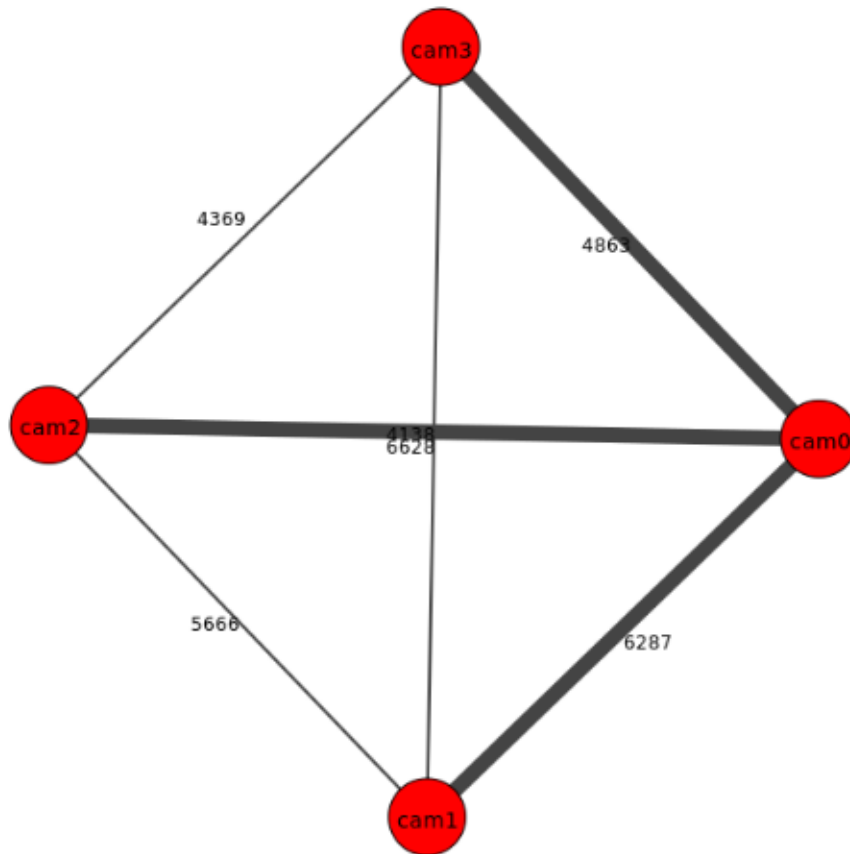
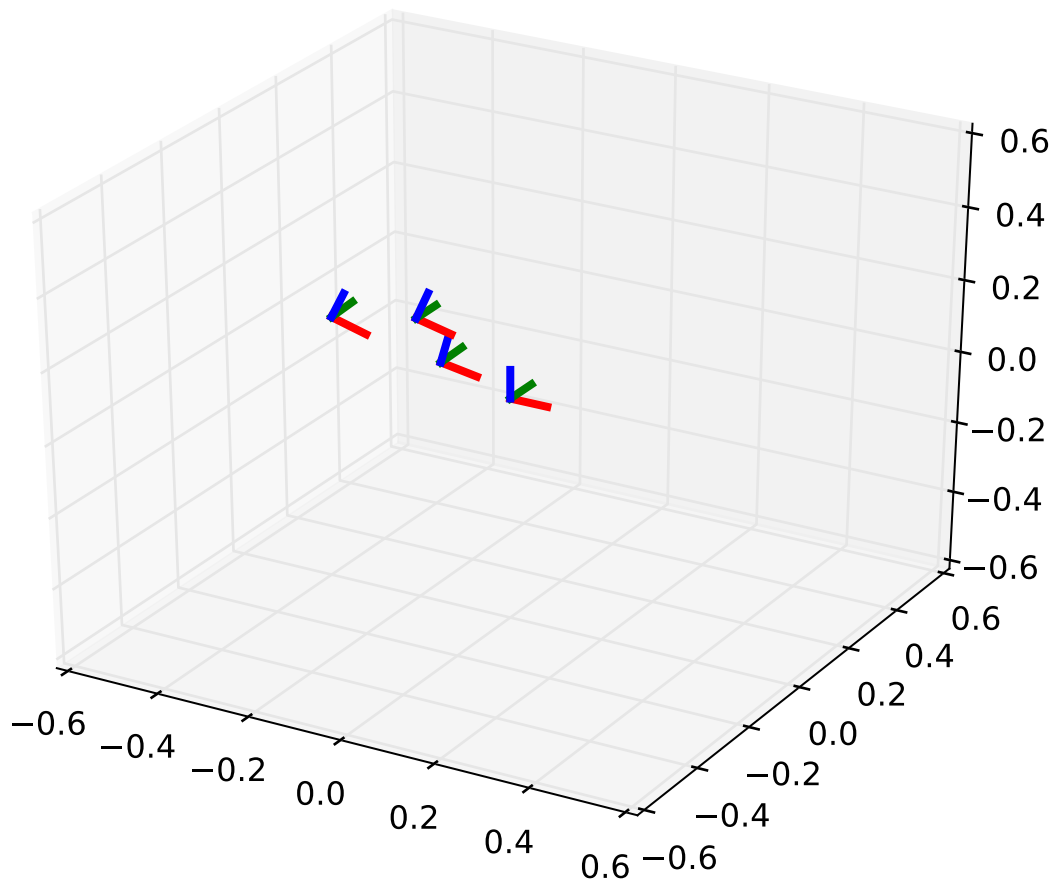


