#### D: Functions

A function  $f: X \to Y$  is an assignment of an element of Y to each element of X.

1. f is **injective** if:

$$\forall x_1, x_2 \in X; f(x_1) = f(x_2)$$

$$\implies x_1 = x_2$$

and this implies that  $|X| \leq |Y|$ .

2. f is **surjective** if:

$$\forall y \in Y; \exists x \in X : y = f(x)$$

and this implies that  $|X| \geq |Y|$ .

3. f is **bijective** if it is injective and surjective.



# D: Groups

A group G is a set with a composition operator  $(\circ)$  such that  $\forall x, y, z, \in G$ :

- 1.  $x \circ y = xy \in G$
- 2. (xy)z = x(yz)
- 3.  $\exists e \in G : ex = xe = x$
- 4.  $\exists x^{-1} \in G : xx^{-1} = x^{-1}x = e$ .

G is **Abelian** if  $\forall x, y \in G; xy = yx$ .

# D1.2.1(i): Fields

A field F is a set defined with addition and multiplication such that:

- 1.  $(+): F \times F \to F; (\lambda, \mu) \mapsto \lambda + \mu$
- 2.  $(\cdot): F \times F \to F; (\lambda, \mu) \mapsto \lambda \cdot \mu$
- 3.  $\exists (-\lambda) \in F : \lambda + (-\lambda) = 0_F$
- 4.  $\exists (\lambda^{-1}) \in F : \lambda \cdot (\lambda^{-1}) = 1_F$  except when  $\lambda = 0$ .
- 5. (+) and  $(\cdot)$  are associative, commutative and distributive.

#### Remark

(F,+) and  $(F \setminus \{0_F\},\cdot)$  are groups.

#### Remark

Let n be prime or a prime power. Then  $\mathbb{F}_n$  is a finite field with n elements under modulo n. Also,  $\mathbb{Q}$  and  $\mathbb{R}$  are fields.

#### D1.2.1(ii): Vector spaces

A vector space V over a field F is an Abelian group V := (V, +) with mapping:

$$F \times V \to V; (\lambda, \mathbf{v}) \mapsto \lambda \mathbf{v}$$

where for  $\forall \lambda, \mu \in F$  and  $\forall \boldsymbol{v}, \boldsymbol{w} \in V$ :

- 1.  $\lambda(\boldsymbol{v} + \boldsymbol{w}) = (\lambda \boldsymbol{v}) + (\lambda \boldsymbol{w})$
- 2.  $(\lambda + \mu)\mathbf{v} = (\lambda \mathbf{v}) + (\mu \mathbf{v})$
- 3.  $\lambda(\mu \mathbf{v}) = (\lambda \mu) \mathbf{v}$
- 4.  $1_F v = v$

and is known as a F-vector space.

#### Remark

Let V be a F-vector space and  $\mathbf{v} \in V$ .

- 1. 0v = 0
- 2. (-1)v = -v
- 3.  $\lambda \mathbf{0} = \mathbf{0}$  for  $\forall \lambda \in F$ .

# D: Cartesian products

The **cross product** of sets  $X_1, \ldots, X_n$  is:

$$X_1 \times \cdots \times X_n := \{(x_1, \dots, x_n) : x_i \in X_i\}$$

with bijection  $X^n \times X^m \to X^{n+m}$ .

The **projection** of a cross product is:

$$\operatorname{pr}_i: X_1 \times \cdots \times X_n \to X_i;$$
  
 $(x_1, \dots, x_n) \mapsto x_i.$ 

# D1.4.1: Vector subspaces

A vector subspace U of F-vector space V has the following properties:

- 1.  $U \subset V$  and  $\mathbf{0} \in U$ .
- 2. Let  $u, v \in U$  and  $\lambda \in F$ . Then  $u + v \in U$  and  $\lambda u \in U$ .

and is also a vector space.

### P1.4.5

Let  $T \subset V$  where V is a F-vector space. Then for all vector subspaces containing T, there exists a <u>smallest</u> vector subspace:

$$\operatorname{span}(T) = \langle T \rangle_F \subset V$$

known as the vector subspace generated by T, or the span of T.

# D1.4.7: Generating set

Let  $T \subset V$  where V is a F-vector space. Set T is a **generating set** of V if:

$$\operatorname{span}(T) = V$$

and is the linear combination of vectors in T over field F. V is **finitely generated** if its generating set T is finite.

#### D1.4.9: Power sets

The power set of set X is:

$$\mathcal{P}(X) := \{U : U \subseteq X\}.$$

Let  $\mathcal{U} \subseteq \mathcal{P}(X)$ . Then:

$$\bigcup_{U \in \mathcal{U}} U := \{ x \in X : (\exists U \in \mathcal{U} : x \in U) \}$$

$$\bigcap_{U \in \mathcal{U}} U := \{ x \in X : \forall U \in \mathcal{U}; x \in U \}.$$

# D1.5.1: Linear independence

Let V be a F-vector space and  $L \subseteq V$ . Subset L is **linearly independent** if:

$$\alpha_1 \mathbf{v}_1 + \dots + \alpha_r \mathbf{v}_r = \mathbf{0}$$
  
 $\implies \alpha_1 = \dots = \alpha_r = 0$ 

for  $v_i \in L$  and is pairwise distinct.

