# Computational Finance

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## 1 Introduction

- <u>Forward contract</u>: a customized *binding* contract to buy/sell an asset at a specific price (**forward price**) on a *future* date.
- American option: gives the holder the *right* to exercise the option at any time before the date of expiration.
- European option: can only be exercised at the date of expiration.
- call/put option: gives the holder the right to buy/sell.
- **Derivative asset**: assets defined in terms of underlying financial asset.

## 2 The Binomial Model

### 2.1 The One Period Model

### 2.1.1 Definitions

• **Bond** price process is deterministic and given by

$$B_0 = 1,$$
  
$$B_1 = 1 + R.$$

where constant R is the spot rate for the period.

• Stock price process is stochastic and given by

$$S_0 = s,$$
  
$$S_1 = s \cdot Z$$

where Z is a stochastic variable defined as

$$Z = \begin{cases} u, & \text{with probability } p_u, \\ d, & \text{with probability } p_d. \end{cases}$$

with  $p_u + p_d = 1$  and the assumption that d < u.

• **Portfolio** on the (B, S) market is a vector

$$h = (x, y).$$

with a deterministic market value at t = 0 and stochastic value at t = 1.

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• Value Process of the portfolio h is defined as

$$V_t^h = xB_t + yS_t, \quad t = 0, 1,$$

or, in more detail,

$$V_0^h = x + ys,$$
  

$$V_1^h = x(1+R) + ysZ.$$

• **Arbitrage** portfolio is an h with the properties

$$V_0^h = 0,$$
  
 $V_1^h > 0,$  with probability 1

### 2.1.2 Contingent Claim Pricing

**Proposition 1.** The model h is free of arbitrage  $\iff d \leq (1+R) \leq u$ .

**Comments** The above proposition implies that (1 + R) is a convex combination of u and d, i.e.

$$1 + R = q_u \cdot u + q_d \cdot d,$$

where  $q_u$  and  $q_d$  can be interpreted as probabilities for a new probability measure Q with  $P(Z = u) = q_u$  and  $P(Z = d) = q_d$ . Denoting expectation w.r.t. this measure by  $E^Q$  and with the following calculation

$$\frac{1}{1+R}E^{Q}[S_{1}] = \frac{1}{1+R}[q_{u}su + q_{d}sd] = \frac{1}{1+R} \cdot s(1+R) = s,$$

we arrive at the following relation

$$s = \frac{1}{1+R} E^Q[S_1].$$

**Definition 2.** A probability measure Q is <u>martingale</u> if the following condition holds:

$$S_0 = \frac{1}{1+R} E^Q[S_1].$$

**Proposition 3.** Arbitrage-free model  $\iff \exists$  martingale measure Q.

**Proposition 4.** For the binomial model above, the martingale probabilities are

$$\begin{cases} q_u = \frac{(1+R) - d}{u - d}, \\ q_d = \frac{u - (1+R)}{u - d}. \end{cases}$$

*Proof.* Solve the system of equation

$$\begin{cases} 1 + R = q_u \cdot u + q_d \cdot d \\ q_u + q_d = 1. \end{cases}$$

**Definition 5.** A <u>contingent claim</u> (financial derivative) is any stchastic variable  $\overline{X}$  of the form  $X = \Phi(Z)$ , where Z is the stochastic variable driving the stock price process above,  $\Phi$  is the **contract function**.

**Example 6.** European call option on the stock with strike price K. Assuming that sd < K < su, we have

$$X = \begin{cases} su - K, & \text{if } Z = u, \\ 0, & \text{if } Z = d, \end{cases}$$

so the contract function is given by

$$\Phi(u) = su - K,$$
  

$$\Phi(d) = 0.$$

**Definition 7.** A given contingent claim X can be  $\underline{\mathbf{replicated}}$  / is  $\mathbf{reachable}$  if

$$\exists h \text{ s.t. } V_1^h = X, \text{ with probability } 1.$$

We call such an h a <u>hedging/replicating</u> portfolio. If all claims can be replicated, then the market is **complete**.

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**Proposition 8.** If a claim X is reachable with replicating portfolio h, then the only reasonable price process for X is

$$\Pi_t[X] = V_t^h, \ t = 0, 1.$$

Here, "reasonable" means that  $\Pi_0[X] \neq V_0^h \Rightarrow$  arbitrage possibility.

**Proposition 9.** The general binomial model is free of arbitrage  $\Rightarrow$  it is complete.

*Proof.* Say a claim X has contract function  $\Phi$  s.t.

$$V_1^h = \begin{cases} \Phi(u), & \text{if } Z = u\\ \Phi(d), & \text{if } Z = d, \end{cases}$$

we can obtain the following system of equations by expanding  $V_1^h$ 

$$(1+R)x + xuy = \Phi(u),$$
  
$$(1+R)x + xdy = \Phi(d),$$

and solve it to find out the replicating portfolio as

$$x = \frac{1}{1+R} \cdot \frac{u\Phi(d) - d\Phi(u)}{u - d},$$
$$y = \frac{1}{s} \cdot \frac{\Phi(u) - \Phi(d)}{u - d}.$$

