supported versions.

2. Before you begin

Before you work through this guide, you will need an Arm account. You will use this account for downloads and license creation. If you do not already have an Arm account, register at <https://developer.arm.com/>.

Fast Models is currently supported on Windows 10. Windows users must have Microsoft Visual Studio 2019 installed. Without this compiler, it is not possible to compile and run Fast Model systems.

Fast Models is currently supported on Red Hat Enterprise Linux (RHEL) 7 or 8 and Ubuntu 16.04, 18.04, or 20.04 Long Term Support (LTS). Linux users should have the GNU Compiler Collection installed. Supported g++ versions are 7.3 and 9.3 but there is general compatibility across major versions.

Check the Release Notes inside the Docs directory in your Fast Models installation for the latest operating system and compiler support and any specific requirements around versions and libraries required.

A faster CPU and more memory will generally achieve better simulation performance, but the examples are very small and can run fine on any recent computer.

3. Generate Fast Models product license

In this section of the guide, we will describe how to generate a Fast Models product license. If you already have access to a license, you can skip this section.

Fast Models uses either [User-Based Licensing](#) or [FlexNet Licensing](#). User-based licensing is supported in Fast Models 11.18 and later. For FlexNet licensing, many companies already have a common license server which hosts licenses for multiple products, for example, Arm Compilers, or Electronic Design Automation (EDA) tools. Check with your license administrator to find out whether Fast Models licenses are available for you or if new licenses can be added to a common license server. If a server exists but does not have Fast Model licenses, ask for the hostid of the server.

If you need a FlexNet license, [contact support](#) to request a 30-day trial license for Fast Models.

If you request a license, we will send you a serial number. When you have your serial number, follow these steps to create your own license:

1. Download and install the FlexNet software if it is not already installed and available on your network, and set up a Windows or Linux machine as a license server following the instructions here: [How do I install my license for my FlexNet Publisher license managed tools?](#).
2. Visit [Software Licensing](#) to generate a license file. This area allows license files to be generated, previous license files to be viewed and retrieved, and other operations like merging multiple files or moving licenses to a different server. All activity is connected to the Arm Developer account that is associated with the license.
3. Click Generate and enter the serial number that you have been issued, and the hostid where you set up the Flex tools. This will generate a license file.
4. Download the license file to the machine where the license server will run. A common name for the file is license.dat, but you can use any file name.
5. Edit the license file and start the license server as described in [How do I install my license for my FlexNet Publisher license managed tools?](#).
6. To learn more about licensing, visit the [FAQ](#) where you can find solutions for many common problems with licensing.

4. Download and install Fast Models for Windows or Linux

In this section of the guide, we will describe the steps that are required to download and install Fast Models for Windows and Linux.

Follow these steps:

1. Navigate to the [Fast Models page on Arm Developer](#) and the Evaluate buttons for Linux and Windows. The packages that these link to are the complete Fast Models product, there is no functional difference implied by the evaluation label.

Arm typically releases a new version of Fast Models on a quarterly basis. Each release adds new models, or models for new revisions of existing IP, as they become available. For details on the current release, see the Release Notes inside the Docs folder in your Fast Models Portfolio installation.

2. Extract the downloads using tar on Linux or a program like 7-Zip for extracting zip files on Windows.
3. Run the setup.sh on Linux or Setup.exe on Windows. In the download, there is an Installation_Guide.txt with information covering machine, OS, and compiler requirements.

During the installation, a dialog prompts for the installation location and the location of the license file.

4. Enter the port@host of the FlexNet server for the location of the license file in the dialog box. The port number is from the SERVER line of the license file and the host is either the IP address or the machine name of the computer that is running the lmgrd. For example, 7010@localhost is for the current computer using port 7010.

On completion, the Linux installer prints how to set up the shell environment for Fast Models, with slight differences depending on the installation path.

- For sh/ksh source: `<install path>/FastModelsTools_<version>/source_all.sh`
 - For csh source: `<install path>/FastModelsTools_<version>//source_all.csh`
 - Add the appropriate configuration setup to your startup script, for example, `~/.bashrc`, so that the environment is set up each time you login.
 - There is no additional setup required for Windows. The environment variables are set automatically.
5. You can optionally use environment variables to set the license file, if it was not specified during installation.
 - The variable `ARMLMD_LICENSE_FILE` can be used for all Arm products.
 - The variable `LM_LICENSE_FILE` can be used for all products using FlexNet.
 - Using `ARMLMD_LICENSE_FILE` is recommended for Arm products. These environment variables can be set using `export` (bash), `setenv` (csh), or in the Windows environment variables dialog.

5. Run an example system and hello world software

To verify that the Fast Models license setup and installation are correct, let's work through a simple bare-metal software application "hello world" with a simple Fast Models Virtual Platform.

