

Introduction to Computational Statistics

First Concepts in Data Simulation – juliette.chevallier@insa-toulouse.fr

Spring School on Statistics and Machine Learning

1. Basic Simulation Methods

1.1 Inversion Method

1.2 Acceptance-Rejection Method

2. The Metropolis-Hastings Algorithm

2.1 Principle

2.2 Independence Sampling

2.3 Symmetric Random Walk

2.4 Metropolis-Adjusted Langevin Algorithm

3. The Gibbs Sampler

3.1 Principle

All materials for the course are available at

plmlab.math.cnrs.fr/chevallier-teaching/hcmus-springschool-computationalstatistics



- **Aim:** Given a probability distribution π , more or less well known
 \rightsquigarrow How sampling according to π ?
 - **Remark:** Here, we assume that we are able to sample according to $\mathcal{U}([0, 1])$
 \rightsquigarrow pseudo-random number generator (pRNG)
-

Program

1. Basic methods
2. Monte Carlo Markov Chain (MCMC) methods

Basic Simulation Methods

1.1 Inversion Method

1.2 Acceptance-Rejection Method

Cumulative Distribution Function and Quantiles

Definition (Cumulative distribution function)

$$F: \mathbb{R} \rightarrow [0, 1]$$

$$x \mapsto F(x) = \mathbb{P}(X \leq x)$$

Theorem (Properties of F)

- (i) F is growing
- (ii) $\lim_{x \rightarrow -\infty} F(x) = 0$, $\lim_{x \rightarrow +\infty} F(x) = 1$
- (iii) F is *càdlàg*: “right continuous with left limits”

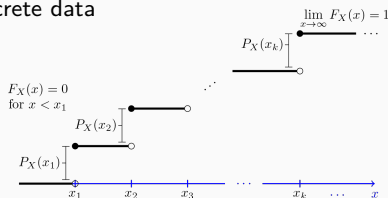
⚠ F not necessarily bijective \rightsquigarrow See discrete data

Definition (Quantiles)

Generalized inversion of F

$$F^{-1}:]0, 1[\rightarrow \mathbb{R}$$

$$p \mapsto \inf\{x \in \mathbb{R} \text{ s.t. } F(x) \geq p\}$$



Theorem (Properties of F^{-1})

- (i) F^{-1} is growing, continuous on the left
- (ii) $F(x) \geq p \iff x \geq F^{-1}(p)$
- (iii) $F(F^{-1}(p)) \geq p$ with equality if F continuous in p

Inversion Method: For real-valued data only \equiv Values in \mathbb{R}

Theorem (Inversion Method)

- Let $U \sim \mathcal{U}([0, 1])$. Then $X = F^{-1}(U) \sim F$
- If $X \sim F$ and F is continuous. Then $F(X) \sim \mathcal{U}([0, 1])$

Proof:

- $\mathbb{P}(F^{-1}(U) \leq x) \stackrel{(ii)}{=} \mathbb{P}(F(x) \geq U) \stackrel{U \text{ uniform}}{=} F(x)$
- $\mathbb{P}(F(X) < u) = 1 - \mathbb{P}(F(X) \geq u) \stackrel{(ii)}{=} 1 - \mathbb{P}(X \geq F^{-1}(u))$
 $= \mathbb{P}(X < F^{-1}(u)) \stackrel{FC^0}{=} F(F^{-1}(u)) \stackrel{FC^0}{=} u$

Inversion Algorithm

To sample $X \sim F$

- Sample
 $U \sim \mathcal{U}([0, 1])$
- Set $X = F^{-1}(U)$

Expl: $X \sim \text{Exp}(\lambda)$

$F(x) = 1 - e^{-\lambda x}$ continuous and invertible

$$F^{-1}(u) = -\frac{1}{\lambda} \log(1 - u)$$

Note: $U \sim \mathcal{U}([0, 1]) \implies 1 - U \sim \mathcal{U}([0, 1])$

$$\rightsquigarrow F^{-1}(u) = x = -\frac{1}{\lambda} \log(u)$$

How to compute F^{-1} ?

