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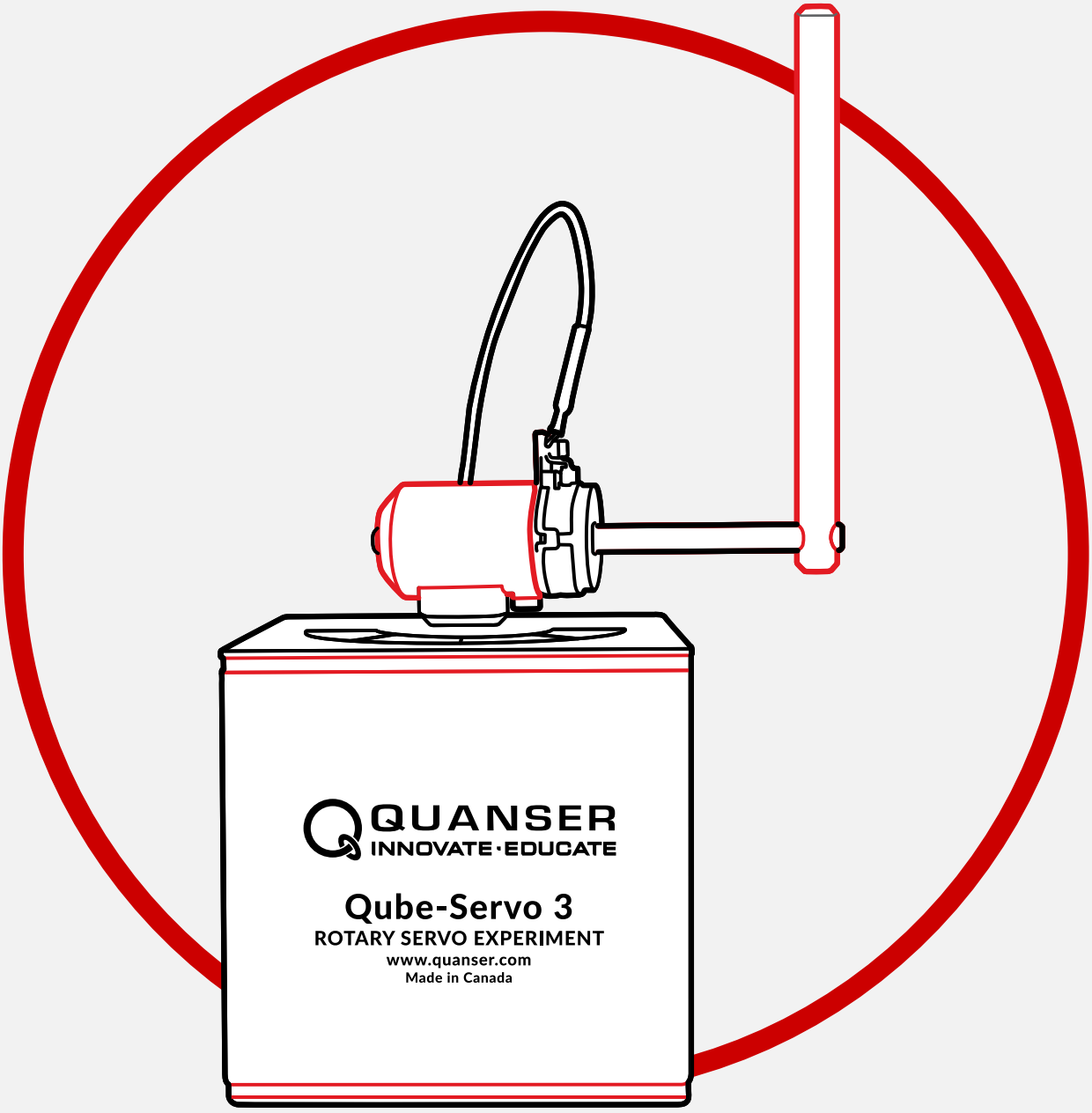

Qube-Servo 3

Hardware Interfacing

V1.2 – 27th February 2025

For more information on the solutions Quanser offers,
please visit the web site at: http://www.quanser.com

Quanser Consulting Inc. info@quanser.com
119 Spy Court Phone : 19059403575
Markham, Ontario Fax : 19059403576
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Caution

This equipment is designed to be used for educational and research purposes and is not intended for use by the public. The user is responsible for ensuring that the equipment will be used by technically qualified personnel only. Users are responsible for certifying any modifications or additions they make to the default configuration.

