

LECTURE 11 — ELEMENTARY GRAPH ALGORITHMS (PART 1)

COMPSCI 308 — DESIGN AND ANALYSIS OF ALGORITHMS

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SUMMARY

ITA 20.1 Representation of Graphs

ITA 20.2 Breadth-First Search

ASSIGNMENTS¹



Practice makes perfect!

Introduction to Algorithms (ITA)

📘 Required Readings:

- Section 20.1.
- Section 20.2.

✏️ Required Exercises:

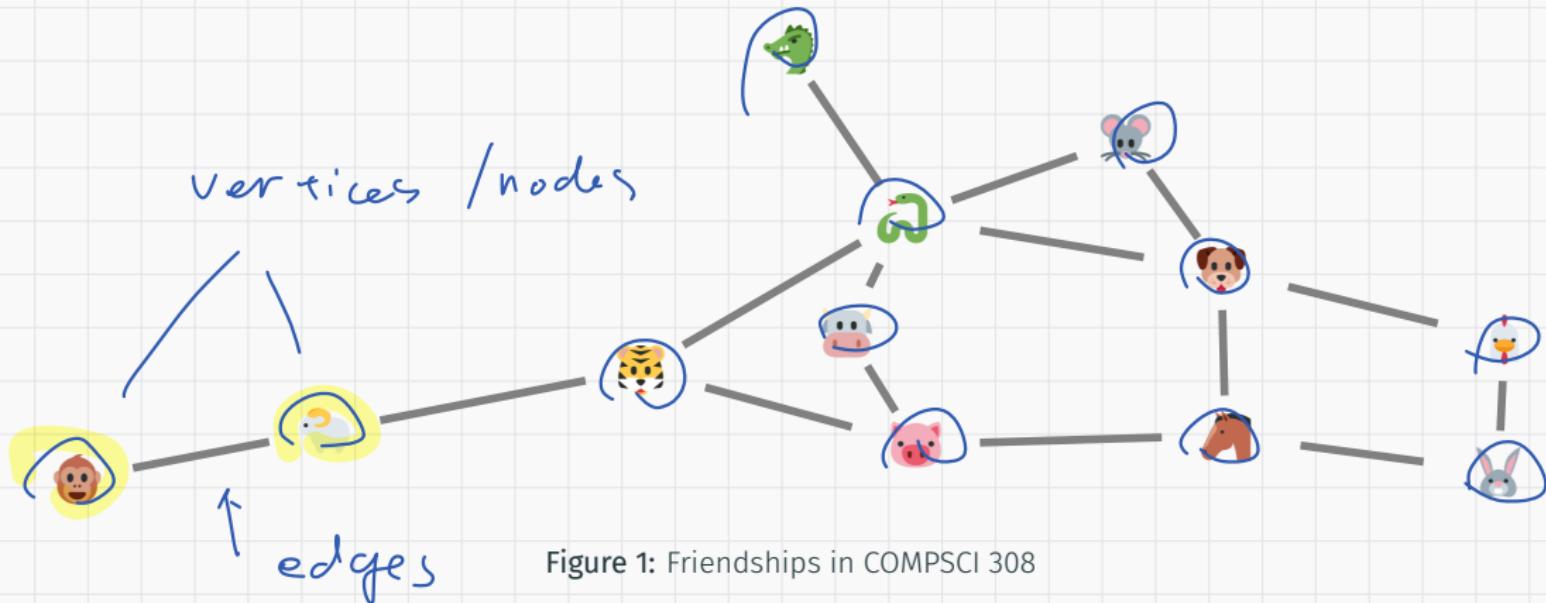
- Exercises 20.1 – 1, 3–6.
- Exercises 20.2 – 1–6.

¹ ⚪ Assignments will not be collected; however, quiz problems will be selected from them. (This includes both Readings and Exercises.)

ITA 20.1 REPRESENTATION OF GRAPHS

FRIENDSHIPS

We can model friendships as a graph in which each vertex (node) represents a friend and each edge (line) represents a friendship.



METRO NETWORK AS A GRAPH

A metro network can also be modeled as a graph.



Figure 2: Mini Metro game screenshot. Source — [Wikipedia](#).

DEFINITION OF GRAPH

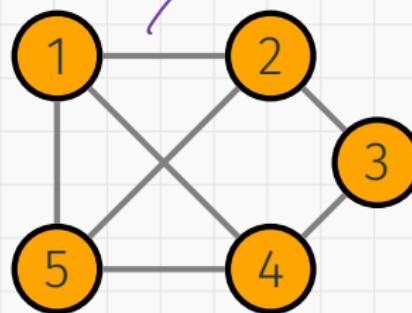
A graph G is defined as a pair (V, E) , where V is the vertex set, and E is the edge set.

An element in V is called a vertex or node.

An element in E is called an edge.

🎂 What is V and E of the following graph?

$$V = \{1, 2, 3, 4, 5\}$$



$$\begin{aligned} & \subseteq V \times V \\ E = & \{ \{1;2\}, \{2,3\}, \\ & \{3,4\}, \{1,4\}, \\ & \{4,5\}, \{1,5\} \\ & \{2,5\} \}. \end{aligned}$$

Figure 3: An undirected graph G

DEFINITION OF GRAPH

If $(x, y) \in E$, then x and y are adjacent, and the edge (x, y) is incident to both x and y .

If the edges are undirected, i.e., (x, y) and (y, x) are the same edge, the graph is said to be undirected.

🎂 What is the maximum number of edges a graph with $|V|$ vertices can have?

$$\binom{|V|}{2} = \frac{|V|(|V|-1)}{2}$$

$$= \Theta(|V|^2)$$

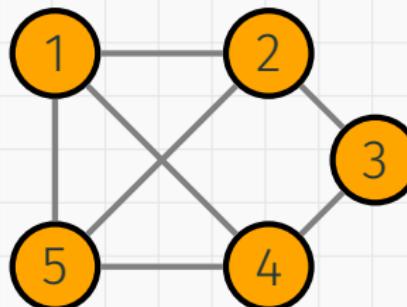


Figure 3: An undirected graph G

DEFINITION OF GRAPH

If the edges are directed, i.e., (x, y) and (y, x) are different edges, the graph is said to be **directed** or a **digraph**.

Parents
and
children.

Teacher

student relationships,

Bosses and subordinates

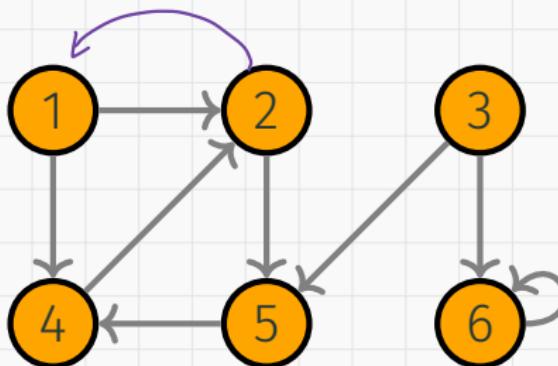


Figure 3: A directed graph G

real world
example:
one-way road
network,
unrequited
love,

ADJACENCY LIST REPRESENTATION OF A GRAPH

If G is sparse, i.e., $|E| = o(|V|^2)$, then we often represent G in adjacency-list form.

