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## 1 Toy Version

### 1.1 Promote elliptic containment to equality

1 DEFINITION (Simplicial Map). A map between simplicial complexes is simplicial if the image of a set of vertices that spans a simplex also spans a simplex.

2 DEFINITION (Collapse Map). Given a  $G$ -tree, collapsing components of an invariant forest to points gives a  $G$ -map.

1 PROPOSITION (Subgraph Collapse). Replacing a connected subgraph in a graph of groups decomposition with a vertex group with the same group as the collapsed graph corresponds to collapsing an invariant forest to points.

2 PROPOSITION (Folds “factor” as an elementary collapse and a collapse map). If  $X \rightarrow Y$  is a fold, then there exists a tree  $Z$  along with collapse maps to  $X$  and  $Y$ . Moreover, the map to  $X$  is a collapse map corresponding to an elementary collapse.

1.1 LEMMA (Hyperbolic elements are preserved). Suppose  $X \rightarrow Y$  is a collapse map between locally finite  $G$ -trees. Suppose  $Y$  is not a single point. Then, if an element is hyperbolic for  $X$  it is also hyperbolic for  $Y$ .

*Proof.* [warning] really we are using the fact that the image of this map contains more than two points. We could assume minimality and equivariance to get onto as well. Collapse maps are onto by construction. Suppose for sake of a contradiction that  $g \in G$  were hyperbolic for  $X$  and elliptic for  $Y$ . Let  $y \in Y$  be some vertex fixed by the elliptic element  $g$  and  $G_y$  it's stabilizer. Since  $Y$  is not a single point, there is another vertex  $y \neq z \in Y$ . Because  $Y$  is locally finite,  $G_y$  and  $G_z$  are commensurable. The pre-images of  $G$ -maps are invariant. By the construction of a collapse map, the preimage of vertices are connected. Putting these together we have that the preimages of vertices are invariant trees. This means that the minimal subtrees of  $G_y$  and  $G_z$  are contained in the disjoint preimages of  $y$  and  $z$  respectively. However, since they are commensurable and  $G_y$  contains the hyperbolic element  $g$ , these minimal trees are non-empty and equal. This is a contradiction.  $\square$

1.1 THEOREM (Elliptic elements determine elliptic subgroups). ?? For nice tree actions, elliptic elements are enough to determine elliptic subgroups.

1.2 THEOREM (Factoring as folds, from Bestvina paper, p455). Let  $G$  be a finitely generated group. Suppose that  $\alpha : T' \rightarrow T$  is a simplicial equivariant map from a  $G$ -tree  $T'$  to a minimal  $G$ -tree  $T$  such that no edge in  $T'$  is mapped to a point by  $\alpha$ . If all edge stabilizers of  $T$  are finitely generated and if  $T'/G$  is finite, then  $\alpha$  can be represented as a finite composition of folds.

1.3 THEOREM (Elliptic containment implies equality). If  $X$  and  $Y$  are  $G$ -trees of finite type with finitely generated vertex and edge stabilizers then  $\mathcal{E}(X) \subseteq \mathcal{E}(Y) \implies \mathcal{E}(X) = \mathcal{E}(Y)$ .

*Proof.* We first collapse our general  $G$ -map to a morphism. Then we use 1.2 to factor the result as a sequence of folds. Then we use 2 and finite generation to get that same elliptic elements give us same elliptic subgroups which gives us same deformation space which means the second collapse was an elementary one which means we keep local finiteness.  $\square$

## 1.2 Toy version of main result

1.4 THEOREM (F, "On uniqueness...", Thm 3.2). Let  $G$  be a group and let  $X$  and  $Y$  be cocompact  $G$ -trees. Then  $X$  and  $Y$  are related by an elementary deformation if and only if they have the same elliptic subgroups.

### 1.2.1 Definitions

3 DEFINITION (Finite Type). We say a tree action is of *finite type* if the action is non-trivial, the tree is locally finite, and the vertex stabilizers are FP, with finite quotient graph.

1.1 Remark. We will assume a group of dimension 2 and in that case Bieri gives that actions of finite type have vertex and edge stabilizers that are finitely generated free groups.

*1.2 Remark.* Bieri gives us that if we have an action of finite type then the group is FP.

**4 DEFINITION (Transverse).** We say that two tree actions  $X$  and  $Y$  are *transverse* if they are not in the same deformation space and there exist two stabilizers, one for each tree, such that their intersection is FP.

*1.3 Remark.* The definition of transverse does not depend on the vertices chosen and remains unchanged up to deformation spaces

### 1.2.2 Result

**3 PROPOSITION.** Let  $G$  a group of cohomological dimension 2. If  $X$  and  $Y$  are  $G$ -trees of finite type that are in different deformation spaces then the following are equivalent:

1.  $X, Y$  transverse
2.  $x \in V(X), y \in V(Y) \implies G_x \cap G_y = \{1\}$
3. There exists a cocompact VH-complex  $K$  with  $\pi_1(K) = G$  whose horizontal and vertical splittings are  $X$  and  $Y$ .

