

# **Model Shell for Fast Models**

Version 11.24

# Reference Guide

Non-Confidential

Issue 00

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## Model Shell for Fast Models

### Reference Guide

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# 1. Introduction

This document describes how to use Model Shell to configure and run Component Architecture Debug Interface (CADI)-compliant models.

## 1.1 Conventions

The following subsections describe conventions used in Arm documents.

#### Glossary

The Arm® Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the Arm Glossary for more information: developer.arm.com/glossary.

Convention	Use		
italic	Citations.		
bold	Terms in descriptive lists, where appropriate.		
monospace	Text that you can enter at the keyboard, such as commands, file and program names, and source code.		
monospace <u>underline</u>	A permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.		
<and></and>	Encloses replaceable terms for assembler syntax where they appear in code or code fragments.  For example:		
	MRC p15, 0, <rd>, <crn>, <crm>, <opcode_2></opcode_2></crm></crn></rd>		
SMALL CAPITALS	Terms that have specific technical meanings as defined in the Arm® Glossary. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.		



Recommendations. Not following these recommendations might lead to system failure or damage.



Requirements for the system. Not following these requirements might result in system failure or damage.



Requirements for the system. Not following these requirements will result in system failure or damage.



An important piece of information that needs your attention.



A useful tip that might make it easier, better or faster to perform a task.



A reminder of something important that relates to the information you are reading.

## 1.2 Other information

See the Arm® website for other relevant information.

- Arm® Developer.
- Arm® Documentation.
- Technical Support.
- Arm® Glossary.

## 1.3 Useful resources

This document contains information that is specific to this product. See the following resources for other useful information.

Access to Arm documents depends on their confidentiality:

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- Confidential documents are available to licensees only through the product package.

Arm product resources	Document ID	Confidentiality
Fast Models User Guide	100965	Non-Confidential



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# 2. Model Shell

Model Shell is a command-line tool for configuring and running Component Architecture Debug Interface (CADI)-compliant models.

Model Shell launches CADI-compliant models and provides:

- Semihosting stdio.
- CADI logging.
- A launch platform for debuggers, profilers, and operating environments.

Model Shell can start a CADI server to enable other debuggers to connect to the model in the following ways:

- The simulation is initialized, but does not run. An external debugger must control the simulation. This is the default behavior.
- The simulation is initialized and runs immediately. An external debugger can connect to the simulation after it starts.

Model Shell provides semihosting input and output only for standard streams:

- When a CADI server is started, semihosting output goes to the Model Shell console and to all debuggers.
- If a debugger is attached, it performs semihosting input. If not, Model Shell provides the input.

Model Shell is included in the Fast Models package and in the Fast Models FVP Standard Library package. For installation information for the Fast Models package, see Installation in the Fast Models User Guide.

## 2.1 ISIM targets

An Integrated SIMulator (ISIM) target is a standalone executable that runs without the need for Model Shell or Model Debugger. SimGen generates ISIMs by statically linking a specific model library with the SystemC framework.

All Model Shell command-line options, except --model, can be used with an ISIM target. Because the model is integrated into the ISIM, there is no need to specify the model on the command line.

#### Related information

Fast Models User Guide

## 2.2 Model Shell command-line syntax

To start Model Shell from the command line, type model\_shell with any options.

model shell -m model [options]

#### model

File name of the model, including .so or .dll extension.



Build a .so or .dll library from the .sgproj file for the model, using System Canvas.

#### options

List of command-line options.

#### Related information

Model Shell command-line options on page 11 Configuration file syntax for specifying model parameters on page 13 Fast Models User Guide

# 2.3 Model Shell command-line options

Use these options to control Model Shell behavior from the command line.

