

Let rotate, scale, translate T

$$T(\vec{x}; \theta, c, a, b) = c \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} a \\ b \end{pmatrix}$$

$$= \begin{pmatrix} cx \cos \theta - cy \sin \theta + a \\ cx \sin \theta + cy \cos \theta + b \end{pmatrix} = \begin{pmatrix} T_x(\vec{x}) \\ T_y(\vec{x}) \end{pmatrix}$$

Let \vec{x}_n be position of n-th feature
 " \vec{x}_n^* " desired position

$$\text{Objective } \Phi = \sum_n (T(\vec{x}_n) - \vec{x}_n^*)^T (T(\vec{x}_n) - \vec{x}_n^*)$$

$$= \sum_n (T_x(\vec{x}_n) - x_n^*)^2 + (T_y(\vec{x}_n) - y_n^*)^2$$

$$\text{Minimize } \Phi : \frac{\partial \Phi}{\partial a} = \frac{\partial \Phi}{\partial b} = \frac{\partial \Phi}{\partial c} = \frac{\partial \Phi}{\partial \theta} = 0$$

$$\textcircled{1} \frac{\partial \Phi}{\partial a} = 0 = 2 \sum_n (T_x(\vec{x}_n) - x_n^*)$$

$$= 2 \sum_n (cx_n \cos \theta - cy_n \sin \theta + a - x_n^*)$$

$$\rightarrow a = -c\hat{x} \cos \theta + c\hat{y} \sin \theta + \hat{x}^*$$

Mass center of transformed feats
is same of target feats

$$\textcircled{2} \frac{\partial \Phi}{\partial b} = 0$$

$$\rightarrow b = -c\hat{x} \sin \theta - c\hat{y} \cos \theta + \hat{y}^*$$

$$\textcircled{3} \frac{\partial \Phi}{\partial \theta} = 0 = 2c \sum_n [(cx_n \cos \theta - cy_n \sin \theta + a - x_n^*)(-x_n \sin \theta - y_n \cos \theta)$$

$$+ (cx_n \sin \theta + cy_n \cos \theta + b - y_n^*)(x_n \cos \theta - y_n \sin \theta)]$$

c-terms cancel out

$$\text{inject } \textcircled{1} \text{ \& } \textcircled{2} = 2c \sum_n (-c\hat{x} \cos \theta + c\hat{y} \sin \theta + \hat{x}^* - x_n^*)(-x_n \sin \theta - y_n \cos \theta)$$

$$+ (-c\hat{x} \sin \theta - c\hat{y} \cos \theta + \hat{y}^* - y_n^*)(x_n \cos \theta - y_n \sin \theta)$$

$$= 2c \sum_n [\cancel{c\hat{x}x_n \cos \theta \sin \theta} - \cancel{c\hat{y}x_n \sin^2 \theta} - \hat{x}^*x_n \sin \theta + x_n x_n^* \sin \theta$$

$$+ \cancel{c\hat{x}y_n \cos^2 \theta} - \cancel{c\hat{y}y_n \cos \theta \sin \theta} - \hat{x}^*y_n \cos \theta + y_n x_n^* \cos \theta$$

$$- \cancel{c\hat{x}x_n \cos \theta \sin \theta} - \cancel{c\hat{y}x_n \cos^2 \theta} + \hat{y}^*x_n \cos \theta - x_n y_n^* \cos \theta$$

$$+ \cancel{c\hat{x}y_n \sin^2 \theta} + \cancel{c\hat{y}y_n \cos \theta \sin \theta} - \hat{y}^*y_n \sin \theta + y_n y_n^* \sin \theta]$$

$$= 2c \sum_n [\underbrace{c\hat{x}y_n - c\hat{y}x_n}_{\text{cancel out upon summation}} + \left(-\hat{x}^*x_n - \hat{y}^*y_n + x_n x_n^* + y_n y_n^* \right) \sin \theta$$

