George Yin

Qing Zhang Editors

Modeling, Stochastic Control, Optimization, and Applications



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George Yin · Qing Zhang Editors

Modeling, Stochastic Control, Optimization, and Applications



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Foreword

This volume contains a selection of papers based on a thematic summer program "Modeling, Stochastic Control, Optimization, and Related Applications" held at the Institute for Mathematics and its Applications from May 1-June 30, 2018 and organized by George Yin and Qing Zhang. This summer program included four weeklong workshops over the eight week focus period:

- Stochastic Control, Computational methods, and Applications,
- Queuing Theory and Networked Systems,
- Ecological and Biological Applications, and
- Finance and Economics Applications.

The papers found in this volume cover a broad array of application areas and utilize a wide variety of techniques, from applied probability and network science to stochastic differential equations and numerical methods. We would like to thank volume editors, George Yin and Qing Zhang. Finally, we acknowledge the National Science Foundation for its support of this program.

The Institute for Mathematics and its Applications was established by a grant from the National Science Foundation to the University of Minnesota in 1982. The primary mission of the IMA is to foster research of a truly interdisciplinary nature, establishing links between mathematics of the highest caliber and important scientific and technological problems from other disciplines and industries. IMA Volumes are used to communicate results of these programs that we believe are of particular value to the broader scientific community. The full list of IMA books can be found at the web site of the Institute for Mathematics and its Applications:

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Minneapolis, MN, USA, May 2019

Daniel Spirn

Preface

This volume collects papers, based on invited talks given at the IMA workshop in Modeling, Stochastic Control, Optimization, and Related Applications, held at the Institute for Mathematics and Its Applications, University of Minnesota, during May and June, 2018.

There were four week-long workshops during the conference. They are (1) stochastic control, computation methods, and applications, (2) queueing theory and networked systems, (3) ecological and biological applications, and (4) finance and economics applications. For broader impacts, researchers from different fields covering both theoretically oriented and application intensive areas were invited to participate in the conference. It brought together researchers from multi-disciplinary communities in applied mathematics, applied probability, engineering, biology, ecology, and networked science, to review, and substantially update most recent progress. As an archive, this volume presents some of the highlights of the workshops, and collect papers covering a broad range of topics. After the conference, 23 papers were submitted. All papers were reviewed.

Without the help and assistance of the IMA directors and staffs, the conference could not come into being. We thank Fadil Santosa for the initial suggestion and encouragement as well as subsequent help. Our thanks go to Daniel Spirn, Benjamin Brubaker, and Katherine Dowd for their support throughout the workshops. It had been a pleasure working with Rebecca Malkovich and Georgia Kroll and all the IMA professionals. Their supports are greatly acknowledged. Finally, we thank the contributors of this volume, invited speakers of the workshops, and the attendees for making the conference a successful and memorable event.

Detroit and Athens, Feb., 2019,

George Yin Qing Zhang

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American Option Model and Negative Fichera Function on Degenerate Boundary

Xiaoshan Chen, Zhuo Jin, and Qingshuo Song

Abstract We study American put option with stochastic volatility whose value function is associated with a 2-dimensional parabolic variational inequality with degenerate boundaries. Given the Fichera function on the boundary, we first analyze the existences of the strong solution and the properties of the 2-dimensional manifold for the free boundary. Thanks to the regularity result of the underlying PDE, we can also provide the uniqueness of the solution by the argument of the verification theorem together with the generalized Itos formula even though the solution may not be second order differentiable in the space variable across the free boundary.

1 Introduction

Option pricing is one of the most important topics in the quantitative finance research. Although the Black-Scholes model has been well studied, empirical evidence suggests that the Black-Scholes model is inadequate to describe asset returns and the behavior of the option markets. One possible remedy is to assume that the volatility of the asset price also follows a stochastic process, see [9] and [10].

In the standard Black-Scholes model, a standard logarithmic change of variables transforms the Black-Scholes equation into an equation with constant coefficients which can be studied by a general PDE theory directly. Different from the standard Black-Scholes PDE, the general PDE methods does not directly apply to the PDE

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associated with the option pricing underlying the stochastic volatility model in the following cases: 1) The pricing equation is degenerate at the boundary; 2) The drift and volatility coefficients may grows faster than linear, see [9].

In the related literatures, [9] derived a closed-form solution for the price of a European call option on some specific stochastic volatility models. [6] also studied the Black-Scholes equation of European option underlying stochastic volatility models, and showed that the value function was the unique classical solution to a PDE with a certain boundary behavior. Also, [2] showed a necessary and sufficient condition on the uniqueness of classical solution to the valuation PDE of European option in a general framework of stochastic volatility models. In contrast to the European option pricing on the stochastic volatility model, although there have been quite a few approximate solutions and numerical approaches, such as [1, 4], the study of the existence and uniqueness of strong solution for PDE related to American option price on the stochastic volatility model is rather limited. In particular, the unique solvability of PDE associated with American options of finite maturity with the presence of degenerate boundary and super-linear growth has not been studied in an appropriate Sobolev space.

Note that, American call options with no dividend is equivalent to the European call option. For this reason, we only consider a general framework of American put option model with stochastic volatility whose value function is associated by a 2-dimensional parabolic variational inequality. On the other hand, in the theory of linear PDE, boundary conditions along degenerate boundaries should not needed if the Fichera function is nonnegative, otherwise it should be imposed, see [16]. Therefore, we only consider the case when Fichera function is negative on the degenerate boundary y=0 in this paper, and leave the other case in the future study.

To resolve solvability issue, we adopt similar methodology of [3] to work on a PDE of truncated version backward in time using appropriate penalty function and mollification. The main difference is that [3] studies constant drift and volatility, while the current paper considers functions of drift and volatility and the negative Fichera function plays crucial role in the proof.

Uniqueness issue is usually tackled by comparison result implied by Ishii's lemma with notions of viscosity solution, see [5]. However, this approach does not apply in this problem due to the fast growth of drift and volatility functions on unbounded domain. The approach to establish uniqueness in our paper is similar to the classical verification theorem conducted to classical PDE solution. In fact, a careful construction leads to a local regularity of the solutions in Sobolev space, and this enables us to apply generalized Ito's formula (see [12]) with weak derivatives. Note that this approach not only provides uniqueness of strong solution of PDE, but also provides that the value function of American option is exactly the unique strong solution.

In the next section, we first introduce the generalized stochastic volatility model. Section 3 shows the existence of strong solution to the truncated version of the variational inequality. We characterize the free boundary in section 4. Section 5 shows that the value function of the American option price is the unique strong

solution to the variational inequality with appropriate boundary datum. Concluding remarks are given in section 6.

2 Stochastic volatility model

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a filtered probability space with a filtration $(\mathcal{F}_t)_{t\geq 0}$ that satisfies the usual conditions, W_t and B_t be two standard Brownian motions with correlation ρ . Suppose the stock price follows

(Stk)
$$dX_s = X_s(rds + \sigma(Y_s)dW_s), X_t = x > 0,$$

and volatility follows

(Vol)
$$dY_s = \mu(Y_s)ds + b(Y_s)dB_s$$
, $Y_t = y > 0$.

Let $X^{x,t}$ and $Y^{y,t}$ be dynamics satisfying (Stk) and (Vol) with respective initial conditions on superscripts.

We consider an American put option underlying the asset X_s with strike K > 0 and maturity T, which has the payoff $(K - X_\tau)^+$ at the exercise time $\tau \in \mathcal{T}_{t,T}$. Here $\mathcal{T}_{t,T}$ denotes the set of all stopping times in [t,T]. Define value function of the optimal stopping by

$$V(x, y, t) = \sup_{\tau \in \mathcal{F}_{t, T}} \mathbb{E}_{x, y, t} [e^{-r(\tau - t)} (K - X_{\tau})^{+}], \quad (x, y, t) \in \bar{\mathbb{R}}^{+} \times \bar{\mathbb{R}}^{+} \times [0, T].$$
 (1)

Following assumptions will be imposed:

(A1) μ , σ^2 , b^2 are locally Lipschitz continuous on \mathbb{R} with $\mu(0) = \sigma(0) = b(0) = 0$ and $\sigma(y)$, b(y) > 0, $\sigma'(y) \ge 0$ for all y > 0.