1. Explicit formula

2. Numerical resolution of $F(x) = u$

↪ Bisection algorithm

- If $x \in [a, b]$, we compare $F\left(\frac{a+b}{2}\right)$ to u
- We get into the correct half-interval
- We iterate

3. Newton-Raphson algorithm

↪ ⚠ Stop conditions

4. Approximation of F^{-1}

↪ Gaussian variable: Let A and B be 2 polynomial function

$$g(u) = \sqrt{-2 \ln u} + \frac{A(\sqrt{-2 \ln u})}{B(\sqrt{-2 \ln u})}$$

Basic Simulation Methods

1.1 Inversion Method

1.2 Acceptance-Rejection Method

Uniform Distribution on \mathcal{C} 1/2

Theorem (Uniform Distribution on \mathcal{C} – Thm 1)

(a) Denote $\mathcal{C} = \{(x, y) \text{ s.t. } 0 \leq y \leq cf(x)\}$.

Assume:

- $X \sim f$, with f density on \mathbb{R}^d
- $U \sim \mathcal{U}([0, 1])$ such that $U \perp\!\!\!\perp X$
- $c > 0$

Then:

$$(X, cUf(X)) \sim \mathcal{U}(\mathcal{C})$$

(b) Conversely if $(X, Y) \sim \mathcal{U}(\mathcal{C})$ then X admits f for density

Proof: Since $X \perp\!\!\!\perp U$, (X, U) admits for density $f(x)\mathbb{1}_{[0,1]}(u) dx du$

$$\begin{aligned} \text{(a)} \quad \mathbb{E}[h(X, cUf(X))] &= \iint h(x, cuf(x)) f(x)\mathbb{1}_{[0,1]}(u) dx du \\ &= \iint h(x, y) f(x)\mathbb{1}_{\mathcal{C}}(x, y) \frac{dy}{cf(x)} dx \quad \text{setting } y = cuf(x) \end{aligned}$$

$$\text{Note that } \int_{\mathcal{C}} dx dy = \iint_0^{cf(x)} dy dy = c \int f(x) dx = c$$

\rightsquigarrow c normalization constant and $(X, Y) \sim \mathcal{U}(\mathcal{C})$

$$\text{(b)} \quad \text{Conversely } f_X(x) = \int f_{(X,Y)}(x, y) dy = \frac{1}{c} \int_0^{cf(x)} dy = f(x)$$

Uniform Distribution on \mathcal{C} 2/2

Theorem (Uniform Distribution on \mathcal{C} – Thm 1)

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- $c > 0$

Then:

$$(X, cUf(X)) \sim \mathcal{U}(\mathcal{C})$$

(b) Conversely if $(X, Y) \sim \mathcal{U}(\mathcal{C})$ then X admits f for density

Algorithm: Uniform distribution on \mathcal{C} , i.e. below the curve g

1. Sample $X \sim \frac{g(x)}{\int g(x) dx}$
2. Sample $U \sim \mathcal{U}([0, 1])$ and set $Y = g(x) \times u$
3. Return (X, Y)

Requirements for the Accept-Reject Method

Theorem (Requirements for the accept-reject method – Thm 2)

- Let $(X_k)_{k \in \mathbb{N}}$ a seq. of random variables valued in \mathbb{R}^d , same law than X
- Let $A \in \mathcal{X}$ s.t. $\mathbb{P}(X \in A) = p > 0$
- Let $Y = X_{\tau_A}$, where $\tau_A = \inf\{k \geq 1 \text{ s.t. } X_k \in A\}$ “First instant in A ”

Then: $\forall B \in \mathcal{X}$, $\mathbb{P}(Y \in B) = \mathbb{P}(X \in B | X \in A)$, conditional proba knowing A

