Q 1.

(a) From the parametric functional,

$$\Phi = (\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{\frac{1}{2}} - \lambda (x\dot{y} - \dot{x}y), \quad \lambda > 0,$$

$$\frac{\partial \Phi}{\partial \dot{x}} = \frac{1}{2} (\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{-\frac{1}{2}} (2\dot{x} + 2\gamma \dot{y}) + \lambda y.$$

$$\frac{\partial \Phi}{\partial x} = -\lambda \dot{y}.$$

The Euler-Lagrange equation is given by

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial \Phi}{\partial \dot{x}} \right) - \frac{\partial \Phi}{\partial x} = 0.$$

Substituting into the Euler-Lagrange equation for the derivatives obtained above gives,

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{1}{2} \left(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2 \right)^{-\frac{1}{2}} \left(2\dot{x} + 2\gamma \dot{y} \right) + \lambda y \right) + \lambda \dot{y} = 0,$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\left(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2 \right)^{-\frac{1}{2}} \left(\dot{x} + \gamma \dot{y} \right) + \lambda y \right) + \lambda \dot{y} = 0,$$

and integrating the above express with respect to t gives,

$$\left[\left(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2 \right)^{-\frac{1}{2}} \left(\dot{x} + \gamma \dot{y} \right) + \lambda y \right] + \lambda y = 2c,$$

where c is an arbitrary constant. So,

$$(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{-\frac{1}{2}}(\dot{x} + \gamma \dot{y}) = 2(c - \lambda y). \tag{1.1}$$

Now from the definition of s

$$\frac{\mathrm{d}s}{\mathrm{d}t} = \left(\dot{x}^2 + 2\gamma\dot{x}\dot{y} + \dot{y}^2\right)^{\frac{1}{2}},$$

and

$$\frac{\mathrm{d}t}{\mathrm{d}s} = \left(1/\frac{\mathrm{d}s}{\mathrm{d}t}\right) = \left(\dot{x}^2 + 2\gamma\dot{x}\dot{y} + \dot{y}^2\right)^{-\frac{1}{2}}.$$
 (1.2)

Substituting (1.2) into (1.1) gives,

$$\frac{\mathrm{d}t}{\mathrm{d}s}(\dot{x} + \gamma \dot{y}) = 2(c - \lambda y),$$

and noting that

$$\frac{\mathrm{d}x}{\mathrm{d}t} = \dot{x}$$
 and $\frac{\mathrm{d}y}{\mathrm{d}t} = \dot{y}$,

then

$$\frac{\mathrm{d}t}{\mathrm{d}s} \left(\frac{\mathrm{d}x}{\mathrm{d}t} + \gamma \frac{\mathrm{d}y}{\mathrm{d}t} \right) = 2 \left(c - \lambda y \right)$$

$$\frac{\mathrm{d}t}{\mathrm{d}s} \cdot \frac{\mathrm{d}x}{\mathrm{d}t} + \gamma \frac{\mathrm{d}t}{\mathrm{d}s} \cdot \frac{\mathrm{d}y}{\mathrm{d}t} = 2 \left(c - \lambda y \right),$$

thus, by the chain rule,

$$\frac{\mathrm{d}x}{\mathrm{d}s} + \gamma \frac{\mathrm{d}y}{\mathrm{d}s} = 2\left(c - \lambda y\right). \tag{1.3}$$

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Similarly for \dot{y}

$$\Phi = (\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{\frac{1}{2}} - \lambda (x\dot{y} - \dot{x}y), \quad \lambda > 0,$$

$$\frac{\partial \Phi}{\partial \dot{y}} = \frac{1}{2} (\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{-\frac{1}{2}} (2\gamma \dot{x} + 2\dot{y}) - \lambda x.$$

$$\frac{\partial \Phi}{\partial y} = \lambda \dot{x}.$$

The Euler-Lagrange equation is given by

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial \Phi}{\partial \dot{y}} \right) - \frac{\partial \Phi}{\partial y} = 0.$$