Table 2-1: Model Shell command line options

Long	Short	Description	
application file1 file2	-a	Load application list. Use -a [INST=] file to load an application into a system instance:	
		<pre>model_shell \$MODEL -a cluster0.cpu0=app1.axf -a cluster0. cpu1=app2.axf</pre>	
		Use * to load the same application image into all the cores in a cluster:	
		model_shell \$MODEL -a "cluster0.*=app.axf"	
		Unless you specify a core, Model Shell loads the image into the first cluster or instance that can run software.	
break address	-b	Set program breakpoint at the address. Use -b [INST=][threadid:]address to set a breakpoint for the system instance. Multiplebreaks set multiple breakpoints.	
cadi-log	-L	Log all CADI calls to an XML log file.	
cadi-server	-S	Start a CADI server. This enables attaching a debugger to debug targets in the simulation. To shut down the server, return to the command window that you used to start the model and press <b>Ctrl+C</b> . The Model Shell process must be in the foreground before you can shut it down.	
cadi-trace	-t	Enable diagnostic output from CADI calls and callbacks.	
config-file file	-f	Use model parameters from a configuration file.	

Long	Short	Description
cpulimit <i>n</i>	-	Specify the maximum number of host seconds for the simulation to run, excluding simulation startup and shutdown. Fractions of a second can be specified, but the remaining time is only tested to a resolution of 100ms. If $\it n$ is omitted, the default is unlimited.
cyclelimit n	-	Specify the maximum number of cycles to run. If $n$ is omitted, the default is unlimited.
data file@address	-	Specify raw data to load at this address. The full format is: data [INST=] file@[memspace:] address
dump file@address,size -		Dump a section of memory into a file at model shutdown. Multipledumps are possible. The full format is: dump [INST=] file@[memspace:] address, size
help	-h	List the Model Shell command-line options, and then exit.
keep-console	-K	Keep console window open after completion. Microsoft Windows only.
list-instances	-	Print list of target instances to standard output.
list-memory	-	Print memory information for the model to standard output.
list-params	-1	Print list of target instances and their parameters to standard output. Use this to help identify the correct syntax for configuration files, and to find out what the target supplies.
list-regs	-	Print model register information to standard output.
model file	-m	Model to load. Optional.
output file	-0	Redirect output from thelist-instances,list-memory,list-params, andlist-regs commands to a file.  The contents of the file are formatted correctly for use as input by theconfig-file option.
parameter [inst.]param=value	-C	Set a parameter to this value. For hierarchical systems, specify the complete name of the parameter.
plugin file	-	Specify plugins. These plugins or those in environment variable FM_PLUGINS are loaded.
prefix	-P	Prefix semihosting output with the name of the target instance.
print-port-number	-	Prints the port number on which the CADI server is listening.
quiet	-q	Suppress Model Shell output.
run	-R	Run simulation on load, with a CADI server: -srun. The default is to start the simulation in a stopped state.
start address -		Initialize the PC to this application start address, overriding the .axf start. The full format is: start [INST=]address
stat	_	Print statistics at the end of the simulation.
5040		Three states at the end of the simulation.

Long	Short	Description
timelimit n	-T	Specify the maximum number of wall clock seconds for the simulator to run. If $n$ is omitted, the default is unlimited.
		If $n$ is specified as 0, Model Shell initializes the system, loads all applications and data, sets breakpoints and PC, and exits immediately without running the model. Use this option to convert applications to raw binary. For example:
		<pre>model_shelltimelimit 0 -m mymodel.dll -a app.axfdump app. raw@0x8000,0x10000</pre>
verbose	-V	Enable verbose messages.
version	-v	Print the Model Shell version number, then exit.

#### Related information

Automatic Model Shell shutdown on page 15

# 2.4 Configuration file syntax for specifying model parameters

Text files can configure models for Model Shell from the command line, thus setting many parameters at once.

```
model_shell --config-file my_configuration_file.txt ...
```

Each line of the configuration file must have the same <code>instance.parameter=value</code> syntax as used for command-line assignments.

Include comment lines and blank lines in configuration files with a # character before the comment or blank text.

To generate a configuration file, use the --list-instances and --list-params options on the command line. The command line can also include parameter assignments.