Proof: Since τ_A is the first time in A ,

$$\begin{aligned}\mathbb{E}[h(Y)] &= \sum_{n \geq 1} \mathbb{E}[h(X_n) \mathbb{1}_{\{\tau=n\}}] = \sum_{n \geq 1} \mathbb{E}[h(X_n) \mathbb{1}_{\{X_1 \notin A\}} \cdots \mathbb{1}_{\{X_{n-1} \notin A\}} \mathbb{1}_{\{X_n \in A\}}] \\ &\stackrel{i.i.d.}{=} \sum_{n \geq 1} \mathbb{P}(X_1 \notin A) \cdots \mathbb{P}(X_{n-1} \notin A) \mathbb{E}[h(X_n) \mathbb{1}_{\{X_n \in A\}}] \\ &\stackrel{X_i \sim X}{=} \sum_{n \geq 1} (\mathbb{P}(X \notin A))^{n-1} \mathbb{E}[h(X_n) \mathbb{1}_{\{X_n \in A\}}] = \left(\sum_{n \geq 1} (1-p)^{n-1} \right) \mathbb{E}[h(X) \mathbb{1}_{\{X \in A\}}]\end{aligned}$$

And the result follows with $h = \mathbb{1}_{\{X \in B\}}$

$$\rightsquigarrow \mathbb{P}(Y \in B) = \frac{1}{1 - (1-p)} \mathbb{P}(X \in A \cup B) = \frac{\mathbb{P}(X \in A \cap B)}{\mathbb{P}(X \in A)}$$

Accept-Reject Method

Corollary

Let $X \sim \mathcal{U}(\mathcal{C})$ where $\mathcal{C} \subset \mathbb{R}^d$. Let $\mathcal{B} \subset \mathcal{C}$. Then: $Y = X_{\tau_{\mathcal{B}}} \sim \mathcal{U}(\mathcal{B})$

Idea Accept-Reject Method:

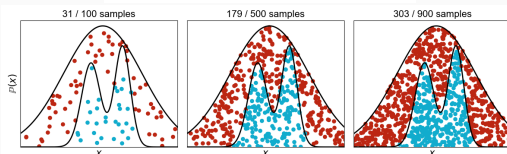
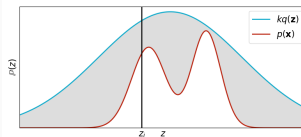
- Consider a density g s.t. $\exists c > 0$ s.t. $\forall x \in \mathbb{R}^d, f(x) \leq c g(x)$
- [Thm 1] Sample $U \sim \mathcal{U}(\mathcal{C})$, where $\mathcal{C} = \{(x, y) \text{ s.t. } 0 \leq y \leq c g(x)\}$
- [Thm 2] As long as U is not in $\mathcal{B} = \{(x, y) \text{ s.t. } 0 \leq y \leq f(x)\}$, draw new U
- [Cor] As soon as U falls into \mathcal{B} , we know that its abscissa $X \sim f$

Algorithm: Accept-Reject

While $Y \geq f(x)$

1. Sample $X \sim g$ ($\Rightarrow x$)
2. Sample $U \sim \mathcal{U}([0, 1])$
Set $Y = c g(x) U$

Return X



Calibration of the Method 1/2

⚠ *Easy simulation according to g is essential, and the choice of g is crucial!*

Question (Waiting time): What is the proba distribution of τ_A ?

$$\bullet \mathbb{P}(\tau_A = n) \stackrel{11}{=} \mathbb{P}(X_1 \notin A) \dots \mathbb{P}(X_{n-1} \notin A) \mathbb{P}(X_n \in A) \stackrel{i.i.d.}{=} (1-p)^{n-1}p$$

$\rightsquigarrow \tau_A \sim \text{Geom}(p)$ with $p = \mathbb{P}(X \in A)$

$$\text{In particular, } \mathbb{E}[\tau_A] = \frac{1}{p} \text{ and } \text{Var}(\tau_A) = \frac{1-p}{p^2}$$