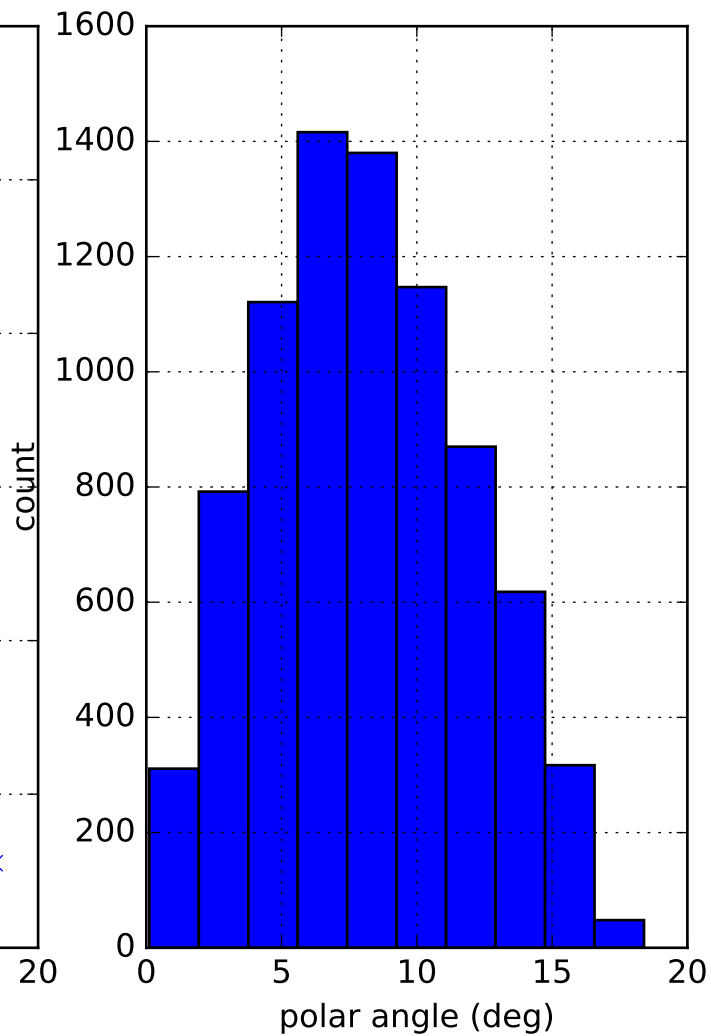
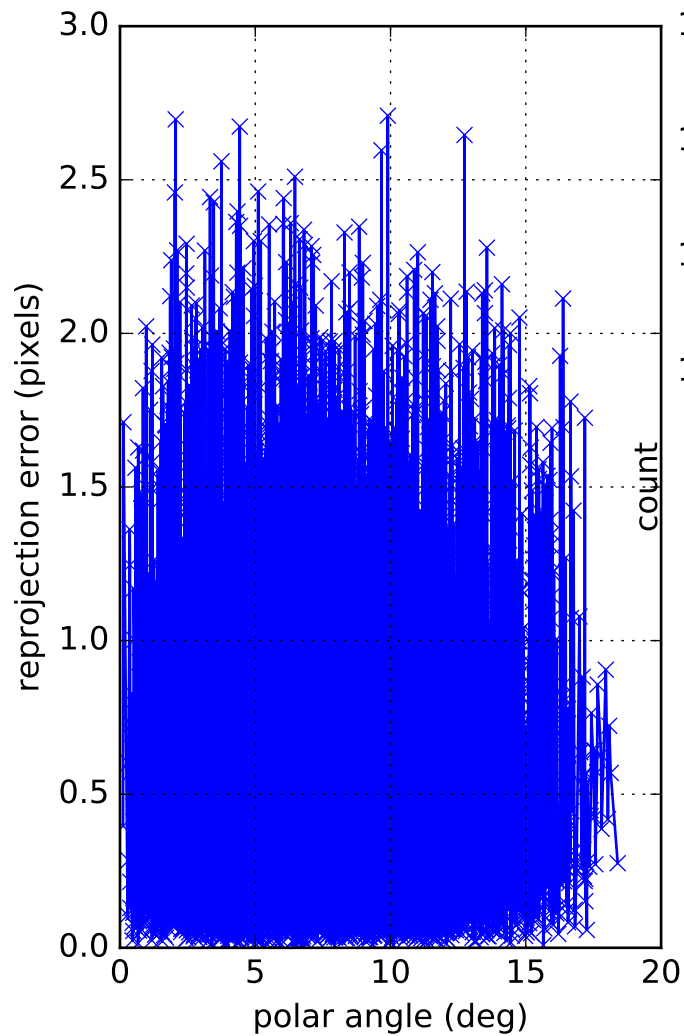
Inter-camera observations graph (edge weight=#mutual obs.)