$$+ \left(-\hat{x}^*y_n + \hat{y}^*x_n + y_n x_n^* - x_n y_n^* \right) \cos \theta]$$

$$= 0$$

$$0 = p \sin \theta + q \cos \theta \Rightarrow -q/p = \sin \theta / \cos \theta = \tan \theta$$

$$\theta = \text{atan}(-q/p)$$

$$\textcircled{4} \frac{\partial \Phi}{\partial c} = 0 = 2 \sum_n [(cx_n \cos \theta - cy_n \sin \theta + a - x_n^*)(x_n \cos \theta - y_n \sin \theta)$$

$$+ (cx_n \sin \theta + cy_n \cos \theta + b - y_n^*)(x_n \sin \theta + y_n \cos \theta)]$$

$$= 2 \sum_n [\cancel{cx_n^2 \cos^2 \theta} - \cancel{cx_n y_n \cos \theta \sin \theta} + ax_n \cos \theta - x_n x_n^* \cos \theta$$

$$- \cancel{cx_n y_n \cos \theta \sin \theta} + \cancel{cy_n^2 \sin^2 \theta} - ay_n \sin \theta + y_n x_n^* \sin \theta$$

$$+ \cancel{cx_n^2 \sin^2 \theta} + \cancel{cx_n y_n \cos \theta \sin \theta} + bx_n \sin \theta - x_n y_n^* \sin \theta$$

$$+ \cancel{cx_n y_n \cos \theta \sin \theta} + \cancel{cy_n^2 \cos^2 \theta} + by_n \cos \theta - y_n y_n^* \cos \theta]$$

$$= 2 \sum_n [cx_n^2 + cy_n^2 - \cancel{c\hat{x}x_n \cos^2 \theta} + \cancel{c\hat{y}x_n \cos \theta \sin \theta} + \hat{x}^*x_n \cos \theta - x_n x_n^* \cos \theta$$

$$+ \cancel{c\hat{x}y_n \cos \theta \sin \theta} - \cancel{c\hat{y}y_n \sin^2 \theta} - \hat{x}^*y_n \sin \theta + y_n x_n^* \sin \theta$$

$$- \cancel{c\hat{x}x_n \sin^2 \theta} - \cancel{c\hat{y}x_n \cos \theta \sin \theta} + \hat{y}^*x_n \sin \theta - x_n y_n^* \sin \theta$$

$$= 2 \sum_n [C x_n^2 + C y_n^2 - \cancel{C \hat{x} x_n \cos^2 \theta} + \cancel{C \hat{y} x_n \cos \theta \sin \theta} + \hat{x}^* x_n \cos \theta - x_n x_n^* \cos \theta \\ + \cancel{C \hat{x} y_n \cos \theta \sin \theta} - \cancel{C \hat{y} y_n \sin^2 \theta} - \hat{x}^* y_n \sin \theta + y_n x_n^* \sin \theta \\ - \cancel{C \hat{x} x_n \sin^2 \theta} - \cancel{C \hat{y} x_n \cos \theta \sin \theta} + \hat{y}^* x_n \sin \theta - x_n y_n^* \sin \theta \\ - \cancel{C \hat{x} y_n \cos \theta \sin \theta} - \cancel{C \hat{y} y_n \cos^2 \theta} + \hat{y}^* y_n \cos \theta - y_n y_n^* \cos \theta]$$

$$= 2 \sum_n C (x_n^2 + y_n^2 - \hat{x} x_n - \hat{y} y_n) + [(\hat{x}^* - x_n^*) x_n + (\hat{y}^* - y_n^*) y_n] \cos \theta \\ + [-(\hat{x}^* - x_n^*) y_n + (\hat{y}^* - y_n^*) x_n] \sin \theta]$$

$$= 2 (\alpha C + \beta \cos \theta + \gamma \sin \theta)$$

$$C = - \frac{\beta \cos \theta + \gamma \sin \theta}{\alpha}$$