

ONELOOP4PT

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February 28, 2009

Abstract

In this document, we caculate scalar One Loop four point function with complex internal mass.

1 The Form of One Loop Four Point in Paralell and Orthogonal Space

In Paralell and Orthogonal Space, the form of One Loop Four Point is

$$D_0 = 2 \int_{-\infty}^{\infty} dl_0 dl_1 dl_2 \int_0^{\infty} dl_{\perp} \frac{1}{P_1 P_2 P_3 P_4}$$

Here

$$\begin{aligned} P_1 &= (l_0 + q_{10})^2 - l_1^2 - l_2^2 - l_{\perp}^2 - m_1^2 + i\varepsilon \\ P_2 &= (l_0 + q_{20})^2 - (l_1 + q_{21})^2 - l_2^2 - l_{\perp}^2 - m_2^2 + i\varepsilon \\ P_3 &= (l_0 + q_{30})^2 - (l_1 + q_{31})^2 - (l_2 + q_{32})^2 - l_{\perp}^2 - m_3^2 + i\varepsilon \\ P_4 &= l_0^2 - l_1^2 - l_2^2 - l_{\perp}^2 - m_4^2 + i\varepsilon \end{aligned}$$

(1)

And

$$\begin{aligned} q_1^2 &= q_{10}^2. \\ q_2^2 &= q_{20}^2 - q_{21}^2 \\ q_3^2 &= q_{30}^2 - q_{31}^2 - q_{32}^2 \\ q_4^2 &= 0. \\ l^2 &= l_0^2 - l_1^2 - l_2^2 - l_{\perp}^2 \end{aligned}$$

(2)

$m_i^2 = Re(m_k^2) - i\Gamma_k$ are complex internal mass.

2 The partial fraction

We have

$$\begin{aligned}
\frac{1}{P_1 P_2 P_3 P_4} &= \frac{1}{P_1(P_2 - P_1)(P_3 - P_1)(P_4 - P_1)} \\
&+ \frac{1}{P_2(P_1 - P_2)(P_3 - P_2)(P_4 - P_2)} \\
&+ \frac{1}{P_3(P_1 - P_3)(P_2 - P_3)(P_4 - P_3)} \\
&+ \frac{1}{P_4(P_1 - P_4)(P_2 - P_4)(P_3 - P_4)} \\
&= \sum_{k=1}^4 \frac{1}{P_k \prod_{l=1, l \neq k}^4 (P_l - P_k)}
\end{aligned} \tag{3}$$

here

$$\begin{aligned}
P_k &= (l_0 + q_{k0})^2 - (l_1 + q_{k1})^2 - (l_2 + q_{k2})^2 - l_\perp - m_k^2 + i\varepsilon \\
P_l &= (l_0 + q_{l0})^2 - (l_1 + q_{l1})^2 - (l_2 + q_{l2})^2 - l_\perp - m_l^2 + i\varepsilon \\
P_k - P_l &= 2(q_{l0} - q_{k0})l_0 - 2(q_{l1} - q_{k1})l_1 - 2(q_{l2} - q_{k2})l_2 + q_l^2 - q_k^2 - (m_l^2 - m_k^2) \\
&= a_{lk}l_0 + b_{lk}l_1 + c_{lk}l_2 + q_l^2 - q_k^2 - (m_l^2 - m_k^2).
\end{aligned} \tag{4}$$

It is important to note that a_{lk}, b_{lk}, c_{lk} in R .