- [Reject Algo] “While $U > \frac{f(x)}{cg(x)}$ sample $X \sim g$ and $U \sim \mathcal{U}([0, 1])$ ”

$$p = \mathbb{P}\left(U \leq \frac{f(x)}{cg(x)}\right) = \int \mathbb{1}_{\{ucg(x) \leq f(x)\}} \mathbb{1}_{[0,1]}(u)g(x) \, dx \, du = \int \frac{f(x)}{cg(x)}g(x) \, dx = \frac{1}{c}$$

\rightsquigarrow The greater the c , the smaller the p and therefore the greater the average number of draws before success $\mathbb{E}[\tau_A] = \frac{1}{p} = c$

\implies *Less efficient algorithm*

Choice of (c, g)

- $f > 0 \implies g > 0$
 - $c = \sup_{x \text{ s.t. } f(x) > 0} \frac{f(x)}{g(x)}$
 - g belongs to a parametric family, and we optimize the parameter
-

Evaluating f can be costly

- Major and minor f with easily evaluable functions to make comparisons

Exercise: Box-Muller Algorithm

- Let R a random variable with Rayleigh distribution with parameter 1

$$\forall r \in \mathcal{R}, \quad f_R(r) = r \exp\left(-\frac{r^2}{2}\right) \mathbb{1}_{\mathbb{R}^+}(r)$$

- Let Θ with uniform distribution on $[0, 2\pi]$
- Assume that R and Θ are independent

1. Let X and Y such that

$$X = R \cos(\Theta) \quad \text{and} \quad Y = R \sin(\Theta).$$

Prove that both X and Y have $\mathcal{N}(0, 1)$ distribution and are independent.

2. Write an algorithm for sampling independent Gaussian distribution $\mathcal{N}(0, 1)$.

The Metropolis-Hastings Algorithm

2.1 Principle

2.2 Independence Sampling

2.3 Symmetric Random Walk

2.4 Metropolis-Adjusted Langevin Algorithm

Motivation

- The Metropolis-Hastings (MH) algorithm manage to sample from “almost any” probability distribution (up to the burn-in period) in a very simple way
 - It only requires to know the target π up to a multiplicative constant (usually the normalization constant)
-

Aim and setting:

- Denote π our *target distribution*, which we assume to have a pdf w.r.t the Lebesgue measure
- We know π up to a multiplicative constant
- Assume that we are able to sample from a proposal density $q(x, \cdot)$

The Metropolis-Hastings Algorithm

1. Start with an initial value X_0
2. Given X_n , we propose a candidate $Y_n \sim q(X_n, \cdot)$ from the *proposal distribution* $q(x, \cdot)$
3. Compute the *acceptation ratio*

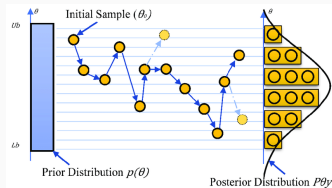
$$\alpha(X_n, Y_{n+1}) = \begin{cases} \min \left(1; \frac{\pi(Y_{n+1}) q(Y_{n+1}, X_n)}{\pi(X_n) q(X_n, Y_{n+1})} \right) & \text{if } \text{denom} > 0 \\ 1 & \text{otherwise} \end{cases}$$

4. If we accept Y_{n+1} , set $X_{n+1} = Y_{n+1}$. Otherwise $X_{n+1} = X_n$

Algorithm: Metropolis Hastings

For $n = 1 \dots N$

- $U_{n+1} \sim \mathcal{U}([0, 1])$
- $Y_{n+1} \sim q(X_n, \cdot)$
- If $U_{n+1} < \alpha(X_n, Y_n)$
Then $X_{n+1} = Y_{n+1}$
Otherwise Then $X_{n+1} = X_n$



Interpretation: We accept move $X_n \mapsto Y_{n+1}$ when the “likelihood ratio” $\frac{\pi(Y_{n+1})}{q(X_n, Y_{n+1})}$ is greater than the one for the opposite move $Y_{n+1} \mapsto X_n$

Transition Kernel, Ergodicity, etc.

