

Dimension Reduction of Stiff Systems

MF

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1 Reduction of source term for isothermal 6-species H₂ mechansim – i.e. 1st approximation

Subject: Evaluation of manifold at each function call

General set-up (througout) – reduce 6 species onto 2:

For `ComputeManifold<double,6,2,true>` take:

- rpv index: 0,4
- order of rpvs: H₂, H₂O
- rpv start values: 0.3, 0.6
- time horizon: $[t_0, T] = [0.0, 0.2]$

Jochen's tool: In *MoRe_examples/H2C6/SETTING/general_settings.dat* set:

- `<method>`
s

1st Testcase:

Initial value (IV) for solution of ODE (on manifold):

$u_0(t_0) = [0.4549999999992859, 0.7780585738931507, 0.2366143850825262, 0.3628298037265891, 0.147999999999196, 0.01594142610843904]^T$

(The red dyed numbers correspond to starting values of the reduced ODE)

Solution of of full ODE (via implicit Euler with stepsize control due to Johnson, Nie, Thomée):

$u^*(T) = [0.3786723144539595, 0.04850834768192609, 0.1884211778006195, 0.01922020051004056, 0.5902095795214345, 0.01372786436728766]^T$

Solution of reduced ODE (via classical adaptive Runge-Kutta-Fehlberg (show this by default)):

$u^*(T)_{\text{red}} = [0.3623960518126658, 0.6046053938719057]^T$

solver	time [secs]	ℓ_2 -error	slowdown	tol(s)	figure
implicit Euler	128.16	0.0230448	6408	1.e-04/1.e-03	1
runge-kutta-fehlberg	3.22	0.021729	82.25	1.e-04	2