### Remark

L is linearly dependent if some  $\alpha_i \neq 0$ .

# D1.5.8: Basis

A basis of a vector space V is a **linearly** independent generating set in V.

# T1.5.11: Basis evaluation mappings

Let V be a F-vector space.

Then  $A = \{v_1, \dots, v_r\}$  is a basis of V iff the following evaluation mapping:

$$\Phi_A: F^r \to V;$$

$$(\alpha_1, \dots, \alpha_r) \mapsto \alpha_1 v_1 + \dots + \alpha_r v_r$$
 is a bijection.

#### Remark

 $\Phi$  is surjective if A is generating.

#### T1.5.12

Let V be a vector space and  $E \subseteq V$ . Then the following statements are equivalent:

- 1. E is a basis of V.
- 2. E is minimal among all generating sets, or that  $E \setminus \{e\}$  is not a basis for  $\forall e \in E$ .
- 3. E is maximal amongst all linearly independent subsets. i.e.  $E \cup \{v\}$  is linearly dependent for  $\forall v \in V$ .

#### C1.5.13

Every finitely generated vector space has  $\$  Let V be a finitely generated vector space. a finite basis.

#### T1.5.14

Let V be a vector space.

- 1. Let  $L \subseteq V$  be linearly independent and set E be minimal amongst all generating sets of V. Let  $L \subseteq E$ . Then E is a basis of V.
- 2. Let  $E \subseteq V$  be a generating set and L be maximal amongst all linearly independent subsets of V.

Let  $L \subseteq E$ . Then E is a basis of V.

#### D1.5.15

Let X be a set and F be a field. Then:

$$\mathrm{maps}(X,F) := \{f : (\forall f : X \to F)\}$$

and is a F-vector space under pointwise addition and multiplication via scalars.

Let  $F\langle X\rangle\subseteq \operatorname{maps}(X,F)$  be the subset of all mappings that sends all but finitely many elements of X to 0:

$$F\langle X\rangle := \left\{ f : \left( \forall f : X \to \{0\} \right) \right\}.$$

It contains all linear combinations of Xin F and forms a vector subspace.

### T1.5.16

Let V be a F-vector space.

Then  $(v_i)_{i\in I}$  is a basis for V iff:

$$\forall \boldsymbol{v} \in V; \exists ! (a_i)_{i \in I} \subseteq F: \boldsymbol{v} = \sum_{i \in I} a_i \boldsymbol{v}_i.$$

# T1.6.1

Let V be a vector space. Let  $L \subset V$  be a linearly independent subset and  $E \subseteq V$  a generating set. Then  $|L| \leq |E|$ .

### T1.6.2: Steinitz exchange theorem

Let V be a vector space,  $L \subset V$  be a finite linearly independent subset and  $E \subseteq V$ be a generating set.

Then there exists an **injective** function  $\phi: L \to E$  such that:

 $(E \setminus \phi(L)) \cup L$  is a generating set for V.

# L1.6.3: Exchange lemma

Let V be a vector space. Let  $M \subset V$  be a finite linearly independent subset and  $E \subseteq V$  be a generating set where  $M \subseteq E$ .

If  $\exists \boldsymbol{w} \in V \setminus M$  such that set  $M \cup \{\boldsymbol{w}\}$  is linearly independent then:

 $\exists e \in E \setminus M : (E \setminus e) \cup \{w\}$  is generating.

### C1.6.4

- 1. V has finite basis.
- 2. V cannot have infinite basis.
- 3. Any two basis of V have the same number of elements.

### D1.6.5: Dimension

The dimension of finite F-vector space Vis the cardinality of one of its basis.

For infinite vector spaces:  $\dim(V) = \infty$ . We also define  $\dim(\{\mathbf{0}\}) := 0$ .

#### C1.6.7

Let V be a finitely generated vector space.

- 1. Every linearly independent  $L \subseteq V$ has at most  $\dim(V)$  elements and if  $|L| = \dim(V)$  then L is a basis.
- 2. Every generating set  $E \subseteq V$  has at least  $\dim(V)$  elements and if  $|E| = \dim(V)$  then E is a basis.

# C1.6.8

A proper vector subspace of a vector space with finite dimension has itself a strictly smaller dimension.

### T1.6.10: Dimension theorem

Let V be a vector space and  $U, W \subseteq V$ be vector subspaces. Then:

$$\dim(U+W) + \dim(U \cap W)$$
$$= \dim(U) + \dim(W)$$

where  $U + W := \langle U \cup W \rangle \subseteq V$ .