(A2) $|\mu| + b$ is at most linear growth, and $(\sigma^2)'$ is at most polynomial growth.

In the above, $\sigma'(y)$ and $(\sigma^2)'(y)$ stand for the first and second derivatives of $\sigma(y)$, respectively. Under the assumptions (A1)–(A2), we have unique non-negative, non-explosive strong solutions for both (Stk) and (Vol). Furthermore, $X_s^{x,t} > 0$ for all s > t. Such a stock price model includes Heston model.

Provided that the value function V(x,y,t) is smooth enough, applying dynamic programming principle and Itô's formula, the value of the option V(x,y,t) formally satisfies the variational inequality

$$\begin{cases}
\min\left\{-\partial_{t}V - \mathcal{L}_{x}V, V - (K - x)^{+}\right\} = 0, & (x, y, t) \in Q := \mathbb{R}^{+} \times \mathbb{R}^{+} \times [0, T), \\
V(x, y, T) = (K - x)^{+}, & (x, y) \in \mathbb{R}^{+} \times \mathbb{R}^{+},
\end{cases}$$
(2)

where

$$\mathscr{L}_x V = \frac{1}{2} x^2 \sigma^2(y) \partial_{xx} V + \rho x \sigma(y) b(y) \partial_{xy} V + \frac{1}{2} b^2(y) \partial_{yy} V + r x \partial_x V + \mu(y) \partial_y V - r V.$$

On the boundary x = 0, the Fichera condition on linear parabolic equation suggests us not to impose any boundary condition. On the boundary y = 0, the Fichera function is

$$F = \left[\mu(y) - \frac{1}{2} \rho \sigma(y) b(y) - b(y) b'(y) \right] \Big|_{y=0} = \mu(0) - \lim_{y \to 0} b(y) b'(y).$$

So

- (F1) when $\mu(0) < \lim_{y \to 0} b(y)b'(y)$, one has to impose the boundary condition; (F2) when $\mu(0) \geq \lim_{y \to 0} b(y)b'(y)$, one should not impose any boundary condition.

Although the problem (2) is a variational inequality instead of linear PDE, the Fichera condition in the linear PDE theory does not directly prove the existence of solution to the problem (2). Throughout this paper, we study the relation between value function (1) and PDE of (2) with an appropriate boundary data on y = 0 under the case (F1), while the case (F2) is left in the future study.

Then, what boundary condition should be imposed on the boundary y = 0? To proceed, we define $v := \inf\{s > t : Y_s = 0\}$ the first hitting time of the process Y_s to the boundary y = 0. Then for any stopping time $\tau > \nu$, we have

$$e^{-r(\tau-t)}(K-X_{\tau})^{+} \le e^{-r(v-t)}(K-X_{v})^{+},$$
 (3)

thus

$$V(x,0,t) = \sup_{\tau \in \mathscr{T}_{t,T}} \mathbb{E}_{x,0,t}[e^{-r(\tau-t)}(K-X_{\tau})^{+}] \le (K-x)^{+}.$$

On the other hand, by taking $\tau = t$,

$$V(x,0,t) = \sup_{\tau \in \mathcal{T}_{t,T}} \mathbb{E}_{x,0,t}[e^{-r(\tau-t)}(K-X_{\tau})^{+}] \ge (K-x)^{+}.$$

Hence

$$V(x,0,t) = (K-x)^{+} = \sup_{\tau \in \mathscr{T}_{t,T}} \mathbb{E}_{x,0,t} [e^{-r(\tau-t)}(K-X_{\tau})^{+}], \quad (x,t) \in \mathbb{R}^{+} \times [0,T).$$
 (4)

Due to the non-linearity of the variational inequality (2), we may not expect the heuristic argument in the above assuming the enough regularity on V. In addition, Fichera condition on the boundary data is suitable only for linear second order PDE, see [16]. Our objective in this paper is to justify the regularity of the value function in the Sobolev space, so that the value function (1) can be characterized as the unique solution of the variational inequality (2) and an additional boundary data (4).

3 Solvability on the transformed problem

In order to obtain the existence of solution to the variational inequality (2) with boundary condition (4) in Sobolev space, we consider the existence of strong solution to the associated transformed problem of (2) with boundary condition (4) in this section.

To proceed, we take a simple logarithm transformation to the variational inequality. Let $s = \ln x$, $\theta = T - t$, $u(s, y, \theta) = V(x, y, t)$, then

$$\mathcal{L}_{x}V = \frac{1}{2}\sigma^{2}(y)\partial_{ss}u + \rho\sigma(y)b(y)\partial_{sy}u + \frac{1}{2}b^{2}(y)\partial_{yy}u + \left(r - \frac{1}{2}\sigma^{2}(y)\right)\partial_{s}u + \mu(y)\partial_{y}u - ru := \mathcal{L}_{s}u.$$

Thus $u(s, y, \theta)$ satisfies

$$\begin{cases}
\min\left\{\partial_{\theta}u - \mathcal{L}_{s}u, u - (K - e^{s})^{+}\right\} = 0, & (s, y, \theta) \in \mathcal{Q} := \mathbb{R} \times \mathbb{R}^{+} \times (0, T], \\
u(s, y, 0) = (K - e^{s})^{+}, & s \in \mathbb{R}, y \in \mathbb{R}^{+}, \\
u(s, 0, \theta) = (K - e^{s})^{+}, & s \in \mathbb{R}, \theta \in (0, T].
\end{cases} \tag{5}$$

Problem (5) is a variational inequality, we apply penalty approximation techniques to show the existence of strong solution to (5). Suppose $u_{\varepsilon}(s, y, \theta)$ satisfies

$$\begin{cases} \partial_{\theta}u_{\varepsilon} - \mathcal{L}_{s}^{\varepsilon}u_{\varepsilon} + \beta_{\varepsilon}(u_{\varepsilon} - \pi_{\varepsilon}(K - e^{s})) = 0, & (s, y, \theta) \in \mathcal{Q}, \\ u_{\varepsilon}(s, y, 0) = \pi_{\varepsilon}(K - e^{s}), & s \in \mathbb{R}, y \in \mathbb{R}^{+}, \\ u_{\varepsilon}(s, 0, \theta) = \pi_{\varepsilon}(K - e^{s}), & s \in \mathbb{R}, \theta \in (0, T]. \end{cases}$$
(6)

where
$$\mathscr{L}_{s}^{\varepsilon}u = \frac{1}{2}(\sigma^{2}(y) + \varepsilon)\partial_{ss}u + \rho(\sigma(y)b(y) + \varepsilon)\partial_{sy}u + \frac{1}{2}(b^{2}(y) + \varepsilon)\partial_{yy}u + (r - \frac{1}{2}\sigma^{2}(y) - \frac{1}{2}\varepsilon)\partial_{s}u + \mu(y)\partial_{y}u - ru$$
, and $\beta_{\varepsilon}(\xi)$ (Fig. 1.), $\pi_{\varepsilon}(\xi)$ (Fig. 2.) satisfy

$$\beta_{\varepsilon}(\xi) \in C^{2}(-\infty, +\infty), \ \beta_{\varepsilon}(\xi) \leq 0, \ \beta_{\varepsilon}(0) = -2r(K+1), \ \beta_{\varepsilon}'(\xi) \geq 0, \ \beta_{\varepsilon}''(\xi) \leq 0.$$

$$\lim_{\varepsilon \to 0} \beta_{\varepsilon}(\xi) = \begin{cases} 0, & \xi > 0, \\ -\infty, & \xi < 0, \end{cases} \pi_{\varepsilon}(\xi) = \begin{cases} \xi, & \xi \geq \varepsilon, \\ \nearrow, & |\xi| \leq \varepsilon, \\ 0, & \xi \leq -\varepsilon, \end{cases}$$

$$\pi_{arepsilon}(\xi) \in C^{\infty}, \ 0 \leq \pi'_{arepsilon}(\xi) \leq 1, \ \pi''_{arepsilon}(\xi) \geq 0, \ \lim_{arepsilon o 0} \pi_{arepsilon}(\xi) = \xi^{+}.$$

