# Regularization Gradient Descent with Momentum RMSprop Adam

13th December 2021

#### Overview

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- Gradient descent with momentum
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#### Regularization

What is regularization and why do we need it?

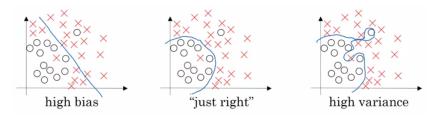


Figure: Bias-Variance <sup>1</sup>

https://www.coursera.org/learn/deep-neural-network

# Regularization - Logistic Regression

$$z^{(i)} = w_0 + w_1 x_1^{(i)} + w_2 x_2^{(i)} + \ldots + w_d x_d^{(i)}$$
  
$$a^{(i)} = \sigma(z^{(i)})$$

L2 regularization:

$$\min_{\mathbf{w}} L2(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} L^{(i)}(a^{(i)}, y^{(i)}) + \frac{\lambda}{2N} \|\mathbf{w}\|_{2}^{2}$$

where  $\|\mathbf{w}\|_{2}^{2} = \sum_{j=1}^{d} w_{j}^{2}$ .

L1 regularization:

$$\min_{\mathbf{w}} L1(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} L^{(i)}(a^{(i)}, y^{(i)}) + \frac{\lambda}{2N} \|\mathbf{w}\|_{1}$$

where  $\|\mathbf{w}\|_1 = \sum_{i=1}^{d} |w_i|$ .

**Note**: We can omit regularization on  $w_0$ .

#### Regularization - Neural Network

$$a^{(i)} = f^{[K]}(\mathbf{W}^{[K]}(\dots(f^{[2]}(\mathbf{W}^{[2]}(f^{[1]}(\mathbf{W}^{[1]}\mathbf{x}^{(i)}))))))$$

L2 regularization:

$$\min_{\mathbf{w}} L2(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} L^{(i)}(a^{(i)}, y^{(i)}) + \frac{\lambda}{2N} \sum_{k=1}^{K} \left\| \mathbf{W}^{[k]} \right\|_{F}^{2}$$

where  $\|\mathbf{W}^{[k]}\|_2^2 = \sum_{i=1}^{n^{[k]}} \sum_{j=1}^{n^{[k-1]}} (w_{ij}^{[k]})^2$  is the Frobenius norm of the weight matrix in layer k.

L1 regularization:

$$\min_{\mathbf{w}} L1(\mathbf{w}) = \frac{1}{N} \sum_{i=1}^{N} L^{(i)}(a^{(i)}, y^{(i)}) + \frac{\lambda}{2N} \sum_{k=1}^{K} \|\mathbf{W}^{[k]}\|_{1}$$

where  $\|\mathbf{W}^{[k]}\|_1 = \sum_{i=1}^{n^{[k]}} \sum_{j=1}^{n^{[k-1]}} |w_{ij}^{[k]}|$ .

**Note**: We can omit regularization on  $w_{i0}^{[k]}$ .

#### Regularization - Neural Network

 $\nabla L(\mathbf{W}^{[k]})$  is the gradient of the loss function without regularization obtained from backpropagation.

The gradient of the loss function with L2 regularization can be computed to update the weight matrix of layer k as:

$$\nabla L2(\mathbf{W}^{[k]}) \longleftarrow \nabla L(\mathbf{W}^{[k]}) + \frac{\lambda}{N} \mathbf{W}^{[k]}$$

$$\mathbf{W}^{[k]} \longleftarrow \mathbf{W}^{[k]} - \gamma \nabla L2(\mathbf{W}^{[k]})$$

$$\mathbf{W}^{[k]} \longleftarrow \mathbf{W}^{[k]} - \gamma \left(\nabla L(\mathbf{W}^{[k]}) + \frac{\lambda}{N} \mathbf{W}^{[k]}\right)$$

$$\mathbf{W}^{[k]} \longleftarrow \left(1 - \frac{\gamma \lambda}{N}\right) \mathbf{W}^{[k]} - \gamma \nabla L(\mathbf{W}^{[k]})$$

# Gradient descent for *L*-layer neural network

```
Result: weights \mathbf{W}^{[k]} for all layers.
for k \leftarrow 1 to l do
      \mathbf{W}^{[k]} \leftarrow \text{random}() [Random initialization]
end
for t \leftarrow 1 to max iterations do
       for k \leftarrow 1 to l do
        \mathbf{A}^{[k]} \leftarrow f(\mathbf{Z}^{[k]}) \leftarrow f(\mathbf{W}^{[k]} \cdot \mathbf{A}^{[k-1]}) [Forward propagation]
       end
       for k \leftarrow 1 to 1 do
             \nabla L(\mathbf{Z}^{[k]}) \longleftarrow \nabla L(\mathbf{A}^{[k]}) \circ f'(\mathbf{Z}^{[k]})
             \nabla L(\mathbf{W}^{[k]}) \longleftarrow \frac{1}{N} \nabla L(\mathbf{Z}^{[k]}) \cdot \mathbf{A}^{[k-1]T} [Backpropagation]

abla \mathcal{L}(\mathsf{A}^{[\mathsf{k}-1]}) \longleftarrow \mathsf{W}^{[\mathsf{k}]\mathsf{T}} \cdot 
abla \mathcal{L}(\mathsf{Z}^{[\mathsf{k}]})
       end
       for k \leftarrow 1 to l do
       \mathbf{W}^{[k]} \longleftarrow \mathbf{W}^{[k]} - \gamma \nabla L(\mathbf{W}^{[k]})
                                                                                    [Update parameters]
       end
```

#### Batch gradient descent

If the training set is too large, it takes a lot of time to process the whole training set for each step of gradient descent.