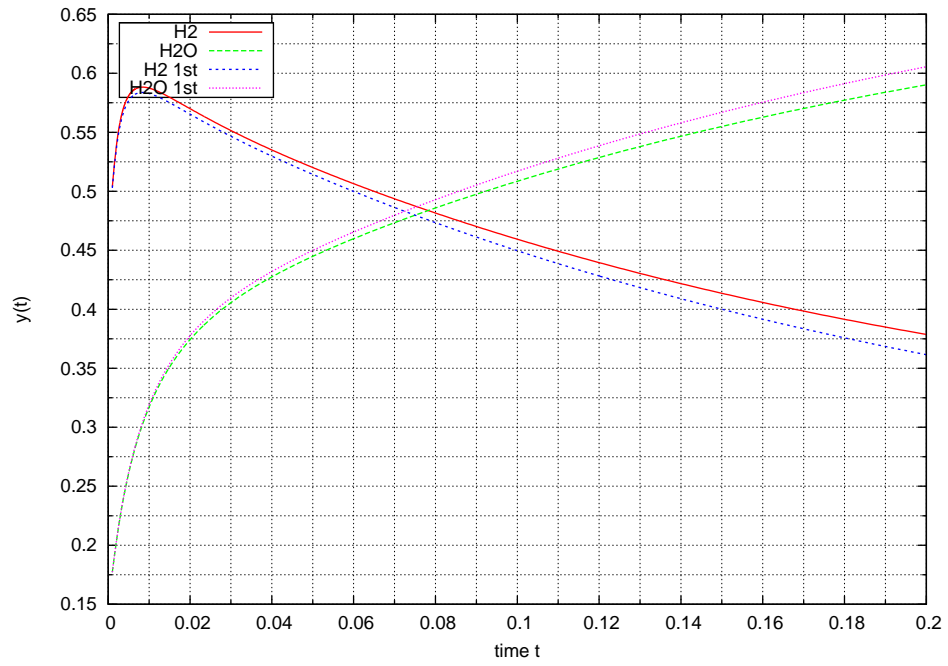


Figure 1: Reduced vs full temporal evolution – implicit method

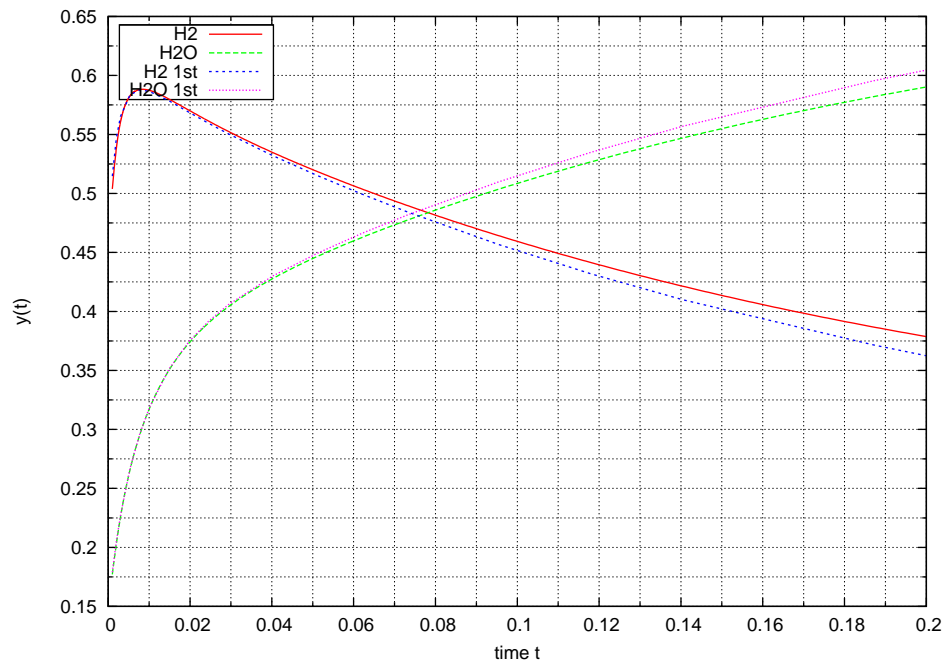


Figure 2: Reduced vs full temporal evolution – explicit method

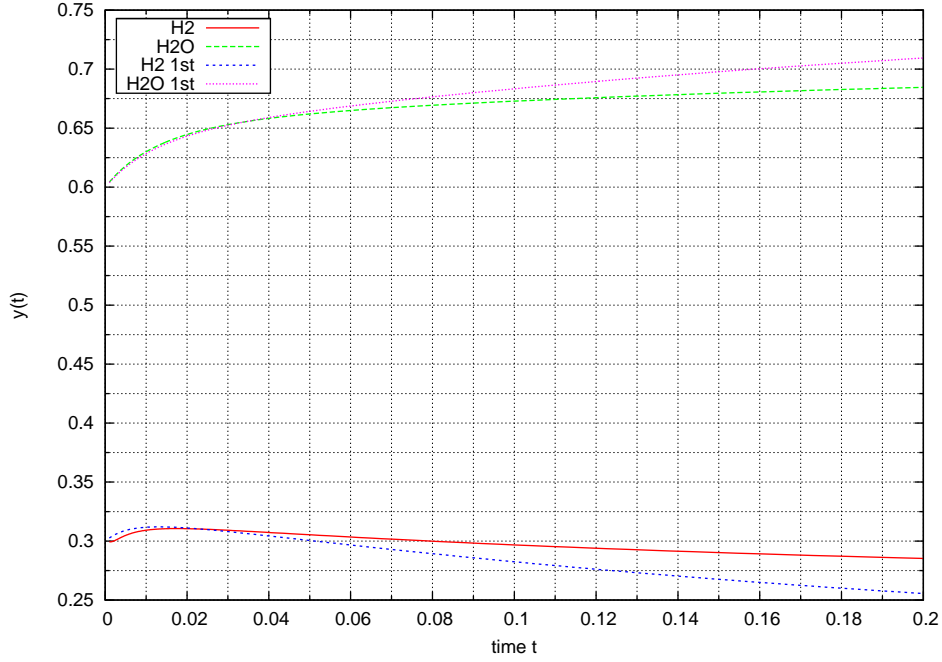


Figure 3: Reduced vs full temporal evolution – implicit method

2nd Testcase:

Initial value (IV) for solution of ODE (on manifold near to equilibrium):

$$u_0(t_0) = [0.3, 0.1894550821939027, 0.1437566945658673,$$

$$0.101941693062168, 0.6, 0.01054491780609743]^T$$

(The red dyed numbers correspond to starting values of the reduced ODE)

Solution of of full ODE (via implicit Euler with stepsize control due to Johnson, Nie, Thomée):

$$u^*(T) = [0.285310199565836, 0.04976927314406539, 0.1425291708195627,$$

$$0.01987354660256563, 0.6845422159659538, 0.01052589579235477]^T$$

Solution of reduced ODE (via classical adaptive Runge-Kutta-Fehlberg (show this by default)):

$$u^*(T)_{\text{red}} = [0.2553611536492239, 0.7095534070528229]^T$$

solver	time [secs]	ℓ_2 -error	slowdown	tol(s)	figure
implicit Euler	31.38	0.0387793	3138	1.e-04/1.e-03	3
runge-kutta-fehlberg	1.8	0.039019	180	1.e-04	4

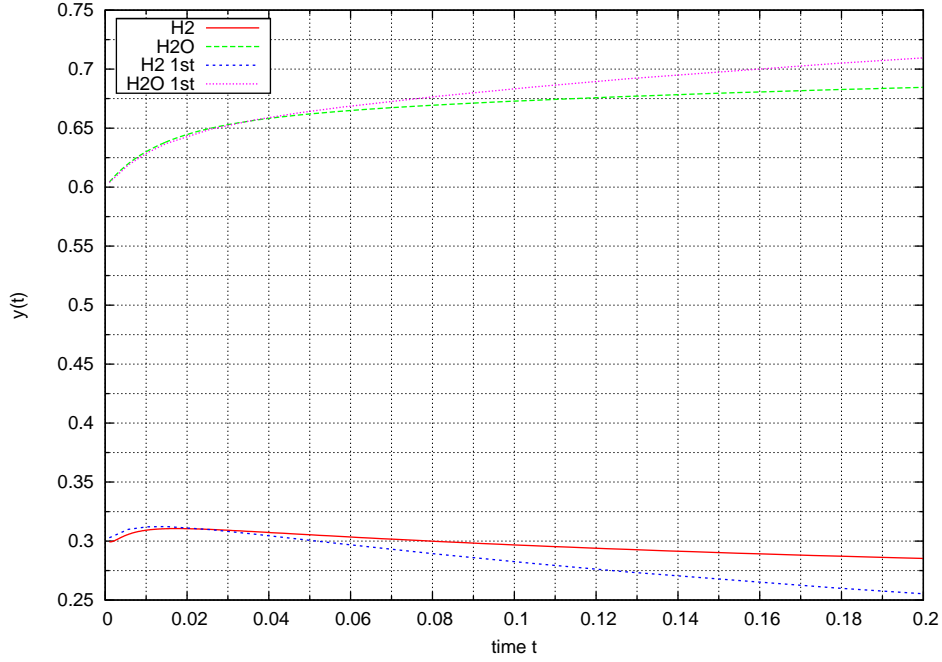


Figure 4: Reduced vs full temporal evolution – explicit method

2 1D Manifold – Is one species capable of fitting all?

Finally, it seems that reducing 6 species onto a single one (either H_2 or H_2O) doesn't yield good results (see figures beneath). This may result from the fact that one species (or in particular one of the aforementioned) are not capable of simulating the complete system within reasonable accuracy.

3 Solution over long time interval

In order to verify that the solution doesn't depart further, once the time horizon gets larger, we simulated the temporal evolution once again with the same settings as before, except that we changed the time horizon into $[0.0, 23.66]$.

Compared to the solution of the full system

$U^*(T = 23.66) = [0.269998, 0.0499998, 0.134999, 0.0199999, 0.700002, 0.00999992]^T$, the solution of the reduction is

$u^*(T = 23.66)_{\text{red}} = [0.205539, 0.756834]^T$ with $\ell_2 = 0.0859348$.

Similar results were obtained for even longer time horizons (here $[0., 60]$):

$u^*(T = 60.) = [0.205506, 0.75679]^T$ with $\ell_2 = 0.0859303$.