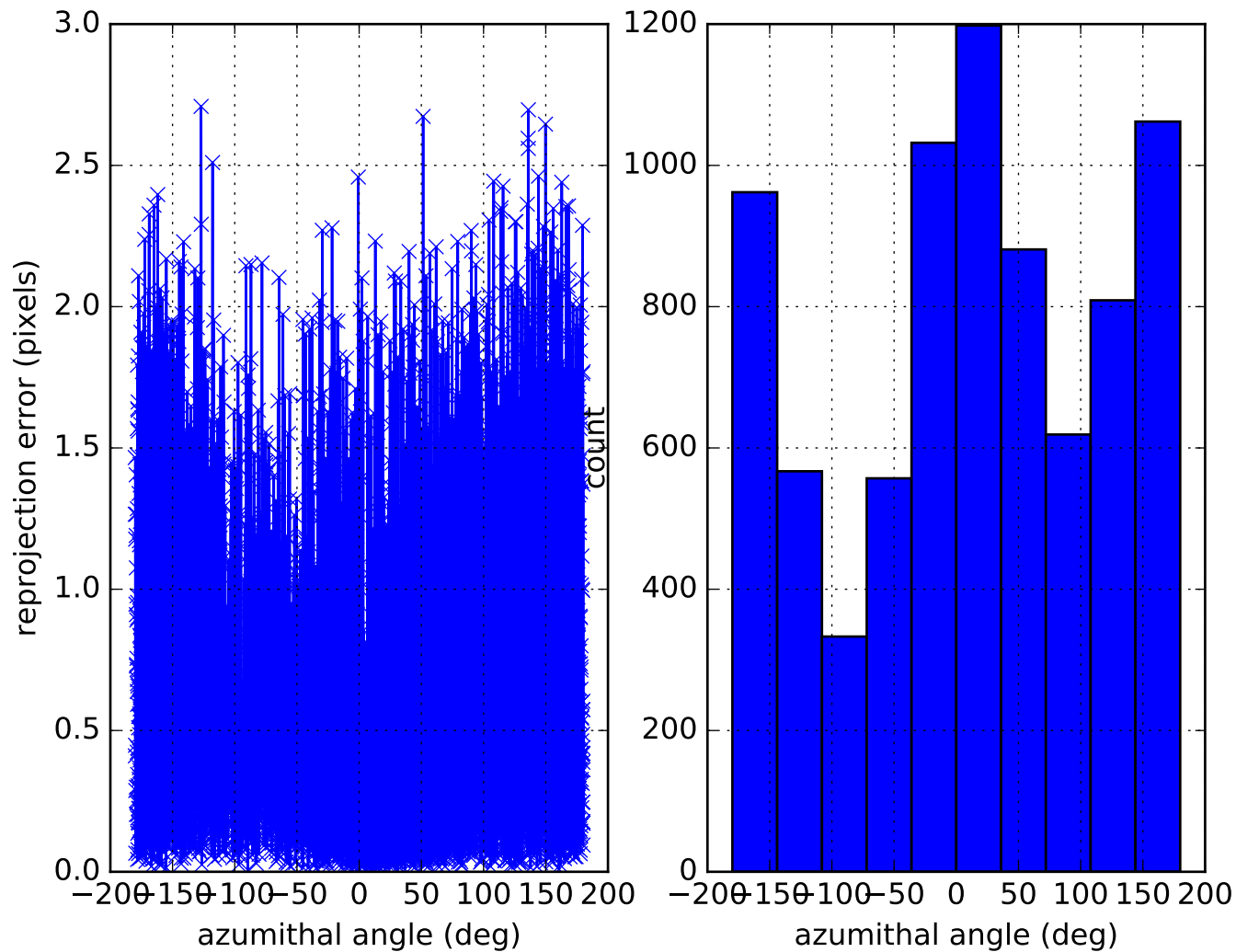
camera system



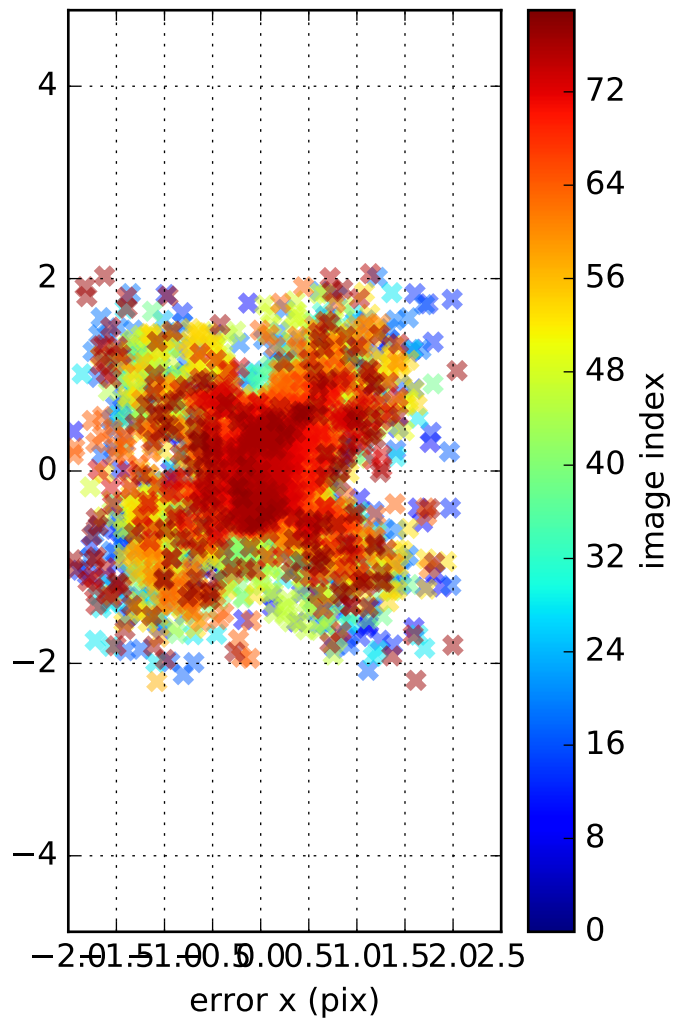
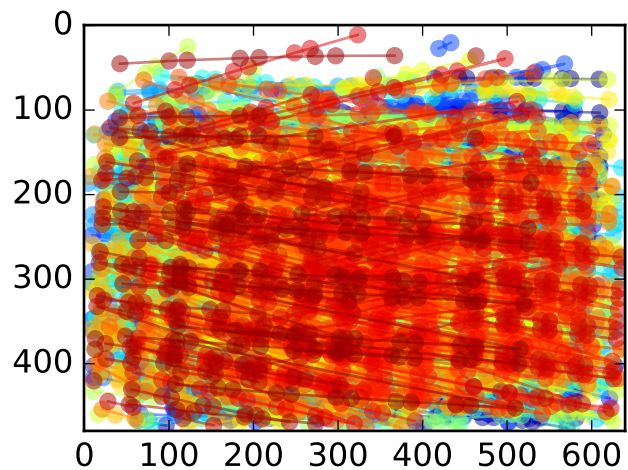
cam0: polar error



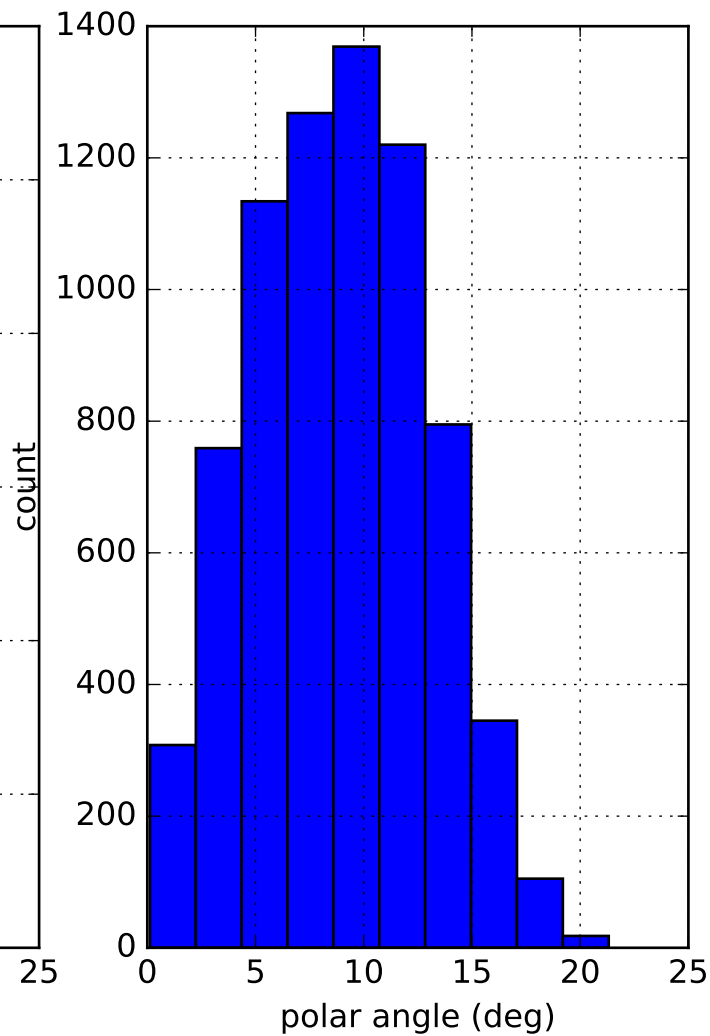
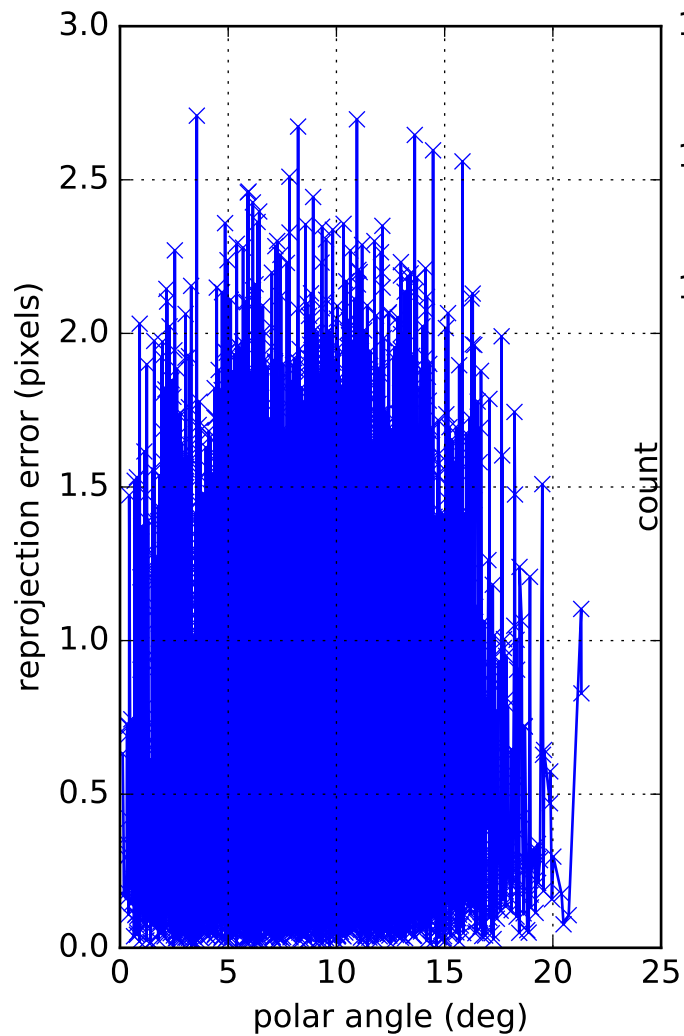
cam0: azimuthal error