*Proof.* 1.  $1 \Rightarrow 2$ : Fix  $x_0 \in V(X)$  Let  $y \in V(Y)$ . Then  $G_{x_0} \cap G_y = (G_{x_0})_y$ . By (1)  $X$  is transverse to  $Y$  hence  $G_{x_0} \cap G_y$  is FP. Since the choice of  $y \in V(Y)$  was arbitrary, the vertex groups of the  $G_{x_0}$  action on  $Y$  are FP. Note,  $Y$  locally finite implies it's edge groups are finite index subgroups of it's vertex groups. Hence the edge groups are also FP. We claim that the action of  $G_{x_0}$  on  $Y$  is non-trivial. Given this we apply Bieri to get:

$$\begin{aligned} 2 &= dG \\ &= dG_{x_0} + 1 \\ &= d(G_{x_0})_y + 1 + 1 \\ &= d(G_{x_0} \cap G_y) + 2 \end{aligned}$$

Hence,  $d(G_{x_0} \cap G_y) = 0$  so  $G_{x_0} \cap G_y$  is trivial.

**CLAIM.** The action of  $G_{x_0}$  on  $Y$  is non-trivial.

*Proof.* Suppose the action were trivial. That is, there exists some  $y \in V(Y)$  such that  $(G_{x_0})_y = G_{x_0}$ . Hence,  $G_{x_0}$  is elliptic for the action of  $G$  on  $Y$ . By the local finiteness of  $Y$ , for all  $x \in V(X)$   $G_x$  acts elliptically on  $Y$ . Hence,  $\mathcal{E}(X) \subset \mathcal{E}(Y)$ . Again by local finiteness we can promote this using 1.1 to  $\mathcal{E}(X) = \mathcal{E}(Y)$  which by theorem 1.4 gives  $X \sim Y$  which contradicts the fact that  $X$  and  $Y$  were assumed to be in different deformation spaces.  $\square$

2.  $2 \Rightarrow 1$ : Trivial groups are FP.

3.  $2 \Rightarrow 3$ : Take  $X \times Y$  and give it the VH-structure where  $X$  and  $Y$  correspond to horizontal and vertical edges respectively. Condition (2) says that  $G$  acts freely on  $X \times Y$ . Guirardel gives us a simply-connected co-compact core [\[fix\]](#) [Needs prop 4.14](#)  $G \subset X \times Y$ . The action is also free on subsets of  $X \times Y$ . Since the action is cellular and free it's a covering space action. (We avoid situations like irrational rotations on a circle that are free but not covering space actions)

It remains to show that  $C/G$  is VH. Is it enough to say that the action respects the tree factors. (The edge partition on the cover descends to a well-defined edge partition on the quotient and attaching maps constructed in the standard way for the quotient alternate between vertical and horizontal edges)

4.  $3 \Rightarrow 2$ : Suppose  $1 \neq g \in G$  is an element of  $G_x \cap G_y$  where  $x \in V(X)$  and  $y \in V(Y)$ . Since  $K$  is a VH-complex it has a decomposition as a graph of groups where the vertex spaces are connected subgraphs whose edges are all vertical. Each  $x \in V(X)$  is in correspondence with the inclusion of a vertex space (composed entirely of vertical edges) into  $K$ . The inclusion of vertex spaces is always injective on fundamental groups. Lastly, after picking basepoints the image of the induced map is the stabilizer of  $x$ .

By Wise, we have that the universal cover of  $K$  is contained in  $X \times Y$ . Because the action respects the product structure, and because vertex spaces (in our case, graphs) are covered by embedded copies of their own universal covers we have that the non-trivial element  $g$  when represented by a loop in a vertex space lifts to a path with distinct endpoints in a tree consisting entirely of vertical edges in  $X \times Y$ . In fact,  $G_x$  acts on  $\{x\} \times Y$  and freely on  $\tilde{K} \cap (\{x\} \times Y)$  because the action on  $\tilde{K}$  is a covering space action. This means that  $g$  acts hyperbolically on  $Y$  and we get an axis in  $Y$ . This remains an axis in  $X \times Y$ .

Thus from looking at the vertical splitting (where vertex spaces were made of vertical edges) we obtained an axis consisting entirely of vertical edges. Similarly, after looking at the horizontal splitting we obtain an axis consisting entirely of horizontal edges.

Finally, since  $X \times Y$  is CAT(0) these axes would have to be parallel. This is a contradiction.

□

## 2 Problem Statement

We want to show the following statement or similar: if a group is the fundamental group of a VH-complex, then there are at most two pairwise inequivalent actions on locally finite trees with FP vertex stabilizers. The following proof sketch uses or builds on VH-complexes introduced by Wise, Guirardel's core,

and a theorem of Bieri. To start we have that  $G = \pi_1(K)$  where  $K$  is a VH-complex; according to Wise this comes with a vertical and horizontal splitting. For sake of a contradiction suppose there was a third tree as above. A generalization of Guirardel's core to three actions would imply that our  $G$  was the fundamental group of a VHD-complex (here "D" is for "depth") which would further imply, among other things, that our group splits along groups of cohomological dimension two. (This is analogous to Wise's work on VH-complexes) However, a theorem of Bieri and local finiteness forces the cohomological dimension of the resulting group to be dimension three which contradicts our original VH assumption so there are at most two such actions.