### D1.7.1: Linear mappings

Let V and W be F-vector spaces. A mapping  $f: V \to W$  is F-linear or a homomorphism of vector spaces if for  $\forall \boldsymbol{v}_1, \boldsymbol{v}_2 \in V \text{ and } \forall \lambda \in F$ :

- 1.  $f(v_1 + v_2) = f(v_1) + f(v_2)$
- 2.  $f(\lambda \mathbf{v}_1) = \lambda f(\mathbf{v}_1)$ .

Furthermore bijective linear mappings are an **isomorphism** of vector spaces.

A homomorphism from a vector space to itself is an endomorphism.

An isomorphism of a vector space to itself is an automorphism.

# D1.7.5: Fixed points

In a linear mapping a fixed point is sent to itself. Given mapping  $f: X \to X$  the set of fixed points is:

$$X^f = \{x \in X : f(x) = x\}.$$

# D1.7.6: Complementary subspaces

Vector subspaces  $V_1, V_2$  of vector space Vare complementary if the direct sum of vector subspaces is bijective:

$$\oplus: V_1 \times V_2 \to V; (\boldsymbol{v}_1, \boldsymbol{v}_2) \mapsto \boldsymbol{v}_1 + \boldsymbol{v}_2.$$

i.e. 
$$V_1 \oplus V_2 = V$$
.

# T1.7.7

Let  $n \in \mathbb{N}$  and V a F-vector space. V is isomorphic to  $F^n$  iff  $\dim(V) = n$ .

### L1.7.8

Let V, W be F-vector spaces and let B be a basis of V. Then the following mapping:

$$hom_F(V, W) \to maps(B, W); f \mapsto f_B$$

is a bijection. The set of all linear maps or homomorphisms from V to W is:

$$hom_F(V, W) \subseteq maps(B, W).$$

# P1.7.9

Let  $f: V \to W$  be a linear mapping, where V, W are vector spaces.

- 1. If f is injective, there exists map  $g: W \to V$  such that  $g \circ f = \mathrm{id}_V$ . i.e. it has a **left inverse**.
- 2. If f is surjective, there exists map  $g: W \to V$  such that  $f \circ g = \mathrm{id}_W$ . i.e. it has a right inverse.

# D1.8.1: Image and kernel

Let  $f: V \to W$  be a linear mapping. The **image** of this linear mapping f is:

$$\operatorname{im}(f) := f(V)$$
  
=  $\{ \boldsymbol{w} \in W : \forall \boldsymbol{v} \in V; \boldsymbol{w} = f(\boldsymbol{v}) \}$ 

and is a vector subspace of W.

The **kernel** of this linear mapping f is:

$$\ker(f) := f^{-1}(\mathbf{0}) = \{ \mathbf{v} \in V : f(\mathbf{v}) = \mathbf{0} \}$$

and is a vector subspace of V.

 $\mathbf{0} = e_H$  for group homomorphisms.

# L1.8.2

A linear mapping  $f:V\to W$  is injective **iff**  $ker(f) = \{0\}.$ 

### T1.8.4: Rank-nullity theorem

Let  $f:V\to W$  be a linear mapping and V,W are vector spaces. Then:

$$\dim(V) = \dim\Bigl(\ker(f)\Bigr) + \dim\Bigl(\operatorname{im}(f)\Bigr).$$

# T2.1.1: Matrix mappings

Let F be a field and  $m, n \in \mathbb{N}$ .

Then there exists a bijection:

$$M: \hom_F(F^m, F^n) \to \max(n \times m; F);$$

$$f \mapsto [f]$$

and attaches each linear mapping f with its representing matrix M(f) := [f].

#### Remark

The set of  $n \times m$  matrices in F is defined:

$$mat(n \times m; F)$$
.

i.e. matrices with n rows and m columns.

# D2.1.6: Matrix products

The product  $A \circ B = AB$  for A is  $n \times m$ , B is  $m \times \ell$  and AB is  $n \times \ell$  is defined as:

$$(AB)_{ik} = \sum_{j=1}^{m} A_{ij} B_{jk}$$

with the following mapping:

$$\max(n \times m; F) \times \max(m \times \ell; F)$$
  
  $\rightarrow \max(n \times \ell; F); (A, B) \mapsto AB.$ 

# T2.1.8

Let  $g: F^{\ell} \to F^m$  and  $f: F^m \to F^n$  be linear mappings. Then  $[f \circ g] = [f] \circ [g]$ .

## P2.1.9

Let A, A' be  $n \times m, B, B'$  be  $m \times \ell$  and C, C' be  $\ell \times k$ . Denote  $I = I_m$  as the  $m \times m$  identity matrix. Then:

- 1. (A + A')B = AB + A'B
- 2. A(B + B') = AB + AB'
- 3. IB = B
- $4. \ AI=A$
- 5. (AB)C = A(BC).

### D2.2.1: Invertible matrices

A matrix A is **invertible** if:

$$\exists B, C : BA = I \text{ and } AC = I.$$

### D2.2.2: Elementary matrices

Elementary matrices are square matrices that differs from the identity matrix by at most one entry.