**Proposition 10.** If the binomial model is free of arbitrage, then the arbitrage free price of a contingent claim X is

$$\Pi_0[X] = \frac{1}{1+R} E^Q[X],$$

where the martingale measure Q is uniquely determined by the relation

$$S_0 = \frac{1}{1+R} E^Q[S_1].$$

Proof. Using the results derived previously, we can find out that

$$\begin{split} \Pi_0[X] &= x + sy \\ &= \frac{1}{1+R} \left[ \frac{(1+R) - d}{u-d} \cdot \Phi(u) + \frac{u - (1+R)}{u-d} \cdot \Phi(d) \right] \\ &= \frac{1}{1+R} \left[ \Phi(u)q_u + \Phi(d)q_d \right] \\ &= \frac{1}{1+R} E^Q[X]. \end{split}$$

## 2.2 The Multiperiod Model

### 2.2.1 Definitions

Model

- The bond price dynamics is given by

$$B_{n+1} = (1+R)B_n, \quad B_0 = 1.$$

- The stock price dynamics is given by

$$S_{n+1} = S_n \cdot Z_n, \quad S_0 = s.$$

where  $Z_0, Z_1, \dots, Z_{T-1}$  are assumed to be i.i.d. stochastic variables, with only two variables u and d and probabilities

$$P(Z_n = u) = p_u, \quad P(Z_n = d) = p_d.$$

- Illustrating the stock dynamics by means of a tree, we can see that it is **recombining**.
- A portfolio strategy is a stochastic process

$$\{h_t = (x_t, y_t); t = 1, \dots, T\}$$

- s.t.  $h_t$  is a function of  $S_0, S_1, \ldots, S_{t-1}$ . By convention,  $h_0 = h_1$ .
  - Interpretation of  $h_t$ : at t-1,  $x_t$  and  $y_t$  of bonds and stocks are bought and held until time t.

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• The value process corresponding to the portfolio h is defined by

$$V_t^h = x_t(1+R) + y_t S_t.$$

• A portfolio strategy  $h_t$  is said to be **self-financing** if  $\forall t = 0, \dots, T-1$ ,

$$x_t(1+R) + y_t S_t = x_{t+1} + y_{t+1} S_t$$

which says that the market value of the "old" portfolio  $h_t$  equals to the purchase value of the "new" portfolio  $h_{t+1}$ .

• An <u>arbitrage</u> possibility is a self-financing portfolio *h* with the properties

$$V_0^h = 0,$$
  

$$P(V_T^h \ge 0) = 1,$$
  

$$P(V_T^h > 0) > 0.$$

• The martingale probabilities  $q_u$  and  $q_d$  are defined as the probabilities for which the following relation holds

$$s = \frac{1}{1+R} E^{Q}[S_{t+1}|S_t = s]$$

### 2.2.2 Binomial Model Pricing Algorithm

**Proposition 11.** The model is free of arbitrage  $\Rightarrow d \leq (1+R) \leq u$ .

**Assumption 12.** From now, assume that d < u and  $d \le (1 + R) \le u$ .

**Definition 13.** A <u>contingent claim</u> is a stochastic variable X of the form

$$X = \Phi(S_T),$$

where the <u>contract function</u>  $\Phi$  is some given real valued function.

**Definition 14.** A given contingent claim X can be <u>replicated</u> / is reachable if

 $\exists$  self-financing h s.t.  $V_T^h = X$ , with probability 1.

We call such an h a <u>hedging/replicating</u> portfolio. If all claims can be replicated, then the market is (dynamically) complete.

(Binomial Algorithm) Proposition 15. Consider a T-claim  $X = \Phi(S_T)$ , which could be replicated with a self-financing portfolio h. Let k be the number of up-moves occurred. So  $V_t(k)$  can be computed recursively as

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$$\begin{cases} V_t(k) &= \frac{1}{1+R} \left[ q_u V_{t+1}(k+1) + q_d V_{t+1}(k) \right], \\ V_T(k) &= \Phi(su^k d^{T-k}). \end{cases}$$

where the martingale probabilities  $q_u$  and  $q_d$  are

$$\begin{cases} q_u = \frac{(1+R) - d}{u - d} \\ q_d = \frac{u - (1+R)}{u - d}. \end{cases}$$

and the hedging portfolio is given by

$$\begin{cases} x_t(k) &= \frac{1}{1+R} \cdot \frac{uV_t(k) - dV_t(k+1)}{u - d}, \\ y_t(k) &= \frac{1}{S_{t-1}} \cdot \frac{V_t(k+1) - V_t(k)}{u - d}. \end{cases}$$

**N.B.** In Fig 2.9 in notes, (the figure might be confusing) (-22.5, 5/8) is both  $h_0$  and  $h_1$ , (-42.5, 95/120) is  $h_2(1)$ , (-2.5, 1/8) is  $h_2(0)$ , etc.