#### Mini-batch gradient descent

If the training set is too large, it takes a lot of time to process the whole training set for each step of gradient descent.

 $\longrightarrow$  Divide the training set into multiple mini-batches of **reasonable** sizes.

$$\begin{aligned} \mathbf{X} &= [\mathbf{x}^{(1)} \quad \mathbf{x}^{(2)} \dots \mathbf{x}^{(s)} \quad | \quad \mathbf{x}^{(s+1)} \dots \mathbf{x}^{(2s)} \quad | \quad \mathbf{x}^{(2s+1)} \dots \quad | \quad \dots \mathbf{x}^{(N)}] \\ &= [\mathbf{X}_{\{1\}} \quad | \quad \mathbf{X}_{\{2\}} \quad | \quad \dots | \quad \mathbf{X}_{\{N/s\}}] \\ \mathbf{Y} &= [y^{1} \quad y^{2} \dots y^{s} \quad | \quad y^{s+1} \dots y^{2s} \quad | \quad y^{2s+1} \dots \quad | \quad \dots y^{N}] \\ &= [\mathbf{Y}_{\{1\}} \quad | \quad \mathbf{Y}_{\{2\}} \quad | \quad \dots | \quad \mathbf{Y}_{\{N/s\}}] \end{aligned}$$

At each iteration t, perform gradient descent using one mini-batch of training examples  $(\mathbf{X}_{\{t\}}; \mathbf{Y}_{\{t\}})$ .

#### Mini-batch gradient descent

- Mini-batch size  $s = N \longrightarrow \text{Normal gradient descent}$ .
- Mini-batch size  $s = 1 \longrightarrow \mathsf{Stochastic}$  gradient descent.
- Mini-batch sizes are normally set as powers of 2, e.g., s = 64, 128, 256, 512

#### Problem with gradient descent

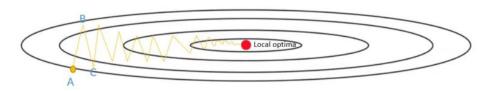


Figure: Gradient descent <sup>2</sup>

<sup>&</sup>lt;sup>2</sup>https://engmrk.com/gradient-descent-with-momentum/.

#### Problem with gradient descent

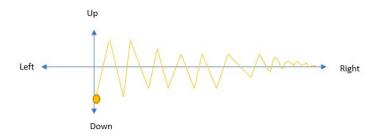
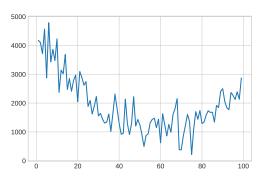
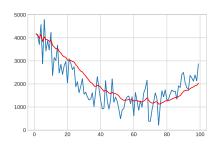


Figure: Gradient descent <sup>3</sup>

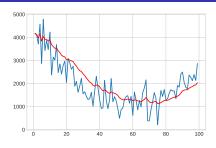
 $<sup>^3</sup> https://engmrk.com/gradient-descent-with-momentum/.\\$ 

Example: How to model/forecast the stock/share price of a certain company?





$$egin{aligned} m_{100} &= eta m_{99} + (1-eta) extit{price}_{100} \ m_{99} &= eta m_{98} + (1-eta) extit{price}_{99} \ & \dots \ m_t &= eta m_{t-1} + (1-eta) extit{price}_t \ & \dots \ m_1 &= eta m_0 + (1-eta) extit{price}_1 \end{aligned}$$



$$\beta = 0.9$$

$$m_{100} = 0.9m_{99} + (1 - 0.9)price_{100}$$

$$= 0.1price_{100} + 0.9m_{99}$$

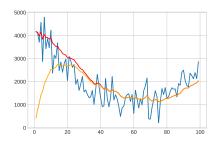
$$= 0.1price_{100} + 0.9(0.1price_{99} + 0.9m_{98})$$

$$= 0.1price_{100} + 0.9 \cdot 0.1price_{99} + (0.9)^2m_{98}$$

$$= 0.1price_{100} + 0.09price_{99} + (0.9)^2(0.1price_{98} + 0.9m_{97})$$

$$= 0.1price_{100} + 0.09price_{99} + 0.081price_{98} + (0.9)^3m_{97}$$

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Actually, without the below correction, we will get the orange line instead of the red line. Why?

$$m_t = eta m_{t-1} + (1-eta) extit{price}_t \ m_t^{corrected} = rac{m_t}{1-eta^t}$$