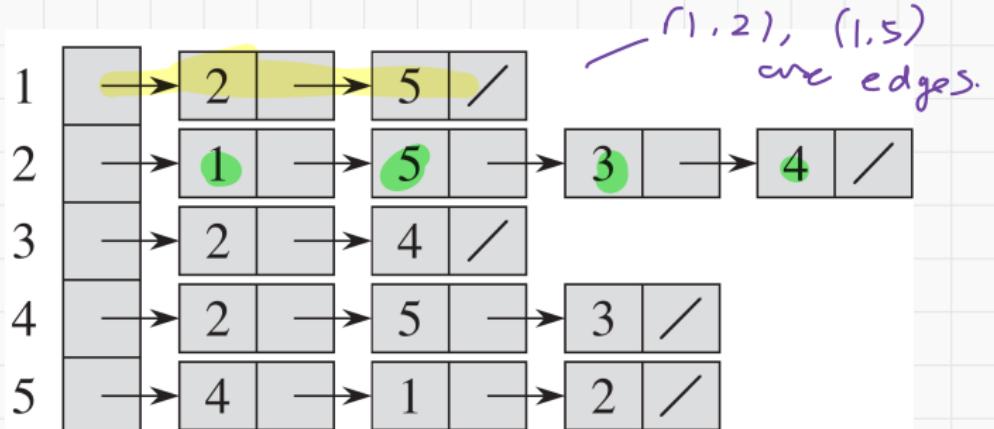
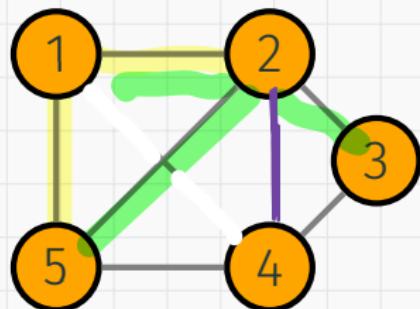
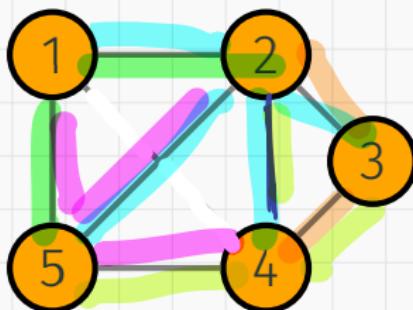


Figure 4: A graph and its adjacency-list representation

ADJACENCY MATRIX REPRESENTATION OF A GRAPH

If G is **dense**, i.e., $|E| = \Theta(|V|^2)$, then we often represent G in **adjacency-matrix** form.



	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

Figure 5: A graph and its adjacency-matrix representation

🎂 Why is the adjacency-matrix for an undirected graph symmetric over the diagonal?
This is an undirected graph.

REPRESENTATION OF DIGRAPHS

We can also represent a **digraph** in both adjacency-list and adjacency-matrix form.

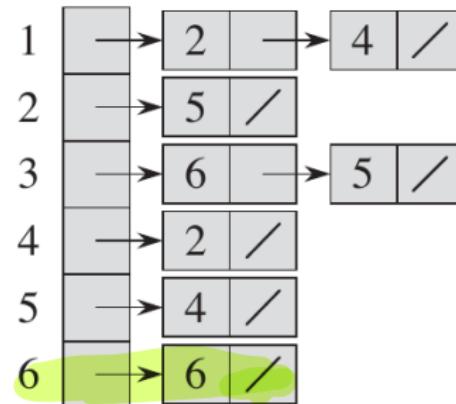
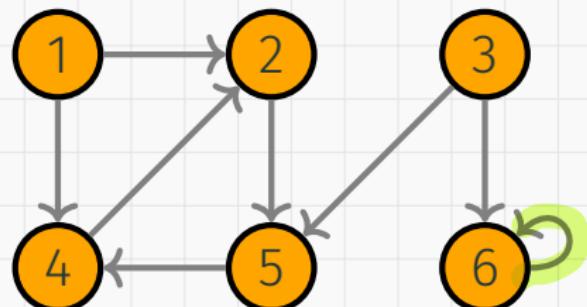
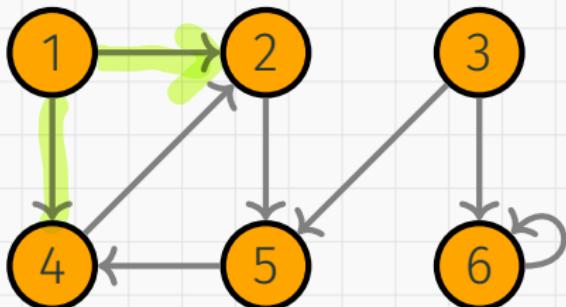


Figure 6: A digraph and its representations

REPRESENTATION OF DIGRAPHS

We can also represent a **digraph** in both adjacency-list and adjacency-matrix form.



	1	2	3	4	5	6
1	0	1	0	1	0	0
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	1	0	0	0	0
5	0	0	0	1	0	0
6	0	0	0	0	0	1

Figure 6: A digraph and its representations

Note that the adjacency matrix is **not necessarily** symmetric for a digraph.

ATTRIBUTES

We use the notations $u.f$ and $(u, v).f$ to indicate the attributes of a vertex or an edge.

These attributes, such as edge weight, can also be stored in adjacency-list or adjacency-matrix form.

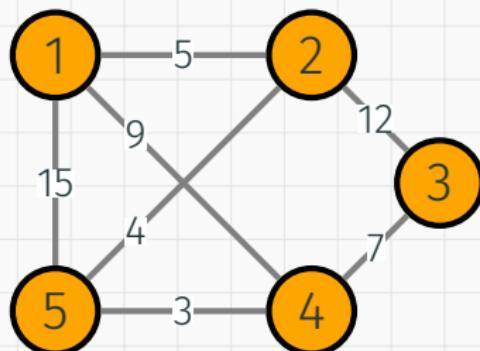


Figure 7: A weighted graph

③ cost of time/money
to travel

0	5	0	9	15
5	0	12	0	4
0	12	0	7	0
9	0	7	0	3
15	4	0	3	0

Real world example :

- ① Markov chain.
- ② length of roads.

B F S.

ITA 20.2 BREADTH-FIRST SEARCH

8-Puzzle

🎂 Can you design an algorithm which moves the tiles to their correct positions using the empty space?

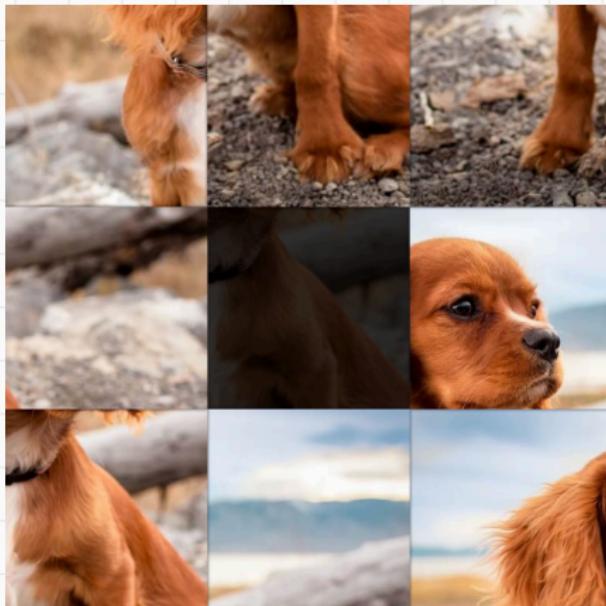


Figure 8: An 8-puzzle

A PANDEMIC ON A GRAPH

Assume that a 😷 is spreading on a graph $G = (V, E)$.