The MH algorithm produces a Markov chain of *transition kernel*

$$P(x, A) = \int_A q(x, y) \, dy + \delta_x(A) \int_{\mathbb{X}} (1 - \alpha(x, y)) q(x, y) \, dy$$

Intuition

- If we accept y which has been proposed $p(x, y) = q(x, y) \alpha(x, y)$
- If we have rejected, we stay at x and $p(x, \{x\}) = \int q(x, y) (1 - \alpha(x, y)) \, dy$

Invariant measure

$$\pi P = \pi$$

To ensure that the MCMC chain converges to the correct minima, we need the chain's **ergodicity** \rightsquigarrow Depends on the choice of the proposal!

Remark: $\lim_{n \rightarrow \infty} \sup_{A \in \mathcal{X}} |\mu P^n(A) - \pi(A)| = 0$ and π is independent of μ

The Metropolis-Hastings Algorithm

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Independence sampling – IS-MH

$$q(x, y) = q(y)$$

- The proposal **does not depend on the current state** of the chain
 - **Remark**
 - The dependence is present through the acceptance ratio $\alpha(x, y) = \frac{\pi(y) q(x)}{q(y) \pi(x)} \wedge 1$
 - Looks like a generalization of the accept-reject method
 - Convergence properties of the generated chain obviously depends on Under certain conditions on q
-

Definition (Total Variation norm)

Use notation P for both the kernel and its corresponding probability measure

$$\|P(x, \cdot) - \pi\|_{TV} = \sup_{A \in \mathcal{X}} \left| \int_A (P(x, y) - f(y)) dy \right|$$

Convergence of the Independence Sampling

Following theorem provides simple conditions to prove strong convergence property i.e. the **geometric ergodicity**

Theorem

- The MCMC algorithm given by the Independence Sampling (IS) MH algorithm produces a **uniformly ergodic** Markov Chain if:

(M) There exists a constant $M > 0$ s.t. that $\forall x \in \text{Supp}(\pi), \pi(x) \leq Mq(x)$

In this case $\|P^n(x, \cdot) - \pi(\cdot)\|_{TV} \leq \left(1 - \frac{1}{M}\right)^n$

- Moreover if $\forall M > 0 \exists A \in \mathcal{X}$ s.t. $\pi(A) \neq 0$ and (M) is not satisfied, then (X_n) is not geometrically ergodic

Efficiency of the Independence Sampling ?

Measures through its mean acceptance ratio $\mathbb{E}[\alpha(X, Y)]$

Lemma

If the chain is stationnary and q satisfies (M) then

$$\mathbb{E}[\alpha(X, Y)] \geq \frac{1}{M}$$

Example: $\pi = \mathcal{N}(0, 1)$ from $q = \mathcal{N}(0, \sigma^2)$

Example Simulation of $\pi = \mathcal{N}(0, 1)$ using $q = \mathcal{N}(0, \sigma^2)$

$$\begin{aligned}\alpha(x, y) &= \inf \left\{ 1, \exp \left(-\frac{1}{2}y^2 + \frac{1}{2}x^2 + \frac{1}{2\sigma^2}y^2 - \frac{1}{2\sigma^2}x^2 \right) \right\} \\ &= \inf \left\{ 1, \exp \left(-\frac{1}{2} (y^2 - x^2) (1 - \sigma^{-2}) \right) \right\}\end{aligned}$$

- If $\sigma^{-1} > 1$:
 - The proposal have heavier tail than the target distribution
 - We will propose many elements far from 0, i.e. such that $|Y_{n+1}| > |X_n|$
 - But $1 - \frac{1}{\sigma^2} > 0$. Hence:
 - If $Y_{n+1}^2 \gg X_n^2$, $\exp \left(-\frac{1}{2} (y^2 - x^2) (1 - \sigma^{-2}) \right) < 1$
(and the more $Y_{n+1}^2 \gg X_n^2$, the more $\exp(\cdot) < 1$)
 \rightsquigarrow These elements are very likely to be reject
 - The elements s.t. $Y_{n+1}^2 \leq X_n^2$ will be accepted with probability 1