FCC Notice This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.
Note: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment.

Industry Canada Notice This Class A digital apparatus complies with CAN ICES-3 (A). Cet appareil numérique de la classe A est conforme à la norme NMB-3 (A) du Canada.
Japan VCCI Notice This is a Class A product based on the standard of the Voluntary Control Council for Interference (VCCI). If this equipment is used in a domestic environment, radio interference may occur, in which case the user may be required to take corrective actions.

この装置は、クラス A 情報技術装置です。この装置を家庭環境で使用すると電波妨害を引き起こすことがあります。この場合には使用者が適切な対策を講ずるよう要求されることがあります。 VCCI-A

Waste Electrical and Electronic Equipment (WEEE)
This symbol indicates that waste products must be disposed of separately from municipal household waste, according to Directive 2012/19/EU of the European Parliament and the Council on waste electrical and electronic equipment (WEEE). All products at the end of their life cycle must be sent to a WEEE collection and recycling center. Proper WEEE disposal reduces the environmental impact and the risk to human health due to potentially hazardous substances used in such equipment. Your cooperation in proper WEEE disposal will contribute to the effective usage of natural resources.

电子信息产品污染控制管理办法 (中国 RoHS)

中国客户Quanser Consulting Inc. 关于关于限制在电子电气设备中使用某些有害成分的指令 (RoHS)。

CE Compliance CE

This product meets the essential requirements of applicable European Directives as follows:
- 2014/30/EU; Electromagnetic Compatibility Directive (EMC)

Warning: This is a Class A product. In a domestic environment this product may cause radio interference, in which case the user may be required to take adequate measures.

Qube-Servo 3 – Application Guide

Hardware Interfacing

What is Hardware Interfacing?

Before getting into lab content related to modeling, measuring and controlling the motor in the Qube-Servo 3 device, it is essential to understand how to interface to it. Often, what changes from device to device is the physical characteristics of the device as well as the hardware and software interface to the device. This is a starting point for any hardware experiment.

Background

Prior to starting this lab, please review the following concept reviews (should be located in Documents/Quanser/4_concept_reviews/),

- Concept Review – Modeling & IO → Rotary Sensors (Rotary Encoders Section)

Getting started

The goal of this lab is to get you familiarized with the Qube-Servo 3 hardware. Equipped with a motor, encoder, tachometer and varying loads, it serves as a fundamental system to understand the basics of actuation, sensing, modeling and control. Before you begin this lab, ensure that the following criteria are met.

- If using a physical Qube-Servo 3, make sure it has been setup and tested. See the Qube-Servo 3 Quick Start Guide for details on this step. Make sure the inertia disc load is attached to the Qube-Servo 3.
- If using the virtual Qube-Servo 3, make sure you have Quanser Interactive Labs open in the Qube 3 - DC Motor → Servo Workspace.
- You have the Qube-Servo 3 User Manual. It will be required for some of the exercises.
- You are familiar with the basics of Simulink. See the Simulink Onramp for more help with getting started with Simulink.

QUARC Software

The QUARC software is used with Simulink to interact with the hardware of the Qube-Servo 3 system. QUARC is used to drive the DC motor and read angular position of the disc. Creating this will be highlighted in the lab procedure. In general, the basic steps to create a Simulink model with QUARC in order to interact with the Qube-Servo 3 hardware are,

1. Make a Simulink model that interacts with your installed data acquisition device using blocks from the *QUARC Targets* library.
2. Build the real-time code.
3. Execute the code.

Type `doc quarc` in MATLAB to access QUARC documentation and demos.