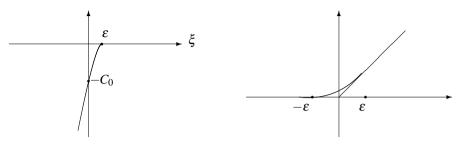


Fig. 1. $\beta_{\varepsilon}(\xi)$ Fig. 2. $\pi_{\varepsilon}(\xi)$

Since $\mathcal{Q} = (-\infty, +\infty) \times (0, +\infty) \times (0, T]$ is infinitely, we consider the truncated version of (6), denote $\mathcal{Q}^N = (-N, N) \times (0, N) \times (0, T]$, let $u_{\mathcal{E}}^N(s, y, \theta)$ satisfy

$$\begin{cases} \partial_{\theta}u_{\varepsilon}^{N} - \mathcal{L}_{s}^{\varepsilon}u_{\varepsilon}^{N} + \beta_{\varepsilon}(u_{\varepsilon}^{N} - \pi_{\varepsilon}(K - e^{s})) = 0, & (s, y, \theta) \in \mathcal{Q}^{N}, \\ u_{\varepsilon}^{N}(s, y, 0) = \pi_{\varepsilon}(K - e^{s}), & (s, y) \in (-N, N) \times (0, N), \\ u_{\varepsilon}^{N}(s, 0, \theta) = \pi_{\varepsilon}(K - e^{s}), & (s, \theta) \in (-N, N) \times (0, T], \\ \partial_{y}u_{\varepsilon}^{N}(s, N, \theta) = 0, & (s, \theta) \in (-N, N) \times (0, T], \\ u_{\varepsilon}^{N}(s, N, \theta) = \pi_{\varepsilon}(K - e^{-N}), & (y, \theta) \in (0, N) \times (0, T], \\ \partial_{s}u_{\varepsilon}^{N}(N, y, \theta) = 0, & (y, \theta) \in (0, N) \times (0, T]. \end{cases}$$

$$(7)$$

Lemma 1. For any fixed ε , N > 0, there exists a unique solution $u_{\varepsilon}^N \in W_p^{2,1}(\mathcal{Q}^N)$ to the problem (7), and

$$\pi_{\varepsilon}(K - e^s) \le u_{\varepsilon}^N(s, y, \theta) \le K + 1,$$
 (8)

$$\partial_{\theta} u_{\varepsilon}^{N}(s, y, \theta) \ge 0.$$
 (9)

Proof. For any fixed ε , N > 0, it is not hard to show by the fixed point theorem that problem (7) has a solution $u_{\varepsilon}^N \in W_p^{2,1}(\mathscr{Q}^N)$, and

$$|u_{\varepsilon}^{N}|_{0} \leq C(|\beta_{\varepsilon}(u_{\varepsilon}^{N} - \pi_{\varepsilon}(K - e^{s}))|_{0} + |\pi_{\varepsilon}(K - e^{s})|_{0}) \leq C(|\beta_{\varepsilon}(-K - 1)| + K + 1) \leq C.$$

The proof of uniqueness is a standard way as well.

Since

$$\begin{split} &\partial_{\theta}\pi_{\varepsilon}(K-e^{s})-\mathscr{L}_{s}^{\varepsilon}(\pi_{\varepsilon}(K-e^{s}))+\beta_{\varepsilon}(0)\\ &=-\frac{1}{2}(\sigma^{2}(y)+\varepsilon)(\pi_{\varepsilon}''(\cdot)e^{2s}-\pi_{\varepsilon}'(\cdot)e^{s})+\Big(r-\frac{1}{2}\sigma^{2}(y)-\frac{1}{2}\varepsilon\Big)\pi_{\varepsilon}'(\cdot)e^{s}+r\pi_{\varepsilon}(K-e^{s})+\beta_{\varepsilon}(0)\\ &\leq r(K+\varepsilon)+r(K+\varepsilon)+\beta_{\varepsilon}(0)\leq 0. \end{split}$$

Combining with the initial and boundary conditions, we know $\pi_{\varepsilon}(K - e^s)$ is a subsolution of (7). Similarly we know K + 1 is a supersolution of (7).

Next we will prove (9). Set $u^{\delta}(s, y, \theta) := u_{\varepsilon}^{N}(s, y, \theta + \delta)$, then $u^{\delta}(s, y, \theta)$ satisfies

$$\begin{cases} \partial_{\theta}u^{\delta} - \mathscr{L}_{s}^{\varepsilon}u^{\delta} + \beta_{\varepsilon}(u^{\delta} - \pi_{\varepsilon}(K - e^{s})) = 0, \\ u^{\delta}(s, y, 0) = u_{\varepsilon}^{N}(s, y, \delta) \geq \pi_{\varepsilon}(K - e^{s}) = u_{\varepsilon}^{N}(s, y, 0), \\ u^{\delta}(s, 0, \theta) = \pi_{\varepsilon}(K - e^{s}), \\ \partial_{y}u^{\delta}(s, N, \theta) = 0, \\ u^{\delta}(-N, y, \theta) = \pi_{\varepsilon}(K - e^{-N}), \\ \partial_{s}u^{\delta}(N, y, \theta) = 0. \end{cases}$$

Applying the comparison principle, we have

$$u^{\delta}(s, y, \theta) \ge u_{\varepsilon}^{N}(s, y, \theta), \quad (s, y, \theta) \in (-N, N) \times (0, N) \times (0, T - \delta],$$

which yields $\partial_{\theta} u_{\varepsilon}^{N} \geq 0$.

Letting $N \to +\infty$, the existence of strong solution to the penalty problem (6) with some estimates is given in the following theorem.

Lemma 2. For any fixed $\varepsilon > 0$, there exists a unique solution $u_{\varepsilon}(s, y, \theta) \in W_{p,loc}^{2,1}(\mathcal{Q}) \cap C^{1}(\overline{\mathcal{Q}})$ to the problem (6) for any 1 , and

$$\pi_{\varepsilon}(K - e^s) \le u_{\varepsilon}(s, y, \theta) \le K + 1,$$
 (10)

$$\partial_{\theta} u_{\varepsilon}(s, y, \theta) \ge 0,$$
 (11)

$$-e^{s} \le \partial_{s} u_{\varepsilon}(s, y, \theta) \le 0, \tag{12}$$

$$\partial_{\nu}u_{\varepsilon}(s,y,\theta) \ge 0.$$
 (13)

Proof. For any fixed $\varepsilon > 0$, R > 0, applying $W_p^{2,1}$ interior estimate with part of boundary [13] to the problem (7) (N > R), then

$$|u_{\varepsilon}^N|_{W_p^{2,1}(\mathscr{Q}^R)} \leq C(|\beta_{\varepsilon}(u_{\varepsilon}^N - \pi_{\varepsilon}(K - e^s))|_{L^{\infty}(\mathscr{Q}^R)} + |\pi_{\varepsilon}(K - e^s)|_{W_p^{2,1}(\overline{\mathscr{Q}^R} \cap \{\theta = 0\})}) \leq C,$$

where C depends on ε, R but is independent of N. Letting $N \to +\infty$, by the imbedding theorem, we know problem (6) has a solution $u_{\varepsilon}(s, y, \theta) \in W^{2,1}_{p,loc}(\mathcal{Q}) \cap C^1(\overline{\mathcal{Q}})$. (10)–(11) are consequences of (8)–(9).