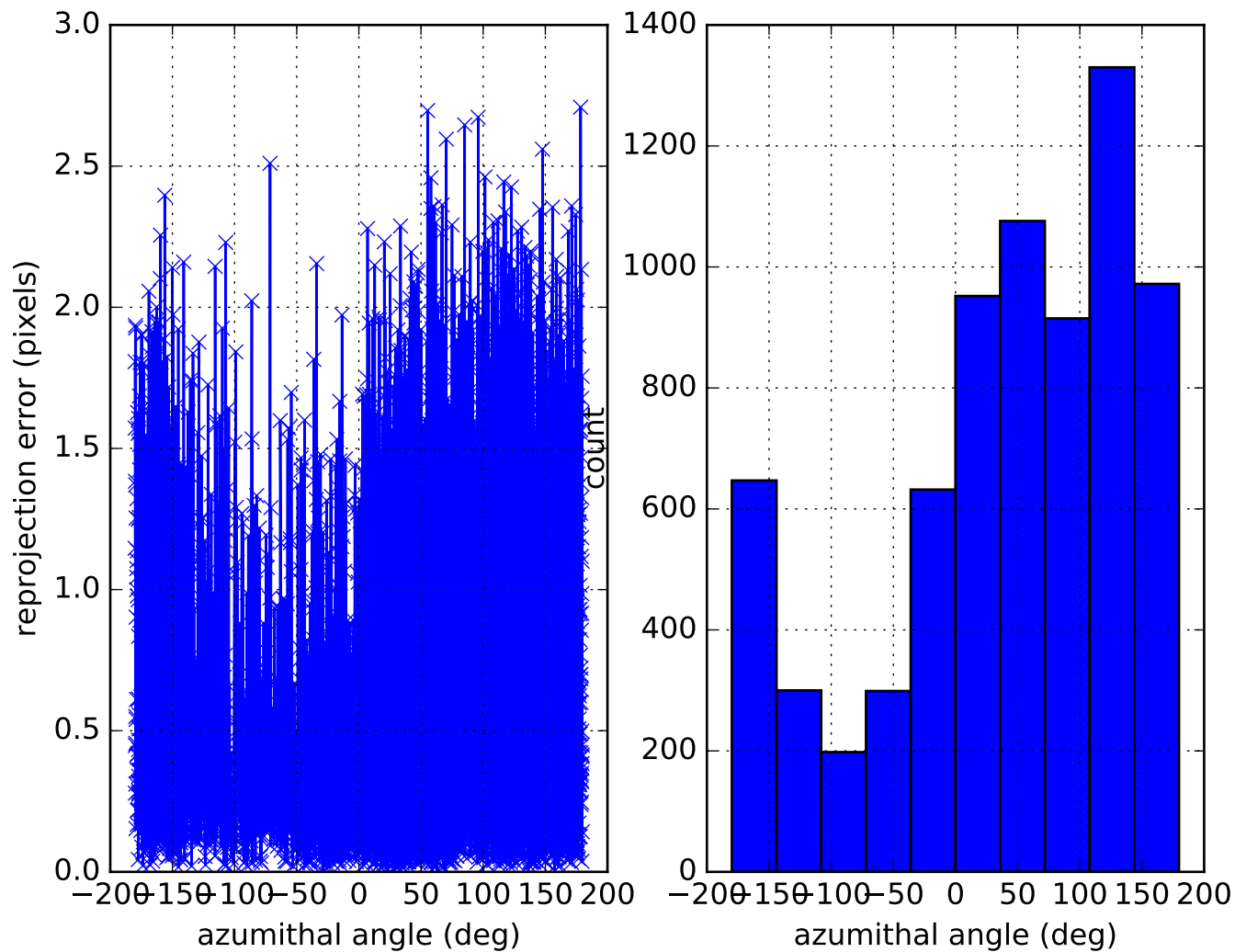
cam0: reprojection errors



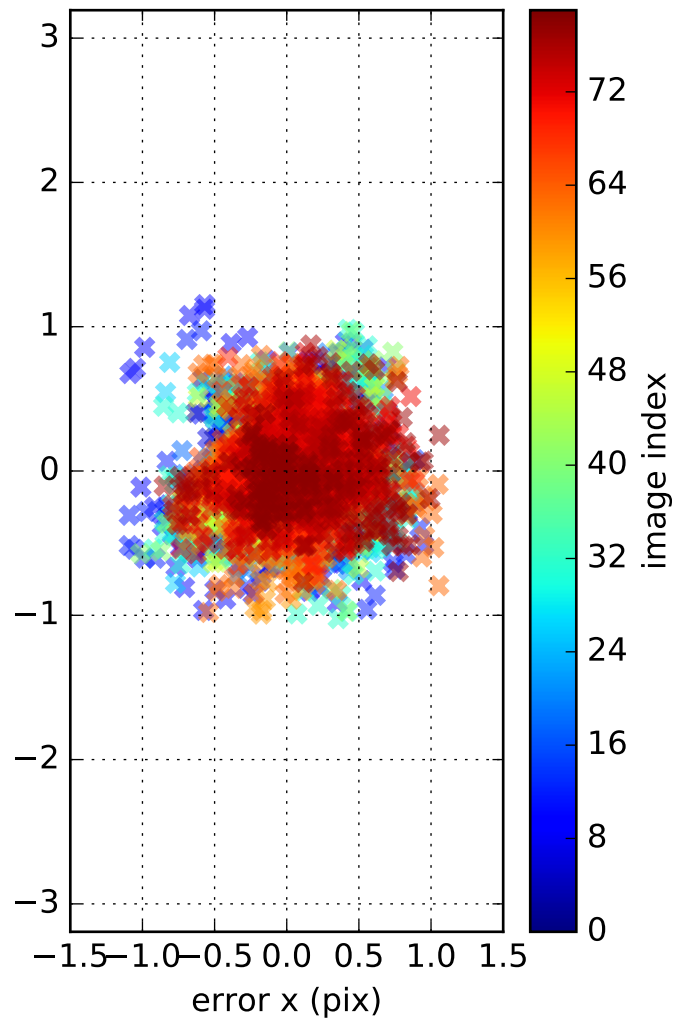
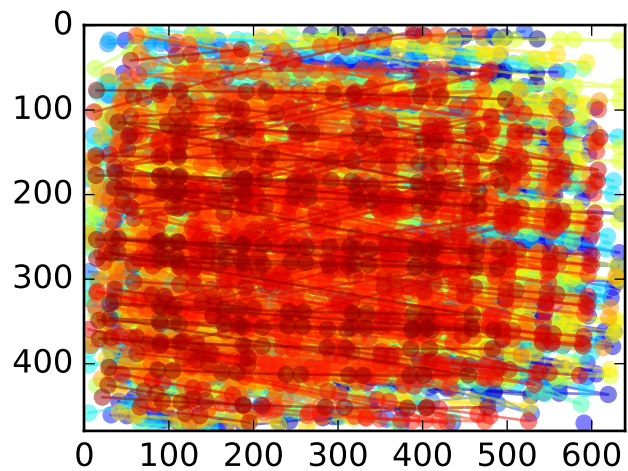
cam1: polar error