#### T2.2.3

Every square matrix with entries in a field can be written as a  $\underline{\text{product}}$  of elementary matrices.

#### D2.2.4: Smith normal form

Matrices with **only** non-zero entries along the diagonal are in Smith normal form:

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{pmatrix}.$$

### T2.2.5

Let A be an  $n \times m$  matrix. Then:

PAQ is of Smith normal form where P and Q are invertible.

#### Remark

rank(A) = rank(PAQ).

#### D2.2.7: Column and row rank

Let matrix  $A \in \text{mat}(n \times m; F)$ .

The column rank of A is the dimension of the subspace of  $F^n$  generated by the columns of A.

Similarly the row rank of A is the dimension of the subspace of  $F^m$  generated by the rows of A.

#### T2.2.8

Column and row ranks are equal.

### D2.2.9: Full rank matrices

Let A be  $n \times m$  with entries in F. A is **full rank** if rank(A) = min(m, n).

Let A = [a] with mapping  $a : F^m \to F^n$ . Then  $\dim(\operatorname{im}(a)) := \operatorname{rank}(A)$ .

# T2.3.1: Representing matrices

Let V and W be F-vector spaces with bases  $A = \{\boldsymbol{v}_1, \dots, \boldsymbol{v}_m\}$  s.t.  $\langle A \rangle = V$  and  $B = \{\boldsymbol{w}_1, \dots, \boldsymbol{w}_n\}$  s.t.  $\langle B \rangle = W$ .

Then for every linear map  $f: V \to W$  there exists a **representing matrix**:

$$(_B[f]_A)_{ij} = a_{ij}$$

 $f(\mathbf{v}_j) = a_{1j}\mathbf{w}_1 + \dots + a_{nj}\mathbf{w}_n \in W$ which produces the following bijection:

$$M_B^A : \hom_F(V, W) \to \operatorname{mat}(n \times m; F);$$

$$f \mapsto {}_B[f]_A$$

and  $M_B^A(f) = {}_B[f]_A$  is the representing matrix of linear mapping f with respect to bases A and B.

If A and B are standard bases then [f].

#### T2.3.2

Let U, V, W be F-vector spaces with finite dimension and bases A, B, C respectively.

If  $f: U \to V$  and  $g: V \to W$  are linear mappings then  $C[g \circ f]_A = C[g]_B \circ B[g]_A$ .

### D2.3.3: Vector representations

Let V be a finite dimensional vector space with basis  $A = \{v_1, \dots, v_m\}$ . Then:

$$\Phi_A^{-1}: V \to F^r; \boldsymbol{v} \mapsto {}_A[\boldsymbol{v}]$$

is a bijection and the column vector  $_{A}[v]$  is known as the representation of vector v with respect to basis A.

### T2.3.4

Let V, W be finite dimensional F-vector spaces with bases A and B respectively.

Let  $f: V \to W$  be a linear mapping. Then  $_B[f(\boldsymbol{v})] = _B[f]_A \circ _A[\boldsymbol{v}]$  for  $\forall \boldsymbol{v} \in V$ .

#### D2.4.1

Let V be a F-vector space and let sets  $A = \{v_1, \ldots, v_n\}$  and  $B = \{w_1, \ldots, w_n\}$  be bases of V. The representation matrix of the identity mapping:

$$\mathrm{id}_V:V o V; oldsymbol{v}\mapsto oldsymbol{v}$$

is a **change of basis matrix**  $_B[id_V]_A$  with entries  $a_{ij}$  given by definition:

$$\boldsymbol{v}_j = \sum_{i=1}^n a_{ij} \boldsymbol{w}_i.$$

### T2.4.3: Change of basis

Let V and W be finite dimensional vector spaces with linear mapping  $f: V \to W$ . Let A, A' be ordered bases of V and B, B' be ordered bases of W. Then:

$$_{B'}[f]_{A'} = _{B'}[\mathrm{id}_W]_B \circ _B[f]_A \circ _A[\mathrm{id}_V]_{A'}.$$

#### C2.4.4

Let V be a finite dimensional vector space and let  $f: V \to V$  be an endomorphism. Let A, A' be bases of V. Then:

$${}_{A'}[f]_{A'} = {}_A[\operatorname{id}_V]_{A'}^{-1} \circ {}_A[f]_A \circ {}_A[\operatorname{id}_V]_{A'}.$$

#### T2.4.5

Let V and W be finite dimensional vector spaces and let  $f:V\to W$  be linear.

Then there exists a basis A of V and a basis B of W such that the representing matrix  $_B[f]_A$  has nonzero entries only on the diagonal.