Vertex 1 is infected first on day 0.

Each day, an infected vertex v infects all its neighbours.

How many days will it take for all vertices to become 😷?

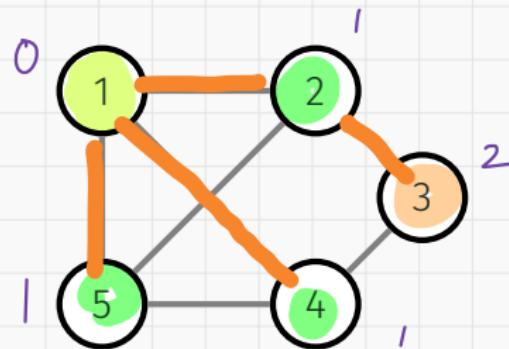
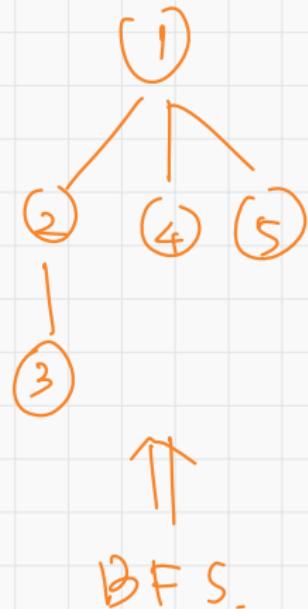
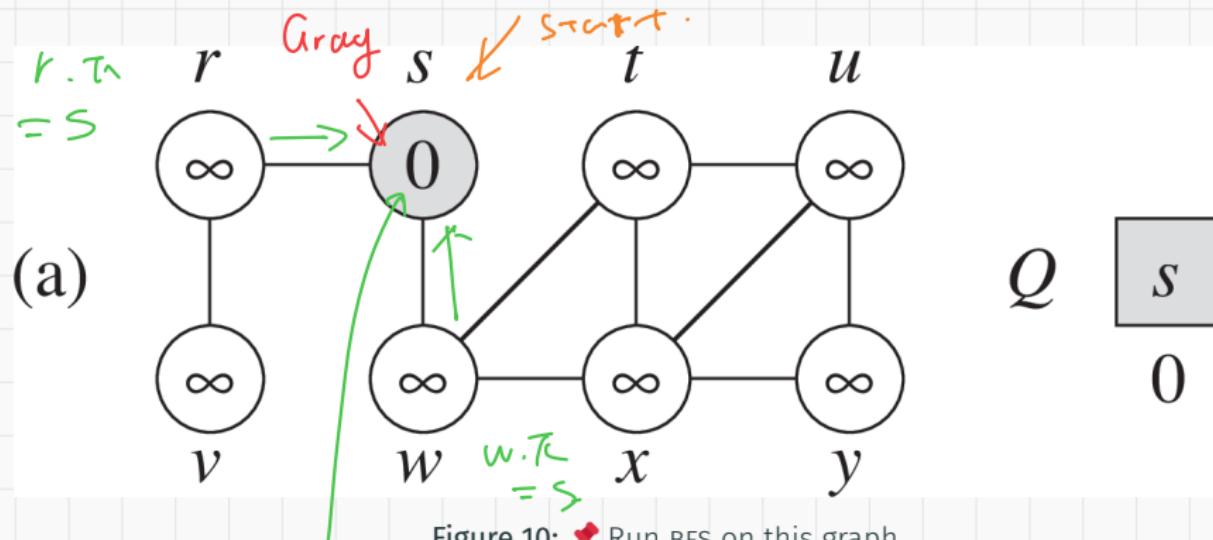


Figure 9: A graph G



EXAMPLE OF BFS

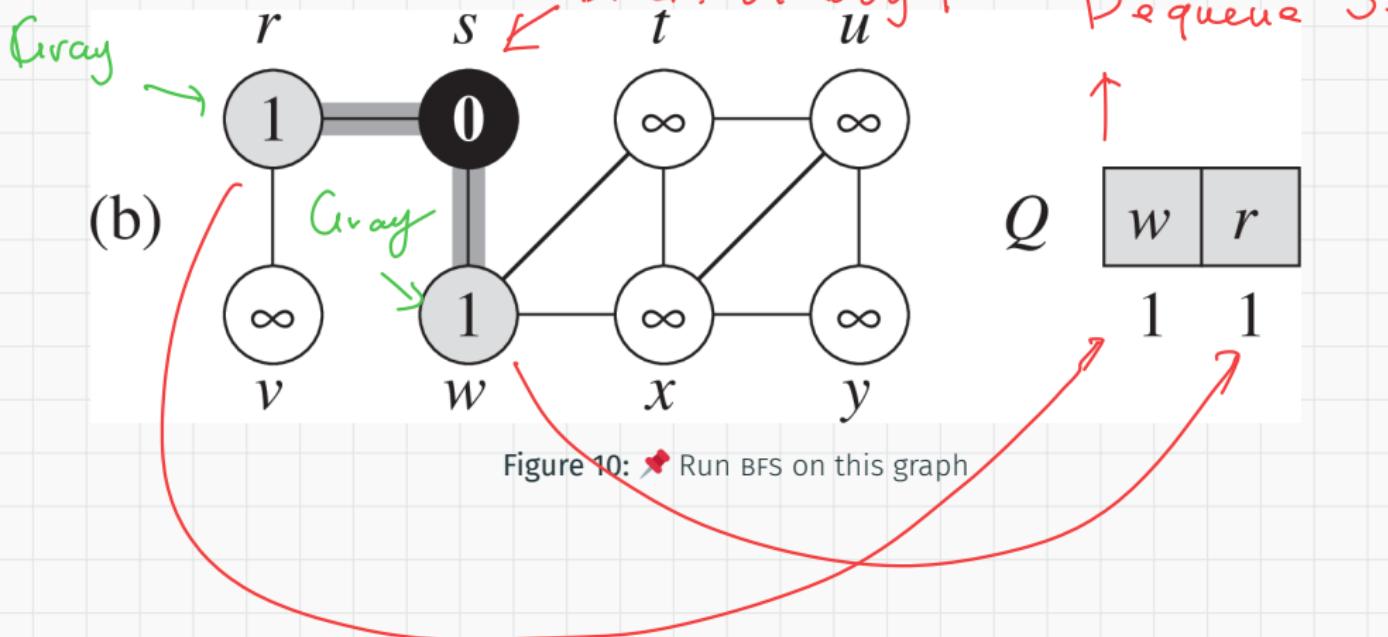
Breadth First Search (BFS) essentially works like the spread of 😊.