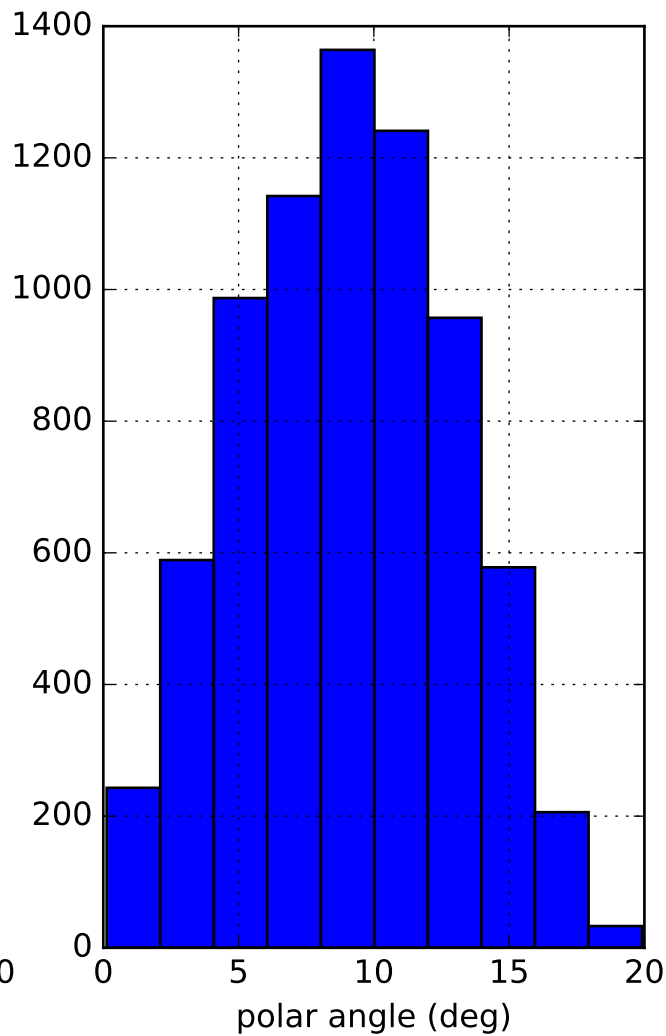
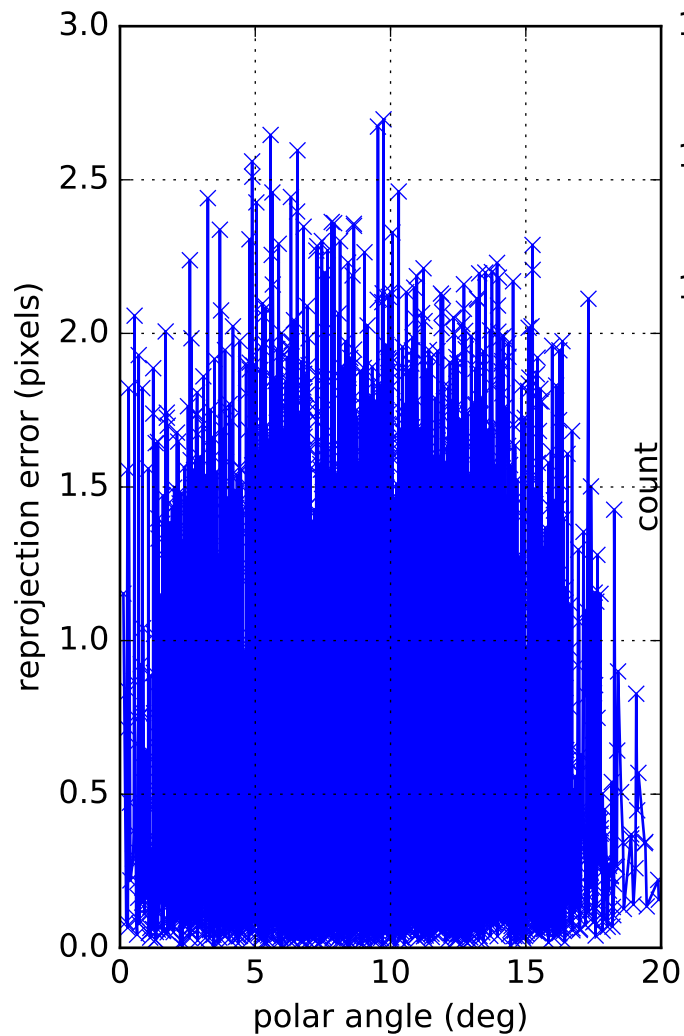
cam1: azimuthal error