## 2.1 Dramatis Personæ

- $X$  a compact connected VH-complex
- $G = \pi_1(X)$
- $T_1$  the tree from the horizontal splitting of  $X$
- $T_2$  the tree from the vertical splitting of  $X$
- $T_3$  an interloping locally finite  $G$ -tree with FP vertex stabilizers
- $\mathcal{T} = T_1 \times T_2 \times T_3$
- $X^+$  a certain complex containing  $X$
- $f : X^+ \rightarrow \mathcal{T}$  an equivariant map
- $\Gamma$  a certain compact connected subgraph of  $X^{(1)}$  the 1-skeleton of  $X$
- $J = \text{Im}(f)$
- $K = \text{cell}(J)$
- $C = \text{fill}(K)$  the hero of our story, the simply-connected core on which  $G$  acts

## 2.2 Definitions

5 DEFINITION (Split Maps). Given a graph of spaces we obtain an invariant map as follows ...

6 DEFINITION (Setup). We say that  $K = (T, x_0, \sigma = \sigma_1 \cdots \sigma_N, \lambda)$  satisfies property *setup* if:

1.  $T$  is a simplicial tree
2. We have that  $x_0$  is a valence one vertex
3.  $\sigma$  is a concatenation of non-degenerate edgepaths

$$4. \sigma(t) = x_0 \implies t \in \{0, 1\}$$

$$5. \lambda(1) \neq \lambda(N)$$

7 DEFINITION (Bad). Given  $K = (T, x_0, \sigma = \sigma_1 \cdots \sigma_N, \lambda)$  we say that an edge is *bad* if:

1. The edge  $e$  separates the basepoint from some endpoint. i.e.

$$e^+ \cap \text{endpoints} \neq \emptyset$$

where  $e^+$  is the halfspace of  $e$  not containing  $x_0$ .

2. The edge  $e$  always has the same color. i.e.  $|\{\lambda(k) \mid e \subseteq \text{Im}\sigma_k\}| = 1$ .

8 DEFINITION (bad edge snipping). Let  $K$  satisfy property setup with  $e$  a bad edge. Let  $\sigma_i$  and  $\sigma_j$  be the first and second subpaths of  $\sigma$  that use  $e$ . Take  $\sigma'$  to be the concatenation of  $\sigma_k$  for  $k < i$  with the subpath denoted  $\sigma'_{ij}$ , that is the concatenation of the largest initial subpath of  $\sigma_i$  not using  $e$  and the longest tail of  $\sigma_j$  not using  $e$  with  $\sigma_k$  for  $k > j$ . The unmodified subpaths of  $\sigma$  in  $\sigma'$  receive the same colors as before and we take  $\sigma'_{ij}$  to have the color that  $\sigma_i$  and  $\sigma_j$  shared.

### 2.2.1 Miscellaneous

2.1 LEMMA (Geometric Condition). (Theorem 0.6 in LP97) A minimal simplicial action of a finitely generated group is geometric if and only if all edge groups are finitely generated.

9 DEFINITION (Fiberwise Connected). Let  $S \subseteq X \times Y \times Z$ . If  $S \cap \{\text{pt}_1\} \times \{\text{pt}_2\} \times Z$  and all similar sets as well as permutations are connected then we say  $S$  is one dimensional fiberwise connected.

2.2 LEMMA (Extension). (Lemma 8.9 in Guirardel) Consider a geometric action of a finitely generated group  $G$  on an  $\mathbb{R}$ -tree  $T$ , and let  $X$  be a 2-complex endowed with a free properly discontinuous cocompact action of  $G$ . Let  $\mathcal{F}$  be a  $G$ -invariant measured foliation on  $X$ . Consider a map  $f : X \rightarrow T$  which is constant on leaves of  $\mathcal{F}$ , and isometric in restriction to transverse edges of  $X$ . Then there exists a 2-complex  $X'$  containing  $X$ , endowed with a free properly discontinuous cocompact action of  $G$ , a measured foliation  $\mathcal{F}'$  extending  $\mathcal{F}$ , and which induces an isometry between  $X'/\mathcal{F}'$  and  $T$ . Moreover, the inclusion  $X \subseteq X'$  induces an epimorphism of fundamental groups.

2.3 LEMMA (Affine Equivariant Map). Suppose that  $G$  acts freely on a simplicial complex  $K$  and acts on a simplicial tree  $T$ . Then there exists an equivariant map  $f : K \rightarrow T$  where  $\mathcal{F}$  the connected components of the fibration from  $f$  is a measured foliation and  $f$  is an isometry on edges transverse to  $\mathcal{F}$ .

*Proof.* Part 1: Construct an equivariant map.

We start by defining  $f$  on  $K^{(0)}$  the 1-skeleton. By equivariance it is enough to define the map on a single vertex in each vertex orbit. These choices can be arbitrary. Next we check that the resulting map is well-defined. Indeed, if  $gv = hv$  then  $g^{-1}h = 1$  by freeness and so

$$f(v) = g^{-1}hf(v) = g^{-1}f(hv)$$

but then

$$f(gv) = gf(v) = f(hv).$$

Next we define the map on edges. If  $vw$  is an edge, map it to the geodesic  $[f(v), g(w)]$ .

Lastly, for 2-cells we use the standard fibration from mapping triangles to tripods.

Part 2: Fibration details. □

2.4 LEMMA (Guirardel Lemma 5.4, Corollary 5.5). Let  $T_1, T_2$  be two  $\mathbb{R}$ -trees and let  $F$  be a nonempty connected subset of  $T_1 \times T_2$  with convex fibers. Then the complement of  $\overline{F}$  is a union of quadrants. That is,  $\overline{F}$  is also nonempty, connected, and has convex fibers.

CLAIM. If  $K$  satisfies property setup then the first and last edge of  $\sigma$  are equal.