Now we aim to prove (12). Differentiate the equation in (6) w.r.t. s and denote $w_1 = \partial_s u_{\varepsilon}$, then

$$\begin{cases} \partial_{\theta} w_{1} - \mathcal{L}_{s}^{\varepsilon} w_{1} + \beta_{\varepsilon}'(\cdot)w_{1} = -\beta_{\varepsilon}'(\cdot)\pi_{\varepsilon}'(\cdot)e^{s} \leq 0, & (s, y, \theta) \in \mathcal{Q}, \\ w_{1}(s, y, 0) = w_{1}(s, 0, \theta) = -\pi_{\varepsilon}'(\cdot)e^{s} \leq 0. \end{cases}$$

$$(14)$$

Applying the maximum principle [17] we know $w_1 = \partial_s u_{\varepsilon} \le 0$. In view of

$$(\partial_{\theta} - \mathscr{L}_{s}^{\varepsilon})(-e^{s}) + \beta_{\varepsilon}'(\cdot)(-e^{s}) = -\beta_{\varepsilon}'(\cdot)e^{s} \leq -\beta_{\varepsilon}'(\cdot)\pi_{\varepsilon}'(\cdot)e^{s}.$$

Combining with the initial and boundary conditions, applying the comparison principle we have

$$-e^s \le w_1(s, y, \theta) = \partial_s u_{\varepsilon}(s, y, \theta) \le 0.$$

Finally we want to prove (13). We first differentiate (14) w.r.t. s, denote $w_2 = \partial_{ss} u_{\varepsilon}$, we obtain

$$\begin{cases} \partial_{\theta} w_{2} - \mathcal{L}_{s}^{\varepsilon} w_{2} + \beta_{\varepsilon}'(\cdot)w_{2} = -\beta_{\varepsilon}'(\cdot)\pi_{\varepsilon}'(\cdot)e^{s} + \beta_{\varepsilon}'(\cdot)\pi_{\varepsilon}''(\cdot)e^{2s} - \beta_{\varepsilon}''(\cdot)[\pi_{\varepsilon}'(\cdot)e^{s} + w_{1}]^{2}, \\ w_{2}(s, y, 0) = w_{2}(s, 0, \theta) = -\pi_{\varepsilon}'(\cdot)e^{s} + \pi_{\varepsilon}''(\cdot)e^{2s}. \end{cases}$$

$$(15)$$

Set $w_3(s, y, \theta) := w_2(s, y, \theta) - w_1(s, y, \theta)$, in view of (14) and (15)

$$\begin{cases} \partial_{\theta} w_3 - \mathscr{L}_s^{\varepsilon} w_3 + \beta_{\varepsilon}'(\cdot)w_3 = \beta_{\varepsilon}'(\cdot)\pi_{\varepsilon}''(\cdot)e^{2s} - \beta_{\varepsilon}''(\cdot)[\pi_{\varepsilon}'(\cdot)e^s + w_1]^2 \ge 0, \\ w_3(s, y, 0) = w_3(s, 0, \theta) = \pi_{\varepsilon}''(\cdot)e^{2s} \ge 0. \end{cases}$$

Applying maximum principle we know $w_3(s,y,\theta) \ge 0$, i.e., $\partial_{ss}u_{\varepsilon} - \partial_su_{\varepsilon} \ge 0$. Differentiate (6) w.r.t. y, denote $w_4(s,y,\theta) = \partial_v u_{\varepsilon}(s,y,\theta)$. Then we get

$$\begin{cases} \partial_{\theta}w_4 - \mathscr{L}_s^{\varepsilon}w_4 - \rho(\sigma'(y)b(y) + \sigma(y)b'(y))\partial_sw_4 - b(y)b'(y)\partial_yw_4 \\ -\mu'(y)w_4 + \beta'_{\varepsilon}(\cdot)w_4 = \sigma(y)\sigma'(y)(\partial_{ss}u_{\varepsilon} - \partial_su_{\varepsilon}), \end{cases}$$

$$w_4(s, y, 0) = 0,$$

$$w_4(s, 0, \theta) \ge 0.$$

Since $\sigma'(y) \ge 0$, $u_{\varepsilon} \in C^{2,1}(\mathcal{Q})$ and $\partial_{ss}u_{\varepsilon} - \partial_{s}u_{\varepsilon} \ge 0$, by maximum principle [17], we have $\partial_{v}u_{\varepsilon}(s, y, \theta) \ge 0$.

Now we are able to show the solvability on the variational inequality (5) in the Sobolev space by the approximation of a subsequence of $\{u_{\varepsilon}\}$.

Lemma 3. There exists a solution $u \in W_p^{2,1}(\mathcal{Q}_{\delta}^N \setminus B_h)$ to the problem (5), where $\mathcal{Q}_{\delta}^N = (-N,N) \times (\delta,N) \times (0,T]$, $B_h = (\ln K - h, \ln K + h) \times (0,+\infty) \times (0,T]$ for any N, δ , h > 0. Moreover,

$$(K - e^s)^+ \le u(s, y, \theta) \le K + 1,$$
 (16)

$$\partial_{\theta} u(s, y, \theta) \ge 0,$$
 (17)

$$-e^{s} \le \partial_{s} u(s, y, \theta) \le 0, \tag{18}$$

$$\partial_{y}u(s,y,\theta) \ge 0.$$
 (19)

Proof. Since $\sigma(y)$, b(y) are continuous and $\sigma'(y) \geq 0$, in $\mathscr{Q}^N_{\frac{1}{2}}$, we have $\sigma^2(y) + \varepsilon \geq \sigma^2(\frac{1}{2}) > 0$, and $\lambda_1 |\xi|^2 \leq a^{ij} \xi_i \xi_j \leq \Lambda_1 |\xi|^2$, with Λ_1 , λ_1 independent of ε . Applying $C^{\alpha,\alpha/2}$ estimate [14] and $W^{2,1}_p$ interior estimate with part of boundary [13], we have

$$\begin{split} |u_{\varepsilon}|_{C^{\alpha,\alpha/2}\left(\overline{\mathcal{Q}_{\frac{1}{2}}^{N}}\right)} &\leq C(|u_{\varepsilon}|_{0} + |\beta_{\varepsilon}(u_{\varepsilon} - \pi_{\varepsilon}(K - e^{s}))|_{0} + [\pi_{\varepsilon}(K - e^{s})]_{C^{\gamma}(-N,N)}) \leq C_{1}, \\ |u_{\varepsilon}|_{W_{p}^{2,1}(\mathcal{Q}_{\frac{1}{2}}^{N} \setminus B_{h})} &\leq C(|u_{\varepsilon}|_{L^{\infty}} + |\beta_{\varepsilon}(u_{\varepsilon} - \pi_{\varepsilon}(K - e^{s}))|_{L^{\infty}} + |(K - e^{s}) \vee 0|_{W_{p}^{2,1}(\mathcal{Q}_{\frac{1}{2}}^{N} \setminus B_{h})}) \leq C_{2}, \end{split}$$

where C_1 , C_2 are independent of ε due to the estimate (10) and the definitions of β_{ε} , π_{ε} . Thus there exists a subsequence of $\{u_{\varepsilon}\}$, denote $\{u_{\varepsilon}^{(1)}\}$, and $u^{(1)} \in W_p^{2,1}(\mathcal{Q}_{\frac{1}{2}}^N \setminus B_h) \cap C(\overline{\mathcal{Q}_{\frac{1}{2}}^N})$, such that

$$u_{\varepsilon}^{(1)}(s,y,\theta) \rightharpoonup u^{(1)}(s,y,\theta) \quad in W_p^{2,1}(\mathcal{Q}_{\frac{1}{2}}^N \setminus B_h) \text{ weakly},$$

$$u_{\varepsilon}^{(1)}(s,y,\theta) \rightarrow u^{(1)}(s,y,\theta) \quad in C(\overline{\mathcal{Q}_{\frac{1}{2}}^N}) \text{ uniformly}.$$

In a same way, in $\mathscr{Q}_{\frac{1}{3}}^N$, we have $\sigma^2(y) + \varepsilon \geq \sigma^2(\frac{1}{3})$, and $\lambda_2 |\xi|^2 \leq a^{ij} \xi_i \xi_j \leq \Lambda_2 |\xi|^2$, with Λ_2 , λ_2 independent of ε . Thus there exists $\{u_{\varepsilon}^{(2)}\} \subseteq \{u_{\varepsilon}^{(1)}\}$, $u^{(2)} \in W_p^{2,1}(\mathscr{Q}_{\frac{1}{3}}^N \setminus B_h) \cap C\left(\overline{\mathscr{Q}_{\frac{1}{3}}^N}\right)$, such that

$$\begin{split} u_{\varepsilon}^{(2)}(s,y,\theta) &\rightharpoonup u^{(2)}(s,y,\theta) &\quad \text{in } W_p^{2,1}(\mathcal{Q}_{\frac{1}{3}}^N \setminus B_h) \text{ weakly}, \\ u_{\varepsilon}^{(2)}(s,y,\theta) &\to u^{(2)}(s,y,\theta) &\quad \text{in } C\Big(\overline{\mathcal{Q}_{\frac{1}{3}}^N}\Big) \text{ uniformly}. \end{split}$$