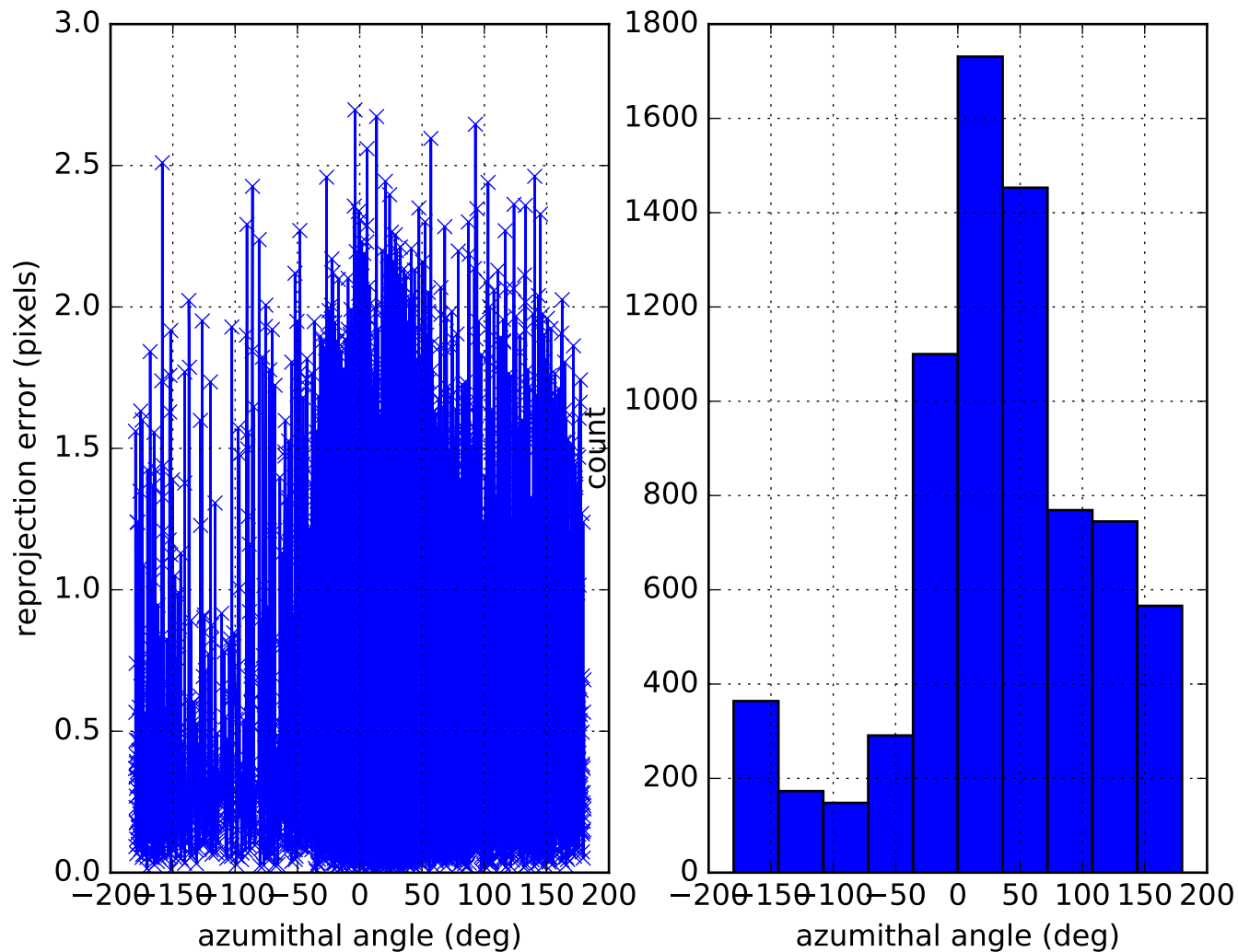
cam1: reprojection errors



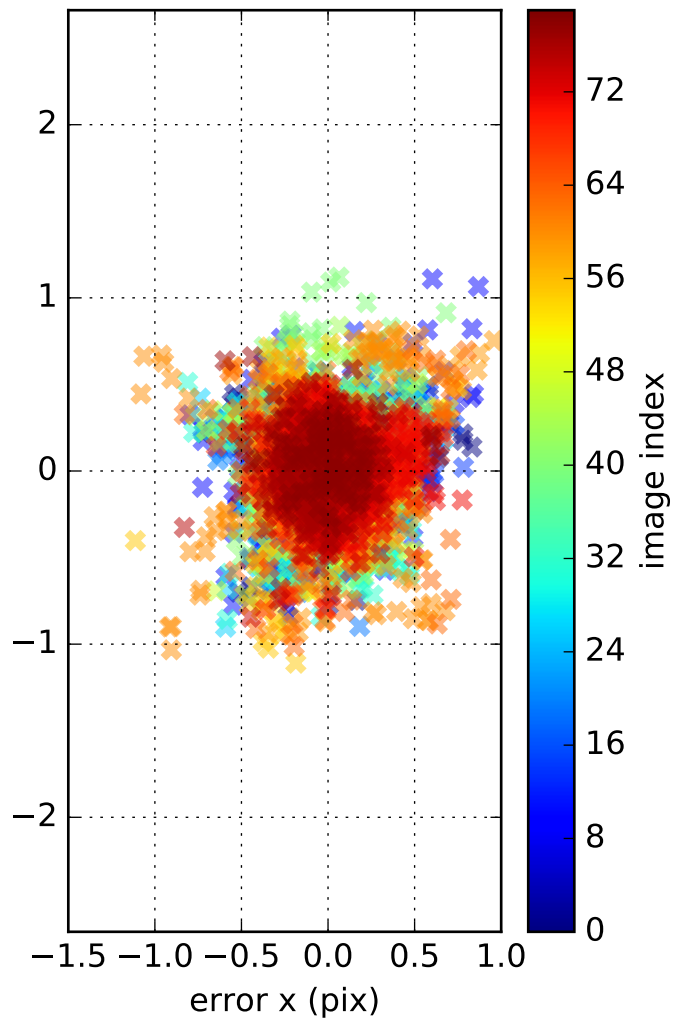
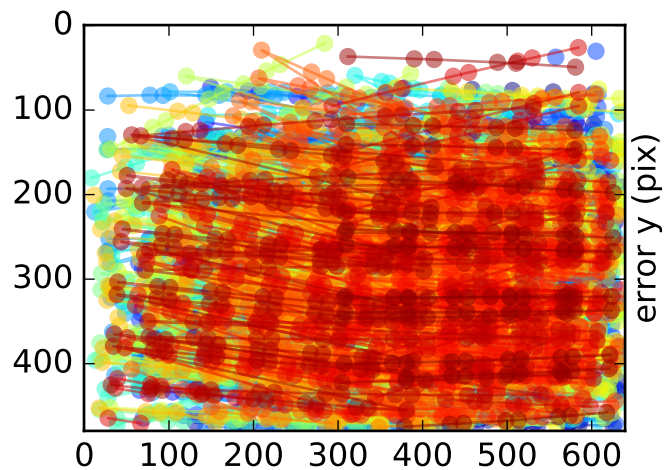
cam2: polar error