Substituting into the Euler-Lagrange equation for the derivatives obtained above gives,

$$\frac{d}{dt} \left[\frac{1}{2} \left(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2 \right)^{-\frac{1}{2}} (2\gamma \dot{x} + 2\dot{y}) - \lambda x \right] - \lambda \dot{x} = 0,$$

$$\frac{d}{dt} \left[\left(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2 \right)^{-\frac{1}{2}} (\gamma \dot{x} + \dot{y}) - \lambda x \right] - \lambda \dot{x} = 0,$$

and integrating the above express with respect to t gives,

$$(\dot{x}^2 + 2\gamma \dot{x}\dot{y} + \dot{y}^2)^{-\frac{1}{2}}(\gamma \dot{x} + \dot{y}) - \lambda x - \lambda x = 2d,$$

where d is an arbitrary constant. So,

$$\left(\dot{x}^2 + 2\gamma\dot{x}\dot{y} + \dot{y}^2\right)^{-\frac{1}{2}} \left(\gamma\dot{x} + \dot{y}\right) = 2\left(d + \lambda x\right).$$

Recall, (1.2) from above,

$$\frac{\mathrm{d}t}{\mathrm{d}s} = \left(\dot{x}^2 + 2\gamma\dot{x}\dot{y} + \dot{y}^2\right)^{-\frac{1}{2}},$$

and hence,

$$\frac{\mathrm{d}t}{\mathrm{d}s} (\gamma \dot{x} + \dot{y}) = 2 (d + \lambda x),$$

$$\frac{\mathrm{d}t}{\mathrm{d}s} \left(\gamma \frac{\mathrm{d}x}{\mathrm{d}t} + \frac{\mathrm{d}y}{\mathrm{d}t} \right) = 2 (d + \lambda x),$$

$$\gamma \frac{\mathrm{d}t}{\mathrm{d}s} \cdot \frac{\mathrm{d}x}{\mathrm{d}t} + \frac{\mathrm{d}t}{\mathrm{d}s} \cdot \frac{\mathrm{d}y}{\mathrm{d}t} = 2 (d + \lambda x),$$

Thus, by the chain rule,

$$\gamma \frac{\mathrm{d}x}{\mathrm{d}s} + \frac{\mathrm{d}y}{\mathrm{d}s} = 2(d + \lambda x).$$
(1.4)

Hence, the stationary paths of the given parametric functional are given by the solutions to equations (1.3) and (1.4).

- (b)
- (c)

- Q 2.
 - (a)
 - (b)
 - (c)

- Q 3.
 - (a)
 - (b)

Q 4.

Q 5.

Q 6.

(a) The model of tumour growth under radiotherapy from time t = 0 to $t = t_1 > 0$ is given as

$$\frac{\mathrm{d}C}{\mathrm{d}t} = -C \, \log \left(\frac{C}{C_{max}} \right) - \frac{DC}{1+D},\tag{6.1}$$

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where, at time t, C(t) is the size of the tumour, $C_{max} > 0$ is the maximum size of the tumour, a constant, so that $0 < C(t) \le C_{max}$, and $D(t) \ge 0$ is the rate at which the drug is administered.

Now, making a change of variable

$$x = \log\left(\frac{C}{C_{max}}\right),\,$$

then (6.1) becomes

$$\begin{split} \frac{\mathrm{d}x}{\mathrm{d}t} &= \frac{\mathrm{d}C}{\mathrm{d}t} \cdot \frac{\mathrm{d}x}{\mathrm{d}C}, \\ \frac{\mathrm{d}x}{\mathrm{d}t} &= \frac{\mathrm{d}C}{\mathrm{d}t} \cdot \frac{1}{C}, \\ \frac{\mathrm{d}x}{\mathrm{d}t} &= \left[\mathcal{C} \log \left(\frac{C}{C_{max}} \right) - \frac{D\mathcal{C}^{1}}{1+D} \right] \cdot \frac{1}{\mathcal{C}^{1}}, \\ \frac{\mathrm{d}x}{\mathrm{d}t} &= -\log \left(\frac{C}{C_{max}} \right) - \frac{D}{1+D}, \\ \text{thus,} \quad \frac{\mathrm{d}x}{\mathrm{d}t} &= -x - \frac{D}{1+D}, \quad \text{where } -\infty < x \leq 0. \end{split}$$

(b) We are told that:

It is required to reduce the size of the tumour from C_0 at t = 0 to C_1 at $t = t_1$. Let $x_0 = \log(C_0/C_{max})$ and $x_1 = \log(C_1/C_{max})$. For the health of the patient, it is desired to minimise the total amount of drug administered, which is given by the functional

$$S[D] = \int_0^{t_1} \mathrm{d}t \ D(t).$$

So, by expressing D in terms of x and $\dot{x} = dx/dt$ it should be possible to show that S[D] may be written as

$$S[x] = -\int_0^{t_1} dt \, \frac{\dot{x} + x}{1 + \dot{x} + x}.$$

From part (a)

$$\dot{x} = -x - \frac{D}{1+D},$$

$$\dot{x} + x = -\frac{D}{1+D},$$

$$(\dot{x} + x)(1+D) = -D,$$

$$(\dot{x} + x) + D(\dot{x} + x) = -D,$$

$$D(\dot{x} + x) + D = -(\dot{x} + x),$$

$$D(\dot{x} + x + 1) = -\dot{x} - x,$$

$$D = \frac{-\dot{x} - x}{\dot{x} + x + 1}.$$

So

$$S[x] = -\int_0^{t_1} \mathrm{d}t \; \frac{\dot{x} + x}{\dot{x} + x + 1} \qquad \text{as required.}$$

(c) To show that the Euler-Lagrange equation for S[x] is given by

$$2\ddot{x} + 3\dot{x} + x = -1$$
, where $\ddot{x} = d^2x/dt^2$,

consider the following.

The Euler-Lagrange equation is given by

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$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial F}{\partial \dot{x}} \right) - \frac{\partial F}{\partial x} = 0, \qquad y(a) = A, \quad y(b) = B.$$

$$\text{Let, } F = \frac{\dot{x} + x}{\dot{x} + x + 1},$$

then using the quotient rule to determine $\partial F/\partial \dot{x}$ and $\partial F/\partial x$

$$\frac{\partial}{\partial \dot{x}} \left(\frac{u}{v} \right) = \left[v \frac{\partial u}{\partial \dot{x}} - u \frac{\partial v}{\partial \dot{x}} \right] / v^2 \quad \text{where, } u = \dot{x} + x \text{ and } v = \dot{x} + x + 1.$$

$$\frac{\partial F}{\partial \dot{x}} = \frac{(\dot{x} + x + 1) \cdot 1 - (\dot{x} + x) \cdot 1}{(\dot{x} + x + 1)^2} = \frac{1}{(\dot{x} + x + 1)^2},$$
$$\frac{\partial F}{\partial x} = \frac{(\dot{x} + x + 1) \cdot 1 - (\dot{x} + x) \cdot 1}{(\dot{x} + x + 1)^2} = \frac{1}{(\dot{x} + x + 1)^2}.$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial F}{\partial \dot{x}} \right) = \frac{\mathrm{d}}{\mathrm{d}t} \left(\dot{x} + x + 1 \right)^{-2},$$

$$= -2 \left(\dot{x} + x + 1 \right)^{-3} \left(\ddot{x} + \dot{x} \right),$$

$$= \frac{-2 \left(\ddot{x} + \dot{x} \right)}{\left(\dot{x} + x + 1 \right)^{3}}.$$

Therefore, the Euler-Lagrange equation is

$$-\frac{2(\ddot{x}+\dot{x})}{(\dot{x}+x+1)^3} - \frac{1}{(\dot{x}+x+1)^2} = 0,$$

$$\frac{2(\ddot{x}+\dot{x})}{(\dot{x}+x+1)^3} = -\frac{1}{(\dot{x}+x+1)^2},$$

$$\frac{2(\ddot{x}+\dot{x})}{(\dot{x}+x+1)} = -1,$$

$$2(\ddot{x}+\dot{x}) = -(\dot{x}+x+1),$$

$$2(\ddot{x}+\dot{x}) + (\dot{x}+x) = -1,$$

$$2\ddot{x}+3\dot{x}+x=-1, \text{ as required.}$$

$$(6.2) \quad \ddot{x} = d^2x/dt^2.$$

(d) Now solving the second-order linear ordinary differential equation (6.2) with the boundary conditions $x(0) = x_0$ and $x(t_1) = x_1$ as follows.