**Proposition 16.** The arbitrage free price at t = 0 of a T-claim X is given by

$$\Pi_0[X] = \frac{1}{(1+R)^T} \cdot E^Q[X],$$

where Q denotes the martingale measure, or more explicitly,

$$\Pi_0[X] = \frac{1}{(1+R)^T} \cdot \sum_{k=0}^T \binom{T}{k} q_u^k q_d^{T-k} \Phi(su^k d^{T-k}).$$

**Proposition 17.**  $d < (1+R) < u \iff$  free of arbitrage.

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## 3 Brownian Motion

### 3.1 Definitions

- Let A, B be two random variables, we define equal in distribution
  - $A \stackrel{d}{=} B \iff P(A \in C) = P(B \in C) \ \forall \text{ possible sets } C.$
- $\bullet$  We say a random variable X has **stationary increments** if

$$X_t - X_s \stackrel{d}{=} X_{t+h} - X_{s+h} \quad \forall h > 0.$$

- A stochastic process  $B_t$  is called a **Brownian motion** if
  - $-B_0=0,$
  - $-B_t B_s \sim N(0, t-s) \ \forall t \geq s \geq 0$ , implying stationary increments,
  - it has *independent* increments.

with

- $\mathbb{E}[B_t] = 0,$
- $Cov(B_t, B_s) = min\{t, s\}$ . Show this using (Practice!)
  - \*  $Cov(B_t, B_s) = \mathbb{E}[(B_t \mathbb{E}[B_t])(B_s \mathbb{E}[B_s])]$
  - \*  $Cov(B_t, B_s) = \mathbb{E}[B_t B_s] \mathbb{E}[B_t]\mathbb{E}[B_s].$

## 3.2 Path Properties

- Paths are continuous (no jumps).
- Nowhere differentiable.
- Paths are **self-similar**, i.e.

$$(T^H B_{t_1}, \dots, T^H B_{t_n}) \stackrel{d}{=} (B_{Tt_1}, \dots, B_{Tt_n})$$

with H = 0.5 is the Hurst coefficient.

### 3.3 Brownian Motion with Drift

- A <u>Gaussian Process</u> is a stochastic process s.t. every finite collection of those random variables has a multivariate normal distribution.
- The process is

$$X_t = \mu t + \sigma B_t, \quad t \ge 0.$$

- It is a Gaussian process with the following properties:
  - $\mathbb{E}[X_t] = \mu t,$
  - $Cov(X_t, X_s) = \sigma^2 \min\{t, s\}$ . (Practice!)

### 3.4 Geometric Brownian Motion with Drift

• The process is

$$X_t = e^{\mu t + \sigma B_t}, \quad t \ge 0.$$

 $\bullet$  It is not Gaussian, but log-normal instead, with the following properties:

$$-\mathbb{E}[X_t] = e^{\mu t + \frac{1}{2}\sigma^2 t}$$
, (Practice!)

- 
$$\operatorname{Cov}(X_t, X_s) = e^{\left(\mu + \frac{1}{2}\sigma^2\right)(t+s)} \left(e^{\sigma^2 s} - 1\right)$$
. (Practice!)

## 4 Stochastic Integration

## 4.1 Time Value of Money

- £x today is worth more than £x in the future.
- Compensation for postponed consumption
- Inflation: prices may rise so £x in the future will not have the same purchasing power
- Risk money in the future may never be received.

### 4.2 Interest

### 4.2.1 Definitions

- V(t): value of investment at time t
- r: interest rate  $r \ge 0$
- t: time measured in years
- P: principal/initial investment (£)
- simple/annual compounding:

$$\begin{cases} V(0) &= P \\ V(t) &= (1+tr)P \end{cases}$$

### 4.2.2 Compounding

• Periodic, e.g. monthly compounding:

$$V(t) = \left(1 + \frac{r}{12}\right)^t P$$

• Continuous:

$$V(t) = e^{tr}P \implies \frac{\mathrm{d}V(t)}{\mathrm{d}t} = rV(t)$$
  
 $\implies V(t) = V(0) + \int_0^t rV(s)\mathrm{d}s.$ 

## 4.2.3 Stochastic Integral

Example:

$$I(T) = \int_0^T B(t) dB(t)$$

Using left-hand point approximation, we can get

$$I(T) = \lim_{L \to \infty} \sum_{i=0}^{L-1} B(t_i) \left[ B(t_{i+1}) - B(t_i) \right]$$
$$= \lim_{L \to \infty} \sum_{i=0}^{L-1} -\frac{1}{2} B(t_i)^2 - \frac{1}{2} \left[ B(t_{i+1}) - B(t_i) \right]^2 + \frac{1}{2} B(t_{i+1})^2$$

$$= \frac{1}{2} \lim_{L \to \infty} \sum_{i=0}^{L-1} [B(t_{i+1})^2 - B(t_i)^2] - \delta B_i^2$$

where  $\delta B_i = B(t_{i+1}) - B(t_i)$ . Analyzing the above expression (exercise!), we can obtain

$$I(T) = \frac{1}{2}B(T)^2 - \frac{1}{2}T.$$

We can also show the following: (exercise!)