EXAMPLE OF BFS

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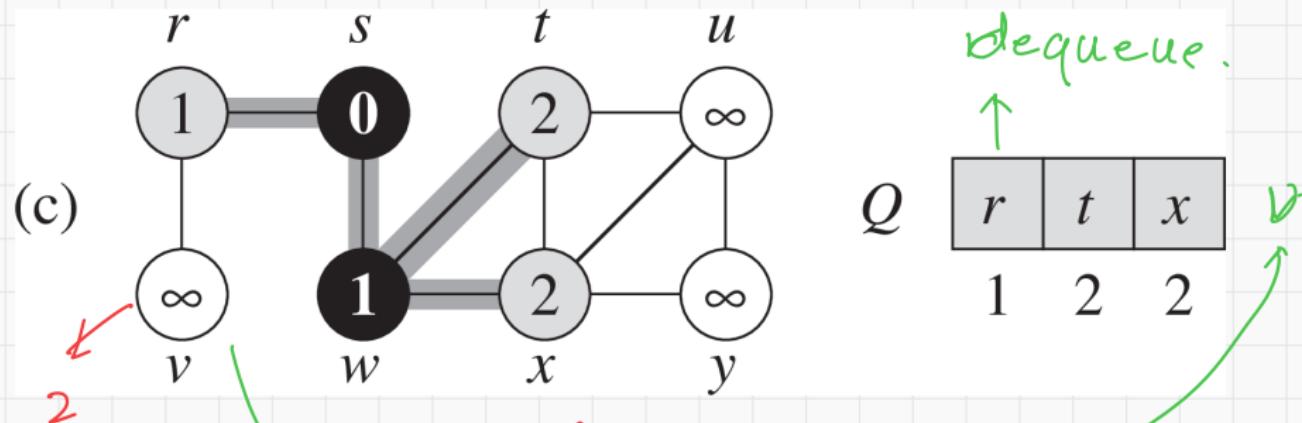
Black: already processed - Dequeue S.



~~Figure 10:~~  Run BFS on this graph

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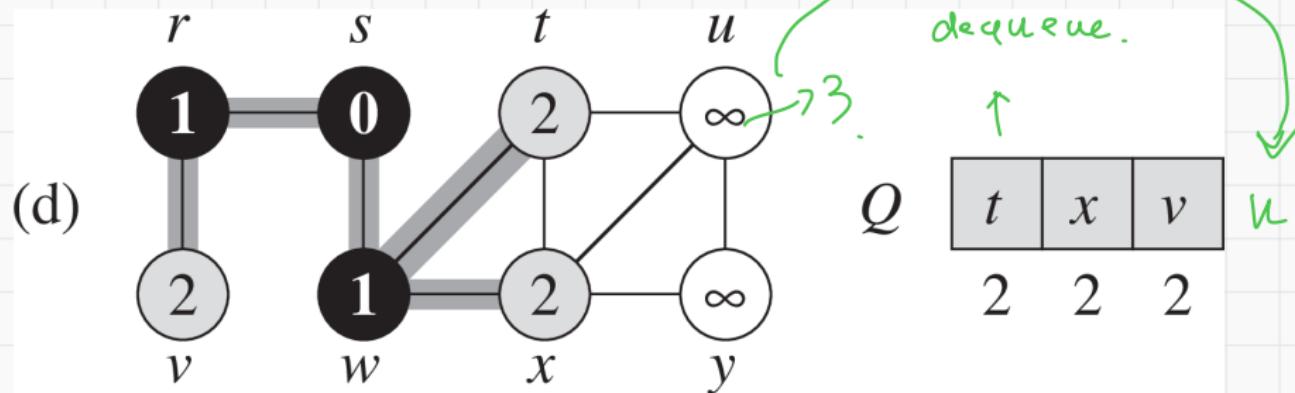
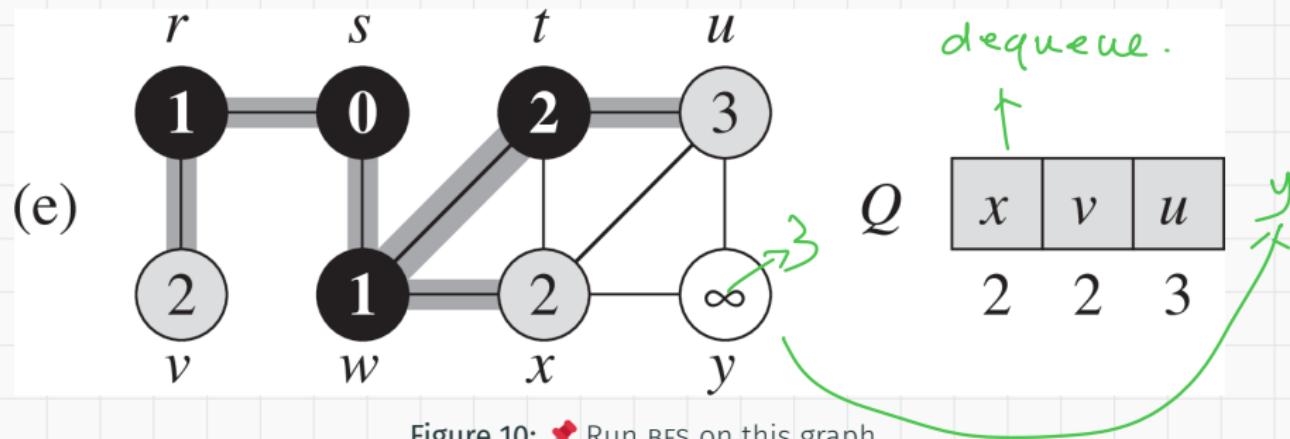


Figure 10: 🚧 Run BFS on this graph

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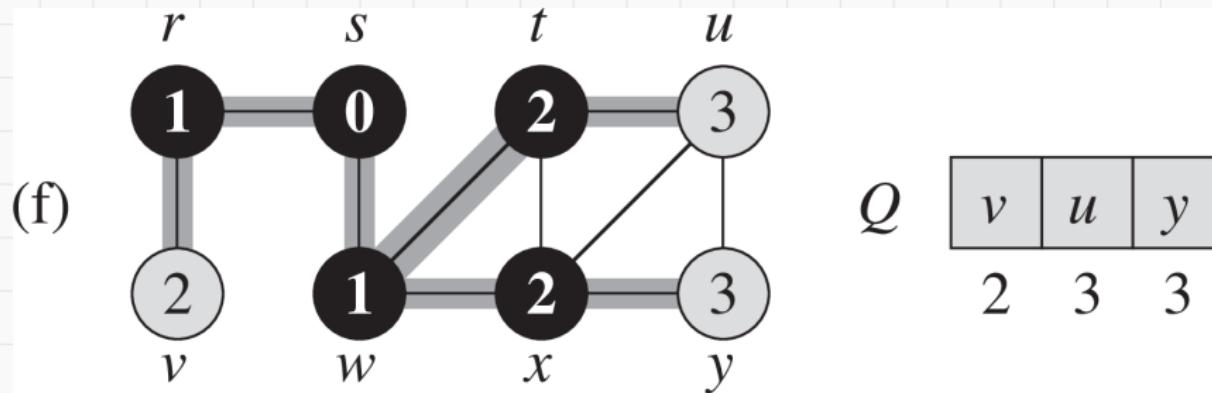