The auxiliary equation is

$$2\lambda^2 + 3\lambda + 1 = 0.$$

This has roots $\lambda_1 = -1$ and $\lambda_2 = -\frac{1}{2}$. These roots are real and different so the complementary function is given by

$$y_c = c_1 e^{-t} + c_2 e^{-\frac{1}{2}t}$$
, where c_1 and c_2 are arbitrary constants.

Using the method of undetermined coefficients to determine the particular solution to (6.2) as follows.

The particular solution to

$$2\frac{d^2x(t)}{dt^2} + 3\frac{dx(t)}{dt} + x(t) = -1,$$

is of the form

$$x_p(t) = a_1,$$

where a_1 is an unknown constant to be determined as follows:

$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = \frac{\mathrm{d}}{\mathrm{d}t}(a_1) = 0,$$

and therefore

$$\frac{\mathrm{d}^2 x(t)}{\mathrm{d}t^2} = 0.$$

Substituting the particular solution $x_p(t)$ in to (6.2) gives

$$2 \times 0 + 3 \times 0 + a_1 = -1.$$

Therefore, $a_1 = -1$ and the general solution is

$$x(t) = c_1 e^{-t} + c_2 e^{-\frac{1}{2}t} - 1. (6.3)$$

Now using the boundary conditions to solve for the unknown constants c_1 and c_2 as follows.

At t = 0, $x(0) = x_0$ and substituting this condition into (6.3) gives,

$$c_1 + c_2 - 1 = x_0. (6.4)$$

At $t = t_1$, $x(t_1) = x_1$ and substituting this condition into (6.3) gives,

$$c_1 e^{-t_1} + c_2 e^{-\frac{1}{2}t_1} - 1 = x_1 \tag{6.5}$$

From (6.4)

$$c_1 = (x_0 + 1) - c_2 (6.6)$$

Substituting into (6.5) for c_1 from (6.6) and rearranging in terms of c_2

$$(x_0 + 1) e^{-t_1} - c_2 e^{-t_1} + c_2 e^{-\frac{1}{2}t_1} = x_1 + 1,$$

$$(x_0 + 1) e^{-t_1} + c_2 \left(e^{-\frac{1}{2}t_1} - e^{-t_1} \right) = (x_1 + 1),$$

$$c_2 \left(e^{-\frac{1}{2}t_1} - e^{-t_1} \right) = (x_1 + 1) - (x_0 + 1) e^{-t_1},$$

$$c_2 = \frac{(x_1 + 1) - (x_0 + 1) e^{-t_1}}{\left(e^{-\frac{1}{2}t_1} - e^{-t_1} \right)}.$$

$$(6.7)$$

Substituting for c_2 in (6.6) from (6.7)

$$c_{1} = (x_{0} + 1) - \left[\frac{(x_{1} + 1) - (x_{0} + 1) e^{-t_{1}}}{(e^{-\frac{1}{2}t_{1}} - e^{-t_{1}})} \right],$$

$$c_{1} = \frac{(x_{0} + 1) \left(e^{-\frac{1}{2}t_{1}} - e^{-t_{1}} \right) - (x_{1} + 1) + (x_{0} + 1) e^{-t_{1}}}{(e^{-\frac{1}{2}t_{1}} - e^{-t_{1}})}$$

$$c_{1} = \frac{(x_{0} + 1) e^{-\frac{1}{2}t_{1}} - (x_{0} + 1) e^{-t_{1}} - (x_{1} + 1) + (x_{0} + 1) e^{-t_{1}}}{(e^{-\frac{1}{2}t_{1}} - e^{-t_{1}})}$$

$$c_{1} = \frac{(x_{0} + 1) e^{-\frac{1}{2}t_{1}} - (x_{1} + 1)}{(e^{-\frac{1}{2}t_{1}} - e^{-t_{1}})} = \alpha.$$
(6.8)

Therefore, from (6.4)

$$c_2 = (x_0 + 1) - \alpha. (6.9)$$

Substituting into (6.3) for c_1 and c_2 from (6.8) and (6.9) respectively gives,

$$x(t) = \alpha e^{-t} + (x_0 + 1 - \alpha) e^{-\frac{1}{2}t} - 1$$
 (\alpha given in (6.8)),

as required.