10 DEFINITION (Filling). Let  $\{X_k\}_{k \in K}$  be a family of spaces where one can take convex hulls. Given  $S \subseteq X := \coprod X_k$  define  $S_k$  for  $k \in K$  via:

$$p \in S_k \iff \exists q, r \in S : \forall j \neq k : p_j = q_j = r_j \text{ and } p_k \in \text{cvxhull}_k(\{q_k, r_k\}).$$

11 DEFINITION (Type  $FP$ ). A group is of type  $FP$  if it is (1) type  $FP_n$  for all  $n$  and (2) finite geometric cohomological dimension.

12 DEFINITION (Finite Type). An action of *finite type* is one on a locally finite tree where vertex stabilizers are of type  $FP$ .

13 DEFINITION (Open Direction). An open direction is a connected component of an  $\mathbb{R}$ -tree minus a point.

14 DEFINITION (Closed Direction). A closed direction is a connected component of an  $\mathbb{R}$ -tree minus a point, union that point.

15 DEFINITION (Open Halfspace). An open halfspace is an open direction obtained from deleting the midpoint of an edge.

16 DEFINITION (Closed Halfspace). A closed halfspace is a closed direction obtained from deleting the midpoint of an edge.

17 DEFINITION (Halfspaces of a product). An open (resp. closed) halfspace of a product (at a certain index) is a subset where exactly one projection is an open (resp. closed) halfspace in its factor and the others are onto.

18 DEFINITION (Generalized quadrants). A generalized open (resp. closed) quadrant with respect to a product of  $k$  spaces is an intersection of  $k$  open (resp. closed) product halfspaces where each one is at a different index.

19 DEFINITION (cellular-product-convex). We say that  $K \subset X$  is cellular-product-convex if its complement is the open cellular neighborhood of a union of generalized closed quadrants.

### 3 Outlines

Our goal is to show that when we have three different actions there exists a well chosen cube complex that  $G$  acts on which has a quotient that is a graph of spaces decomposition for  $G$ . Using properties of this splitting we will conclude that our group has dimension at least three which is impossible because we assumed it was VH.

In terms of properties of the core we need three things: (1) hyperplanes are simply connected, (2) cocompact, (3) hierarchy of splittings. We will take the edge spaces of our graph of spaces to be a subset of the corridors of hyperplanes and the vertex spaces to be the components of the complement of the edge spaces.

Our main result is the following:

COROLLARY. Let  $G$  be the fundamental group of a compact VH-complex that doesn't satisfy *property A*. Let  $T_v$ , and  $T_h$  be the vertical and horizontal splittings. Considering *nice* actions up to deformation these are the only two such actions.

#### 3.1 Misc lemmas

20 DEFINITION (morphism). A map  $X \rightarrow Y$  between two trees is called a morphism if it sends vertices to vertices and edges to edges.

(Formally, there is something to say, however if you think of your edges as intervals of the real line then you might as well take the homeomorphisms to be linear maps. For our purposes, only combinatorial information is relevant. If the maps stretch or squish parts of edges we wouldn't care)

3.1 LEMMA (equivariant map from elliptic inclusion). If  $X$  and  $Y$  are  $G$ -trees such that  $\mathcal{E}(X) \subset \mathcal{E}(Y)$ , then there exists an equivariant map  $X \rightarrow Y$ .

*Proof.* Consider the vertex orbits in  $X$ . Pick a vertex from each orbit. Consider how the stabilizers of these vertices in  $X$  act on  $Y$ . Because of the elliptic subgroup containment, each  $G_{x_i}$  we picked out fixes a non-empty set of vertices in  $Y$ . Begin to define a map on the 0-skeleton by sending  $x_i$  to something in  $Y$  fixed by  $G_{x_i}$ . There are several choices, but a fixed set of choices plus the invariant condition defines a map on the 0-skeleton.

The containment says such a map is well-defined. Indeed, pick  $x \in X^{(0)}$ . Suppose  $x = gx_0 = hx_0$ , then  $(h^{-1}g)x_0 = x_0$  and so  $h^{-1}g \in G_{x_0}$ . Then



$f(x_0) = f((h^{-1}g)x_0)$  which gives  $hf(x_0) = f(gx_0)$  and so  $f(hx_0) = f(gx_0)$  as needed.

Once we have a map on the 0-skeleton we can extend it to the entire tree by drawing unique geodesics in the trees.  $\square$

**3.2 LEMMA** (Invariant to bounded distance). Let  $A$  and  $B$  be invariant subcomplexes of  $X$  with  $G$  acting cocompactly on both  $A$  and  $B$  after restricting the action on  $X$ . Then  $A$  and  $B$  are Hausdorff equivalent.

*Proof.* Because we are dealing with cocompact actions on cell complexes for the action on  $A$  there exists a finite subcomplex  $F \subseteq A$  such that the orbit of  $F$  covers  $A$ . We call  $F$  a fundamental domain. Let  $D_1$  be the diameter of  $F$ . Pick some  $b_0 \in B$  and let  $D_2$  be the distance from  $F$  to  $b_0$ . Pick an arbitrary  $a \in A$ . Because the orbit of  $F$  is  $A$  there exists some  $g \in G$  such that  $a \in gF$ . Then  $a$  is within  $D_1 + D_2$  of  $gy$ . Hence,  $A$  is contained in the  $D_1 + D_2$  neighborhood of  $B$ . Switching  $A$  and  $B$  in this argument and taking the maximum of the distances shows that  $A$  and  $B$  are both contained in  $R$  neighborhoods of each other for some  $R$ ; that is they are Hausdorff equivalent.  $\square$

