

Unsupervised Learning

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“If all you do is follow the herd, you’ll just be stepping in poop all day - Wayne Dyer”

Unsupervised Learning

Often times, we have N (possibly noisy) observations $\mathcal{X} = \{x^{(i)}\}_{i=1}^N$. The desired output corresponding to each pattern is not known - perhaps it is expensive to obtain them, perhaps we do not know the desired outputs i.e. the patterns are unlabeled. Is it possible to induce anything from such data?

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- We can partition the patterns into cohesive groups (clustering). Patterns in the same group are *similar* to each other and *dis-similar* from the patterns in other groups
 - ▶ (Dis-)Similarity implies there is a way of measuring the distance between $x^{(i)}$ and $x^{(j)}$

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- In Euclidean space for example,

$$\|x^{(i)} - x^{(j)}\| = \sqrt{[x^{(i)} - x^{(j)}]^T [x^{(i)} - x^{(j)}]}$$

$$\cos(\psi) = \frac{x^{(i)T} x^{(j)}}{\|x^{(i)}\| \|x^{(j)}\|}$$

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- In the case of text documents, one can convert the document into a vector. For example, a vector of length equal to the size of the vocabulary. Each position corresponds to a word, and is 1 if the word appears in the document. One can then use one of the above distance measures amongst the document vectors.

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 - ▶ This is rather coarse and treats each word as important as another (see for example, TF-IDF that gives a better idea of the importance of a word). There are many other approaches

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- 4 Go to Step 2 until $\mu^{(i)}$'s stop changing i.e. cluster assignment do not change

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- 4 Recompute the cluster centers. $\mu^{(1)} = 1/2(x^{(1)} + x^{(2)}) = [1.5 \ 1.5]^T$
and $\mu^{(2)} = 1/2(x^{(3)} + x^{(4)}) = [4.5 \ 4.5]^T$

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- 5 Go to step 3

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- k -means minimizes a cost function of the type,

$$J = \sum_{i=1}^N \sum_{j=1}^k I(\mu^{(j)} - x^{(i)}) \times \|(\mu^{(j)} - x^{(i)})\| \quad (1)$$

where, $I(\mu^{(j)} - x^{(i)})$ is 1 if $(\mu^{(j)})$ is the closest cluster center to $x^{(i)}$

Density Based Clustering

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- We adopt the definition that a cluster is a set of densely connected points
- We look at a density based clustering algorithm, DBScan, that can detect arbitrary shaped clusters and achieves the clustering based on a single pass through the data

DBScan

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 - ▶ A *core point* has more than m points in its neighborhood
 - ▶ A *border point* has less than m points in its neighborhood but is the neighborhood of a core point
 - ▶ A *noise point* is neither a core point nor a border point

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- *Density-Reachable*: x is directly density-reachable from x' . x' is directly density-reachable from x'' . Then, x is (indirectly) density-reachable from x''

The DBScan Algorithm

```
Initialize all the weights to small random values
for i = 1 to N
    if  $x^{(i)}$  is not yet classified
        if  $x^{(i)}$  is a core object
            Collect all data points density reachable from  $x^{(i)}$  and assign
            them to a new cluster
        else
            Assign  $x^{(i)}$  to noise
    end for
```