Follow these steps:

1. Download the Fast Models hello world examples from the Arm Developer Solutions Repository. To do this, use git from the command line or use another git client:

```
git clone https://github.com/ARM-software/Tool-Solutions.git
```

Navigate to the system and directory of an example. Example systems are provided for Cortex-M, Cortex-R, and Cortex-A.

2. Start System Canvas. System Canvas is the GUI tool that is supplied with Fast Models. Using System Canvas, you can build and edit platforms in either a schematic or text editor:
 - For Linux: Run `sgcanvas` from the terminal.
 - For Windows: Open System Canvas from the Arm section of the Start menu.
3. Open the example project using File > Load Project and navigate to the `.sgproj` file for the Cortex-M, Cortex-R, or Cortex-A example.
4. Make sure that the Select Active Project Configuration pull-down has the correct operating system and compiler.
5. Click Build to compile the system. The resulting executable is in a directory which is specific to an operating system and a compiler, and is based on the selected project configuration. In the configuration subdirectory look for `isim_system` on Linux and `isim_system.exe` on Windows.
6. Run a command-line simulation in a Linux terminal or Windows Command Prompt, by passing the hello world software to the simulation:
 - For Linux: `isim_system -a ../software/hello.axf`
 - For Windows: `isim_system.exe -a ../software/hello.axf`

The included `run_windows.cmd` and `run_linux.sh` scripts are included to automatically run the simulation using the above syntax. Either method works.

The model for the PL011 UART displays the output and the hello world message will appear.

7. Press Ctrl-C to exit the simulation.

Follow these steps to use a debugger to control the hello world software:

1. Start the simulation again with `-S` to enable connection from a debugger which supports Component Architecture Debug Interface (CADI). CADI is the debug API that is linked into Fast Models during the project build step. The simulation waits for a debugger to connect before starting execution.
 - For Linux: `isim_system -a ../software/hello.axf -S`

- For Windows: `isim_system.exe -a ../software/hello.axf -S`

Any debugger with CADI support can be used to connect, control the software execution, and inspect the CPU and software.

Arm debuggers with CADI support are:

- Model Debugger
- Arm DS
- uVision

In this guide, we will work with Model Debugger, which is included in Fast Models.

2. Start Model Debugger:
 - For Linux: Run `modeldebugger` from the terminal.
 - For Windows: Open Model Debugger from the Arm section of the Start menu.
3. Use the File > Connect to Model menu item to open a dialog box which selects the running simulation to connect to.
4. Click OK and select the `hello.axf` when prompted.
5. Use the debugger controls to step, run, and examine instructions, registers, and memory.

System Canvas can launch the simulation directly and connect Model Debugger. Refer to the Fast Models User Guide for more information.

6. Select the correct example for the Cortex-M, Cortex-R, or Cortex-A core, depending on the licenses that are available. If a license for the default CPU is not available, the system can be changed to use a similar CPU which is available. Because the simple hello world program assumes very little about the underlying hardware, or use any special hardware features, the following cores can be substituted in their category:

Armv7-A	Armv8-A	Armv6-M/v7-M/v8-M	Armv7-R	Armv8-R
Cortex-A5	Cortex-A35	Cortex-M0	Cortex-R4	Cortex-R52
Cortex-A7	Cortex-A53	Cortex-M0+	Cortex-R4	
Cortex-A8	Cortex-A55	Cortex-M3	Cortex-R5	
Cortex-A9	Cortex-A57	Cortex-M4	Cortex-R7	
Cortex-A15	Cortex-A72	Cortex-M7	Cortex-R8	
Cortex-A17	Cortex-A73	Cortex-M23		
Cortex-A32*	Cortex-A75	Cortex-M33		
	Cortex-A76			
	Cortex-A77			

*Cortex-A32 is Armv8-A but in this case works with code compiled for Armv7-A. This is because the Armv8-A code assumes 64-bit compatibility.

7. Drag the core that you want to work with from the component list onto the canvas. Connect the new core to the same ports as the initial core.

8. Delete the initial core, and recompile the model. Refer to the System Canvas Tutorial for more information.

6. Related information

Here are some resources related to material in this guide:

- Arm debuggers with CADI support:
 - [Model Debugger](#)
 - [Arm DS](#)
 - [uVision](#)
- [Arm Fast Models](#)
- [Fast Models User Guide](#)
- [FlexNet software](#)
- [System Canvas Tutorial](#)
- To open a support case:
 - support-esl@arm.com
 - [Arm Support](#)

7. Next steps

This guide explained how to get up and running with Arm Fast Models including the license setup, tool download and installation, building and running a simple example and executing a bare metal application on the virtual platform.

From here you can start to expand on the example by, for example, adding more peripherals to the virtual platform, modifying the code example, or running your own applications on the virtual platform.

Arm offers a range of online training modules on these topics, and a range of other topics related to the creation and use of virtual platforms. Click On Demand Online Training on the [Arm Training](#) page to learn more.