### D2.4.6: Trace

The trace of a  $n \times n$  matrix A is the sum of its diagonal entries:

$$\operatorname{tr}(A) = \sum_{i=1}^{n} a_{ii}.$$

# D3.1.1: Rings

A **ring** R is a set equipped with <u>addition</u> and multiplication that satisfy:

- 1. (R, +) is an **Abelian group** with additive identity  $0_R \in R$ .
- 2.  $(R, \cdot)$  is a **monoid**, meaning that:

$$(\cdot): R \times R \to R; (a,b) \mapsto a \cdot b$$

is associative with identity element  $1 = 1_R \in R$  such that:

$$\forall a,b,c \in R; (a \cdot b) \cdot c = a \cdot (b \cdot c),$$

$$a \cdot 1 = 1 \cdot a = a$$

yet  $a \cdot b \neq b \cdot a$  in general.

3. Multiplication in R with respect to addition is distributive:

$$a\cdot (b+c) = (a\cdot b) + (a\cdot c)$$

$$(b+c) \cdot a = (b \cdot a) + (c \cdot a)$$

for  $\forall a, b, c \in R$ .

For **nonzero** rings  $0_R \neq 1_R$ .

**Division rings** are rings where nonzero elements have multiplicative inverses.

### P3.1.7

A natural number is divisible by 3 if the sum of its digits is divisible by 3.

#### **D3.1.8:** Fields

A field F is a nonzero commutative ring with **multiplicative** inverses to every nonzero element:

$$\forall a \in F; \exists a^{-1} \in F: aa^{-1} = a^{-1}a = 1.$$

i.e. a commutative division ring.

#### P3.1.11

 $\mathbb{Z}/m\mathbb{Z}$  is a field **iff** m is prime.

#### L3.2.1

Let R be a ring and  $a, b \in R$ . Then:

- 1. 0a = a0 = 0
- 2. (-a)b = -(ab) = a(-b)
- 3. (-a)(-b) = ab.

#### D3.2.3

Let  $m \in \mathbb{Z}$ . Then mth multiple ma of  $a \in (R, +)$  is  $ma = \underbrace{a + \cdots + a}_{m \text{ times}}$  if m > 0.

0a := 0 and if m < 0, (-m)a = -(ma).

#### L3.2.4

Let R be a ring where  $a,b \in R$  and  $m,n \in \mathbb{Z}$ . Then:

- 1. m(a + b) = ma + mb
- 2. (m+n)a = ma + na
- 3. m(na) = (mn)a
- $4. \ m(ab) = (ma)b = a(mb)$
- 5. (ma)(nb) = (mn)(ab).

#### **D3.2.6:** Units

Let R be a ring. An element  $r \in R$  is a **unit** if it has a **multiplicative** inverse:

$$\exists r^{-1} \in R : rr^{-1} = r^{-1}r = 1_R$$

# P3.2.9: Group of units

 $R^{\times}$  is the **set of units** in ring R and forms a group under multiplication.

#### D3.2.11: Divisor of zero

Let  $r \neq 0_R \in R$  where R is a ring. Then element r is a **divisor of zero** if:

$$\exists s \in R : rs = 0_R \text{ or } sr = 0_R.$$

# D3.2.12: Integral domains

Integral domains are commutative rings with **no** divisors of zeros.

# P3.2.15: Cancellation law

Let  $a, b, c \in R$  for R is an integral domain. If ab = ac and  $a \neq 0$  then b = c.

# P3.2.16

Let  $m \in \mathbb{N}$ . Then  $\mathbb{Z}/m\mathbb{Z}$  is an integral domain **iff** m is prime.

#### T3.2.17

Every finite integral domain is a field.

#### Remark

If  $|R| < \infty$  then  $f: R \to R$  is surjective.

# D3.3.2: Polynomial rings

R[X] is a ring of polynomials over R with zero and identity:  $0, 1 \in R$ . If  $P \in R[X]$ :

$$P = a_0 + a_1 X + a_2 X^2 + \dots + a_m X^m$$

with  $deg(P) = m \ge 0$  and  $a_i \in R$ .

#### L3.3.3

Let R be a ring and let  $P, Q \neq 0 \in R[X]$ .

- 1. deg(PQ) = deg(P) + deg(Q)
- 2. If R is an integral domain then so is polynomial ring R[X].

#### T3.3.4

Let R be an integral domain and let  $P, Q \in R[X]$  where  $\deg(Q) \leq \deg(P)$  and that polynomial Q is a **monic**.

Then  $\exists !A, B \in R[X] : P = AQ + B$  and either  $\deg(B) < \deg(Q)$  or B = 0.

#### Remark

A polynomial Q is monic if:

$$Q = q_0 + \dots + q_m X^m$$

where  $q_m = 1$ .

#### D3.3.6

Let R be a commutative ring and let  $P \in R[X]$  be a polynomial. Then:

$$R[X] \to \operatorname{maps}(R,R)$$

where we **evaluate**  $P(\lambda)$  for  $\lambda \in R$ :

$$P(X) \mapsto \{P_{\lambda} : R \to R; \lambda \mapsto P(\lambda)\}.$$

If  $P(\lambda) = 0$  then  $\lambda$  is a **root** of P.

