Linear System Differential Equation

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Problem 5.2

Show that the systems in Problem 23 through 25 are degenerate. In each problem determine - by attempting to solve the system - whether it has infinitely many solutions or no solutions.

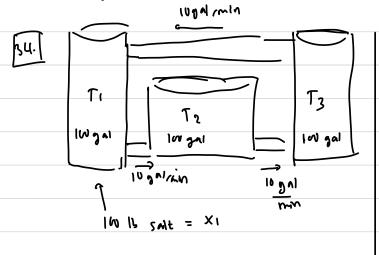
$$\frac{|23|}{(0+2)x} + (0+2)y = e^{-3t}$$

$$(0+3)x + (0+3)y = e^{-2t}$$

Matrix form:

$$\begin{bmatrix} (0+2) & (0+2) \\ (0+3) & (0+3) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} e^{-3t} \\ e^{-2t} \end{bmatrix} \longrightarrow \begin{bmatrix} 0+2 & 0+2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} e^{-3t} \\ e^{-2t} - e^{-3t} \frac{0+3}{0+2} \end{bmatrix}$$

The system is degenerate and it has infinitely many solutions.



Using konsentration equations
$$C : \frac{x_1}{\sqrt{100}} = \frac{100 \text{ Hz}}{100} = 1$$

$$10 \times 1' = -\times 1 + \times 3$$

$$10 \times 1' = \times 1 - \times 2$$

$$10 \times 3' = \times 2 - \times 3$$

determinant

$$\begin{bmatrix}
(100+1) & 0 & -1 \\
-1 & (100+1) & 0 \\
0 & -1 & (100+1)
\end{bmatrix}
\begin{bmatrix}
x_1 \\
x_2 \\
0
\end{bmatrix}
=
\begin{bmatrix}
0 \\
0
\end{bmatrix}
-1 & (100+1) & 0 \\
0 & -1 & (100+1) & 0
\end{bmatrix}
=
0$$

$$(10D+1)^{3}-1 - (0) = (0000^{2} + 3000^{2} + 300 + 1) - (0) [1000^{2} + 300 + 30]$$

$$= 0$$

$$(=) |Or(|w|^2 + 30r + 3) = 0$$

$$\frac{\Gamma_{1}=0}{\Gamma_{2,3}=\frac{-30\pm\sqrt{900-1200}}{2(100)}=\frac{-30\pm\sqrt{-300}}{200}=\frac{-3\pm i\sqrt{3}}{200}$$

$$X_{1}(t) = Ae^{0t} + e^{-\frac{3t}{2}} \left(B \cos(\frac{5}{2}t) + C \sin(\frac{5}{2}t) \right)$$

1)
$$10 \times 1' + \times 1 - \times_3 = 0$$

$$\times_1' = -\frac{3}{30} (100-4) e^{-\frac{3}{30}t} cos(\sqrt{3}t) - (100-4) e^{-\frac{3}{30}t} \int_{10}^{10} sin(\sqrt{9}t) - \frac{3}{30} c e^{-\frac{3}{30}t} sin(\sqrt{\frac{5}{3}t}) + c e^{-\frac{3}{30}t} \int_{10}^{10} cos(\sqrt{3}t)$$

$$\frac{-100 + 3A + (\sqrt{3} = 0)}{2} = 0 \longrightarrow (\sqrt{3} = 100 - 3A)$$

$$C = 100 \sqrt{3} - \sqrt{3} A$$

$$\times 3^{2} = \left(-\frac{3}{2} \omega + \frac{3}{4} \right) \left[-\frac{3}{2} e^{-\frac{3}{2} t} \cos \left(\frac{5}{2} t \right) - e^{-\frac{3}{2} t} \frac{3}{2} \sin \left(\frac{5}{2} t \right) \right] - \left(100 - 4 \right) \frac{5}{2} \left[-\frac{3}{2} e^{-\frac{3}{2} t} \cos \left(\frac{5}{10} t \right) + \frac{5}{2} e^{-\frac{3}{2} t} \cos \left(\frac{5}{10} t \right) \right]$$