From now, we obtain

$$\begin{aligned}
D_0 &= 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dl_0 dl_1 dl_2 \int_0^{\infty} dl_\perp \\
&\frac{1}{\left[(l_0 + q_{k0})^2 - (l_1 + q_{k1})^2 - (l_2 + q_{k2})^2 - l_\perp - m_k^2 + i\varepsilon \right]} \\
&\frac{1}{\prod_{l=1, l \neq k}^4 (a_{lk}l_0 + b_{lk}l_1 + c_{lk}l_2 + q_l^2 - q_k^2 - (m_l^2 - m_k^2))}
\end{aligned} \tag{5}$$

We make a shift

$$\begin{aligned}
l_0 &\rightarrow l_0 + q_{k0} \\
l_1 &\rightarrow l_1 + q_{k1} \\
l_2 &\rightarrow l_2 + q_{k2}
\end{aligned} \tag{6}$$

The Jacobian of this shift is 1. The integration region not change and the form of D_0 now look as

$$\begin{aligned}
D_0 &= 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dl_0 dl_1 dl_2 \int_0^{\infty} dl_\perp \\
&\frac{1}{\left[l_0^2 - l_1^2 - l_2^2 - l_\perp^2 - m_k^2 + i\varepsilon \right]} \frac{1}{\prod_{l=1, l \neq k}^4 (a_{lk}l_0 + b_{lk}l_1 + c_{lk}l_2 + d_{lk})}
\end{aligned} \tag{7}$$

Here

$$\begin{aligned}
& -a_{lk}q_{k0} - b_{lk}q_{k1} - c_{lk}q_{k2} + q_l^2 - q_k^2 - (m_l^2 - m_k^2) = \\
& -2(q_{l0} - q_{k0})q_{k0} + 2(q_{l1} - q_{k1})q_{k1} + 2(q_{l2} - q_{k2})q_{k2} + q_l^2 - q_k^2 - (m_l^2 - m_k^2) \\
& q_l^2 + q_k^2 - 2q_lq_k - (m_l^2 - m_k^2). \tag{9}
\end{aligned}$$

SUMMARIZE:

$$\begin{aligned}
D_0 &= 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dl_0 dl_1 dl_2 \int_0^{\infty} dl_{\perp} \\
& \frac{1}{\left[l_0^2 - l_1^2 - l_2^2 - l_{\perp}^2 - m_4^2 + i\varepsilon \right]} \frac{1}{\prod_{l=1, l \neq k} (a_{lk}l_0 + b_{lk}l_1 + c_{lk}l_2 + d_{lk})}.
\end{aligned}$$

And

$$a_{lk} = 2(q_{l0} - q_{k0})$$

$$b_{lk} = 2(q_{l1} - q_{k1})$$

$$c_{lk} = 2(q_{l2} - q_{k2})$$

$$d_{lk} = (q_l - q_k)^2 - (m_l^2 - m_k^2)$$

Important note

$$a_{lk}, b_{lk}, c_{lk} \text{ in } R; \quad d_{lk} \text{ in } C.$$

(9)

3 Linearize in x and the x — integration

In this section, we take x — integration by residue theorem. To do that, we have to linearize D_0 in x , or take a shift

$$\begin{aligned}
l_0 &= x + z \\
l_1 &= y \\
l_2 &= x \\
l_{\perp} &= t.
\end{aligned}$$

The Jacobian of this shift is

$$|J| = \left| \frac{\delta(l_0, l_1, l_2, l_{\perp})}{\delta(z, y, x, t)} \right| = 1. \tag{10}$$

For this shift, one obtain

$$D_0 = 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dx dy dz \int_0^{\infty} dt \frac{1}{\left[2xz - z^2 - y^2 - t^2 - m_k^2 + i\varepsilon\right]} \frac{1}{\prod_{l=1, l \neq k} (a_{lk}z + b_{lk}y + AC_{lk}x + d_{lk})}. \quad (12)$$

Here $AC_{lk} = a_{lk} + c_{lk}$

3.1 The x - integration

The poles of the D_0 integrand are

$$\begin{aligned} x_0 &= \frac{z^2 + y^2 + t^2 + m_k^2 - i\varepsilon}{2z} \\ x_l &= \frac{-a_{lk}z - b_{lk}y - d_{lk}}{AC_{lk}} \end{aligned} \quad (12)$$

It is important to note that

$$\begin{aligned} \text{Im}(x_0) &= \frac{-\Gamma_k - \varepsilon}{2z} \\ \text{Im}(x_l) &= \frac{-d_{lk}}{AC_{lk}} \end{aligned} \quad (13)$$