#### **Example**

```
model_shell --list-params --list-instances -C top-mm=0x3 -o file.config -m model.so
```

might generate:

```
Instances:
 Instance id: instance name (SW: y/n, component, type, version) : description
 instance.parameter=value #(type, mode)
                                                       default = 'value' : description
 : [min..max]
                               (SW: no , NoCore, , 1.0) : Regression test system without PVLIB
# Instance 0:
  top-p=0x2
   top-str="empty"
top-mm=0x3
                                \# (int , init-time) default = '0x2' : test display name
                                  (int , init-time) default = 'empty' : test string param (int , init-time) default = '0x6' : test min(2) max(6)
                                # (int , init-time) default = '0x6'
  top-mm=0x3
param : [0x2..0x6]
# Instance 1: a1
                               (SW: no , A, , 1.0) :
```

```
, init-time) default = '0x2'
   a1.p1=0x2
                                                                                 : A parameter p1
   a1.p2=0
                                   # (bool , run-time ) default = '0'
                                                                                : A parameter p2
                                 (SW: no , B, , 1.0):
# (int , init-time) default = '0x2'
# (string, run-time) default = ''
# Instance 2: a1.b
                                                                               : B parameter p1
   a1.b.p1=0x2
   a1.b.p2=""
                                                                                : B parameter p2
                                  # (int , init-time) default = '0x2'
# (bool , run-time) default
# Instance 3: a2
                                 (SW: no , A, , 1.0) :
   a2.p1=0x2
                                                                                : A parameter p1
   a2.p2=0
                                                                                 : A parameter p2
                                (SW: no , B, , 1.0):
# (int , init-time) default = '0x2'
# Instance 4: a2.b
   a2.b.p1=0x2
                                                                                : B parameter p1
                                  # (string, run-time ) default = ''
   a2.b.p2="test"
                                                                                : B parameter p2
```

This is another way of specifying run-time parameters:

```
# Disable semihosting using true/false syntax
coretile.core.semihosting-enable=false
#
# Enable VFP at reset using 1/0 syntax
coretile.core.vfp-enable_at_reset=1
#
# Set the baud rate for UART 0
baseboard.uart_0.baud_rate=0x4800
```

## 2.5 SMP support

Model Shell provides Symmetric MultiProcessing support. It can be simple or standard.

#### Simple

This is only suitable for model systems that have one SMP cluster. The same application is loaded in all cores.

```
model_shell -m smp_model.so -a app.axf
```

#### Standard

This is suitable for all cases and uses the -a option to list the applications for each core.

Use the full instance name of each core.

```
model_shell -m smp_model.so -a multiprocessor.processor0=app1.axf -a
multiprocessor.processor1=app2.axf
```

In addition to loading individual applications for each core, the -a option also enables loading the same application in all cores.

Replace the index of the core with \*.

```
model_shell -m smp_model.so -a multiprocessor.processor*=app.axf

model_shell -m smp_model.so -a "multiprocessor.*"=app.axf
```



On Unix, the \* character requires escape quotes.

## 2.6 Manual Model Shell shutdown

User actions that stop Model Shell.

#### Press ctrl+c.

The program starts shutting down the simulator and exits after shutdown is complete. On a second press, Model Shell terminates immediately. Some models can assign their own **ctrl+c** handlers that override Model Shell behavior.

#### Press Ctrl+Break.

Model Shell terminates immediately. Windows only.

#### Close an LCD window.

The simulation stops.

## 2.7 Automatic Model Shell shutdown

Command-line options that control when to stop Model Shell. The first fulfilled condition stops Model Shell. If none are specified, Model Shell shuts down when the simulation ends.

#### --break

Breakpoint. --cadi-server overrides this option.

#### --cyclelimit

Cycles > cycle limit. --cadi-server overrides this option. This option might reduce execution speed. It ignores breakpoints.

#### --timelimit

Time > running time limit.

#### --cpulimit

Time > process time limit. Tested to a granularity of 0.1s to avoid performance loss. Elapsed processor time includes user time and kernel time.

# 2.8 License checking messages from Model Shell and ISIM systems

The license checking messages appear in the stderr and stdout outputs, and are useful for the detection and diagnosis of licensing issues.

The model shell and isim system executables return a status value when they exit:

ono error (for example, clean simulator shutdown).

1 error (for example, license checking or file not found).

For exit status 1, parse the stderr output. A message might, for example, appear in the GUI with other WARNING, ERROR or Fatal Error messages. See the lines that follow for more information from the license checking module. When a license is about to expire, Model Shell prints a warning message to stdout, but the simulation still starts correctly.