- $\mathbb{E}[\delta B_i] = 0$
- $Var(\delta B_i) = \delta t$
- $\mathbb{E}[\delta B_i^2] = \delta t$
- $\operatorname{Var}(\delta B_i^2) = 2(\delta t)^2$  (hint:  $\mathbb{E}[Z^4] = 3$  for  $Z \sim N(0, 1)$ )

## 5 Stochastic Calculus

### 5.1 Ito's Formula

## 5.1.1 Ito's Multiplication Rules

$$(dt)^{2} = 0,$$
  

$$(dt)(dB(t)) = 0,$$
  

$$(dB(t))^{2} = dt.$$

### 5.1.2 Ito's Lemma

Consider an **Ito's process** 

$$dX_t = \mu_t dt + \sigma_t dB_t,$$

where

- $\mu_t$  (or just  $\mu$ ): drift process,
- $\sigma_t$  (or just  $\sigma$ ): diffusion process,

both can be either stochastic or deterministic. Using the multiplication rules, we can derive that

$$(\mathrm{d}X_t)^2 = \mu^2(\mathrm{d}t)^2 + \sigma^2(\mathrm{d}B_t)^2 + 2\mu\sigma(\mathrm{d}t)(\mathrm{d}B_t) = \sigma^2\mathrm{d}t.$$

Let  $Z(t) = f(t, X_t)$ , then

$$dZ(t) = \frac{\partial f}{\partial X_t} dX_t + \frac{\partial f}{\partial t} dt + \underbrace{\frac{1}{2} \frac{\partial^2 f}{\partial X_t^2} (dX_t)^2}_{\text{Itô correction}}$$
$$= \left( \frac{\partial f}{\partial t} + \mu \frac{\partial f}{\partial X_t} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial X_t^2} \right) dt + \frac{\partial f}{\partial X_t} \sigma dB(t).$$

### 5.1.3 Examples

1.  $dX_t = dW_t$ ,  $f(t,x) = te^{\alpha x}$ . Since

$$\frac{\partial f}{\partial t} = e^{\alpha x}, \quad \frac{\partial f}{\partial x} = \alpha t e^{\alpha x}, \quad \frac{\partial^2 f}{\partial x^2} = \alpha^2 t e^{\alpha x},$$

and in this case  $\mu = 0$ ,  $\sigma = 1$ , we have

$$df(t, W_t) = \left(e^{\alpha x} + \frac{1}{2}\alpha^2 t e^{\alpha W_t}\right) dt + \alpha t e^{\alpha W_t} dW_t$$

2. dX = dW,  $f(x) = x^2$ .

$$df(t, W_t) = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dx + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} dt$$
$$= 0 + 2W dW + \frac{1}{2} 2dt$$
$$= dt + 2W_t dW_t$$

3. Compute  $\mathbb{E}[B_t^4]$ . This could be transformed to the question

$$dX_t = dB_t, \quad Z_t = X_t^4.$$

Thus,

$$\mathrm{d}Z_t = 6B_t^2 \mathrm{d}t + 4B_t^3 \mathrm{d}B_t$$

i.e.

$$Z_t = Z_0 + 6 \int_0^t B_s^2 ds + 4 \int_0^t B_s^3 dB_s$$

SO

$$\mathbb{E}[B_t^4] = \mathbb{E}Z_t = 0 + 6 \int_0^t \mathbb{E}[B_s^2] ds + 4 \int_0^t \mathbb{E}[B_s^3] dB_s$$
$$= 6 \int_0^t s ds + 0$$
$$= 3t^2$$

## 5.2 Stochastic Differential Equation

**Example** Given that

$$dS(t) = dB(t), \quad u(t,x) = y_0 e^{\mu t + \sigma x},$$

and

$$Y(t) = u(t, S), \quad Y(0) = y_0,$$

we have

$$dY_t = \mu u(t, S)dt + \sigma u(t, s)dB + \frac{1}{2}\sigma^2 u(t, s)dt$$
$$= \left(\mu + \frac{1}{2}\sigma^2\right)Y(t)dt + \sigma Y(t)dB_t.$$

This gives hint on how to solve

$$dY(t) = \mu Y(t)dt + \frac{1}{2}\sigma Y(t)dB_t,$$

whose solution is

$$Y(t) = u(t, B_t) = y(0)e^{\left(\mu - \frac{1}{2}\sigma^2\right)t + \sigma B_t}.$$

This can be solved with a change of variable

$$Z(t) = \ln Y(t).$$

Applying Ito's lemma, we can derive that

$$dZ(t) = \frac{1}{Y(t)}dY(t) - \frac{1}{2}\frac{1}{Y(t)^2}\sigma^2Y(t)^2dt$$
$$= \mu dt + \sigma dB(t) - \frac{1}{2}\sigma^2dt$$

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$$= \left(\mu - \frac{1}{2}\sigma^2\right) dt + \sigma dB_t$$

Integrating both sides from 0 to t, we get

$$Z(t) - Z(0) = \ln \frac{Y(t)}{Y(0)} = \left(\mu - \frac{1}{2}\sigma^2\right)t + \sigma B_t$$

leading to the solution.

