

# MDP-1d

$T = \{0, 1, 2, 3, 4, 5\} \rightarrow$  time space

$S = \{-3, \dots, 3\} \rightarrow$  state space

$A = \{-1, 1\} \rightarrow$  action space

Trans. prob

act \ prob	DN	Flat	up
1		$\frac{1}{2}$	$\frac{1}{2}$
-1	$\frac{1}{2}$	$\frac{1}{2}$	

DN  $\rightarrow$  flat if state = -3

up  $\rightarrow$  flat if state = 3

Ter. cost

$$g(x) = x^2$$

obj min terminal cost.

soln

① opt policy =  $\begin{cases} 1 & \text{if } x < 0 \\ -1 & \text{if } x > 0 \end{cases}$

② s-val

4.5	6.5	9
1.5	2.5	4
0.5	0.5	1
0.5	0.5	0
		1
		4
		9
		T=5