Summary: Point matching methods for Repetitive Structure in Visual SLAM application

Abstract

Keywords:

1. Introduction: Point matching in Visual SLAM

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Here are two sample references: [1, 2].

References

References

[1] R. Feynman, F. Vernon Jr., The theory of a general quantum system interacting with a linear dissipative system, Annals of Physics 24 (1963) 118–173. doi:10.1016/0003-4916(63)90068-X.

[2] P. Dirac, The lorentz transformation and absolute time, Physica 19 (1-–12) (1953) 888–896. doi:10.1016/S0031-8914(53)80099-6.