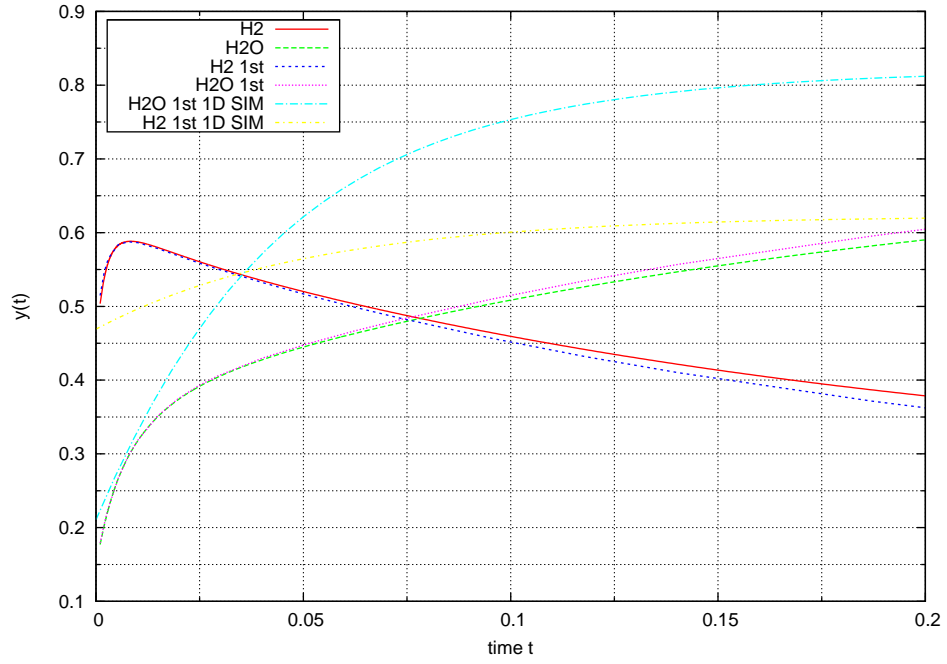


Figure 5: The above figure, completed by simulating only one species (H_2 and H_2O , respectively)

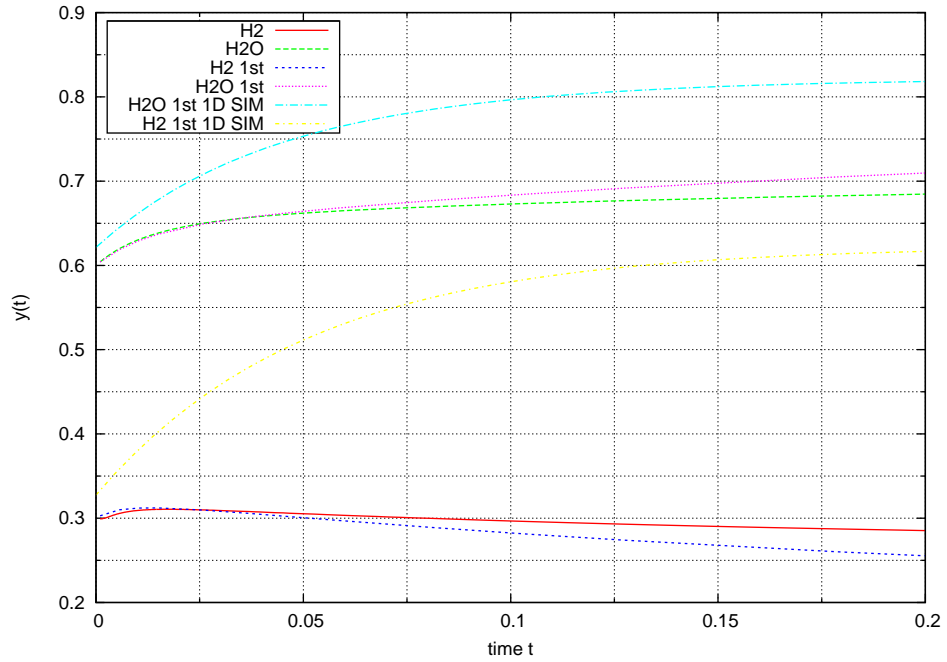


Figure 6: The above figure, completed by simulating only one species (H_2 and H_2O , respectively) – this time with starting values near the equilibrium.