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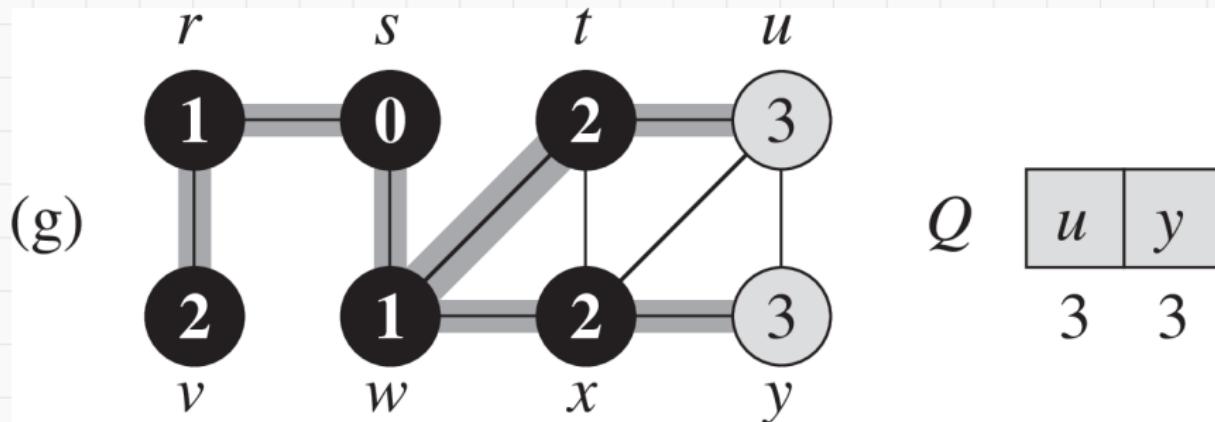


Figure 10: 🚧 Run BFS on this graph

EXAMPLE OF BFS

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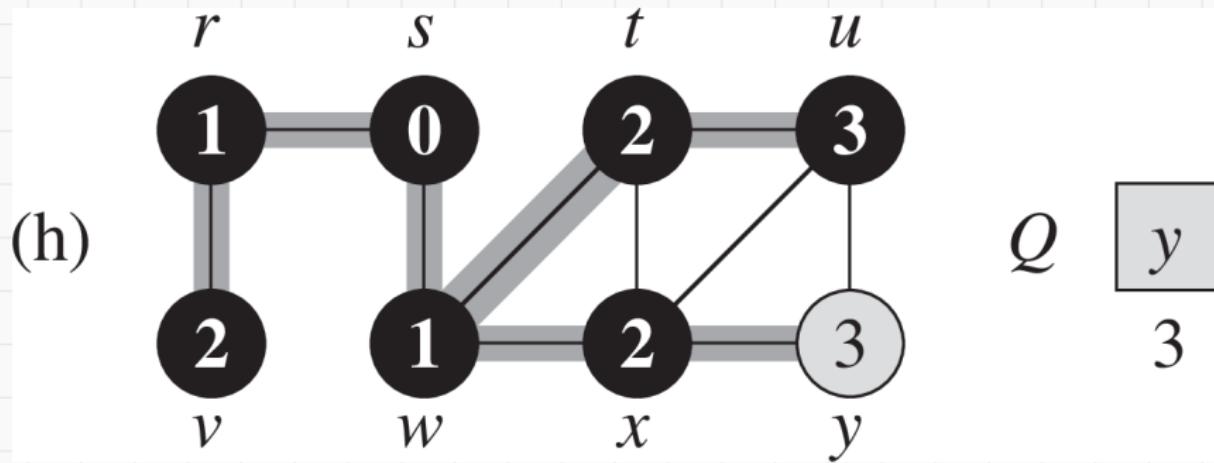


Figure 10: 🚧 Run BFS on this graph

EXAMPLE OF BFS

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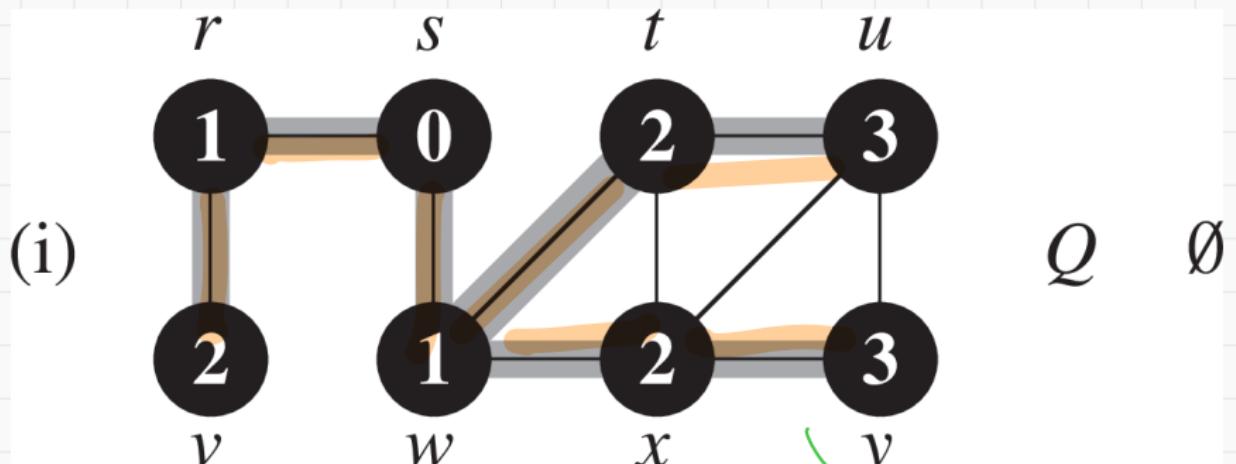


Figure 10: 🚫 Run BFS on this graph

BFS
tree.

WHAT IS BFS

BFS operates on a graph $G = (V, E)$ with a source vertex s .

The algorithm explores edges of G to find all vertices reachable from s .

BFS computes the distance from s to each vertex, constructing a breadth-first tree.

Paths in the tree represent the shortest paths in G . from s .

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Paths in the tree represent the shortest paths in G .

Vertices are initially white, becoming grey upon discovery, and black once fully explored.

Discovery occurs upon first encounter in the search.

A grey vertex has been discovered but not fully explored. Inside Queue.

A black vertex and all its adjacent vertices have been fully explored.

Out Queue.

THE QUEUE DATA STRUCTURE

Definition — A queue is a linear data structure that follows the First-In, First-Out (FIFO) principle.

Operations —

- Enqueue — Add an element to the end of the queue.
- Dequeue — Remove an element from the front of the queue.

Real-World Analogy — A line of customers waiting their turn.