### 3.2 Main Equivariant Map Construction

Let  $X$  be a compact VH-complex and set  $G = \pi_1 X$ . Form the cover  $\tilde{X} \rightarrow X$ . Note that  $G$  acts on  $\tilde{X}$  freely and PDC. Since  $X$  is a VH-complex we get two actions of  $G$  on trees  $T_1$  and  $T_2$  along with invariant 5 maps  $f_1$  and  $f_2$  from the splitting. Suppose we had a third action of  $G$  on a tree  $T_3$  with property *nice*. Given the covering space action and the action on  $T_3$  we use the affine construction 2.3 to get an equivariant map  $f_3 : \tilde{X} \rightarrow T_3$ . Using Guirardel 8.9 2.2 we extend  $f_3$  to  $\hat{f}_3$  a map with connected fibers. We also need the proof of lemma 2.2 to ensure certain properties hold. Then, in order to extend the  $f_1$  and  $f_2$  maps we use the coning off construction. The product of these extensions gives  $f$ .

### 3.3 Simply connected hyperplanes

To be a valid decomposition we need that the edge spaces are injective on fundamental groups. For this we need the corollary below.

**COROLLARY.** The hyperplanes of  $C$  are simply connected.

Which will follow from:

**3.1 THEOREM.** The hyperplanes of  $C$  are quadrant convex.

One way to prove the theorem is to first show that  $C$  is one dimensional fiberwise connected 9 and then apply Guirardel's lemma 2.4 in each hyperplane to conclude that they're quadrant convex as needed.

**3.2 THEOREM** (Connected fibers). The one dimensional fibers of  $C$  are connected.

To achieve this, we'll build  $C$  from a suitable  $G$ -invariant subcomplex  $K \subseteq \mathcal{T}$  by taking  $C = ((K_x)_y)_z$ . Here  $K$  is the cellular hull of  $J$ , the image of  $f$ .

### 3.4 Cocompactness of the Core

The second requirement that  $C$  be cocompact will follow from an argument that starts by bounding the size of fibers.

3.3 LEMMA (Finite fibers). ...need to latex...

3.4 LEMMA (Universal bound on fibers). ...need to latex...

### 3.5 Required splitting properties

Note first we establish that  $C$  is itself simply connected.

3.5 LEMMA. The core  $C$  is simply connected.

Finally, having enough dimension will follow from some assumptions about our actions. With this splitting in hand we want to verify that it's made of successive graphs of groups of items of a certain dimension so we can apply Bieri.

3.6 LEMMA (Directional splittings are non-trivial).

3.3 THEOREM (Not All Trees).

3.7 LEMMA. The action of  $G$  on  $T_1 \times T_2$  is free.

*Proof.* ...look in section II.6 of BH... Need enough facts to avoid non-proper spaces, get a semisimple action, and axes.  $\square$

### 3.6 Combining into main argument

3.8 LEMMA (Filling preserves cocompactness). Since  $S_{23}$  is a cocompact  $G$ -invariant subcomplex that's contained in  $A \times B$  where  $A$  and  $B$  are subcomplexes of  $T_1$  and  $T_2 \times T_3$  respectively and  $B$  is itself cocompact and  $G$  acts freely on  $T_2 \times T_3$  we have that  $(S_{23})_x$  is cocompact as well.

*Proof.* For each vertex orbit of  $B$  choose a particular vertex. By cocompactness this list is finite; call them  $\{b_1, \dots, b_n\}$ . By freeness in the second factor, the stabilizer of  $S' := S_{23} \cap (T_1 \times \{b_1\})$  is trivial. This means that  $S'$  injects into  $S_{23}/G$  which is compact by assumption. Since we are dealing with cell complexes,  $S'$  is also compact. Repeating this argument a finite number of times we have that  $S_{23} \cap (T_1 \times \{b_k\})$  is compact for each  $1 \leq k \leq n$ . Compact items have a well defined diameter. Taking the maximum diameter (in the product metric) and noting we're acting by isometries gives that there is a bound  $D$  on the diameters of  $S_{23} \cap (T_1 \times \{v\})$  as  $v$  ranges over vertices of  $B$ .

Let  $a \times b$  be a vertex of  $(S_{23})_x$ . By construction,  $a$  lies within the convex hull of the projection of  $S_{23} \cap (T_1 \times \{b\})$  (a slice of  $S_{23}$ ) to the  $T_1$  factor, hence

slices of  $(S_{23})_x$  have diameter no greater than  $D$  in the product metric. This means each slice of  $(S_{23})_x$  has a finite number of vertices. It remains to show that there is a universal bound on the number of vertices as we range over all slices. Since  $S_{23}$  is  $G$ -invariant and we're acting by a product, (so the slice at  $gb$  is the slice at  $b$  acted on by  $g$ ) there are a finite number of isometry classes of slices since  $B$  is cocompact. Hence, there are a finite number of vertex orbits so  $(S_{23})_x$  is cocompact as needed.  $\square$

## 4 Core has quadrant convex hyperplanes

4.1 LEMMA (Connected Fibers). Let  $p$  in  $X$  our 2-complex, let  $p'$  be the unique projection. Let  $\Gamma$  be a compact subgraph in our 2-complex  $X$ . Take  $T$  to be either  $T_1$  or  $T_2$ . For now suppose we have defined a map  $f : \Gamma \rightarrow T$ . We will define a map  $F : \Gamma \times I \rightarrow T$ . Choose an arbitrary  $t_0 \in f(\Gamma)$  and define:

$$F(x, s) = \begin{cases} f(x) & s = 0 \\ t_0 & s = 1 \\ \gamma_{f(x), t_0}(s|\gamma|)a & \text{else} \end{cases}$$