### P3.3.9

Let R be a commutative ring, let  $\lambda \in R$  and  $P(X) \in R[X]$ . Then  $P(\lambda) = 0$  iff:

$$P(X) = (X - \lambda)Q(X)$$

where  $Q(X) \in R[X]$ .

### T3.3.10

Polynomial  $P \neq 0 \in R[X] \setminus \{0\}$  has at most  $\deg(P)$  roots in integral domain R.

# D3.3.11: Algebraically closed field

A field F is algebraically closed if every  $P \in F[X] \setminus F$  has a root in field F.

#### T3.3.13: FTA

Field  $\mathbb{C}$  is algebraically closed.

#### T3.3.14

Let field F be algebraically closed. Then every  $P \in F[X] \setminus \{0\}$  decomposes into:

$$P = c(X - \lambda_1) \dots (X - \lambda_n)$$

where  $c \in F^{\times}$  and  $\lambda_1, \ldots, \lambda_n \in F$ .

# D3.4.1: Ring homomorphisms

Let R and S be rings.  $f: R \to S$  is a ring homomorphism if for all  $x, y \in R$ :

$$f(x+y) = f(x) + f(y)$$

$$f(xy) = f(x)f(y).$$

#### L3.4.5

Let R and S be rings. Let  $f: R \to S$  be a **ring homomorphism**. Then for all  $x, y \in R$  and  $m \in \mathbb{Z}$ :

- 1.  $f(0_R) = 0_S$
- 2. f(-x) = -f(x)
- 3. f(x y) = f(x) f(y)
- 4. f(mx) = mf(x)

since (R, +) is a group.

### **D3.4.7:** Ideals

Let  $I \subset R$  where R is a ring. Then I is an **ideal** of ring R if:

- 1.  $I \neq \emptyset$  and  $0_R \in I$
- $2.\ I$  is closed under subtraction.
- 3.  $\forall i \in I; \forall r \in R; ri, ir \in I$

and we denote  $I \subseteq R$ .

# **D3.4.11:** Ideal of R generated by T

Let R be a commutative ring and  $T \subset R$ . Then the ideal of R generated by T is:

$$_{R}\langle T\rangle = \left\{ \sum_{i} r_{i} t_{i} : t_{i} \in T; \forall r_{i} \in R \right\}$$

where  $i \in \{1, \ldots, m\}$  and  $m \leq |T|$ .

# P3.4.14

 $_R\langle T\rangle$  is the smallest ideal containing T.

#### D3.4.15: Principle ideal

An ideal of a commutative ring R is the **principle ideal** if:

$$I = {}_{R}\langle t \rangle$$
 where  $t \in R$ .

#### P3.4.18

Let  $f: R \to S$  be a ring homomorphism. Then  $\ker(f)$  is an ideal of ring R where:

$$\ker(f) = \{ r \in R : f(r) = 0_S \}$$

and is a subgroup of (R, +).

#### L3.4.21 and L3.4.22

The set intersection and addition of ideals also form ideals.

# D3.4.23: Subrings

A subset  $R' \subseteq R$  is a subring of ring R if R' also satisfies D3.1.1.

# P3.4.26: Subring test

 $R' \subseteq R$  is a subring of R iff  $\forall a, b \in R'$ :

- 1. R' has multiplicative identity.
- $2. \ a-b \in R'$
- 3.  $ab, ba \in R'$

i.e. that R' is closed under subtraction and multiplication.

### P3.4.28

Let  $f: R \to S$  be a ring homomorphism.

- 1. If R' is a subring of R then f(R') and im(f) are subrings of S.
- 2. Let  $f(1_R) = 1_S$ . Then:

$$x \in R^{\times} \implies f(x) \in S^{\times}.$$

# D3.5.1: Relations

A **relation** R on set X is a subset of  $X \times X$ . We denote  $(x, y) = xRy \in X \times X$ .

R is an **equivalence relation** on set X if  $\forall x, y, z \in X$  the following is true:

- 1. Reflexive: xRx
- 2. Symmetric:  $xRy \iff yRx$
- 3. Transitive:  $(xRy \wedge yRz) \implies xRz$ .

# D3.5.3: Equivalence classes

Let  $\sim$  be an equivalence relation on X. Then the **equivalence class** of  $x \in X$  is:

$$E(x) = \{ z \in X : z \sim x \} \subseteq X$$

where an element of an equivalence class is a **representative** of the class.

#### D3.5.5

Given an equivalence relation  $\sim$  on set X, the set of equivalence classes is:

$$(X \setminus \sim) := \{ E(x) : x \in X \} \subseteq \mathcal{P}(X).$$

We also define a surjective map:

$$\operatorname{can}: X \to (X/\sim); x \mapsto E(x)$$

known as the canonical mapping.

#### Remark

A mapping  $f: X \to Z$  is **well-defined** if there is an equivalence relation  $\sim$  on X such that  $x \sim y \implies f(x) = f(y)$ .