### 5.3 SDE & PDE

Consider the SDE

$$dX_s = \mu(s, X_s)ds + \sigma(s, B_s)dB_s,$$
  
 $X_t = x,$ 

which starts at x at time t and evolves in the interval [t,T]. Now the parabolic PDE

$$\frac{\partial F}{\partial t} + \mu(t, x) \frac{\partial F}{\partial x} + \frac{1}{2} \sigma^2(t, x) \frac{\partial^2 F}{\partial x^2} = \frac{\partial F}{\partial t} + \mathcal{A}F = 0$$
$$F(T, x) = \phi(x),$$

where

$$\mathcal{A} = \mu(t, x) \frac{\partial}{\partial x} + \frac{1}{2} \sigma^2(t, x) \frac{\partial^2}{\partial x^2}$$

is called the *infinitesimal operator*. Applying Ito's Lemma to F(s, X(s)), we have

$$dF = \frac{\partial F}{\partial t}dt + \frac{\partial F}{\partial X}dX + \frac{1}{2}\sigma^2 \frac{\partial^2 f}{\partial X^2}dt.$$

Integrate from t to T, we get

$$F(T, X_T) - F(t, X_t)$$

$$= \int_t^T \left[ \frac{\partial F(s, X_s)}{\partial t} + \frac{\partial F(s, X_s)}{\partial X} \mu(s, X_s) + \frac{1}{2} \sigma^2 \frac{\partial^2 F(s, X_s)}{\partial X^2} \right] ds$$
exactly the PDE, = 0
$$+ \int_t^T \sigma(s, X_s) \frac{\partial F(s, X_s)}{\partial X} dW_s$$

$$= \int_t^T \left[ \frac{\partial F(s, X_s)}{\partial t} + \mathcal{A}F(s, X_s) \right] ds + \int_t^T \sigma(s, X_s) \frac{\partial F(s, X_s)}{\partial X} dW_s$$

$$= \int_{t}^{T} \sigma(s, X_{s}) \frac{\partial F(s, X_{s})}{\partial X} dW_{s},$$

$$\implies \phi(X_T) - F(t, X) = \int_t^T \sigma(s, X_s) \frac{\partial F(s, X_s)}{\partial X} dW_s$$

Taking expectation on both sides (conditional on t),

$$\mathbb{E}\phi(X_T) - \mathbb{E}[F(t, X(t))|X(t) = x] = \mathbb{E}\left[\int_t^T \sigma(s, X_s) \frac{\partial F(s, X_s)}{\partial X} dW_s | X(t) = x\right].$$

Since stochastic integral has 0 expectation, i.e.

$$F(t, X) = \mathbb{E}\left[\phi(X_T)|X(t) = x\right]$$

The above conclusion is the Feynman Kac Theorem

**Proposition 18.** If F is a solution to

$$\frac{\partial F}{\partial t} + \mathcal{A}F = 0, \quad F(T, X) = \phi(X),$$

where  $\mathcal{A}$  is the infinitesimal operator associated with the SDE

$$dX_s = \mu(s, X_s)ds + \sigma(s, X_s)dW_s, \quad X_t = x$$

then

$$F(t,x) = \mathbb{E}\left[\phi(X_T)|X_t = x\right]$$

**Note** By "associated" means that the quantity  $\mu$  and  $\sigma$  are the same in both SDE and PDE.

Example 19. Solve the PDE

$$\frac{\partial F}{\partial t} + \frac{1}{2}\sigma^2 \frac{\partial^2 F(t,x)}{\partial x^2} = 0, \quad F(T,x) = x^2$$

using the Feynman Kac formula. Let

$$dX_s = \sigma dW_s, \quad X_t = x$$

The solution to the SDE is

$$X_t = x + \sigma \left[ W_T - W_t \right]$$

implying that  $X_T \sim N(x, \sigma^2(T-t))$ . So

$$F(t,x) = \mathbb{E}X_T^2 = \sigma^2(T-t) + x^2$$

6 ARBITRAGE PRICING

## 6 Arbitrage Pricing

### 6.1 Definitions

- out-of-the-money (OTM) for a call means S(t) K < 0.
- in-the-money for a call means S(t) K > 0.
- at-the-money for a call means S(t) = K.
- Exotic options: more complicated products that have "exotic" features, e.g. early exercise, multiple strikes, etc.

## 6.2 The Black & Scholes Model and Arbitrage

### 6.2.1 Model Introduction

The model is based on:

1. risk-free bank (letter B stands for bank):

$$dB(t) = rB(t)dt \implies B(t) = B(0)e^{rt}$$

2. stock:

$$dS(t) = \mu S(t)dt + \sigma S(t)dW(t), \quad S(0) = s(0)$$

$$\Rightarrow \quad S(t) = S(0)e^{\left(\mu - \frac{1}{2}\sigma^2\right)t + \sigma W_t}$$

3. option, that depends on stock price and the current time:

$$V(t,S)$$
.

## 6.2.2 The PDE approach of pricing

The model:

$$dB_t = rB_t dt, \quad dS_t = \mu S_t dt + \sigma S_t dW_t$$

Applying Ito's lemma on V(t, S), we have

$$dV = \frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial S} dS + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} (dS)^2$$
$$= \left[ \frac{\partial V}{\partial t} + \mu S \frac{\partial V}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} \right] dt + \sigma S \frac{\partial V}{\partial S} dW_t.$$

Consider a portfolio P(t) with  $\Delta$  stocks and one short option (**Delta hedging**). The value of the portfolio is

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$$P(t) = \underbrace{\Delta S(t)}_{\text{long the stock}} - \underbrace{V(t)}_{\text{short the option}}$$

The portfolio evolves according to

$$\begin{split} \mathrm{d}P(t) &= \Delta \mathrm{d}S(t) - \mathrm{d}V \\ &= \left[ \Delta \mu S - \frac{\partial V}{\partial t} - \mu S \frac{\partial V}{\partial S} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} \right] \mathrm{d}t + \left[ \Delta \sigma S - \sigma S \frac{\partial V}{\partial S} \right] \mathrm{d}W_t. \end{split}$$