$$- \left(50 \int_{3} - \frac{3}{2} A \int_{3} \right) \left[-\frac{3}{2} e^{-\frac{3}{2} t} \sin \left(\frac{5}{12} t \right) + e^{-\frac{3}{2} t} \frac{5}{2} \cos \left(\frac{5}{12} t \right) \right] + \left(50 - \frac{3}{2} A \right) \left[-\frac{3}{2} e^{-\frac{3}{2} t} \cos \left(\frac{5}{12} t \right) - e^{-\frac{3}{2} t} \sin \left(\frac{5}{12} t \right) \right]$$

$$- \left(50 \int_{3} - \frac{3}{2} A \int_{3} \right) \left[-\frac{3}{2} e^{-\frac{3}{2} t} \sin \left(\frac{5}{12} t \right) + e^{-\frac{3}{2} t} \frac{5}{2} \cos \left(\frac{5}{12} t \right) \right] + \left(50 - \frac{3}{2} A \right) \left[-\frac{3}{2} e^{-\frac{3}{2} t} \cos \left(\frac{5}{12} t \right) - e^{-\frac{3}{2} t} \cos \left(\frac{5}{12} t \right) \right]$$

$$\begin{bmatrix}
4. \\
x = \begin{bmatrix} 2t \\ e^{-t} \end{bmatrix}$$
and
$$y = \begin{bmatrix} t^2 \\ \sin t \\ \cos t \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 0 & -1 \\ 3 & -u & 5 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 3 \\ -1 & 0 \\ 3 & -2 \end{bmatrix}$$

Fird Ay and Bx

$$A \lambda = \begin{bmatrix} 5 & 0 & -1 \\ 5 & 0 & -1 \end{bmatrix} \begin{bmatrix} 5 & 1 \\ 5 & 1 \end{bmatrix} = \begin{bmatrix} 5 & 5 \\ 5 & 5 \end{bmatrix} = \begin{bmatrix} 5 & 5 \\ 5 & 5 \end{bmatrix}$$

$$\begin{bmatrix}
 1 & 3 \\
 -7 & 0 \\
 3 & -2
 \end{bmatrix}
 \begin{bmatrix}
 2t \\
 e^{-t}
 \end{bmatrix}
 =
 \begin{bmatrix}
 2t + 3e^{-t} \\
 -1ut \\
 6t - 2e^{-t}
 \end{bmatrix}$$

The product of Ay and By is not defined because the numbers of colon Ay is not the same as the row of By. So it is not defined.

$$\begin{bmatrix} x' \\ \lambda' \end{bmatrix} = \begin{bmatrix} 0 & -3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ x \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\mathbf{x}^{1} = \begin{bmatrix} 0 & -3 \\ 3 & 0 \end{bmatrix} \mathbf{x}$$

$$\begin{bmatrix} 12 \\ x' \\ y' \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ 2 & 1 \end{bmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$x' = \begin{bmatrix} 3 & -2 \\ 2 & 1 \end{bmatrix} x$$

$$|\widetilde{3}| \times = 2 + 4y + 3e^{t}; \quad y' = 5x - y - t^{2}$$

$$|x'| = 2 + 4y + 3e^{t}; \quad y' = 5x - y - t^{2}$$

$$|x'| = 2 + 4y + 3e^{t}; \quad y' = 5x - y - t^{2}$$

$$x_{1} = \begin{bmatrix} 2 & 4 \\ 3 & 4 \end{bmatrix} \times + \begin{bmatrix} -f_{5} \\ 3e_{6} \end{bmatrix}$$

Poblem 5-3
$$|\overline{u}| \times = \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} \times ; \times 1 = e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \times_2 = e^{3t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

XI and XZ is the given solution for the system.