Then there exists a unique mapping  $\overline{f}$ :

$$\overline{f}: (X/\sim) \to Z; E(x) \mapsto f(x)$$

where  $f = \overline{f} \circ \text{can}$ .

### D3.6.1: Cosets

Let I be an ideal of ring R. Then:

$$x + I = \{x + i : i \in I\} \subseteq R$$

is the coset of x with respect to I in R.

### Remark

- 1. x + I is both a left and right coset of x since (R, +) is Abelian.
- 2. Ideals of rings are subgroups.

#### D3.6.3: Factor rings

Let I be an ideal of ring R and define an equivalence relation on R where:

$$x \sim y \iff x - y \in I.$$

Then the **factor ring** of R by I is the set of cosets of I in R and denoted as R/I:

$$R/I = (R/\sim)$$

for each element is an equivalence class:

$$E(x) = \{z \in R : z - x \in I\}$$
  
= \{x + i \in R : i \in I\}  
= x + I.

#### T3.6.4

Let I be an ideal of ring R. Then R/I is a ring where  $\forall x, y \in R$ :

$$(x+I) + (y+I) = (x+y) + I$$

$$(x+I) \cdot (y+I) = xy + I$$

where  $x + I, y + I \in R/I$ .

#### T3.6.7

Let I be an ideal of ring R. Then:

- 1. can :  $R \to R/I$  is a surjective ring homomorphism with kernel I.
- 2. Let  $f: R \to S$  where  $f(I) = \{0_S\}$ and that f is a ring homomorphism.

Then there is a unique  $\overline{f}: R/I \to S$ such that  $f = \overline{f} \circ \text{can}$  and that  $\overline{f}$  is also a ring homomorphism.



# T3.6.9: FIT for rings

Every ring homomorphism  $f: R \to S$ induces a ring isomorphism:

$$\overline{f}: R/\ker(f) \to \operatorname{im}(f)$$

where  $\overline{f}$  is a **bijection**. This is the first isomorphism theorem for rings.

### D3.7.1: Left modules

A left module M over a ring R is a pair consisting of an Abelian group (M, +)and the following mapping:

$$R \times M \to M; (r, a) \mapsto ra$$

such that  $\forall r, s \in R$  and  $\forall a, b \in M$ :

$$r(a \dotplus b) = (ra) \dotplus (rb)$$
$$(r+s)a = (ra) \dotplus (sa)$$

$$r(sa)=(rs)a$$

 $1_B a = a$ 

also known as an R-module.

# L3.7.8

Let R be a ring and M be a R-module. Then  $\forall r \in R \text{ and } \forall a \in M$ :

- 1.  $0_R a = 0_M$
- $2. r0_M = 0_M$
- 3. (-r)a = r(-a) = -(ra).

### D3.7.11: Module homomorphisms

Let R be a ring, M and N be R-modules. Then  $f: M \to N$  is an R-homomorphism if  $\forall r \in R$  and  $\forall a, b \in M$ :

$$f(a+b) = f(a) + f(b)$$
$$f(ra) = rf(a).$$

$$J(ra) = rJ(a)$$

f is an R-isomorphism if it is bijective and we denote that  $M \cong N$ .

### D3.7.15: Submodules

 $M' \subseteq M$  is a submodule if it also satisfies D3.7.11 but restricted to itself.

#### P3.7.20: Submodule test

Let M be a R-module. M' is a submodule of M iff  $\forall a, b \in M$  and  $\forall r \in R$ :

- 1.  $0_M \in M'$
- $a b \in M'$
- 3.  $ra \in M'$ .

### L3.7.21

Let  $f: M \to N$  be an R-homomorphism. Then ker(f) and im(f) are submodules.

# D3.7.23: Submodule generated by T

Let  $T \subseteq M$  for M is a R-module. Then:

$$_{R}\langle T\rangle = \left\{\sum_{i} r_{i}t_{i}: t_{i} \in T; \forall r_{i} \in R\right\}$$

where  $i \in \{1, \ldots, m\}$  and  $m \leq |T|$ .

Module N is **cyclic** if  $N = {}_{R}\langle t \rangle$ .

### L3.7.29 and L3.7.30

Intersecting and adding collections of submodules also form submodules.

#### D3.7.31: Factor modules

Let R be a ring, M be a R-module and Na submodule of M. Let  $a \in M$ . Then the coset of a with respect to N in M is:

$$a + N = \{a + b : b \in N\}$$

Every coset is an equivalent class of the following equivalence relation:

$$\forall a, b \in M; a \sim b \iff a - b \in N$$

and we define the **factor module** of Mby the submodule N as:

$$M/N = (M/\sim)$$

with the following operators:

$$(a+N) + (b+N) = (a+b) + N$$

$$r(a+N) = ra + N$$

and additive identity  $0_{M/N} = 0_M + N$ .