If we let  $\Delta = \frac{\partial V}{\partial S}$ , because if the market has no arbitrage then its return must equal rPdt, we are left with

$$dP = \left[ \Delta \mu S - \frac{\partial V}{\partial t} - \mu S \frac{\partial V}{\partial S} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} \right] dt = rP dt$$

$$\Rightarrow \quad \Delta \mu S - \frac{\partial V}{\partial t} - \mu S \frac{\partial V}{\partial S} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} = rP$$

Since  $P=\frac{\partial V}{\partial S}S-V, \Delta=\frac{\partial V}{\partial S}$ , after these substitution, we obtain the following second-order parabolic PDE called the **Black & Scholes Equation (BSE)**:

$$\frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} + \frac{\partial V}{\partial t} = rV, \quad V(T, S) = \max(S - K, 0),$$

where the second equation is the boundary condition for European call option.

**Hedge Parameters** The following parameters (appearing in the PDE) are the sensitivities of the option value w.r.t. small changes in the problem.

$$\Delta = \frac{\partial V}{\partial S}$$

It tells the trader how to balance the portfolio so that it is always equal to the option.

•

$$\Gamma = \frac{\partial^2 V}{\partial S^2}$$

It gives an indication of how stable the hedging portfolio is. If  $\Gamma$  is large, the trader needs to rebalance more often.

•

$$\theta = \frac{\partial V}{\partial t}$$

If S stays constant then the value of the option will change by  $\theta$ 

•

$$\zeta = \frac{\partial V}{\partial \sigma}$$

It measures the change in price w.r.t. volatility

•

$$\rho = \frac{\partial V}{\partial r}$$

It measures sensitivity w.r.t. interest rate.

## 6.2.3 The Martingale Method of Pricing

Option valuation could be reduced to the calculation of the following:

$$V(S_0) = \mathbb{E}^Q \left[ e^{-rT} V(S_T) | S_0 \right].$$

In the case of the Black-Scholes model, Q is the probability distribution of the following  ${\rm SDE}$ 

$$dS_t = rS_t dt + \sigma S_t dW_t$$

or

$$S(t) = S(0)e^{\left(r - \frac{1}{2}\sigma^2\right)t + \sigma W_t}$$

where

- r: risk-free rate
- $\sigma$ : volatility
- w: standard brownian motion

This says that the assumption of the Black Scholes model is that the underlying asset follows a geometric Brownian motion i.e. lognormal random walk.

## 7 Monte-Carlo methods

## 7.1 Strong Law of Large Numbers

Let  $\xi^{(i)}$ ,  $i=1,2,\ldots,N$  be i.i.d. random variables with values in  $\mathbb{R}^d$ , and mean  $\mathbb{E}|\xi|<\infty$ . Let  $\hat{S}_N$  denote the empirical mean  $\hat{S}_N=\frac{1}{N}\sum_{i=1}^N \xi^{(i)}$ . Then the SLLN holds true:

$$\lim_{N \to \infty} \hat{S}_N = \mathbb{E}(\xi)$$

### 7.2 Central Limit Theorem

Let  $\xi^{(i)}, i=1,2,\ldots,N$  be i.i.d. random variables with mean  $\mathbb{E}\xi$  and  $\mathrm{Var}(\xi)<\infty$ . Then

$$Y_N = rac{\sqrt{N}}{\sigma} \left( rac{1}{N} \sum_{i=1}^N \xi^i - \mathbb{E}\xi 
ight) \longrightarrow_d Z \sim N(0, 1)$$

as  $N \to \infty$ . In practice, we use empirical variance to compute  $\sigma$  (unbiased estimate):

$$\sigma_N^2 = \frac{1}{N-1} \sum_{i=1}^N \left( \xi^i - \overline{\xi} \right)^2.$$

In other words,

$$\mathbb{P}\left(\left|\frac{\sqrt{N}}{\sigma}\left(\frac{1}{N}\sum_{i=1}^{N}\xi^{i}-\mathbb{E}\xi\right)\right|< R\right) \longrightarrow \int_{-R}^{R}\frac{1}{\sqrt{2\pi}}e^{-\frac{x^{2}}{2}}\mathrm{d}x$$

## 7.3 Monte Carlo for Option Valuation

Since

$$S(T) = S(0)e^{\left(r - \frac{1}{2}\sigma^2\right)T + \sigma\sqrt{T}Z}, \quad Z \sim N(0, 1),$$

if we can generate i.i.d. normal random variables  $\{Z^i\},\,i=1,2,\ldots,N,$  we have

$$V(S_0) \approx \frac{1}{N} \sum_{i=1}^{N} V(S_T^i) e^{-rT} = V_N(S_0),$$

arboro

$$S_T^i = e^{\left(r - \frac{1}{2}\sigma^2\right)T + \sqrt{T}Z^i}$$

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### 7.4 Variance Reduction methods for MC

### 7.4.1 Antithetic Variables

If  $X_1$  and  $X_2$  are i.i.d. RVs,

$$\operatorname{Var}\left(\frac{X_1 + X_2}{2}\right) = \frac{1}{4}\left(\operatorname{Var}(X_1) + \operatorname{Var}(X_2) + 2\operatorname{Cov}(X_1, X_2)\right)$$

so variance is reduced if  $Cov(X_1, X_2) < 0$ .