Moreover,

$$u^{(2)}(s,y,\theta) = u^{(1)}(s,y,\theta), \quad (s,y,\theta) \in \mathcal{Q}_{\frac{1}{2}}^{N}.$$

Define $u(s, y, \theta) = u^{(k)}(s, y, \theta)$, if $(s, y, \theta) \in \mathcal{Q}_{\frac{1}{k+1}}^N$, abstracting diagram subsequence $\{u_{\varepsilon_k}^{(k)}\}$, for any δ , h, N > 0, we have

$$u_{\varepsilon_k}^{(k)}(s, y, \theta) \rightharpoonup u(s, y, \theta)$$
 in $W_p^{2,1}(\mathcal{Q}_{\delta}^N \setminus B_h)$ weakly, $u_{\varepsilon_k}^{(k)}(s, y, \theta) \rightarrow u(s, y, \theta)$ in $C(\overline{\mathcal{Q}_{\delta}^N})$ uniformly,

thus $u(s, y, \theta) \in W_p^{2,1}(\mathcal{Q}_{\delta}^N \setminus B_h) \cap C(\overline{\mathcal{Q}} \setminus \{y = 0\})$ and $u(s, y, \theta)$ satisfies the variational inequality in (5) and the initial condition.

Next we will prove the continuity on the degenerate boundary y=0. For any $s_0 \in \mathbb{R} \setminus \{\ln K\}$, then there exists $\varepsilon_0 > 0$ such that $\pi_{\varepsilon_0}(K - e^{s_0}) = (K - e^{s_0})^+$, denote $w_0(s,y,\theta) = \pi_{\varepsilon_0}(K - e^s) + Ay^\alpha \ge 0$, with $0 < \alpha < 1$, and $A \ge 1$ to be determined, then for any $\varepsilon < \varepsilon_0$

$$\begin{split} &\partial_{\theta}w_{0}-\mathscr{L}_{s}^{\varepsilon}w_{0}+\beta_{\varepsilon}(w_{0}-\pi_{\varepsilon}(K-e^{s}))\\ &=-\frac{1}{2}(\sigma^{2}(y)+\varepsilon)\pi_{\varepsilon_{0}}''(\cdot)e^{2s}-\frac{1}{2}(b^{2}(y)+\varepsilon)A\alpha(\alpha-1)y^{\alpha-2}+r\pi_{\varepsilon_{0}}'(\cdot)e^{s}\\ &-\mu(y)\alpha Ay^{\alpha-1}+rw_{0}+\beta_{\varepsilon}(\pi_{\varepsilon_{0}}(K-e^{s})-\pi_{\varepsilon}(K-e^{s})+Ay^{\alpha})\\ &\geq-\frac{1}{2}(\sigma^{2}(y)+\varepsilon)\pi_{\varepsilon_{0}}''(\cdot)e^{2s}+\frac{1}{2}(b^{2}(y)+\varepsilon)A\alpha(1-\alpha)y^{\alpha-2}-\mu(y)\alpha Ay^{\alpha-1}+\beta_{\varepsilon}(0), \end{split}$$

since the negative Fichera function indicates $\mu(0) < \lim_{y \to 0} b(y)b'(y)$, in addition, $b^2(y) = O(y)$ or $b^2(y) = o(y)$ when $y \to 0$, hence there exists $\delta_0 > 0$ small enough and independent of ε such that

$$-\frac{1}{2}(\sigma^2(y)+\varepsilon)\pi_{\varepsilon_0}''(\cdot)e^{2s}+\frac{1}{2}(b^2(y)+\varepsilon)A\alpha(1-\alpha)y^{\alpha-2}-\mu(y)\alpha Ay^{\alpha-1}+\beta_{\varepsilon}(0)\geq 0$$

for any $y \in (0, \delta_0)$. Moreover, we can choose A large enough such that $A\delta_0^{\alpha} \ge K + 1$. Combining

$$\pi_{\varepsilon_0}(K-e^s) + Ay^{\alpha} \ge \pi_{\varepsilon}(K-e^s), \quad \varepsilon < \varepsilon_0,$$

applying comparison principle, we have

$$\pi_{\varepsilon}(K-e^s) \le u_{\varepsilon}(s,y,\theta) \le \pi_{\varepsilon_0}(K-e^s) + Ay^{\alpha}, \quad (s,y,\theta) \in \mathbb{R} \times (0,\delta_0) \times (0,T].$$

Letting $\varepsilon \to 0^+$ we have

$$(K - e^s)^+ \le u(s, y, \theta) \le \pi_{\varepsilon_0}(K - e^s) + Ay^{\alpha}, \quad (s, y, \theta) \in \mathbb{R} \times (0, \delta_0) \times (0, T].$$

In particular

$$(K - e^{s_0})^+ \le u(s_0, y, \theta) \le (K - e^{s_0})^+ + Ay^{\alpha}, y \in (0, \delta_0).$$

Letting $y \to 0^+$, we obtain

$$u(s_0, 0, \theta) = (K - e^{s_0})^+, \quad \theta \in (0, T],$$

since s_0 is arbitrary, then $u(s,0,\theta)=(K-e^s)^+$, $s \in \mathbb{R} \setminus \{\ln K\}$. Therefore $u(s,y,\theta)$ is a solution to the problem (5). (16)–(19) are consequences of (10)–(13).

4 Characterization of free boundary to the problem (5)

Variational inequality (5) is an obstacle problem, this section aims to characterize the free boundary arise from (5).

Lemma 4. The solution to the problem (5) satisfies

$$u(s, y, \theta) > 0, \quad (s, y, \theta) \in \mathbb{R} \times \mathbb{R}^+ \times (0, T].$$

Proof. For any fixed $y_0 > 0$, we have

$$\begin{cases} \partial_{\theta} u - \mathscr{L}_{s} u \geq 0, & (s, y, \theta) \in \mathbb{R} \times (y_{0}, +\infty) \times (0, T], \\ u(s, y, 0) = (K - e^{s})^{+} \geq 0, & (s, y) \in \mathbb{R} \times (y_{0}, +\infty), \\ u(s, y_{0}, \theta) \geq (K - e^{s})^{+} \geq 0, & (s, \theta) \in \mathbb{R} \times (0, T]. \end{cases}$$

Applying strong maximum principle, we obtain

$$u(s, y, \theta) > 0$$
, $(s, y, \theta) \in \mathbb{R} \times (y_0, +\infty) \times (0, T]$.

Since y_0 is arbitrary, then we know

$$u(s, y, \theta) > 0$$
, $(s, y, \theta) \in \mathbb{R} \times \mathbb{R}^+ \times (0, T]$.

In order to characterize the free boundary, we first define

$$\mathscr{C}[u] := \{(s, y, \theta) : u(s, y, \theta) = (K - e^s)^+\}$$
 (Coincidence set),
 $\mathscr{N}[u] := \{(s, y, \theta) : u(s, y, \theta) > (K - e^s)^+\}$ (Noncoincidence set).

Thanks to the estimates (16)–(19) of the solution to (5), problem (5) gives rise to a free boundary that can be expressed as a function of (y, θ) . The following three lemmas give the existence and properties of the free boundary.

Proposition 1. There exists $h(y, \theta) : \mathbb{R}^+ \times (0, T] \to \mathbb{R}$, such that

$$\mathscr{C}[u] = \{ (s, y, \theta) \in \mathscr{Q} : s \le h(y, \theta), y \in \mathbb{R}^+, \theta \in (0, T] \}. \tag{20}$$

Moreover, for any fixed y > 0, $h(y, \theta)$ is monotonic decreasing w.r.t. θ ; for any fixed $\theta \in (0, T]$, $h(y, \theta)$ is monotonic decreasing w.r.t. y.