To compensate the heavy tail proposal, many elements will be rejected

- If $\sigma^{-1} < 1$:
 - All the candidates s.t. $|Y_{n+1}| > |X_n|$ will be accepted with probability 1
 - But: not all elements in the complementary set

This compensate that many elements will be proposed close to 0

The Metropolis-Hastings Algorithm

2.1 Principle

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2.3 Symmetric Random Walk

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Symmetric Random Walk – SRW-MH

- Assume that \mathbb{X} is a vector space (typically \mathbb{R}^d) on which we can define a **random walk** with transition density $q(x, y) = q(|x - y|)$, q even function

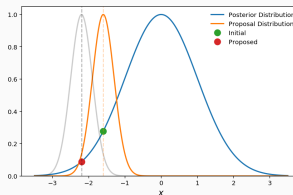
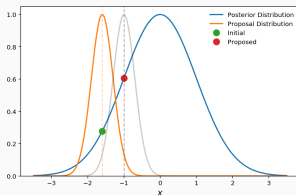
- In this case, the acceptance ratio reduce to

$$\alpha(x, y) = \inf \left(1, \frac{\pi(y)}{\pi(x)} \right)$$

Interpretation:

- In the *usual MH*, with accept the Y_{n+1} s.t. that the “likelihood ratio” $\frac{\pi(\cdot)}{q(X_n, \cdot)}$ is greater than the opposite one
- Here:** Condition becomes π increases \implies Accept with probability 1

In other words, *the SRW-MH biases the Random Walk by promoting samples which move toward the modes of π*



Considerations around the SRW-MH

- Large range of possible $q \rightsquigarrow$ Very versatile algorithm
- But some drawbacks

Theorem

If π has *non-compact support* and q symmetric, the Markov chain $(X_n)_n$ is not uniformly ergodic

- Additional assumptions on π and q allow geometric ergodicity

Example: Simulation of $\pi(x) \propto \exp(-\gamma|x|^\beta)$, $\gamma > 0$ and $\beta > 0$,

From $q(x, y) = \frac{1}{\sqrt{2\pi}\sigma^2} \exp\left(-\frac{(x-y)^2}{2\sigma^2}\right)$

- Given X_n , the SRW samples $Y_{n+1} \sim \mathcal{N}(X_n, \sigma^2)$
 $\rightsquigarrow \alpha(X_n, Y_{n+1}) = \inf \left\{ 1, \exp\left(\gamma \left(|X_n|^\beta - |Y_{n+1}|^\beta\right)\right) \right\}$
- If $|Y_{n+1}| \leq |X_n|$, automatically accept
- If $|Y_{n+1}| > |X_n|$, it may be rejected

Remark: It seems that σ^2 does not have a real impact on the results. In fact, it have but in the ability of the chain to “forget its past”

Auto-Correlation (as a “measure” of stationarity)

Definition (Auto-Correlation)

Consider a chain extended to the N -th iteration and denote $\bar{X} = \frac{1}{N} \sum_{i=1}^N X_i$

$$C_i = \frac{\sum_{j=1}^{N-i} (X_j - \bar{X})(X_{j+i} - \bar{X})}{N - i} \times \frac{N}{\sum_{j=1}^N (X_j - \bar{X})^2}$$

- The auto-correlation measures how “independent” are the first samplers w.r.t. the last ones
- **Expectation:** It decreases quickly
 - ↪ The chain does not depends too long on its initial value

To help the chain to “forget its past”, one may also rely on a **burn-in** period

The Metropolis-Hastings Algorithm

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Intuition behind MALA

- Recall that the SRW-MH can be seen as a **Random-Walk** biased to promote samples around the modes of π

Can we go further, *i.e.* better use the target π into the proposal?