# T3.7.33: FIT for modules

Let M and N be R-modules. Then every R-homomorphism  $f: M \to N$  induces a R-isomorphism:

$$\overline{f}: M/\ker(f) \to \operatorname{im}(f)$$

where  $\overline{f}$  is a bijection.

# D4.1.1: Symmetric group $S_n$

The set of bijections from  $\{1, \ldots, n\}$  to itself is a group under composition with n! elements, denoted by  $S_n$ .

Each bijection  $\sigma \in S_n$  is a **permutation**.

Transpositions are permutations that swap only two elements in  $\{1, \ldots, n\}$ .

### D4.1.2: Inversions

Given a permutation  $\sigma \in S_n$ , an inversion is a pair (i, j) that is interchanged:

$$i < j$$
 and  $\sigma(j) < \sigma(i)$ 

where  $i, j \in \{1, ..., n\}$ . The **length** of  $\sigma$ is the number of inversions:

$$\ell(\sigma) := |\{(i,j) : i < j \text{ and } \sigma(j) < \sigma(i)\}|$$

or the number of crossings in a diagram. We define the **sign** of  $\sigma$ :

$$\operatorname{sgn}(\sigma) = (-1)^{\ell(\sigma)} = \begin{cases} +1 & \text{even } \sigma \\ -1 & \text{odd } \sigma. \end{cases}$$

# Remark

A cycle  $(a_1 \dots a_r)$  sends each element to its right except  $a_r$  which is sent to  $a_1$ .

$$(a_1 a_2 \dots a_r) = (a_1 a_r)(a_1 a_{r-1}) \dots (a_1 a_2)$$

Note that order may not be interchanged.

### D: Group homomorphisms

Let G and H be groups. Then  $f: G \to H$ is a group homomorphism if  $\forall a, b \in G$ :

$$f(ab) = f(a)f(b).$$

 $\operatorname{sgn}: S_n \to \{+1, -1\}$ , which is the sign of permutations, is a group homomorphism:

$$\operatorname{sgn}(\sigma\tau) = \operatorname{sgn}(\sigma)\operatorname{sgn}(\tau)$$

for all  $\sigma, \tau \in S_n$ .

# D4.1.6: Alternating groups

The alternating group is a subgroup of  $S_n$ and is the kernel of sgn function:

$$A_n := \ker(\operatorname{sgn})$$
  
=  $\{ \sigma \in S_n : \operatorname{sgn} = e_{\{\pm 1\}} = +1 \}.$ 

#### D4.2.1: Determinants

Let R be a commutative ring and  $n \in \mathbb{N}$ . Then the determinant map is defined as:

$$\det: \max(n \times n; R) \to R;$$

$$A \mapsto \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) a_{1\sigma(1)} \dots a_{n\sigma(n)}$$

where  $(A)_{ij} = a_{ij}$ .

# D4.3.1: Bilinear forms

Let U, V and W be F-vector spaces. Then a **bilinear form** on  $U \times V$  with values in W is the mapping  $H : U \times V \to W$  where  $\forall u_1, u_2 \in U, \forall v_1, v_2 \in V$  and  $\forall \lambda \in F$ :

$$H(u_1 + u_2, v_1) = H(u_1, v_1) + H(u_2, v_1)$$

$$H(\lambda \boldsymbol{u}_1, \boldsymbol{v}_1) = \lambda H(\boldsymbol{u}_1, \boldsymbol{v}_1)$$

$$H(u_1, v_1 + v_2) = H(u_1, v_1) + H(u_2, v_2)$$

$$H(\boldsymbol{u}_1, \lambda \boldsymbol{u}_1) = \lambda H(\boldsymbol{v}_1, \boldsymbol{u}_1)$$

or that every entry of H is linear.

Consider a bilinear form H where:

$$H: U \times U \to W$$
.

H is symmetric if H(u, v) = H(v, u).

H is alternating if H(u, u) = 0, and these must hold for all  $u, v \in U$ .

# Remark

A bilinear form H that satisfies:

$$H(\boldsymbol{u}, \boldsymbol{u}) + H(\boldsymbol{u}, \boldsymbol{u}) = 0$$

is alternating provided  $1_F + 1_F \neq 0_F$ .

# D4.3.3: Multilinear forms

Let  $V_1, \ldots, V_n, W$  be F-vector spaces. Then the map  $H: V_1 \times \cdots \times V_n \to W$  is a **multilinear form** if every  $V_j \to W$  is linear for all  $m_j \in V_j$ .

H is alternating if  $\exists i \neq j : v_i = v_j$  and:

$$H(\boldsymbol{v}_1,\ldots,\boldsymbol{v}_i,\ldots,\boldsymbol{v}_j,\ldots,\boldsymbol{v}_n)=0.$$

# T4.3.6

Let F be a field. Then the mapping:

$$\det: \max(n \times n; F) \to F$$

is the unique alternating multilinear form on n-tuples of <u>ordered</u> column vectors of the matrix under mapping. Furthermore:

$$\det(I_n) = 1_F.$$

### T4.4.1