

# Quang Nhat Nguyen Le

Delft, Netherlands

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## Experience

### SAM XL - Delft University of Technology

Delft, Netherlands

#### ROBOTICS SOFTWARE ENGINEER

Sep. 2024 - Present

- Develop automated intelligent systems for Smart Manufacturing
- Implement advance motion planning and perception for industrial robot manipulator
- Develop motion planning and navigation stack for autonomous mobile robot platforms
- Skills: Motion Planning, Industrial Manipulator (ABB/KUKA), Mobile Manipulator, CI/CD, ROS2, SLAM, Nav2

### Robert Bosch Campus for Research and Advanced Engineering

Renningen, Germany

#### AUTOMATED DRIVING DEVELOPER

Oct. 2022 - Mar. 2024

- Developed an end-to-end High Definition Map Construction Approach for Autonomous Driving Vehicles with Deep Learning approaches
- Developed end-to-end Visual Object Detection and Tracing pipeline with Deep Learning
- Integrated SOTA computer vision algorithms including Point Cloud Object Detection, Image Segmentation, BEV Feature Extraction, etc.
- Skills: Transformer-based Neural Networks, ROS/ROS2, Computer Vision, Deep Learning, LiDAR, real-time HD Map Construction, C++/Python, Sensor Data Processing, Gazebo, Tracking

### Robotics Lab, Rhine-Waal University of Applied Science

Kleve, Germany

#### RESEARCH ASSISTANT

Sep. 2019 - Apr. 2021

- Led a cross-functional team to develop autonomous small-scaled self-driving vehicles using low-power embedded systems.
- Deployed SLAM algorithms, localization, and state estimation for mobile robotics platforms
- Developed real-time solutions for Artificial Intelligence applications on edge devices
- Tutor the course "Introduction to Machine Learning"
- Tutor the course "Advanced Computer Aided-Design"
- Skills: ROS/ROS2, SLAM, Localization, EKF, Particle Filter, Object Detection, PyTorch, TensorFlow, TensorRT, OpenCV, Nvidia Jetson

### Robert Bosch Engineering and Business Solutions Limited

Ho Chi Minh City, Vietnam

#### TECHNICAL ANALYST FOR FOREIGN TRADE

Oct. 2017 - Mar. 2018

- Build up Master data for Foreign Trade share service included Harmonize system code, preferential determination, and export control for all products of Bosch worldwide
- Analyze Bill of Material of Bosch products for preferential calculation

### Samsung Electronic Ho Chi Minh CE Complex

Ho Chi Minh City, Vietnam

#### DIGITAL APPLIANCES ENGINEER- SENIOR STAFF

June. 2016 - Sep. 2017

- Design and develop new models of Samsung refrigerator for mass production
- Initiate and provides technical direction to enhance production methods, improve quality and reduce production costs
- Develop methods, programs and plans to predict, track, and report production costs during design development

## Education

### RWTH Aachen University

Aachen, Germany

#### M.SC IN ROBOTICS SYSTEM ENGINEERING

Oct. 2021 - Sept. 2023

- Thesis: Towards Mapless Autonomous Driving - Grade: 1.0
- Dean's List Awardee (Top 5% Student)

## Rhine-Waal University of Applied Sciences

M.SC IN BIONICS

Kleve, Germany

Mar. 2018 - Mar. 2021

- GPA: 1.7/1
- Thesis: Design and Development of Intelligent Autonomous Omni-directional Robot
- Association of German Engineers' award for excellent project

## Ho Chi Minh City University of Technology and Education

B.SC IN MECHANICAL ENGINEERING

Ho Chi Minh City, Vietnam

Sep. 2012 - Aug. 2016

- GPA: 8.1/10. Graduated with Distinction.

## Skills

|                      |  |
|----------------------|--|
| <b>Programming</b>   | Python, C++/C, MATLAB, Java, HTML/CSS/Js                         |
| <b>Systems</b>       | Linux, Git, Docker   |
| <b>Robotics</b>      | ROS2/ROS, Embedded Systems, Localization, SLAM                   |
| <b>AI Frameworks</b> | MMDetection, Pytorch, Tensorflow, Scikit-learn, TensorRT, TFLite |
| <b>CAD</b>           | Siemens NX, Solidworks, Inventor, AutoCad                        |
| <b>Languages</b>     | English (Fluent), German (Basic), Vietnamese (Native Language)   |
| <b>Office tools</b>  | Latex, Excel, Word, PowerPoint                                   |
| <b>Hobbies</b>       | Basketball, Guitar, Running                                      |

## Honors & Awards

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|------|--|---------------------------|
| 2023 | <b>Dean's List award excellent academic performance,</b>   | Aachen, Germany           |
| 2021 | <b>Association of German Engineers' award for excellent Master's Thesis,</b>                                     | Dusseldorf, Germany       |
| 2021 | <b>Vingroup Science and Technology Scholarship Program for Overseas Study for Master's and Doctoral Degrees,</b> | Hanoi, Vietnam            |
| 2021 | <b>3rd place at JRC AUTOTRAC 2020: a small-scale automated vehicles competition hosted by EU Science Hub,</b>    | Ispra, Italy              |
| 2016 | <b>Odon Vallet scholarship for excellent students in Vietnam,</b>  | Ho Chi Minh City, Vietnam |
| 2015 | <b>Excellent oral presentation at ICMAS 2015 conference, April 13th-14th, Paris, France,</b>                     | Paris, France             |
| 2014 | <b>Sunflower Mission Engineering and Technology Scholarship 2014,</b>  | Ho Chi Minh City, Vietnam |

## Publication

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|------|--|------------------|
| 2015 | <b>Quang Nhat Nguyen Le</b> , and Nguyen Truong Thinh: "Development of the bending actuator with Nafion-Pt IPMC tube". Advanced Materials Research. Vol. 1119. Trans Tech Publications, 2015.  | Paris, France    |
| 2020 | <b>Quang Nhat Nguyen Le</b> , Abir Bhattacharyya, Mamen Chembakasseril and Ronny Hartanto: "Real-time Sign Detection and Recognition for Self-driving Mini Rovers based on Template Matching and Hierarchical Decision Structure". Proceedings of the 12th International Conference on Agents and Artificial Intelligence. Vol. 1. SciTePress, 2020. | Valletta, Malta  |
| 2023 | <b>22 authors including Quang Nhat Nguyen Le</b> , Robotic Competitions to Design Future Transport Systems: The Case of JRC AUTOTRAC 2020. Transportation Research Record, 2677(2), 1165-1178  | Ispra, Italy     |
| 2024 | <b>Michalke, Thomas Paul, Waeldele, Steffen, Nguyen, Le Quang Nhat</b> , Occlusion Handling and SD Map Fusion for Online Map Generation. International Conference on Intelligent Transportation Systems (ITSC) 2024  | Edmonton, Canada |