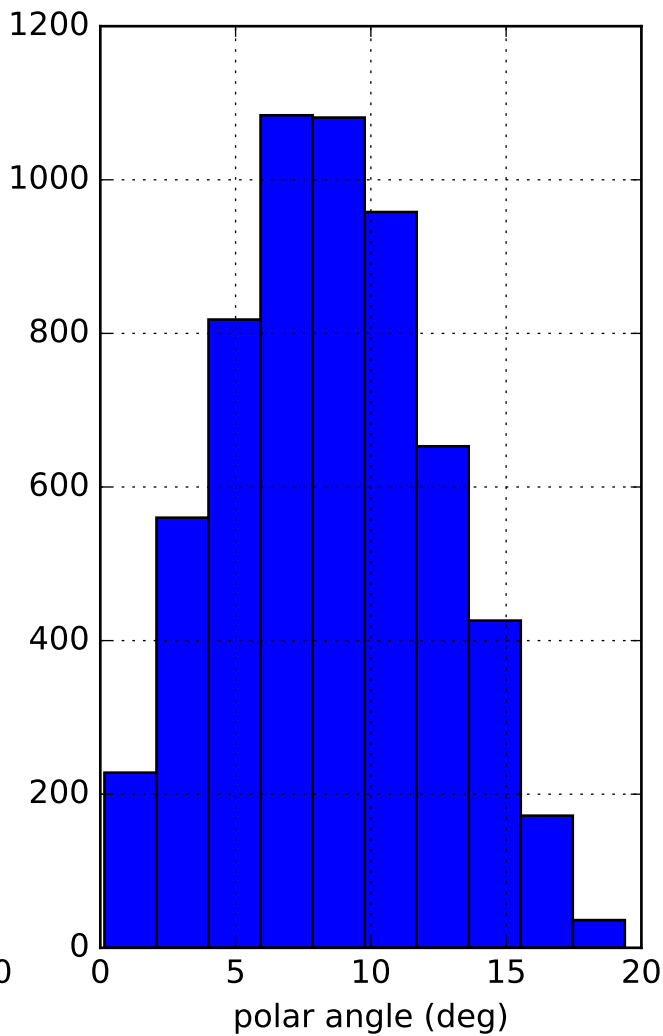
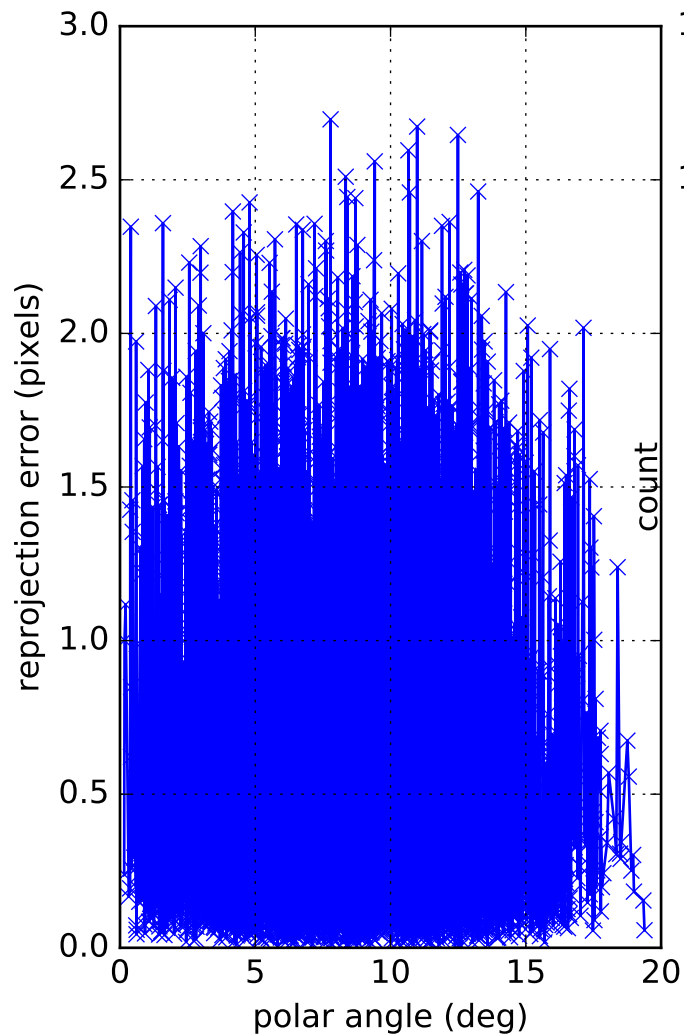
cam2: azimuthal error