Proof. Since $(K - e^s)^+ = 0$ when $s \ge \ln K$, in view of Lemma 4, we have

$${s \ge \ln K} \subset \mathcal{N}[u], \quad \mathscr{C}[u] \subset {s < \ln K}.$$

Hence problem (5) is equivalent to the following problem

$$\begin{cases} \min \left\{ \partial_{\theta} u - \mathcal{L}_{s} u, \ u - (K - e^{s}) \right\} = 0, & (s, y, \theta) \in \mathcal{Q} := \mathbb{R} \times \mathbb{R}^{+} \times (0, T], \\ u(s, y, 0) = (K - e^{s})^{+}, & s \in \mathbb{R}, \ y \in \mathbb{R}^{+}, \\ u(s, 0, \theta) = (K - e^{s})^{+}, & s \in \mathbb{R}, \ \theta \in (0, T]. \end{cases}$$

Together with (18), we can define

$$h(y,\theta) := \max\{s \in \mathbb{R} : u(s,y,\theta) = (K - e^s)\}, \quad (y,\theta) \in \mathbb{R}^+ \times (0,T],$$

by the definition of $h(y, \theta)$, we know (20) is true.

Suppose $h(y, \theta_1) = s_1$, notice that $\partial_{\theta} u(s, y, \theta) \ge 0$, then for any $\theta_2 \le \theta_1$,

$$0 \le u(s_1, y, \theta_2) - (K - e^{s_1}) \le u(s_1, y, \theta_1) - (K - e^{s_1}) = 0,$$

from which we infer that

$$u(s_1, y, \theta_2) = (K - e^{s_1}), \quad \theta_2 \le \theta_1.$$

By the definition of $h(y, \theta)$, we know $h(y, \theta_2) \ge s_1 = h(y, \theta_1)$, thus $h(y, \cdot)$ is monotonic decreasing w.r.t. θ .

Similarly, the monotonicity of $h(y, \theta)$ w.r.t. y can be deduced by virtue of $\partial_y u(s, y, \theta) \ge 0$ and the definition of $h(y, \theta)$.

Proposition 2. $h(y, \theta)$ is continuous on $\mathbb{R}^+ \times [0, T]$ with

$$h(y,0) := \lim_{\theta \to 0^+} h(y,\theta) = \ln K, \quad y > 0.$$

Proof. We first prove $h(y, \theta)$ is continuous w.r.t. θ . Suppose not. There exists $y_0 > 0$, $\theta_0 > 0$ such that $s_1 := h(y_0, \theta_0 +) < h(y_0, \theta_0) := s_2$. Since $h(y_0, \theta_0 +) = s_1$ (see Fig. 3.), then

$$u(s, y_0, \theta) > K - e^s$$
, $s > s_1, \theta > \theta_0$.

In fact, $u \in W_p^{2,1}$ and the embedding theorem imply that u is uniformly continuous, thus there exists $\delta > 0$, take $\mathscr{S}_0 = (s_1, s_2) \times (y_0 - \delta, y_0)$ such that $U_0 := \mathscr{S}_0 \times (\theta_0, T] \subseteq \mathscr{N}[u]$, then

$$\partial_{\theta}u - \mathcal{L}_{s}u = 0, \quad (s, y, \theta) \in U_{0}.$$

Moreover, in view of $h(y_0, \theta_0) := s_2$, then

$$h(y, \theta_0) \ge s_2, \quad y_0 - \delta < y \le y_0,$$

hence

$$u(s, y, \theta_0) = K - e^s$$
, $s \le s_2$, $y_0 - \delta < y \le y_0$.

In particular,

$$u(s, y, \theta_0) = K - e^s, \quad (s, y) \in \overline{U_0} \cap \{\theta = \theta_0\},$$

thus

$$\begin{split} \partial_{\theta}u\big|_{\theta=\theta_0} &= \mathscr{L}_{s}u\big|_{\theta=\theta_0} = \frac{1}{2}\sigma^2(y)(-e^s) + \Big(r - \frac{1}{2}\sigma^2(y)\Big)(-e^s) - r(K - e^s) \\ &= -rK < 0. \end{split}$$

which comes to a contradiction with the fact that $\partial_{\theta} u \ge 0$. Hence $h(y, \theta)$ is continuous w.r.t. θ .

Since $h(y,\theta)$ is monotonic decreasing w.r.t. θ , then we can define $h(y,0) := \lim_{\theta \to 0^+} h(y,\theta)$. In the same way we can prove $h(y,0) = \ln K$.

Now we aim to prove the continuity of $h(y,\theta)$ w.r.t. y. If this is not true, there exists θ_0 , $y_0 > 0$ such that $s_1 := h(y_0 +, \theta_0) < h(y_0, \theta_0) := s_2$. Since $h(y,\theta)$ is continuous w.r.t. θ and $u(s,y,\theta) \in C^{1,1,1/2}(\mathcal{Q})$, take $U_0 := (\tilde{s},\bar{s}) \times (y_0,+\infty) \times (\tilde{\theta},\bar{\theta})$, where $(\tilde{s},\bar{s}) \times (\tilde{\theta},\bar{\theta}) \subseteq (h(y_0+,\theta),h(y_0,\theta))$ (see Fig. 4.), then $u(s,y,\theta)$ satisfies

$$\partial_{\theta}u - \mathcal{L}_{s}u = 0, \quad (s, y, \theta) \in U_{0},
 u(s, y_{0}, \theta) = K - e^{s}, \quad (s, \theta) \in \overline{U_{0}} \cap \{y = y_{0}\},
 \partial_{y}u(s, y_{0}, \theta) = 0, \quad (s, \theta) \in \overline{U_{0}} \cap \{y = y_{0}\}.$$

Thus

$$\partial_{\theta}u(s, y_0, \theta) = \partial_{y\theta}u(s, y_0, \theta) = 0, \quad (s, \theta) \in \overline{U_0} \cap \{y = y_0\}.$$

Since $\partial_{\theta} u \geq 0$ and $\partial_{\theta} (\partial_{\theta} u) - \mathcal{L}_s(\partial_{\theta} u) = 0$ in U_0 , by Hopf lemma we know

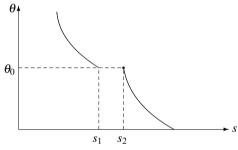
$$\partial_{y\theta}u(s,y_0,\theta)>0, \quad (s,\theta)\in \overline{U_0}\cap \{y=y_0\},$$

or

$$\partial_{\theta} u(s, y, \theta) \equiv 0, \quad (s, y, \theta) \in U_0,$$

but both come to contradictions.

Together with the monotonicity of $h(y, \theta)$ w.r.t. y and θ , we conclude that $h(y, \theta)$ is continuous on $\mathbb{R}^+ \times [0, T]$.



 $h(y_0, \theta)$ $h(y_0, \theta)$ $h(y_0, \theta)$

Fig. 3. Discontinuity of $h(y, \theta)$ w.r.t. θ

Fig. 4. Discontinuity of $h(y, \theta)$ w.r.t.

Proposition 3. The free boundary $h(y, \theta)$ satisfies

$$h_0(y) \le h(y, \theta) < \ln K, \quad y > 0, \ \theta \in (0, T],$$

where $h_0(y)$ is the free boundary curve of

$$\min\{-\mathscr{L}_s u_\infty(s,y), \ u_\infty(s,y) - (K - e^s)^+\} = 0, \quad (s,y) \in \mathbb{R} \times \mathbb{R}^+.$$
 (21)

Proof. Since $\partial_{\theta} u_{\infty}(s, y) = 0$, then we can rewrite (21) as

$$\begin{cases} \min \left\{ \partial_{\theta} u_{\infty} - \mathcal{L}_{s} u_{\infty}, \ u_{\infty} - (K - e^{s})^{+} \right\} = 0, \quad (s, y, \theta) \in \mathcal{Q}, \\ u_{\infty}(s, y)|_{\theta = 0} = u_{\infty}(s, y) \ge (K - e^{s})^{+} = u(s, y, 0). \end{cases}$$

Applying the monotonicity of solution of variational inequality w.r.t. initial value, we have

$$u_{\infty}(s,y) \ge u(s,y,\theta), \quad \theta \ge 0.$$

By the definitions of $h_0(y)$ and $h(y, \theta)$, we know

$$h_0(y) \le h(y, \theta)$$
.