& Wrondian Solutions:

$$\begin{vmatrix} e^{3t} & e^{2t} \\ -e^{t} & -2e^{t} \end{vmatrix} = -2e^{t} + e^{t} = -e^{t} \neq 0 \Rightarrow 14s \text{ linearly mode perclass.}$$

$$| x_1 + x_2 | = -2e^{t} + e^{t} = -e^{t} \neq 0 \Rightarrow 14s \text{ linearly mode perclass.}$$

* General Solutions

$$x(t) = a \begin{bmatrix} e^{3t} \\ -e^{3t} \end{bmatrix} + b \begin{bmatrix} e^{2t} \\ -2e^{2t} \end{bmatrix}$$

$$x(t) = \begin{bmatrix} ae^{3t} + be^{2t} \\ -ae^{3t} - 2be^{2t} \end{bmatrix}$$

$$x_1'z \left[6e^{2t} \right] , x_2'z \left[-5e^{-5t} \right]$$

M Wronkian Solution:
$$3e^{2t}$$
 e^{-3t} $-3t$ $-3t$

* General Solution:
$$x(t) = \begin{bmatrix} 3ae^{2t} + be^{-5t} \\ 2ae^{2t} + 3be^{-5t} \end{bmatrix}$$

Poblem 5.4.

$$x' = \begin{bmatrix} 9 & 5 \\ -6 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
 is find eigenvalue, and eighnvector.

$$\begin{vmatrix} 9-\lambda & 5 \\ -6 & -2-\lambda \end{vmatrix} = 0 \quad (9-\lambda)(-2-\lambda) + 30 = 0$$

$$-18-5\lambda + 2\lambda + \lambda^{2} + 30 = 0$$

$$\lambda^{2} - 7\lambda + 12 = 0$$

$$(\lambda - 3)(\lambda - 4) = 0 \quad | \Lambda_{1} = 3; \lambda_{1} = 4$$

Eigenrectors:

$$\begin{cases} 1 & 1 & 1 \\ 1 & 1$$

$$\lambda_1 = 4$$

$$\begin{vmatrix} 5 & 5 \\ -6 & -6 \end{vmatrix} \times = 0 \quad \text{if } \begin{cases} 5 & 5 \\ -1 & 5 \end{cases}$$

$$x(t) = c_1 e^{3t} \begin{bmatrix} -5 \\ 6 \end{bmatrix} + c_2 e^{4t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \qquad \frac{1}{5} c_2 = \frac{6}{5} \qquad \qquad c_2 = 6$$

$$x_1(t) = \begin{bmatrix} c_1 e^{3t} - 5 + c_2 e^{4t} \\ c_1 e^{3t} + c_2 e^{4t} \end{bmatrix} \qquad -5 c_1 + 6 = 1$$

$$x_1(t) = \begin{bmatrix} c_1 e^{3t} - 5 + c_2 e^{4t} \\ c_1 e^{3t} + c_2 e^{4t} \end{bmatrix} \qquad c_1 = 1$$

$$c_1 = 1$$

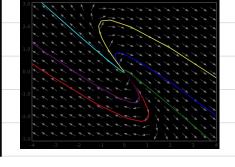
$$\begin{bmatrix} X_{1}(0) \\ X_{2}(0) \end{bmatrix} = \begin{bmatrix} -5c_{1} + c_{2} \\ 6c_{1} + c_{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -5 & 1 \\ 6 & -1 \end{bmatrix} \begin{bmatrix} c_{1} \\ c_{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\frac{1}{5} \quad \begin{array}{c} 1 \\ 2 \end{array} = \frac{6}{5} \quad \begin{array}{c} 1 \\ 2 \end{array} = \frac{6}{5}$$