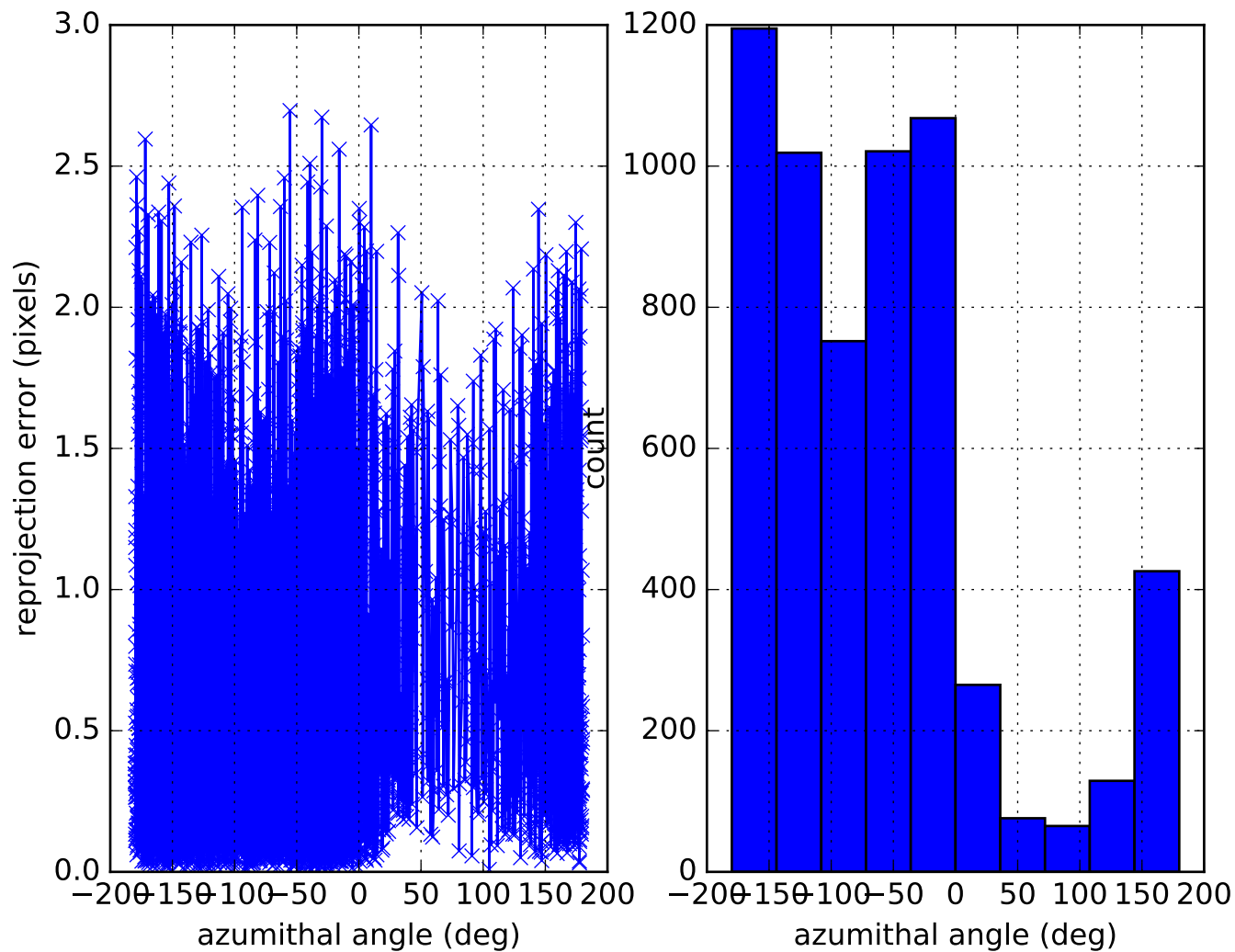
cam2: reprojection errors



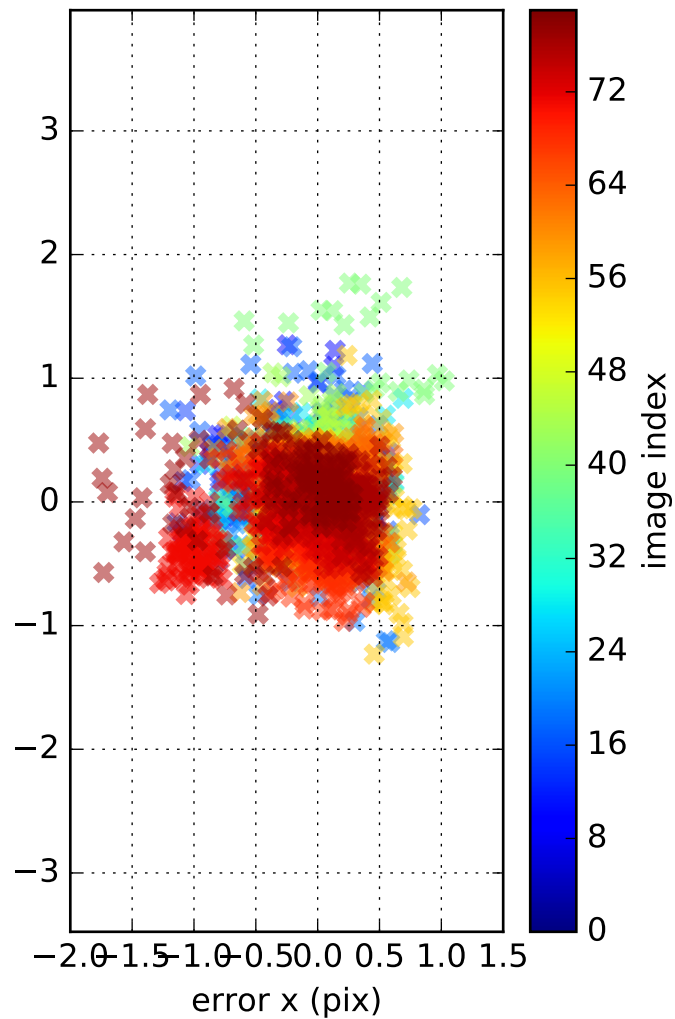
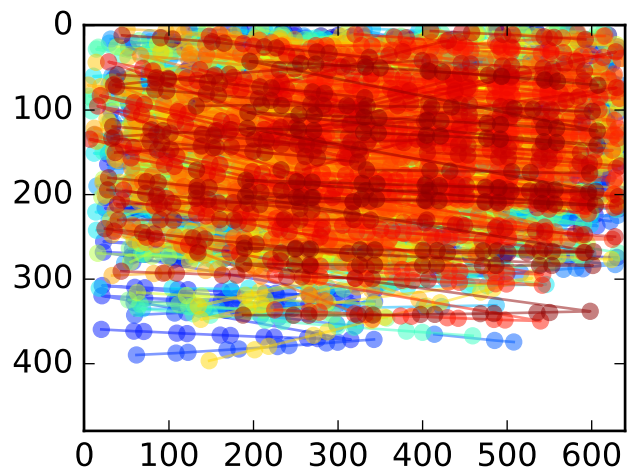
cam3: polar error



cam3: azimuthal error

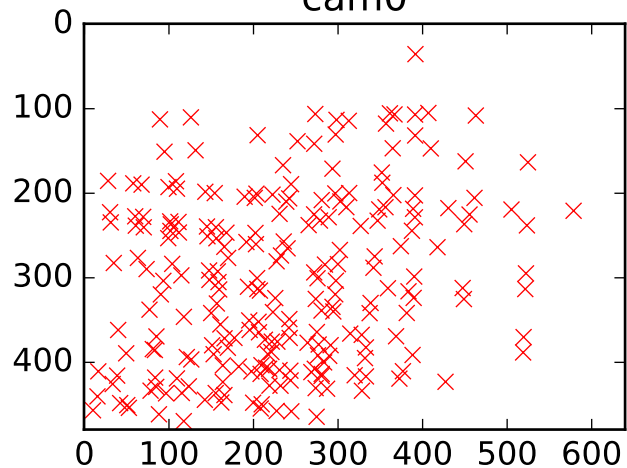


cam3: reprojection errors

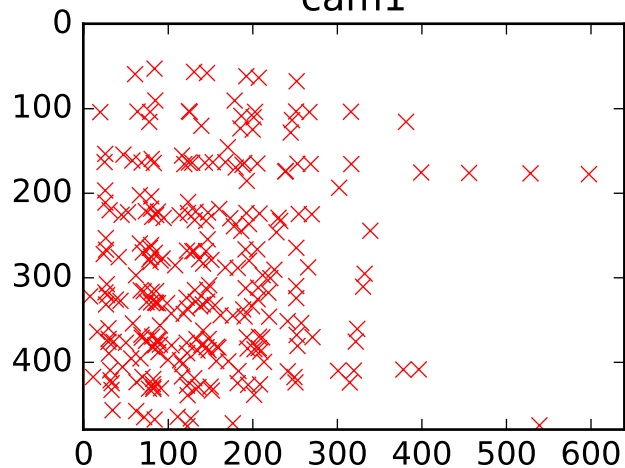


Location of removed outlier corners

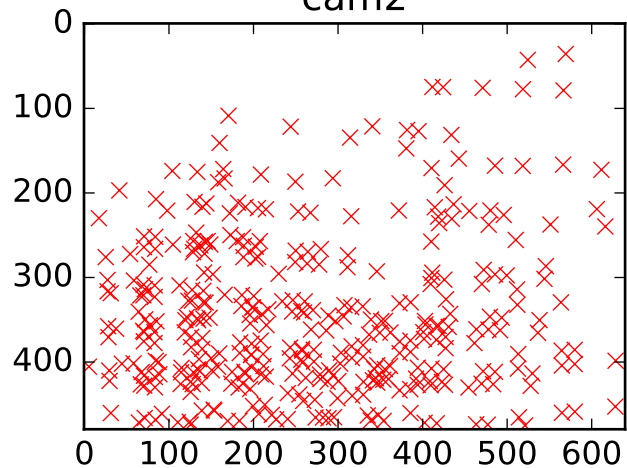
cam0



cam1



cam2



cam3