Let f(x) be monotonic. For instance, in the case of <u>Gaussian variables</u> X, f(x) and f(-x) are negatively correlated, i.e.

$$Cov(f(X), f(-X)) < 0.$$

In the case of uniform distribution variables U,

$$Cov(f(U), f(1-U)) < 0.$$

### 7.4.2 Control Variates

Suppose we want to estimate  $\mathbb{E}X$  and know the mean of another random variable Y,  $\mathbb{E}Y$ , then

$$\mathbb{E}X = \mathbb{E}[X - Y + \mathbb{E}Y].$$

Y is called a control variate. While the expectation of

$$Z = X - Y + \mathbb{E}Y$$

is  $\mathbb{E}X$  its variance will be

$$Var(X - Y) = Var(X) + Var(Y) - 2Cov(X, Y).$$

This idea works when X and Y are close.

## 7.4.3 Importance Sampling

We can write the expectation with respect to the probability density p as

$$\mathbb{E}^p g(X) = \int g(x)p(x)\mathrm{d}x.$$

Suppose that we had another density q that had the same support i.e.  $p(x) > 0 \iff q(x) > 0$ , then

$$\mathbb{E}^{p}g(x) = \int g(x)p(x)dx = \int g(x)\frac{p(x)}{q(x)}q(x)dx = \mathbb{E}^{q}g(x)\frac{p(x)}{q(x)}$$

Thus instead of calculating  $\mathbb{E}^p g(x)$  using i.i.d. samples from p we calculate

$$\mathbb{E}^q g(x) \Lambda(x)$$

using samples from q, where  $\Lambda(x)$  is the likelihood ratio.

## 7.5 Computation of Monte-Carlo Greeks

Monitoring the P&L of the hedging portfolio

$$\pi(t,s) = V(t,s) - \Delta S(t).$$

If  $\pi(t, S)$  is not small, then it means that some element of the model is not performing well i.e. the value of the option is changing well beyond the  $\Delta$  parameter predicts. There will be several parameters deployed:  $\boldsymbol{\theta} = (\theta_1, \dots, \theta_N)$ , so

$$V(t,s,\boldsymbol{\theta})$$

With Monte Carlo, we can use *finite difference* to calculate the Greeks.

### 7.5.1 Finite Difference

For convenience, we consider a single parameter  $\theta$ . We know that by a Taylor series expansion,

$$V(\theta + \Delta\theta) = V(\theta) + \frac{\partial V}{\partial \theta} \Delta\theta + \frac{1}{2} \frac{\partial^2 V}{\partial \theta^2} \Delta\theta^2 + \cdots$$

therefore

$$\begin{split} \frac{\partial V}{\partial \theta} &= \frac{V(\theta + \Delta \theta) - V(\theta)}{\Delta \theta} - \frac{1}{2} \frac{\partial^2 V}{\partial \theta^2} \Delta \theta + O(\Delta \theta^2) \\ &\approx \frac{\overline{V}_N(\theta + \Delta \theta) - \overline{V}_N(\theta)}{\Delta \theta}, \end{split}$$

where

$$\overline{V}_N(\theta) = \frac{1}{N} \sum_{i=1}^N \frac{1}{M(T)} V(T, S^i, \theta),$$

and M(T) is the discount factor, e.g.  $M(T) = e^{r(T-t_0)}$ . Since  $\mathbb{E}\overline{V}_N(\theta) = V(\theta)$ , the error will be  $O(\Delta\theta)$ .

The above is <u>forward finite difference</u>. We could also consider <u>central finite difference</u>:

$$\frac{\partial V}{\partial \theta} = \frac{V(\theta + \Delta \theta) - V(\theta - \Delta \theta)}{2\Delta \theta} + O(\Delta \theta^2),$$

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where the second derivative error in the Taylor expansion of  $V(\theta + \Delta \theta)$  and  $V(\theta - \Delta \theta)$  cancels out. Thus the error is much less than the forward finite difference.

Central F.D. needs one more simulation  $V(\theta - \Delta \theta)$  than forward F.D.

## 8 Numerical Methods for SDEs

### 8.1 Deterministic methods

We are looking at

$$\dot{x} = f(t, x), \quad t \ge t_0, \ x(t_0) = x_0,$$

and assume that f satisfies the **Lipscitz condition**:

$$|f(t,x) - f(t,y)| \le L|x-y|, \quad \forall x, y \in \mathbb{R}, t > t_0,$$

where L is the **Lipscitz constant**.

### 8.1.1 Euler's Method

Given that we know  $t_0, f, x(t_0)$ , the most elementary approximation is

$$x(t) = x(t_0) + \int_{t_0}^{t} f(s, x(s)) ds \approx x(t_0) + f(t_0, x(t_0))(t - t_0).$$

Breaking the time interval  $[t_0, \dots, T]$  into  $t_0 < t_1 < t_2 < \dots < t_{N-1} = T$  s.t.

$$\delta = t_{i+1} - t_i, \quad i = 0, 1, \dots, N - 1,$$

we arrive at the recursive scheme

$$x_{n+1} = x_n + f(t_n, x_n)\delta.$$

The following theorem provides the condition where the above recursive scheme converges.