Now we will prove $h(y,\theta) < \ln K$. Suppose not. There exists $y_0 > 0$, $\theta_0 > 0$ such that $h(y_0,\theta_0) = \ln K$. Then by the monotonicity of $h(y,\theta)$ and the fact that $h(y,\theta) \le \ln K$, we have

$$u(s, y, \theta) = K - e^{s}, \quad (s, y, \theta) \in [0, \ln K] \times (0, y_0] \times (0, \theta_0].$$

Thus

$$\partial_{\theta} u(\ln K, y, \theta) = \partial_{s\theta} u(\ln K, y, \theta) = 0, \quad (y, \theta) \in (0, y_0] \times (0, \theta_0].$$

Since $\partial_{\theta}u(s, y, \theta) \geq 0$ and $\partial_{\theta}(\partial_{\theta}u) - \mathcal{L}_s(\partial_{\theta}u) = 0, s > \ln K$. By Hopf lemma [7] we know

$$\partial_{s\theta}u(\ln K, y, \theta) > 0, \quad (y, \theta) \in (0, y_0] \times (0, \theta_0],$$

or

$$\partial_{\theta} u(s, y, \theta) = 0, \quad (s, y, \theta) \in (\ln K, +\infty) \times (0, y_0] \times (0, \theta_0],$$

but both come to contradictions.

Remark 1. The numerical result of $h_0(y)$ under Heston model is given in [20], and by similar methods, under the assumptions (A1)–(A2), we can also obtain the existence of $h_0(y)$.

5 Characterization of the value function

Now, we are ready to present the characterization of the value function of (1) to the variational inequality (2) with boundary condition (4). To proceed, we present the solvability and regularity results on the variational inequality (2) with boundary condition (4) via the counterpart on the transformed problem obtained in the above.

Theorem 1. Suppose a bounded function $v(x,y,t) \in W^{2,1}_{p,loc}(Q) \cap C(\bar{Q})$ satisfies variational inequality (2) with boundary condition (4), the following assertions hold.

1. v(x,y,t) satisfies the following estimates

$$(K-x)^+ \le v(x, y, t) \le K+1,$$
 (22)

$$-1 \le \partial_x v(x, y, t) \le 0, (23)$$

$$\partial_{y}v(x,y,t) \ge 0.$$
 (24)

2. There exists a continuous function $g(y,t): \mathbb{R}^+ \times [0,T) \to \mathbb{R}^+$, such that for any fixed y > 0, g(y,t) is monotonic increasing w.r.t. t; for any fixed $t \in [0,T)$, g(y,t) is monotonic decreasing w.r.t. y with

$$g(y,t) < g(y,T) = K, \quad y > 0, t \in [0,T),$$

and

$$\begin{cases} -\partial_t v(x, y, t) - \mathcal{L}_x v(x, y, t) = 0, & x > g(y, t), \\ v(x, y, t) = (K - x)^+, & 0 \le x \le g(y, t). \end{cases}$$

3. Especially, $v(x, y, t) \in C^{2,1}$ when x > g(y, t).

Proof. By the transformations $s = \ln x$, $\theta = T - t$, $u(s, y, \theta) = v(x, y, t)$, noting $x \partial_x v(x, y, t) = \partial_s u(s, y, \theta)$ and using estimates (16), (18) and (19), we can obtain (22)–(24).

Let $g(y,t) = \exp\{h(y,\theta)\}\$, by proposition 1–2, we can conclude 2.

For any $x_0 > g(y_0, t_0)$, then $v(x_0, y_0, t_0) > (K - x_0)^+$, since v(x, y, t) is uniformly continuous, there exists a disk $B_{\delta}(x_0, y_0, t_0)$ with center (x_0, y_0, t_0) and radius δ such that

$$v(x,y,t) > (K-x)^+, \quad (x,y,t) \in B_{\delta}(x_0,y_0,t_0).$$

Applying $C^{2,1}$ interior estimate to

$$\partial_t v(x, y, t) + \mathcal{L}_x v(x, y, t) = 0, \quad (x, y, t) \in B_{\delta}(x_0, y_0, t_0),$$

to obtain $v(x, y, t) \in C^{2,1}(B_{\delta}(x_0, y_0, t_0))$, hence $v(x, y, t) \in C^{2,1}$ when x > g(y, t).

Finally, the uniqueness result is given in this below through the arguments of verification theorem.

Theorem 2. Suppose there exists $v(x,y,t) \in W^{2,1}_{p,loc}(Q)$ to the problem (2) with boundary condition (4), then $v(x,y,t) \geq V(x,y,t)$. If, in addition, there exists the region $\mathcal{N}[v] := \{(x,y,t) \in Q, v(x,y,t) > (K-x)^+\}$ satisfies

$$(\partial_t v + \mathscr{L}_x v)(X_s, Y_s, s) = 0, \quad s \in [t, \tau^*],$$

for the stopping time $\tau^* := \inf\{s > t : (X_s, Y_s, s) \notin \mathcal{N}[v]\} \land T$. Then the variational inequality (2) with boundary condition (4) admits a unique solution in $W^{2,1}_{p,loc}(Q)$ and v(x,y,t) = V(x,y,t).

Proof. Let $\tau_x^{\beta} := \inf\{s > t : X_s \leq \frac{1}{\beta} \text{ or } X_s \geq \beta\} \wedge T$ be the first hitting time of the process X_s to the upper bound β or the lower bound $\frac{1}{\beta}$ or terminal time T, $\tau_y^{\beta} := \inf\{s > t : Y_s \leq \frac{1}{\beta} \text{ or } Y_s \geq \beta\} \wedge T$ be the first hitting time of the process Y_s to the upper bound β or the lower bound $\frac{1}{\beta}$ or terminal time T. Let $\tau \in \mathscr{T}_{t,\tau_x^{\beta} \wedge \tau_y^{\beta}}$, by the general Itô's formula [12],

$$e^{-r(\tau-t)}v(X_{\tau},Y_{\tau},\tau) = v(x,y,t) + \int_{t}^{\tau} e^{-r(s-t)}(\partial_{t}v + \mathcal{L}_{x}v)(X_{s},Y_{s},s)ds$$
$$+ \int_{t}^{\tau} e^{-r(s-t)}[\sigma(Y_{s})X_{s}\partial_{x}vdW_{s} + b(Y_{s})\partial_{y}vdB_{s}]. \quad (25)$$

Since v(x, y, t) is bounded and the Itô integrals in (25) are local martingales, hence they are martingales. Moreover, by Theorem 1, we know v(x, y, t) satisfies $\partial_t v + \mathcal{L}_x v \leq 0$, $v(X_\tau, Y_\tau, \tau) \geq (K - X_\tau)^+$, hence

$$v(x,y,t) \geq \mathbb{E}_{x,y,t}[e^{-r(\tau-t)}(K-X_{\tau})^{+}], \quad \tau \in \mathscr{T}_{t,\tau_{r}^{\beta} \wedge \tau_{v}^{\beta}}.$$

Since X_s is a positive, non-explosive local martingale, then

$$\lim_{\beta \to \infty} \tau_x^{\beta} = T, \quad a.s. - \mathbb{P}. \tag{26}$$

Since Y_s is non-negative, non-explosive local martingale, then

$$\lim_{\beta \to \infty} \tau_y^{\beta} = v \wedge T, \quad a.s. - \mathbb{P}, \tag{27}$$

where v is the first hitting time of Y_s to the boundary y = 0. Hence the arbitrariness of $\tau \in \mathscr{T}_{t,\tau^{\beta} \wedge \tau^{\beta}_s}$ and the above two limits imply that

$$v(x,y,t) \ge \sup_{\tau \in \mathscr{T}_{t,v \wedge T}} \mathbb{E}_{x,y,t}[e^{-r(\tau-t)}(K-X_{\tau})^{+}]. \tag{28}$$

In view of (3), when v < T,

$$\mathbb{E}_{x,y,t}[e^{-r(\nu-t)}(K-X_{\nu})^+] \geq \mathbb{E}_{x,y,t}[e^{-r(\tau-t)}(K-X_{\tau})^+], \quad \tau \in \mathscr{T}_{\nu,T}.$$