Let  $k_0 \in \Gamma \cap F^{-1}(F(x, s))$  be the nearest point to  $p'$ . Put  $\gamma_{p', k_0}$ . Then define  $g : \text{Im}(\gamma_{p', k_0}) \rightarrow I$  by  $g(t) = \frac{a(t)}{a(t)+b}$  where  $a(t) = d(f(t), F(x, s))$  and  $b = d(F(x, s), t_0)$ . Then we compute  $F(t, g(t)) = F(x, s)$  so  $\text{Graph}(g) \subseteq F^{-1}(x, s)$ . Now,  $g$  is continuous so  $\text{Graph}(g)$  is connected. Hence,  $(x, s)$  is connected to  $(k_0, 0)$  in  $F^{-1}(F(x, s))$  as needed.

4.2 LEMMA (Fibers homeomorphic to Coordinate planes). Put  $f = \hat{f}_1 \times \hat{f}_2 \times \hat{f}_3 : X^+ \rightarrow T_1 \times T_2 \times T_3$  and  $J = \text{Im}(f)$ . We claim that  $J \cap T_1 \times T_2 \times \{z\} = \text{Im}_f(\hat{f}_3^{-1}(z))$ . Let  $p = (p_1, p_2, p_3) \in T_1 \times T_2 \times T_3$  then we have the following.

$$\begin{aligned} p \in \text{LHS} &\iff p \in \text{Im}(f) \wedge p_3 = z \\ &\iff \exists x \in X^+ (f(x) = p \wedge \hat{f}_3(x) = z) \\ &\iff \exists x \in X^+ (f(x) = p \wedge x \in \hat{f}_3^{-1}(z)) \\ &\iff p \in \text{Im}_f(\hat{f}_3^{-1}(z)) \end{aligned}$$

### 4.1 Wrap up lemmas

The following is a list of statements, the goal is to prove enough of them to arrive at item number 1 for a suitably chosen core  $C$ .

1.  $C \subseteq \mathcal{T}$  has simply connected hyperplanes
2.  $C$  has hyperplanes that are (1) connected (2) quadrant convex
3. The hyperplanes and one dimensional fibers of  $C$  are connected
4. If  $S \subseteq \mathcal{T}$  connected in all coordinate planes, then so are  $S_x, S_y$ , and  $S_z$ .

5. If  $R \subseteq T_1 \times T_2$  has convex fibers then  $(R_x)_y = (R_y)_x$ .
6. If  $S \subseteq \mathcal{T}$  is connected in all coordinate planes then  $((K_x)_y)_z$  is one dimensional fiberwise convex.
7. If  $S \subseteq \mathcal{T}$  and is connected in all coordinate planes then  $(S_x)_y = (S_y)_x$ .
8. Guirardel's Lemma

#### 4.1.1 Using Wrap-up lemmas to prove main statement

The implications are as follows:

$$(4), (7) \Rightarrow (6) \Rightarrow (3) \Rightarrow (2) \Rightarrow (1) \quad (1)$$

$$(8) \Rightarrow (4) \quad (2)$$

$$(5) \Rightarrow (7) \quad (3)$$

4.3 LEMMA (Reduction to vertical subpath). Let  $S$  be a subset of  $T_1 \times T_2$  and let  $p, q, r \in S$  satisfy:

1.  $r \notin S$
2.  $p, q \in S$
3.  $p_2 = q_2 = r_2$
4.  $r_1 \in \text{cvxhull}_{T_1}(\{p_1, q_1\})$

Let  $\sigma : [0, 1] \rightarrow S$  be a path from  $p$  to  $q$ , then there exists a path  $\sigma'$  such that taking  $p, q := \sigma'(0), \sigma'(1)$  satisfies properties (2)-(4) and  $\pi_2(\text{Im}(\sigma' |_{(0,1)}))$  is contained in an open direction of  $T_2$  at  $r_2$ .

*Proof.* Consider the inverse image of  $T_1 \times \{r_2\}$  under  $\sigma$ . After subdividing  $[0, 1]$  and noting that we're taking edge paths we get that this set is a finite union of closed intervals in  $[0, 1]$ . We also have that it contains 0 and 1. Because  $r_1$  is separating in  $T_1$  we have that each closed interval lies within an open direction in  $T_1$  at  $r_1$ . Also, because  $r_1$  lies in the convex hull of  $p_1$  and  $q_1$  we get that the number of intervals is at least 2. Consider pairs of endpoints of the closed intervals making up the closure of the complement of the inverse image. If each pair is in the same direction in  $T_1$  at  $r_1$  then because closed intervals map to horizontal directions we would have that 0 and 1 were in the same direction which contradicts our assumptions; hence there exists a subpath  $\sigma'$  where only the endpoints map into  $T_1 \times \{r_2\}$ . Consider  $\sigma' |_{(0,1)}$ , its image lies in a product of a finite subtree of  $T_1$  and a disjoint union of directions of  $T_2$  at  $r_2$ . Because  $\sigma'$  is continuous it must lie in a single connected component and so projects to a single vertex direction of  $T_2$  at  $r_2$ .  $\square$

4.4 LEMMA (Statement 4). Let  $S \subseteq \mathcal{T}$  be a subcomplex that is connected in all coordinate planes. Then  $S_x, S_y$ , and  $S_z$  are as well.