Theorem 20. Euler's method is convergent if

$$\delta < \frac{1}{L}$$
.

Regarding **order of convergence**, we re-write the Euler's method as

$$x(t_{n+1}) - [x(t_n) + \delta f(t_n, x(t_n))]$$
  
=  $[x(t_n) + \dot{x}(t_n)\delta + O(\delta^2)] - [x(t_n) + \delta f(t_n, x(t_n))]$   
=  $O(\delta^2)$ ,

and we say that the Euler method converges with order 1, i.e. it recovers exactly every polynomial solution of degree 1 or less.

### 8.1.2 The Trapezoidal Rule

Instead of approximating with the left end-point we could just average the two:

$$x(t) = x(t_n) + \int_{t_n}^{t} f(s, x(s)) ds$$
  
 
$$\approx x(t_n) + \frac{1}{2} (t - t_n) \left[ f(t_n, x(t_n)) + f(t, x(t)) \right],$$

giving the trapezoidal rule

$$x_{n+1} = x_n + \frac{1}{2}\delta \left[ f(t_n, x_n) + f(t_{n+1}, x_{n+1}) \right]$$

similarly, using Taylor's expansion and several substituions, we could get

$$x(t_{n+1}) - \left[ x(t_n) + \frac{1}{2} \delta f(t_n, x_n(t_n)) + f(t_{n+1}, x_{n+1}) \right] = O(\delta^3),$$

suggesting that the trapezoidal method has a convergence of order 2. We can also show that it is convergent. Comparing with the Euler method, it has a superior convergence rate but it is implicit, whereas Euler method is explicit.

### 8.1.3 The Theta method

Both the Euler and trapezoidal rule fit in the general scheme

$$x_{n+1} = x_n + \delta \left[ \theta f(t_n, x_n) + (1 - \theta) f(t_{n+1}, x_{n+1}) \right],$$

where  $\theta = 1$  is the Euler's scheme,  $\theta = \frac{1}{2}$  is the trapezoidal scheme.

## 8.2 The Euler-Maruyama (EM) Method

Given that

$$dX(t) = f(X(t))dt + g(X(t))dW(t),$$

with X(0) given,  $0 \le t \le T$ , we define a step-size  $\delta = \frac{T}{N}$ . The exact solution is

$$X(t_{n+1}) = X(t_n) + \int_{t_n}^{t_{n+1}} f(X(s)) ds + \int_{t_n}^{t_{n+1}} g(X(s)) dW(s).$$

Assuming f and g are constant in  $[t_n, t_{n+1}]$ , then

$$X_{n+1} = X_n + f(X_n)\Delta t + g(X_n)\Delta W_n$$

where  $\Delta W_n = W(t_{n+1}) - W(t_n)$  is a Brownian motion increment:

$$\Delta W_n \sim N(0, t_{n+1} - t_n) \sim \sqrt{\delta} N(0, 1).$$

The EM algorithm is then like the following:

- 1. Fix  $\delta$ , the stepsize.
- 2. compute iteratively

$$X_{n+1} = X_n + f(X_n)\delta + \sqrt{\delta}g(X_n)\xi_n,$$

where  $\xi_n \sim N(0,1)$ .

## 8.2.1 Weak v.s. Strong Convergence

Weak error associated with a discretization scheme is

$$e_{\delta}^{\text{weak}} = \max_{n=0,\dots,N-1} \left| \underbrace{\mathbb{E}[\phi(X_n)]}_{\text{EM approx.}} - \underbrace{\mathbb{E}[\phi(X_{t_n})]}_{\text{exact}} \right|$$

where  $\phi$  is a class of functions, e.g. polynomials/Lipscitz. We say that a method **converges weakly** if

$$e_s^{\text{weak}} \longrightarrow 0 \quad \text{as} \quad \delta \longrightarrow 0.$$

We say that the method converges with weak order p if

$$e_{\delta}^{\text{weak}} \leq K \delta^p \quad \forall 0 < \delta \leq \delta^* \text{ for some } \delta^*.$$

Strong error is given by

$$e^{\text{strong}}_{\delta} = \max_{n=0,\dots,N-1} \mathbb{E}[|\underbrace{X_n}_{\text{approx.}} - \underbrace{X(t_n)}_{\text{exact}}|]$$

A method **converges strongly** if

$$e_{\delta}^{\text{strong}} \longrightarrow 0 \quad \text{as} \quad \delta \longrightarrow 0$$

We say that the method **converges with strong order** p if

$$e_{\delta}^{\text{strong}} \leq K\Delta t^p \quad \forall 0 < \Delta t \leq \Delta t^*.$$

## 8.3 Implicit Methods and Numerical Stability

In stability analysis, we are interested in long-time behaviour of the numerical scheme e.g. if we make small errors then will this error propagate?

### 8.3.1 Stochastic $\theta$ -method

$$X_{n+1} = X_n + (1 - \theta)f(X_n)\delta + \theta f(X_{n+1})\Delta t + g(X_n)\Delta W_n.$$