#### Gradient descent with momentum

Update weights at iteration t:

$$\begin{aligned} \mathbf{g}_{\{t\}} &\longleftarrow \nabla L(\mathbf{W}_{\{t-1\}}) \\ \mathbf{m}_{\{t\}} &\longleftarrow \beta_1 \mathbf{m}_{\{t-1\}} + (1 - \beta_1) \mathbf{g}_{\{t\}} \\ \mathbf{W}_{\{t\}} &\longleftarrow \mathbf{W}_{\{t-1\}} - \gamma \mathbf{m}_{\{t\}} \end{aligned}$$

Initialization:  $\mathbf{m}_{\{0\}} = \mathbf{0}$ 

Hyperparameters:  $\beta_1 = 0.9$ ; learning rate  $\gamma$ 

#### Gradient descent with momentum

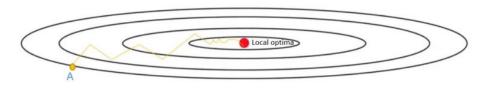


Figure: Gradient descent with momentum <sup>4</sup>

<sup>4</sup>https://engmrk.com/gradient-descent-with-momentum/.

#### Problem with gradient descent

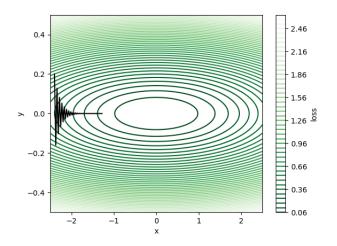


Figure: Gradient descent <sup>5</sup>

<sup>&</sup>lt;sup>5</sup>https://github.com/hengluchang/visualizing\_momentum.

#### Gradient descent with momentum

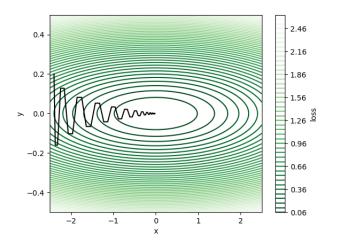


Figure: Gradient descent with momentum  $\beta_1 =$  0.8  $^6$ 

<sup>&</sup>lt;sup>6</sup>https://github.com/hengluchang/visualizing\_momentum.

## **RMSprop**

Update weights at iteration t:

$$\begin{split} \mathbf{g}_{\{t\}} &\longleftarrow \nabla L(\mathbf{W}_{\{t-1\}}) \\ \mathbf{s}_{\{t\}} &\longleftarrow \beta_2 \mathbf{s}_{\{t-1\}} + (1 - \beta_2) \mathbf{g}_t^2 \\ \mathbf{W}_{\{t\}} &\longleftarrow \mathbf{W}_{\{t-1\}} - \gamma \frac{\mathbf{g}_{\{t\}}}{\sqrt{\mathbf{s}_{\{t\}}} + \epsilon} \end{split}$$

Initialization:  $\mathbf{s}_{\{0\}} = \mathbf{0}$ 

Hyperparameters:  $\beta_2 = 0.9$ ;  $\epsilon = 10^{-8}$ ; learning rate  $\gamma$ 

#### Adam - Adaptive moment estimation

Update weights at iteration *t*:

$$\begin{aligned} \mathbf{g}_{\{t\}} &\longleftarrow \nabla L(\mathbf{W}_{\{t-1\}}) \\ \mathbf{m}_{\{t\}} &\longleftarrow \beta_1 \mathbf{m}_{\{t-1\}} + (1-\beta_1) \mathbf{g}_{\{t\}} \\ \mathbf{s}_{\{t\}} &\longleftarrow \beta_2 \mathbf{s}_{\{t-1\}} + (1-\beta_2) \mathbf{g}_t^2 \\ \mathbf{m}_{\{t\}}^{corrected} &\longleftarrow \frac{\mathbf{m}_{\{t\}}}{1-\beta_1^t} \\ \mathbf{s}_{\{t\}}^{corrected} &\longleftarrow \frac{\mathbf{s}_{\{t\}}}{1-\beta_2^t} \\ \mathbf{W}_{\{t\}} &\longleftarrow \mathbf{W}_{\{t-1\}} - \gamma \frac{\mathbf{m}_{\{t\}}^{corrected}}{\sqrt{\mathbf{s}_{\{t\}}^{corrected}} + \epsilon} \end{aligned}$$

Initialization: 
$$\mathbf{m}_{\{0\}} = \mathbf{s}_{\{0\}} = \mathbf{0}$$

Hyperparameters:  $\beta_1=$  0.9;  $\beta_2=$  0.999;  $\epsilon=$  10<sup>-8</sup>; learning rate  $\gamma$ 

#### References

- Visualizing Gradient Descent with Momentum in Python: https://github.com/hengluchang/visualizing\_momentum.
- Coursera Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization: https://www.coursera.org/learn/deep-neural-network/
- Occurred Section 1

  Coursera Neural Networks and Deep Learning:
   https:
   //www.coursera.org/learn/neural-networks-deep-learning/