*Proof.* Without loss of generality, consider  $S_x$ , note that  $S_x$  will be connected in all  $xy$  and  $xz$  planes because  $S$  was. Consider the  $yz$ -planes in  $S_x$ , if there were no new points added then the planes are connected and we are done. Suppose that  $p \in (S_x \setminus S) \cap \pi_1^{-1}(p_1)$ , we will show that there is a path in  $S_x \cap \pi_2^{-1}(p_2)$  between  $p$  and some point in  $S$ .

Since  $p$  isn't in  $S$  there exist distinct points  $r$  and  $s$  in  $S$  that agree in all coordinates except the first where we have that  $p_1 \in \text{cvxhull}_{T_1}(\{r_1, s_1\})$ . Now, because  $S$  is connected in all coordinate planes there is a path  $\sigma$  from  $r$  to  $s$  that lies in  $S \cap \pi_2^{-1}(p_2)$ . In fact, we can take  $\sigma$  to be a path that begins and ends at  $p$  and  $r$  but otherwise has  $T_3$  coordinates lying in exactly one direction of  $T_3$  at  $p_3$ . We have factored out this situation into claim 4.3.

Take  $\sigma$  as in the claim 4.3. It remains to show that there is a path connecting  $p$  to another point in  $S$ . Considering closed quadrants, there exists a sequence  $t_1, \dots, t_n$  such that  $v_i := \sigma(t_i)$  are vertices in  $p_1 \times p_2 \times \bar{\delta}$  (here  $\delta$  is the distinguished  $T_3$  direction) with the property that  $\sigma(t_1) = p$ ,  $\sigma(t_n) = q$ , and  $\sigma_i := \sigma|_{[t_i, t_{i+1}]}$  lie in quadrant  $i$  for  $0 < i < n$ . (Here, quadrant  $i$  is determined by specifying a direction in  $T_1$  at  $p_1$  since we've already chosen  $\delta$  above.) Projecting, we obtain a sequence of subpaths in  $\bar{\delta}$  a direction in  $T_3$  that are colored based on their quadrant. Note that  $\bar{\delta}$  has a valence one vertex at  $p_3$  because our tree is simplicial and subpaths don't end at  $p_3$  unless it's the first or last because the claim has that the interior of the path maps into  $\delta$ . This situation satisfies the conditions for our coloring lemma 4.7.

Multicolored paths in this vertical direction  $\delta$  give paths contained in  $S_x$ , applying the coloring lemma 4.7 gives the required multicolored path. This completes the proof.  $\square$

4.5 LEMMA (Statement 5). If  $R \subseteq T_1 \times T_2$  is a connected subcomplex then  $(R_x)_y = (R_y)_x$ .

*Proof.* We will first show that  $(R_x)_y$  has connected fibers. Note, it already has connected  $y$ -fibers, so it remains to show that it has connected  $x$ -fibers. Suppose that  $(R_x)_y \cap (T_1 \times \{y_0\})$  were a disconnected  $x$ -fiber. Then because  $(R_x)_y$  is a subcomplex we have that the fiber is separated by some edge. Let  $x_0$  be the midpoint of this edge. Let  $\ell$  and  $r$  denote the left and right closed halfspaces of  $T_1 \times \{y_0\}$  at the midpoint  $x_0$ . We will show that either  $\ell \cap (R_x)_y = \emptyset$  or  $r \cap (R_x)_y = \emptyset$ , applying this to all such  $x_0$  will show  $(R_x)_y$  has connected  $x$ -fibers.

Suppose this were false, and that  $\ell \cap (R_x)_y \neq \emptyset$  and  $r \cap (R_x)_y \neq \emptyset$ . We consider three cases: (1)  $\ell$  and  $r$  intersect  $R_x$  nontrivially (2)  $\ell$  and  $r$  don't intersect  $R_x$ , and (3) exactly one of  $\ell$  or  $r$  intersects  $R_x$  nontrivially.

1. Case 1: If both  $\ell$  and  $r$  intersect  $R_x$  then both contain points of  $R$  because we filled in the  $x$ -fiber, but then  $x_0 \times y_0 \in R_x$  a contradiction.
2. Case 2: Pick a point  $x^+$  in  $r \cap (R_x)_y \setminus R_x$ . Let  $q^+$  and  $q^-$  be points above and below  $x^+$  in  $R_x$ . These points are either in  $R$  already, or because we

filled in the  $x$ -fiber there exist points above and below the line  $\ell \cup r$  but this is a contradiction since  $R$  is connected.

3. Case 3: Without loss of generality, suppose  $\ell \cap R_x = \emptyset$  and  $r \cap R_x \neq \emptyset$ . This implies there is some  $s \in R \cap r$ , we will get a contradiction by separating this point from another point in  $R$ .

Let  $u$  and  $d$  be directions of  $x_0 \times T_2$  at  $x_0 \times y_0$ . If both intersected  $R_x$  then  $x_0 \times y_0 \in R$  a contradiction so without loss of generality, suppose  $d \cap R_x \neq \emptyset$ . Now let  $x^-$  be a point in  $\ell$ , by assumption  $x^- \in (R_x)_y \setminus R_x$ . This gives a point  $q^-$  below  $\ell$  in  $R_x$  which is already in  $R$  or there exists a point  $t^- \in R$  to the left of  $q^-$ ; but this is a contradiction since  $\ell \cup d$  separates these points from  $s \in R$ .