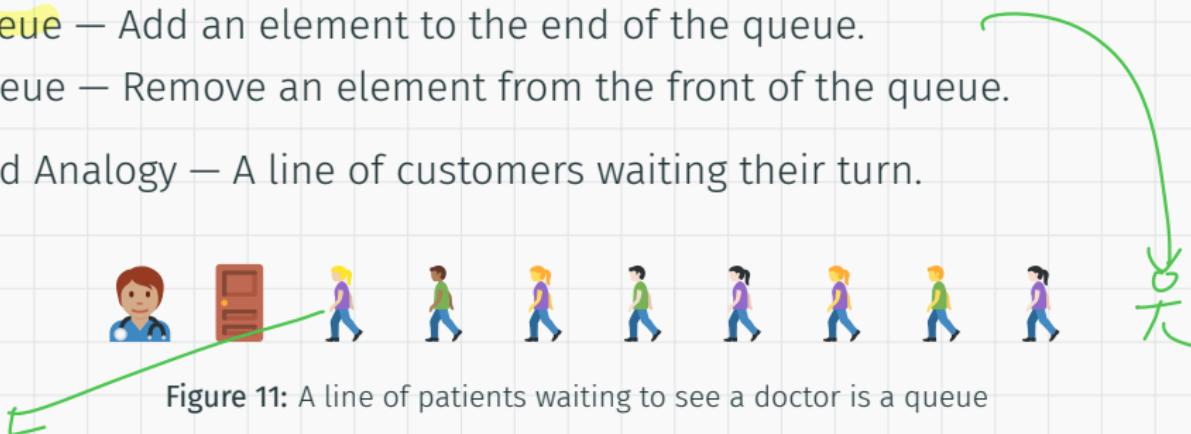


Figure 11: A line of patients waiting to see a doctor is a queue

BFS PSEUDOCODE

```
1: BFS( $G, s$ )
2: for each vertex  $u \in G.V - \{s\}$  do
3:    $u.color = \text{WHITE}$ 
4:    $u.d = \infty$ 
5:    $u.\pi = \text{NIL}$ 
6:  $s.color = \text{GRAY}$ 
7:  $s.d = 0$ 
8:  $s.\pi = \text{NIL}$ 
9:  $Q = \emptyset$ 
10: ENQUEUE( $Q, s$ )
```

Empty s is the first in the queue.

Source.

Not discovered.

initial estimate of distance.

From where it is been discovered.

s to itself has distance 0.

s is the root in BFJ tree.

run $|V| - 1$ times
runtime: $\Theta(|V|)$

}

BFS PSEUDOCODE

Run time: $\Theta(|V|)$

```

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```

Run $\geq |E|$ times

Run time:
 $\Theta(|E|)$.

we have processed
all edges
 v is neighbor
of u -

Not
discovered
discovered

What's the complexity?
 parent child

```

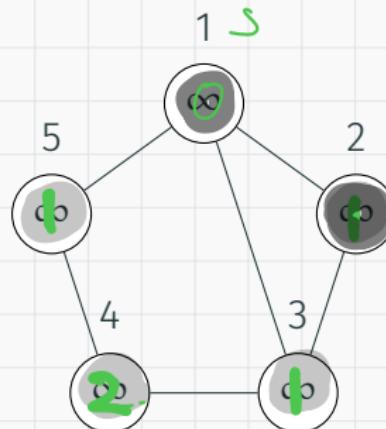
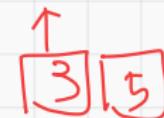
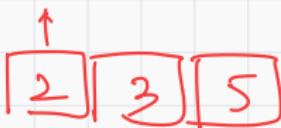
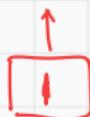
11: while  $Q \neq \emptyset$  do
12:    $u = \text{DEQUEUE}(Q)$ 
13:   for each  $v \in G.\text{Adj}[u]$  do
14:     if  $v.color == \text{WHITE}$  then
15:        $v.color = \text{GRAY}$ 
16:        $v.d = u.d + 1$ 
17:        $v.\pi = u$ 
18:       ENQUEUE( $Q, v$ )
19:    $u.color = \text{BLACK}$  → processed.
    