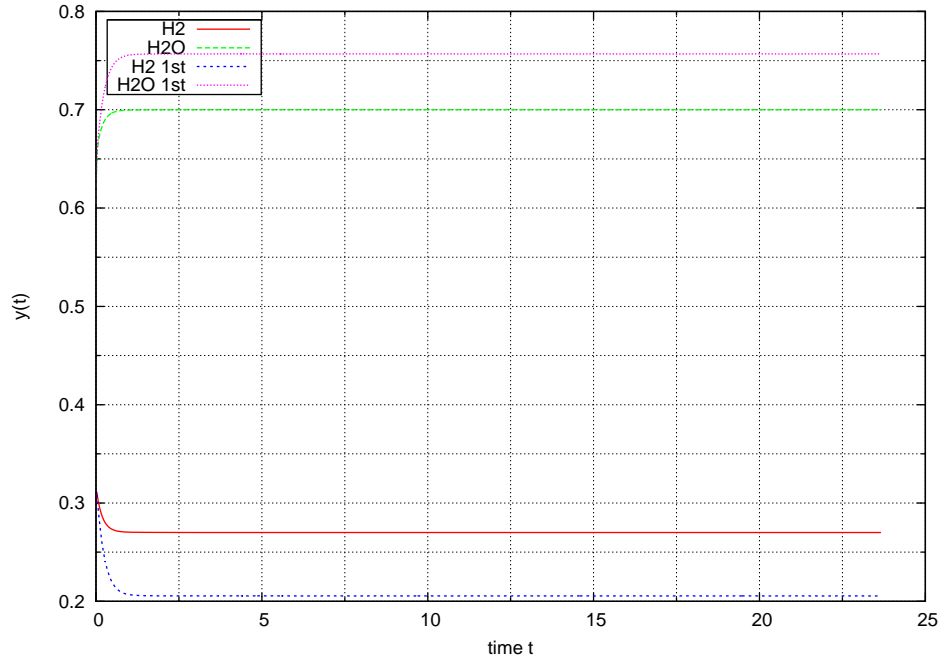


Figure 7: Integration over time horizon $[0.0, 23.66]$ shows that the reduction remains bounded (initial condition was taken to lie further away from equilibrium and similar results are obtained from other ics).