Hence, either  $\ell \cap (R_x)_y = \emptyset$  or  $r \cap (R_x)_y = \emptyset$  as needed, so  $(R_x)_y$  has connected  $x$ -fibers. Similarly,  $(R_y)_x$  also has connected fibers. Hence by 2.4 their complements are unions of quadrants and so they contain  $QH(R)$ . It remains to show that they are contained within  $QH(R)$ .

CLAIM.  $(R_x)_y \subseteq QH(R)$

*Proof.* (sketch) The idea is to show that for every point  $p \in (R_x)_y$  that for every quadrant  $Q$  containing  $p$  (i.e. that would be attempting to remove it) we can find a point  $r \in R \cap Q$ . Picking an open quadrant containing  $p$  amounts to picking a point  $q = (q_1, q_2)$  with halfspaces at each coordinate that contain the corresponding  $p_i$ . The hard case is where  $p \in (R_x)_y \setminus R_x$  - so you pick a point in a vertical direction at  $p$  pointing towards  $p$ , because this point is only there due to filling there's another vertical direction that you're grabbing that contains some  $R_x$ . Then you pick a horizontal place and point towards  $p_1$ , this must contain at least one of the directions with  $R$  in it.  $\square$

*Proof.* We will show for every point  $p \in (R_x)_y$  and every open quadrant  $Q$  with  $p \in Q$  that there exists some  $r \in R \cap Q$ . Let  $q = (q_1, q_2)$  be the point where  $Q$  is based and label the halfspaces so that  $Q = q_1^+ \times q_2^+$ .

Case 1  $p \in R_x \setminus R$ : Let  $p \in R_x \setminus R$ : Let  $\ell = (\ell_1, p_2)$  and  $u = (u_1, p_2)$  be points in  $R$  that cause the vertical filling. Now,  $q_1^+$  contains all but one direction at  $p_1$  and so must contain either  $\ell_1$  or  $u_1$ . Since  $q_2^+$  must contain  $p_2$  we get that  $Q = q_1^+ \times q_2^+$  contains a point of  $R$ .

Case 2  $p \in (R_x)_y \setminus R_x$ : Let  $u = (p_1, u_2)$  and  $d = (p_1, d_2)$  be points that cause the vertical filling. Now,  $q_2^+$  contains all but one direction at  $p_2$  and so must contain either  $u_2$  or  $d_2$ . Without loss of generality, suppose it contains  $u_2$ . If  $u \in R$  then we are done. Suppose  $u \in R_x \setminus R$ . Then we can find  $u' = (p', u_2)$  and  $u'' = (p'', u_2)$  with  $p'$  and  $p''$  in different directions at  $p_1$ . Now,  $q_1^+$  contains all but one direction at  $p_1$  and so must contain either  $p'$  or  $p''$ . Suppose without loss of generality that it contains  $p'$ , then  $Q$  contains  $p' \times u_2 \in R$ .  $\square$

$\square$

4.6 LEMMA (Boxed Implication). Repeatedly applying statement 7 to both  $S$  and  $S_\alpha$  where  $\alpha$  is one of  $x, y$ , or  $z$  and noticing that  $\langle (12), (23) \rangle = S_3$  we get that  $((K_x)_y)_z$  is equal to any of the permutations of the indices. In particular,  $((K_x)_y)_z = ((K_y)_z)_x = ((K_z)_x)_y$  which shows that  $((K_x)_y)_z$  has connected one dimensional fibers.

## 4.2 Planar Path Argument

4.7 LEMMA (Coloring Lemma). Let  $K$  satisfy property setup. Let  $A$  be the set of endpoints minus the basepoint  $x_0$ . Then there exists some  $a \in A$  such that for all edges  $e$  in the geodesic  $[x_0, a]$  there exist some  $i, j$  such that  $\sigma_i$  and  $\sigma_j$  use  $e$  and  $\lambda(i) \neq \lambda(j)$ .

*Proof.* Suppose the lemma were false. Then there exist counterexamples  $K$  satisfying property setup such that for all  $a \in A$  there exists an edge  $e$  on  $[x_0, a]$  such that  $\lambda(i) = \lambda(j)$  whenever  $\sigma_i$  and  $\sigma_j$  use  $e$ . These  $K$  have bad edges and  $|\sigma| > 0$ . Now take a  $K$  such that  $|\sigma|$  is minimized. Let  $K'$  be the result of snipping a bad edge. By lemma 4.8,  $K'$  has property setup so  $|\sigma'| > 0$ . If  $K'$  contained a multicolored path between  $x_0$  and some  $a'$  in  $A'$  then because the path  $\sigma$  in  $K$  can be obtained by inserting subpaths into  $\sigma'$ , we have that  $A' \subseteq A$  and any edge that was multicolored stays multicolored. Therefore  $K'$  has no multicolored path, because that would force  $K$  to have one. Then the fact  $|\sigma'| < |\sigma|$  gives a contradiction because  $K$  was chosen to be minimal.  $\square$

4.8 LEMMA (Snip invariant). If  $K$  satisfies property setup then  $K'$  obtained from snipping a bad edge also satisfies property setup.

*Proof.* Let  $e$  be a bad edge of  $K$ , since  $\sigma_1$  and  $\sigma_N$  have different colors the edge  $e$  is in at most one of them. Because  $x_0$  has valence one,  $\sigma_1$  and  $\sigma_N$  share the edge containing  $x_0$ ; therefore  $e$  cannot be the common edge. The rest follows.  $\square$