```

Total Run time: $\Theta(|V| + |E|)$ $v.d = u.d + 1$

🎂 Run BFS on the following graph with $s = 1$ and stops after three vertices become black. What is $4.d$ at this moment?

Answer: 2

Assume that the neighbours of a vertex are stored in adjacency-list form, ordered by their labels in increasing order.



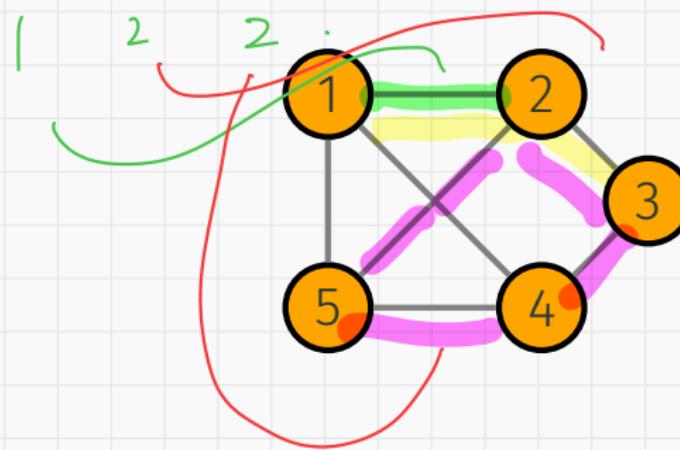
DISTANCE IN A GRAPH

For two vertices u, v in G , the **distance** from u to v is the length of the **shortest path** from u to v .

We denote this distance by $\delta(u, v)$.

If there is no path from u to v , then $\delta(u, v) = \infty$.

🎂 What are $\delta(1, 2), \delta(1, 3), \delta(5, 3)$?

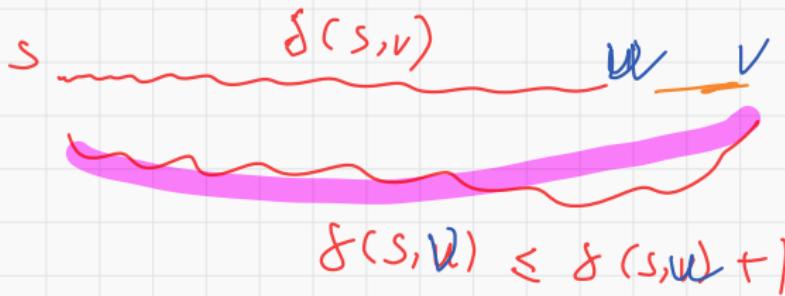


LEMMA 20.1

Let $G = (V, E)$ be a graph. Let $s \in V$ be an arbitrary vertex.

Then for every edge $(u, v) \in E$,

$$\delta(s, v) \leq \delta(s, u) + 1.$$



Proof: Since we can go from s to v by first going from s to u , then u to v , there is a path from s to v of length $\delta(s, u) + 1$.

LEMMA 20.2

Upon termination, for each vertex $v \in V$, the value $v.d$ computed by BFS satisfies
 $v.d \geq \delta(s, v)$.

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Proof Sketch —

We use induction on the number of ENQUEUE operations.

Base Case — Initially, only the source s is enqueued with $s.d = 0 = \delta(s, s)$ and $v.d = \infty \geq \delta(s, v)$ for all other v .

LEMMA 20.2

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Proof Sketch —

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Base Case — Initially, only the source s is enqueued with $s.d = 0 = \delta(s, s)$ and $v.d = \infty \geq \delta(s, v)$ for all other v .

For the inductive step, when a white vertex v is discovered from u , we set

$$v.d = u.d + 1 \geq \delta(s, u) + 1 \geq \delta(s, v)$$

Since $v.d$ is set only once, this maintains the inductive hypothesis.



LEMMA 20.3

Suppose that during the execution of BFS the queue Q contains the vertices

$$\langle v_1, v_2, \dots, v_r \rangle,$$

where v_1 is the head of Q and v_r is the tail. Then,

$$v_r.d \leq v_1.d + 1$$

and

$$v_i.d \leq v_{i+1}.d \quad \text{for } i \in \{1, \dots, r-1\}.$$

LEMMA 20.3

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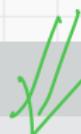
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and

堆証

$$v_i.d \leq v_{i+1}.d \quad \text{for } i \in \{1, \dots, r-1\}.$$

Corollary 20.4



Suppose that vertices v_i and v_j are enqueued during the execution of BFS, and that v_i is enqueued before v_j . Then $v_i.d \leq v_j.d$ at the time that v_j is enqueued.

PROOF OUTLINE OF LEMMA 20.3 (BY INDUCTION)

Base Case –

- Initially, only the source s is in Q , so the lemma holds.

PROOF OUTLINE OF LEMMA 20.3 (BY INDUCTION)

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- Initially, only the source s is in Q , so the lemma holds.

Inductive Step –

• Dequeue Operation –

- If v_1 is dequeued, v_2 becomes the new head.
 - By induction, $v_1.d \leq v_2.d$, and $v_r.d \leq v_1.d + 1 \leq v_2.d + 1$, preserving the inequalities.

\uparrow
Tail.
 \uparrow
New head.

PROOF OUTLINE OF LEMMA 20.3 (BY INDUCTION)

Base Case –

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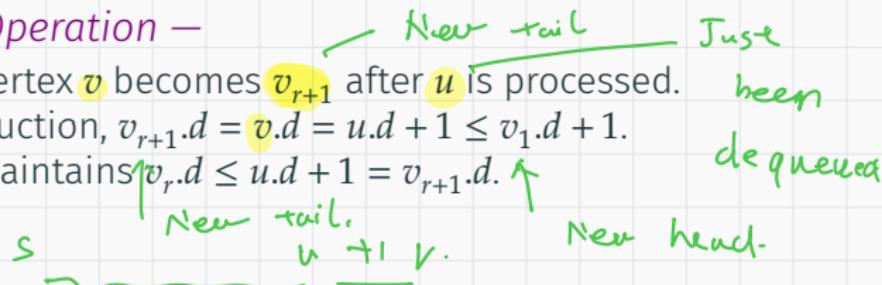
$u | v_1 | v_L \dots v_r$

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• Enqueue Operation –

- New vertex v becomes v_{r+1} after u is processed.
- By induction, $v_{r+1}.d = v.d = u.d + 1 \leq v_1.d + 1$.
- This maintains $v_r.d \leq u.d + 1 = v_{r+1}.d$.



THEOREM 20.5 – CORRECTNESS OF BFS

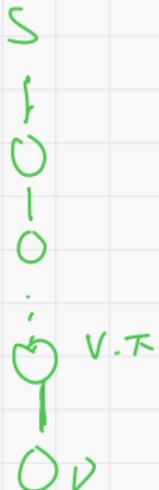
During its execution, BFS discovers every vertex $v \in V$ that is **reachable** from the source s , and upon termination, $v.d = \delta(s, v)$ for all $v \in V$.

THEOREM 20.5 – CORRECTNESS OF BFS

During its execution, BFS discovers every vertex $v \in V$ that is reachable from the source s , and upon termination, $v.d = \delta(s, v)$ for all $v \in V$.

Moreover, for any vertex $v \neq s$ that is reachable from s , one of the shortest paths from s to v is a shortest path from s to $v.\pi$ followed by the edge $(v.\pi, v)$.

- 💡 In short, BFS is **correct**.



PROOF OF BFS CORRECTNESS

Assume, for contradiction, that some vertex v has a d -value different from its shortest-path distance $\delta(s, v)$.

Let v be the vertex with minimum $\delta(s, v)$ that receives an incorrect d value; $v \neq s$.

↑
i

No mistake
in first
step.

PROOF OF BFS CORRECTNESS

Assume, for contradiction, that some vertex v has a d -value different from its shortest-path distance $\delta(s, v)$.

Let v be the vertex with minimum $\delta(s, v)$ that receives an incorrect d value; $v \neq s$.

By Lemma 20.2, $v.d \geq \delta(s, v)$, so

$$v.d > \delta(s, v).$$

can not have =

PROOF OF BFS CORRECTNESS

Assume, for contradiction, that some vertex v has a d -value different from its shortest-path distance $\delta(s, v)$.

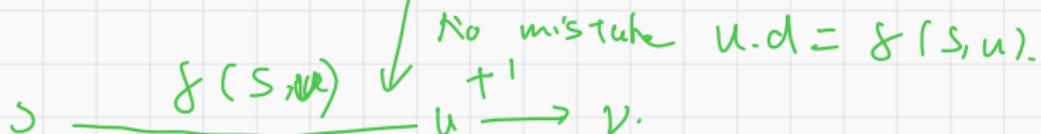
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$$v.d > \delta(s, v).$$

Let u be the vertex immediately before v on a shortest path from s to v , meaning

$$\delta(s, v) = \delta(s, u) + 1.$$



$$\delta(s, w).$$

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Let u be the vertex immediately before v on a shortest path from s to v , meaning

$$\delta(s, v) = \delta(s, u) + 1.$$

Thus, $u.d = \delta(s, u)$, so we have —

$$v.d > \delta(s, v) = \boxed{\delta(s, u) + 1} = u.d + 1.$$

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Thus, $u.d = \delta(s, u)$, so we have —

$$v.d > \delta(s, v) = \delta(s, u) + 1 = u.d + 1.$$



When BFS dequeues u , v is either white, gray, or black —

- If v is white, then $v.d = u.d + 1$, contradicting $v.d > u.d + 1$.
- If v is black, then $v.d \leq u.d$ by Corollary 20.4, again a contradiction.
- If v is gray, it was painted gray when dequeuing some vertex w with $w.d \leq u.d$.
So

$$v.d = w.d + 1 \leq u.d + 1,$$

which also contradicts $v.d > u.d + 1$.

PROOF OF BFS CORRECTNESS

Thus, $u.d = \delta(s, u)$, so we have —

$$v.d > \delta(s, v) = \delta(s, u) + 1 = u.d + 1.$$

When BFS dequeues u , v is either white, gray, or black —

- If v is white, then $v.d = u.d + 1$, contradicting $v.d > u.d + 1$.
- If v is black, then $v.d \leq u.d$ by Corollary 20.4, again a contradiction.
- If v is gray, it was painted gray when dequeuing some vertex w with $w.d \leq u.d$.
So

$$v.d = w.d + 1 \leq u.d + 1,$$

which also contradicts $v.d > u.d + 1$.

Therefore, we have a contradiction and BFS is correct.

PREDECESSOR SUBGRAPH

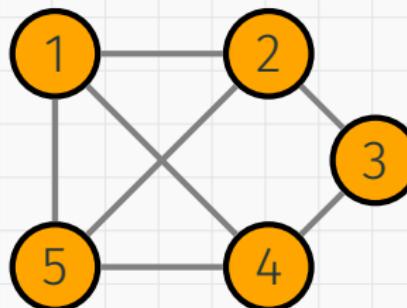
For a graph $G = (V, E)$ with source s , we define the **predecessor subgraph** of a BFS as $G_\pi = (V_\pi, E_\pi)$, where

$$V_\pi = \{v \in V : v.\pi \neq \text{NIL}\} \cup \{s\}$$

and

$$E_\pi = \{(v.\pi, v) : v \in V_\pi - \{s\}\}.$$

🎂 What is G_π for the following graph if $s = 1$?

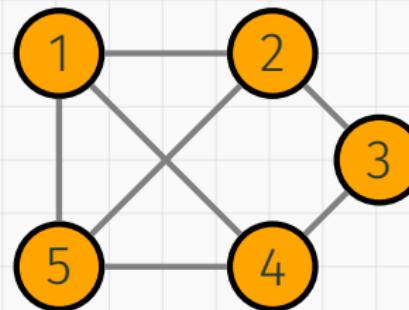


BREADTH-FIRST TREE

A subgraph of G is called a **breadth-first tree** if

- it contains all vertices reachable from s ,
- every path in it is also the shortest path between the two endpoints,
- it is a tree.

🎂 What is a breadth-first tree for the following graph if $s = 1$?



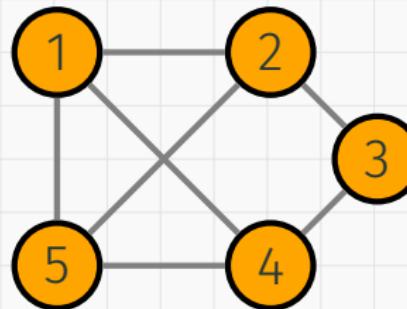
BREADTH-FIRST TREE

A subgraph of G is called a **breadth-first tree** if

- it contains all vertices reachable from s ,
- every path in it is also the shortest path between the two endpoints,
- it is a tree.



Can you think of another one?



 LEMMA 20.6

The predecessor subgraph G_π of a graph G , as produced by BFS, is a breadth-first tree.

Proof Sketch —

- G_π is connected because it contains all vertices reachable from s , by Theorem 20.5.

 LEMMA 20.6

The predecessor subgraph G_π of a graph G , as produced by BFS, is a breadth-first tree.

Proof Sketch –

- G_π is connected because it contains all vertices reachable from s , by Theorem 20.5.
- The number of edges in G_π is one less than the number of vertices, as each vertex (except s) has a unique predecessor. Thus, G_π forms a tree.

 LEMMA 20.6

The predecessor subgraph G_π of a graph G , as produced by BFS, is a breadth-first tree.

Proof Sketch –

- G_π is connected because it contains all vertices reachable from s , by Theorem 20.5.
- The number of edges in G_π is one less than the number of vertices, as each vertex (except s) has a unique predecessor. Thus, G_π forms a tree.
- The distance from s to any vertex v in G_π is $v.d = \delta(s, v)$, by Theorem 20.5. Therefore, the unique path from s to v in G_π represents a shortest path from s to v in G .

FIND THE SHORTEST PATH

Given a graph G whose breadth-first tree has been computed by BFS, we can print the shortest path from s to v using the following algorithm —