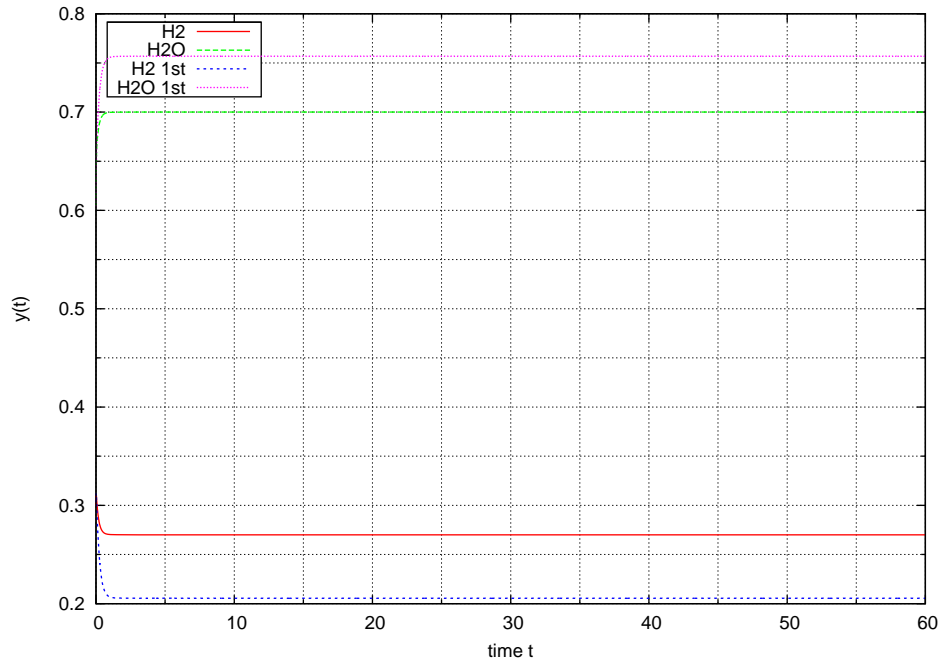


Figure 8: Integration over time horizon $[0.0, 60.]$.

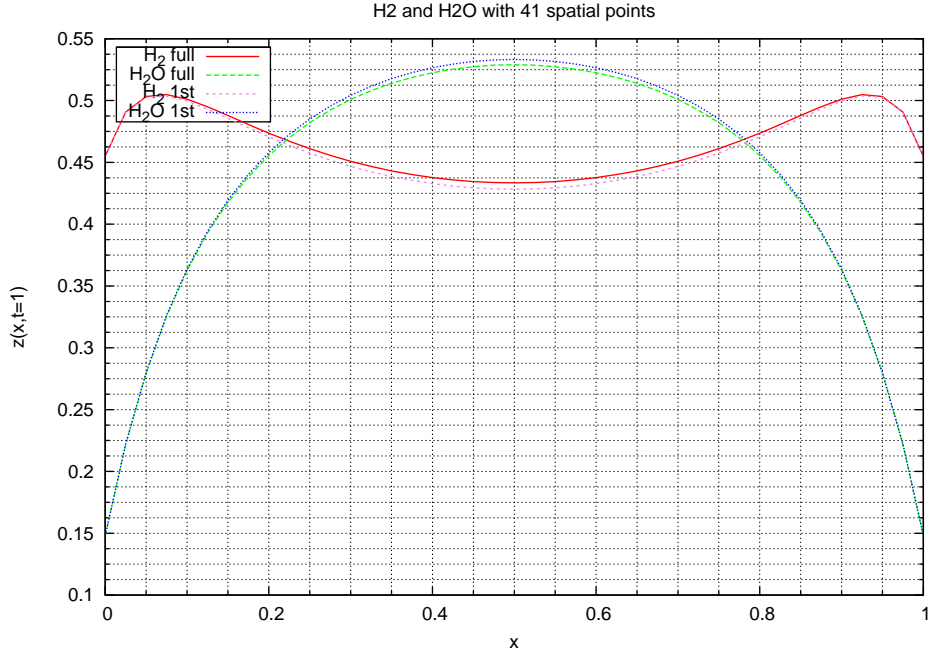


Figure 9: Original system vs. 1st approximation. Integration has been performed over time horizon $[0.0, 0.2.]$ and with 41 spatial points.

4 1D Spatio-temporal evolution

The entries of the initial value vector

$u(t = 0) = [0.4549999999992859, 0.7780585738931507, 0.2366143850825262, 0.3628298037265891, 0.147999999999196, 0.01594142610843904]^T$ have been taken to be *constant* for each spatial grid point.

Furthermore we assume (somewhat very academic) constant and equal diffusion, i.e. $\mathcal{D} = \text{diag}\{1\}_{i=1,\dots,6}$.

The domain has been chosen to be $\Omega =]0, 1[$. At $x = 0$ and $x = 1$, Dirichlet bdy conditions have been assumed, i.e. $U(0, t) = U(1, t) = 0 \forall t \leq 0$.

Invocation of the modelreduction algorithm has been started at *every* function evaluation. The function is just the discretization of the reduced source function via the method of lines.

Aside from the fact that the result looks pretty nice, cf. fig. 9, the running time for the (1st) reduction is rather frightening. . .

system	solver	tol(s)	spatial points	homotopy	AD	time
full	impl. Euler	1.e-03/1.e-02	41	yes	no	3.67 secs
red. (1st)	impl. Euler	1.e-03/1.e-02	41	yes	no	17.40 h