We now separate D_0 into form

$$D_0 = D_0^+ + D_0^-$$

with

$$\begin{aligned} D_0^+ &= 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dx dy \int_0^{\infty} dz \int_0^{\infty} dt \frac{1}{\left[2xz - z^2 - y^2 - t^2 - m_k^2 + i\varepsilon\right]} \frac{1}{\prod_{l=1, l \neq k} (a_{lk}z + b_{lk}y + AC_{lk}x + d_{lk})}. \\ D_0^- &= 2 \sum_{k=1}^4 \int_{-\infty}^{\infty} dx dy \int_{-\infty}^0 dz \int_0^{\infty} dt \frac{1}{\left[2xz - z^2 - y^2 - t^2 - m_k^2 + i\varepsilon\right]} \frac{1}{\prod_{l=1, l \neq k} (a_{lk}z + b_{lk}y + AC_{lk}x + d_{lk})}. \end{aligned} \quad (14)$$

3.1.1 For D_0^+

We close the upper contour in the x plane and D_0^+ is evaluated

$$D_0^+ = 4\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \int_{-\infty}^{\infty} dy \int_0^{\infty} dz \int_0^{\infty} dt \operatorname{Res} [F(x, y, z, t), x_l] \quad (15)$$

or

$$D_0^+ = 4\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \int_0^{\infty} dy \int_0^{\infty} dz \int_0^{\infty} dt \frac{f_{lk}^+ (1 - \delta(AC_{lk}))}{\left[2x_l z - z^2 - y^2 - t^2 - m_k^2 + i\varepsilon \right]} \frac{1}{AC_{lk} \prod_{m=1, m \neq l, k} (a_{mk} z + b_{mk} y + AC_{mk} x + d_{mk})} \quad (16)$$

With

$$x_l = \frac{-a_{lk} z - b_{lk} y - d_{lk}}{AC_{lk}} \quad (17)$$

From now we obtain

$$D_0^+ = 2\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \frac{1}{\prod_{l=1, l \neq l, k}^4 AC_{lk}} \int_{-\infty}^{\infty} dy \int_0^{\infty} dz \int_0^{\infty} dt \frac{1}{\prod_{m=1, m \neq l, k} (A_{mlk} z + B_{mlk} y + C_{mlk})} \frac{f_{lk}^+ (1 - \delta(AC_{lk}))}{\left[\left(1 - \frac{2a_{lk}}{AC_{lk}} \right) z^2 - \frac{2b_{lk}}{AC_{lk}} yz - \frac{2d_{lk}}{AC_{lk}} - y^2 - t^2 - m_k^2 + i\varepsilon \right]}$$

here

$$\begin{aligned} A_{mlk} &= \frac{a_{mk}}{AC_{mk}} - \frac{a_{lk}}{AC_{lk}} \\ B_{mlk} &= \frac{b_{mk}}{AC_{mk}} - \frac{b_{lk}}{AC_{lk}} \\ C_{mlk} &= \frac{d_{mk}}{AC_{mk}} - \frac{d_{lk}}{AC_{lk}} \end{aligned}$$

3.1.2 For D_0^-

We close the lower contour in the x plane and D_0^- is evaluated

$$D_0^- = -2\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \frac{1}{\prod_{l=1, l \neq l, k}^4 AC_{lk}} \int_{-\infty}^{\infty} dy \int_0^{\infty} dz \int_0^{\infty} dt \frac{1}{\prod_{m=1, m \neq l, k} (A_{mlk} z + B_{mlk} y + C_{mlk})} \frac{f_{lk}^- (1 - \delta(AC_{lk}))}{\left[\left(1 - \frac{2a_{lk}}{AC_{lk}} \right) z^2 - \frac{2b_{lk}}{AC_{lk}} yz - \frac{2d_{lk}}{AC_{lk}} - y^2 - t^2 - m_k^2 + i\varepsilon \right]}$$

here

$$\begin{aligned} A_{mlk} &= \frac{a_{mk}}{AC_{mk}} - \frac{a_{lk}}{AC_{lk}} \\ B_{mlk} &= \frac{b_{mk}}{AC_{mk}} - \frac{b_{lk}}{AC_{lk}} \\ C_{mlk} &= \frac{d_{mk}}{AC_{mk}} - \frac{d_{lk}}{AC_{lk}} \end{aligned}$$