- Writes π , known up to a constant, in the form

$$\pi(x) = \frac{e^{-U(x)}}{\int_{\mathbb{R}^d} e^{-U(y)} dy}$$

- Assume that $U: \mathbb{R}^d \rightarrow \mathbb{R}$ is \mathcal{C}^2 and $\exists L > 0$ s.t.

$$\forall x, y \in \mathbb{R}^d, \|\nabla U(x) - \nabla U(y)\| \leq L\|x - y\|$$

(Overdamped) Langevin diffusion SDE:

Denote $(B_t)_{t \geq 0}$ a d -dimensional Brownian Motion

$$dY_t = \nabla U(Y_t) dt + \sqrt{2d}dB_t = -\nabla \log \pi(Y_t) dt + \sqrt{2d}dB_t$$

Properties of the Langevin SDE (admitted)

Theorem

1. $\pi(x) \propto \exp(-U(x))$ is the *unique invariant* probability measure
2. For all $x \in \mathbb{R}^d$, $\lim_{t \rightarrow +\infty} \|\delta_x P_t - \pi\|_{TV} = 0$
3. For “nice” (i.e. sufficiently regular) functions f

$$\frac{1}{T} \int_0^T f(X_t) dt \xrightarrow{\mathbb{P}_x \text{-a.s.}} \pi(f) = \int f(x) \pi(dx)$$
$$\frac{1}{\sqrt{T}} \int_0^T (f(X_t) - \pi(f)) dt \xrightarrow{\mathbb{P}_x} \mathcal{N}(0, \sigma^2(\pi, f))$$

In other words, Langevin diffusion provides a way to sample any smooth distribution
Of course, this is a highly theoretical solution!

↪ *Discretized Langevin diffusion*

Metropolis-Adjusted Langevin Algorithm – MALA

Sample the diffusion paths using the Euler–Maruyama (EM) scheme:

$$X_{k+1} = X_k - \gamma_{k+1} \nabla U(X_k) + \sqrt{2\gamma_{k+1}} Z_{k+1} = X_k + \gamma_{k+1} \nabla \log \pi(X_k) + \sqrt{2\gamma_{k+1}} Z_{k+1}$$

where

- $(Z_k)_{k \geq 1}$ is a sequence of *i.i.d.* standard Gaussian random vectors
- $(\gamma_k)_{k \geq 1}$ is a sequence of stepsizes, which can either be held constant or be chosen to decrease to 0 at a certain rate

Remark: Can be viewed as a noisy (stochastic) gradient descent in some sense

Metropolis-Adjusted Langevin Algorithm:

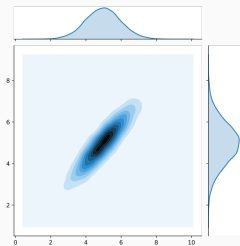
↪ Use this discretization scheme as a proposal in the MH algorithm

1. Propose $Y_{n+1} \sim \mathcal{N}(X_n + \gamma \nabla \log \pi(X_n), 2\gamma)$
2. Compute the acceptance ratio $\alpha(X_n, Y_{n+1})$
3. Accept/Reject the proposal

The Gibbs Sampler

3.1 Principle

Gibbs Sampler



Idea: Substitute the sampling of a r.v. in \mathbb{R}^d by the sampling of d r.d. in \mathbb{R} (or at least smaller)

Example (cf figure):

- Narrow shape in \mathbb{R}^2 that induce many rejection with a MH algorithm
- Larger possibilities in \mathbb{R}

Algorithm – Assumptions:

- \mathbb{X} can be decomposed into $\mathbb{X}_1 \times \dots \times \mathbb{X}_k$
We denote x^i the element of the i -th bloc, and $x^{(-i)}$ the vector x where i have been removed
- We know how to sample from the conditional distribution of the bloc i given the other while targeting π : $X_i | X_{(-i)} \sim \pi_i(x^i | x^{(-i)}) = \frac{\pi(x)}{\pi_{(-i)}(x)}$

Algorithm – Pseudo-Code: Given X_0 , iterate:

For $j = 1 \rightarrow k$,

For $n = 1 \rightarrow N$

$$X_{n+1}^j \sim \pi_j(\cdot | X_{n+1}^1, \dots, X_{n+1}^{j-1}, X_n^{j+1}, \dots, X_n^k)$$