$$X_1(t) = -5e^{3t} + 6e^{4t}$$

 $X_1(t) = 6e^{3t} - 6e^{4t}$



Field

Eigenvetors:
$$\lambda = 9$$

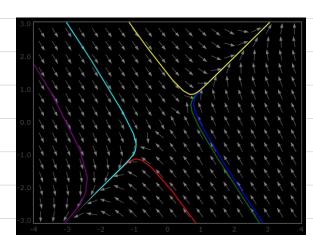
$$\begin{bmatrix} 6 & 4 \\ 6 & 4 \end{bmatrix} V_1 = 0 \longrightarrow V_1 = \begin{bmatrix} -2 \\ 3 \end{bmatrix} \qquad \begin{bmatrix} -4 & 4 \\ 6 & -b \end{bmatrix} V_2 = 0 \longrightarrow V_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$x(t) = c_{1} e^{-9t} \begin{bmatrix} -2 \\ 3 \end{bmatrix} + c_{2} e^{t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$x_{1}(t) = -2c_{1} e^{-9t} + c_{2} e^{t}$$

$$x_{2}(t) = 3c_{1} e^{-9t} + c_{2} e^{t}$$

$$x_{3}(t) = 3c_{1} e^{-9t} + c_{3} e^{t}$$



Directional Field.

$$\begin{vmatrix} 3-\lambda & 0 & 1 & 3-\lambda & 0 \\ 9 & -1-\lambda & 2 & 9 & -1-\lambda \\ -9 & 4 & -1-\lambda & -9 & 4 & = -\lambda^3 + \lambda^2 + 4\lambda + 6 = 0 \end{vmatrix}$$

using calculator:
$$\lambda_1 = 3$$
; $\lambda_2 3 = -1 \pm i$

$$x_1(t) = 4c_1e^{-t} + e^{-t} (c_2 c_3 t + c_3 s_n t)$$

 $x_1(t) = 9c_1e^{3t} + e^{-t} ((2(2-c_3)c_0)t + (c_2+2c_3) s_n t)$
 $x_3(t) = e^{-t} ((-4c_2+c_3)c_0)t + (-c_2-4c_3) s_n t)$

$$X_{1}(t) = t e^{3t} + e^{-t} (-4 \cos t + \sin t)$$

 $X_{1}(t) = 9 e^{3t} + e^{-t} (-9 \cos t - 2 \sin t)$
 $X_{2}(t) = e^{-t} (13 \cos t)$

Eigenvector:
$$\lambda_1 = -3$$
 $\begin{bmatrix} 7 & 1 & 1 & 7 \\ 1 & 7 & 10 & 1 \\ 1 & 10 & 7 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 1 & 1 & 7 \\ 1 & 1 & 1 & 7 \\ 1 & 1 & 1 & 7 \end{bmatrix}$ $\begin{bmatrix} 1 & 1 & 1 & 7 \\ 0 & 1 & 1 & 7 \\ 0 & 1 & 1 & 7 \end{bmatrix}$

$$X_{1}(t) = -C_{1}e^{-3t} + 2c_{3}e^{-10t} + C_{4}e^{-15t}$$

 $X_{2}(t) = -C_{2}e^{-6t} - C_{3}e^{10t} + 1C_{4}e^{-15t}$
 $X_{3}(t) = C_{2}e^{-6t} - (3e^{10t} + 2C_{4}e^{-15t})$
 $X_{4}(t) = C_{1}e^{-3t} + 2C_{3}e^{10t} + C_{4}e^{15t}$

$$x_1(0) = -C_1 + 2C_3 + C_4 = 3$$

 $x_2(0) = -C_2 - C_3 + 2C_4 = 1$
 $x_3(0) = C_2 - C_3 + 2C_4 = 1$
 $x_4(0) = C_1 + 2C_3 + C_4 = 3$

$$x_1(0) = -C_1 + 2C_3 + C_4 = 3$$

 $x_2(0) = -C_2 - C_3 + 2C_4 = 1$
 $x_3(0) = C_2 - C_3 + 2C_4 = 1$
 $x_4(0) = C_1 + 2C_3 + C_4 = 3$

C1 = 0; C2 = 0; (3 = 1; Cu = 1

Portioner Solutions.

$$x_1(t) = 2e^{10t} + e^{15t}$$

 $x_2(t) = -e^{10t} + 2e^{15t}$
 $x_3(t) = -e^{10t} + 2e^{15t}$
 $x_4(t) = 2e^{10t} + e^{15t}$

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