SUMMARIZE:

$$\begin{aligned} D_0 &= D_0^+ + D_0^- \\ \text{and} \\ D_0^+ &= 2\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \frac{1}{\prod_{l=1, l \neq l, k}^4 AC_{lk}} \int_{-\infty}^{\infty} dy \int_0^{\infty} dz \int_0^{\infty} dt \frac{1}{\prod_{m=1, m \neq l, k} (A_{mlk}z + B_{mlk}y + C_{mlk})} \\ &\quad \frac{f_{lk}^+ (1 - \delta(AC_{lk}))}{\left[\left(1 - \frac{2a_{lk}}{AC_{lk}} \right) z^2 - \frac{2b_{lk}}{AC_{lk}} yz - \frac{2d_{lk}}{AC_{lk}} z - y^2 - t^2 - m_k^2 + i\varepsilon \right]} \\ D_0^- &= -2\pi i \sum_{k=1}^4 \sum_{l=1, l \neq k}^4 \frac{1}{\prod_{l=1, l \neq l, k}^4 AC_{lk}} \int_{-\infty}^{\infty} dy \int_{-\infty}^0 dz \int_0^{\infty} dt \frac{1}{\prod_{m=1, m \neq l, k} (A_{mlk}z + B_{mlk}y + C_{mlk})} \\ &\quad \frac{f_{lk}^- (1 - \delta(AC_{lk}))}{\left[\left(1 - \frac{2a_{lk}}{AC_{lk}} \right) z^2 - \frac{2b_{lk}}{AC_{lk}} yz - \frac{2d_{lk}}{AC_{lk}} z - y^2 - t^2 - m_k^2 + i\varepsilon \right]} \end{aligned} \quad (18)$$

here

$$\begin{aligned} A_{mlk} &= \frac{a_{mk}}{AC_{mk}} - \frac{a_{lk}}{AC_{lk}} \\ B_{mlk} &= \frac{b_{mk}}{AC_{mk}} - \frac{b_{lk}}{AC_{lk}} \\ C_{mlk} &= \frac{d_{mk}}{AC_{mk}} - \frac{d_{lk}}{AC_{lk}} \end{aligned}$$

4 The y integration

The next we are going to take y integration. To do that we have to perform Wick rotation $t \rightarrow it$ then linearize in y .

4.1 t- wick rotation

To linearize in y , the sign of y^2 and t^2 must be opsite. To do that we have to perform t- wick rotation.

The poles of t - integrand are

$$t_{1,2} = \pm \sqrt{\left(1 - \frac{2a_{lk}}{AC_{lk}}\right)z^2 - \frac{2b_{lk}}{AC_{lk}}yz - \frac{2d_{lk}}{AC_{lk}}z - y^2 - m_k^2 + i\varepsilon} \quad (19)$$

Because

$$\text{Im}\left[-\frac{2d_{lk}}{AC_{lk}}z - m_k^2 + i\varepsilon\right] > 0. \quad (20)$$

then $t_{1,2}$ locate in the first or the third quarter t - complex plane.

We have

$$\oint f(t^2)dt = \left\{ \int_0^R + \int_{C_k} + \int_{-iR}^0 \right\} f(t^2)dt = 0 \quad (21)$$

When R go to ∞ , one obtain

$$\left\{ \int_0^\infty + \int_{-i\infty}^0 \right\} f(t^2)dt = 0. \quad (22)$$

or

$$\int_0^\infty f(t^2)dt = - \int_{-i\infty}^0 f(t^2)dt \quad (23)$$

Making t - rotation, one obtain

$$\int_0^\infty f(t^2)dt = -i \int_0^\infty f(-t^2)dt \quad (24)$$