Together with (28), we have

$$\nu(x,y,t) \geq \sup_{\tau \in \mathscr{T}_{t,T}} \mathbb{E}_{x,y,t}[e^{-r(\tau-t)}(K-X_{\tau})^{+}] = V(x,y,t).$$

On the other hand, define $\tilde{\tau}_x^{\beta} := \inf\{s > t : X_s \ge \beta\} \land T$ be the first hitting time of the process X_s to the upper bound β or terminal time T, $\tilde{\tau}_y^{\beta} := \inf\{s > t : Y_s \ge \beta\} \land T$ be the first hitting time of the process Y_s to the upper bound β or terminal time T. By (26) and (27) we know

$$\lim_{\beta \to \infty} \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} = T, \quad a.s. - \mathbb{P}.$$

Together with Monotone Convergence Theorem, we obtain

$$\lim_{\beta \to \infty} \mathbb{E}_{x,t} \left[X_T I_{\{\tilde{\tau}_x^{\beta} = T\}} \right] = \mathbb{E}_{x,t} \left[\lim_{\beta \to \infty} X_T I_{\{\tilde{\tau}_x^{\beta} = T\}} \right] = \mathbb{E}_{x,t} \left[X_T \right], \tag{29}$$

$$\lim_{\beta \to \infty} \mathbb{E}_{y,t} \left[Y_T I_{\{\tilde{\tau}_y^{\beta} = T\}} \right] = \mathbb{E}_{y,t} \left[\lim_{\beta \to \infty} Y_T I_{\{\tilde{\tau}_y^{\beta} = T\}} \right] = \mathbb{E}_{y,t} \left[Y_T \right]. \tag{30}$$

Moreover, by the definitions of $\tilde{\tau}_x^{\beta}$, $\tilde{\tau}_y^{\beta}$, we can have

$$\begin{split} \mathbb{E}_{x,t} \left[X_{\tilde{\tau}_x^{\beta}} \right] &= \mathbb{E}_{x,t} \left[X_{\tilde{\tau}_x^{\beta}} I_{\{\tilde{\tau}_x^{\beta} < T\}} \right] + \mathbb{E}_{x,t} \left[X_T I_{\{\tilde{\tau}_x^{\beta} = T\}} \right] \\ &= \beta \mathbb{P} \{ \tilde{\tau}_x^{\beta} < T \} + \mathbb{E}_{x,t} \left[X_T I_{\{\tilde{\tau}_x^{\beta} = T\}} \right]. \end{split}$$

Forcing the limit $\beta \to \infty$, due to (29),

$$\lim_{\beta \to \infty} \mathbb{E}_{x,t}[X_{\tilde{\tau}_x^{\beta}}] = \lim_{\beta \to \infty} \beta \mathbb{P}\{\tilde{\tau}_x^{\beta} < T\} + \mathbb{E}_{x,t}[X_T].$$

For all $\beta > x$, since $\{X_{\overline{\tau}_x^{\beta} \wedge s} : s > t\}$ is a bounded local martingale, hence it is a martingale. So, $\mathbb{E}_{x,t}[X_{\overline{\tau}_x^{\beta}}] = x$ for all $\beta > x$. Rearranging the above equality, we have

$$\lim_{\beta \to \infty} \beta \mathbb{P} \{ \tilde{\tau}_x^{\beta} < T \} = x - \mathbb{E}_{x,t} [X_T] \le x. \tag{31}$$

Similarly,

$$\lim_{\beta \to \infty} \beta \mathbb{P} \{ \tilde{\tau}_{y}^{\beta} < T \} = y - \mathbb{E}_{y,t} [Y_T] \le y.$$
 (32)

By Theorem 1 we know $\mathcal{N}[v] = \{(x, y, t) \in Q : x > g(y, t)\}$, noting that $v(x, y, t) \in C^{2,1}$ and $\partial_t v + \mathcal{L}_x v = 0$ in $\mathcal{N}[v]$, using the classical Itô's formula [15] in $[t, \tau^* \wedge \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}]$, we have

$$\begin{split} v(x,y,t) &= \mathbb{E}_{x,y,t} \Big[e^{-r(\tau^* \wedge \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} v\big(X_{\tau^* \wedge \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tau^* \wedge \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tau^* \wedge \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} \big) \Big] \\ &= \mathbb{E}_{x,y,t} \Big[e^{-r(\tau^* - t)} v\big(X_{\tau^*}, Y_{\tau^*}, \tau^* \big) I_{\{\tau^* \leq \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\}} \Big] \\ &+ \mathbb{E}_{x,y,t} \Big[e^{-r(\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} v\big(X_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} \big) I_{\{\tau^* > \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\}} \Big]. \end{split}$$

Forcing $\beta \to +\infty$, since $\lim_{\beta \to \infty} \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} = T$,

$$\begin{split} v(x,y,t) &= \mathbb{E}_{x,y,t} \big[e^{-r(\tau^*-t)} (K-X_{\tau^*})^+ \big] \\ &+ \lim_{\beta \to \infty} \mathbb{E}_{x,y,t} \Big[e^{-r(\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} v(X_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}) I_{\{\tau^* > \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\}} \Big]. \end{split}$$

In the following we show the limit $\lim_{\beta \to \infty} \mathbb{E}_{x,y,t} \left[e^{-r(\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} v(X_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}) I_{\{\tau^* > \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\}} \right]$ in the above equality is 0. Since $v(x,y,t) \le K+1$, then there exists

 $g(\beta) = o(\beta), \ \beta \to +\infty$ such that $v(X_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}) \leq g(\beta) = o(\beta)$, together with (31) and (32), we can obtain

$$\begin{split} 0 &\leq \lim_{\beta \to \infty} \mathbb{E}_{x,y,t} \Big[e^{-r(\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} \nu(X_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, Y_{\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}}, \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}) I_{\left\{\tau^* > \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\right\}} \Big] \\ &\leq \lim_{\beta \to \infty} g(\beta) \mathbb{E}_{x,y,t} \Big[e^{-r(\tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} - t)} I_{\left\{\tau^* > \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta}\right\}} \Big] \\ &\leq \lim_{\beta \to \infty} \frac{g(\beta)}{\beta} \lim_{\beta \to \infty} \beta \mathbb{P} \big\{ \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} < \tau^* \big\} \\ &\leq \lim_{\beta \to \infty} \frac{g(\beta)}{\beta} \lim_{\beta \to \infty} \beta \mathbb{P} \big\{ \tilde{\tau}_x^{\beta} \wedge \tilde{\tau}_y^{\beta} < T \big\} = 0. \end{split}$$

Hence $v(x, y, t) = \mathbb{E}_{x, y, t}[e^{-r(\tau^* - t)}(K - X_{\tau^*})^+]$, therefore v(x, y, t) = V(x, y, t).

6 Conclusion

In this paper, we consider an American put option of stochastic volatility with negative Fichera function on the degenerate boundary y=0, we impose a proper boundary condition from the definition of the option pricing to show that the solution to the associated variational inequality is unique, which is the value of the option, and the free boundary is the optimal exercise boundary of the option. Although the asset-price volatility coefficient may grow faster than linear growth and the domain is unbounded, we are able to show the uniqueness by verification theorem. In this paper we only consider the payoff function $(K-x)^+$, but the method in this paper will be useful for any nonnegative, continuous payoff function f(x) which is of strictly sublinear growth, i.e., $\lim_{x\to +\infty} \frac{f(x)}{x}=0$.

The problem under study belongs to a general category of stochastic control

The problem under study belongs to a general category of stochastic control problems, see for instance [18, 8]. Due to the nonlinearity, the numerical solution is always an issue in the general setup, see for instance [11] for Markov chain approximation method. In particular, regarding the current formulation of variational inequalities with Fichera functions on the boundary, it is unclear how its associated Markov chain behaves asymptotically as the step size goes to zero, see [19]. Appropriate scaling of step size at the boundary may be a key to make the obtained Markov chain consistent to the variational problem, and it will be pursued in our future work.

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