```
Print-Path( $G, s, v$ )
if  $v == s$  then
    print  $s$ 
else if  $v.\pi == \text{NIL}$  then
    print "no path from"  $s$  "to"  $v$ 
else
    PRINT-PATH( $G, s, v.\pi$ )
    print  $v$ 
```

🍰 How can we solve this maze using BFS?

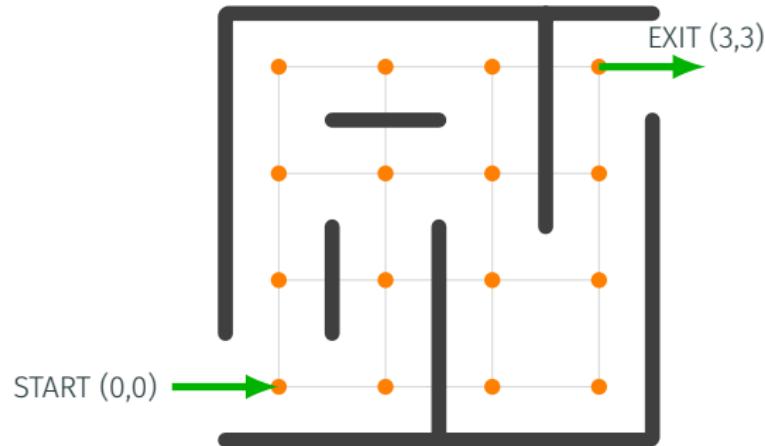


Figure 12: 4x4 Maze for BFS Visualization

Try it out at <https://brkwok.github.io/Maze-Solver/>.

SOLVE THE 8-Puzzle



How can we solve the 8-puzzle using BFS?

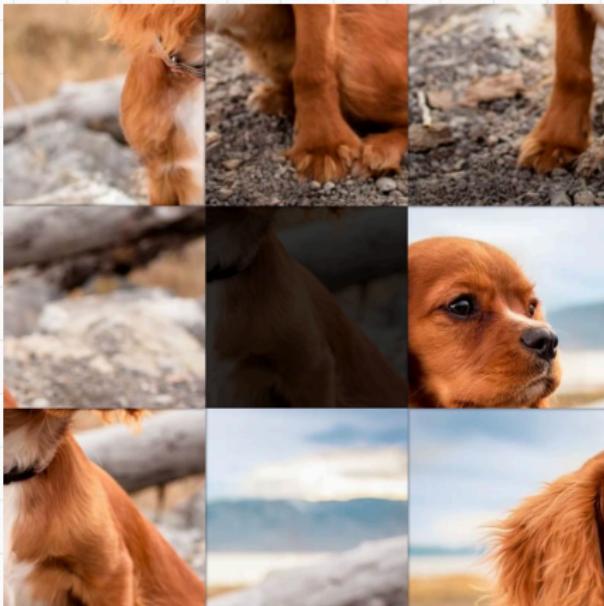


Figure 13: An 8-puzzle

8	5	4
1		3
6	7	2



8	5	4
	1	3
6	7	2



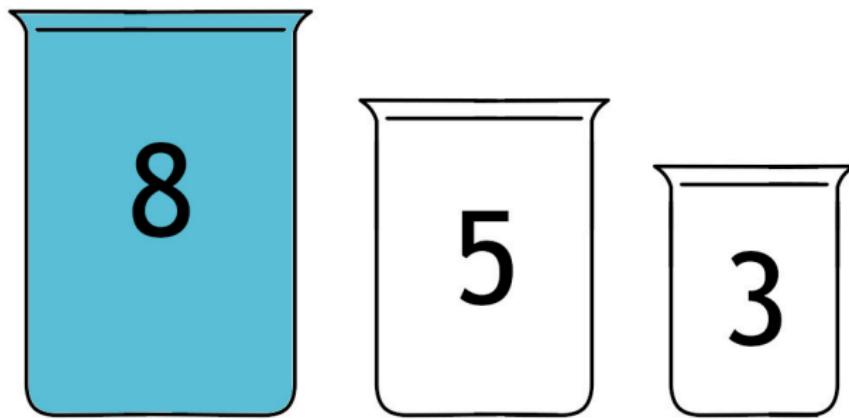
8	5	4
1	3	
6	7	2

WATER POURING PUZZLE

We have a jug filled with 8 units of water, and two empty jugs of sizes 5 and 3.

How can we make the first and second jugs both contain 4 units, and the third is empty, without using any extra tools?

💡 How to solve this puzzle using BFS?



WHAT ARE YOUR MAIN TAKEAWAYS TODAY? ANY QUESTIONS?

