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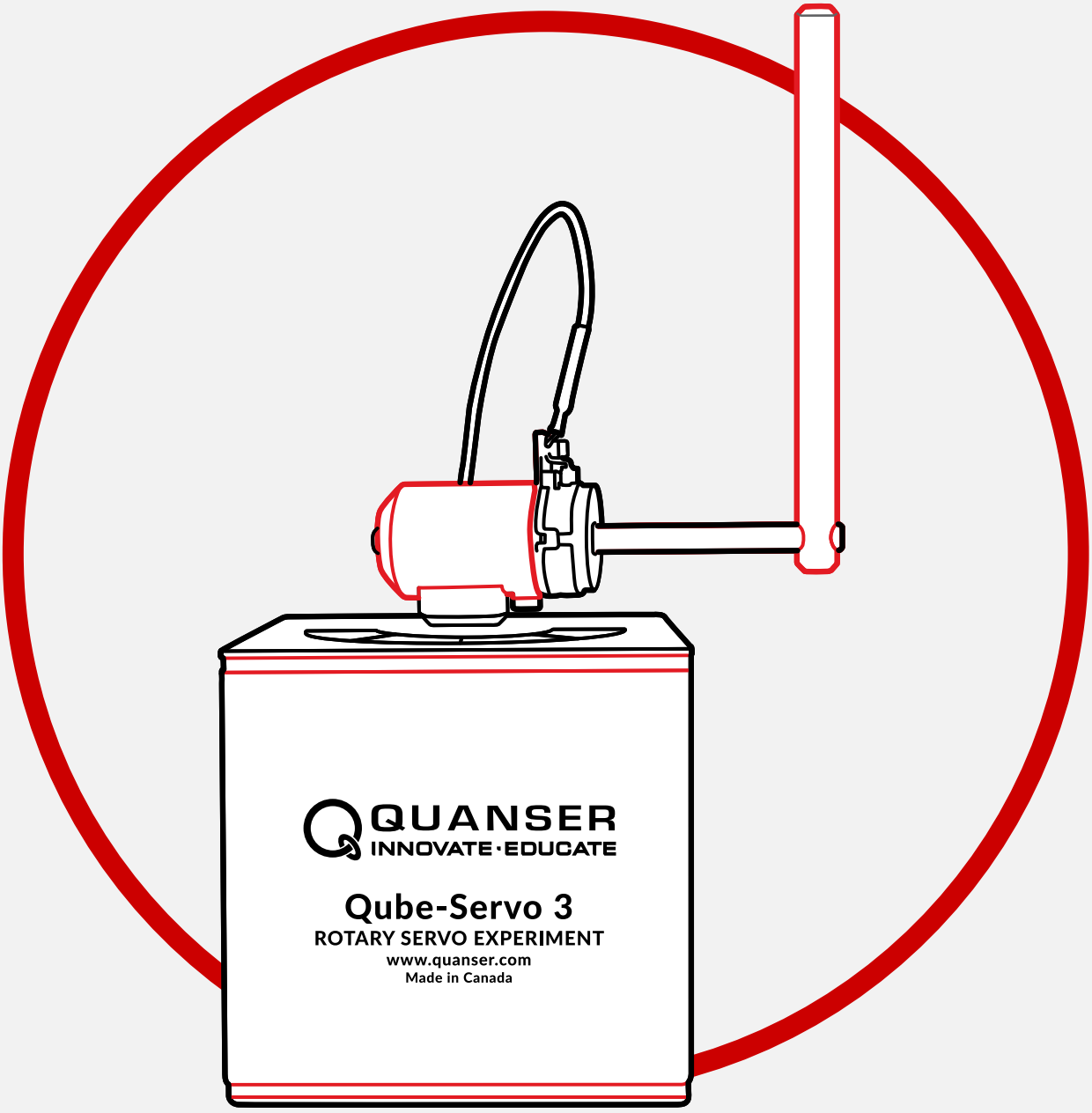

Qube-Servo 3

Parameter Estimation

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For more information on the solutions Quanser offers,
please visit the web site at: http://www.quanser.com

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Caution

This equipment is designed to be used for educational and research purposes and is not intended for use by the public. The user is responsible for ensuring that the equipment will be used by technically qualified personnel only. Users are responsible for certifying any modifications or additions they make to the default configuration.

FCC Notice This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.
Note: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment.

Industry Canada Notice This Class A digital apparatus complies with CAN ICES-3 (A). Cet appareil numérique de la classe A est conforme à la norme NMB-3 (A) du Canada.
Japan VCCI Notice This is a Class A product based on the standard of the Voluntary Control Council for Interference (VCCI). If this equipment is used in a domestic environment, radio interference may occur, in which case the user may be required to take corrective actions.

この装置は、クラス A 情報技術装置です。この装置を家庭環境で使用すると電波妨害を引き起こすことがあります。この場合には使用者が適切な対策を講ずるよう要求されることがあります。 VCCI-A

Waste Electrical and Electronic Equipment (WEEE)
This symbol indicates that waste products must be disposed of separately from municipal household waste, according to Directive 2012/19/EU of the European Parliament and the Council on waste electrical and electronic equipment (WEEE). All products at the end of their life cycle must be sent to a WEEE collection and recycling center. Proper WEEE disposal reduces the environmental impact and the risk to human health due to potentially hazardous substances used in such equipment. Your cooperation in proper WEEE disposal will contribute to the effective usage of natural resources.

电子信息产品污染控制管理办法 (中国 RoHS)

中国客户Quanser Consulting Inc. 关于关于限制在电子电气设备中使用某些有害成分的指令 (RoHS)。

CE Compliance

This product meets the essential requirements of applicable European Directives as follows:
- 2014/30/EU; Electromagnetic Compatibility Directive (EMC)

Warning: This is a Class A product. In a domestic environment this product may cause radio interference, in which case the user may be required to take adequate measures.

Qube-Servo 3 – Application Guide

Parameter Estimation

What is Parameter Estimation?

Parameter estimation is the process of determining the key numerical values that describe a DC motor's behavior in mathematical models. These parameters can be found through system identification, that is, using input-output data to mathematically determine parameters. In the case of a DC motor, it is possible to estimate some of the motor parameters by simply looking at the current, voltage and speed response of the motor. Understanding and calculating these parameters is crucial because rather than using general datasheet values, they help us have a more accurate prediction on how the motor will behave in different situations, design appropriate control systems and simulate motor performance before building real systems.

Background

This is one of multiple labs describing how to model a servomotor. Any of these labs can be done in any order. These modeling labs include modeling through frequency response, step response, parameter estimation, block diagrams and state space.

Prior to starting this lab, please review the following concept reviews (should be located in Documents/Quanser/4_concept_reviews/),

- Concept Review –Modeling & IO → Modeling (Fundamental DC Motor Concepts section). You will need to understand the motor parameters as well as the mechanical and electrical equations.

Getting started

In this lab you will use the parameters found in the user manual and DC motor equations of motion from the concept review to model the system response of the Qube-Servo 3. You will calculate the motor resistance, the torque constant/back EMF and the moment of inertia of the system by running the Qube under different conditions and observing its outputs.

Ensure you have completed the following labs

- **Hardware Interfacing Lab**
- **Filtering Lab**

Before you begin this lab, ensure that the following criteria are met.

- If using a physical Qube-Servo 3, make sure it has been setup and tested. See the Qube-Servo 3 Quick Start Guide for details on this step. Make sure the inertia disc load is attached to the Qube-Servo 3.
- If using the virtual Qube-Servo 3, make sure you have Quanser Interactive Labs open in the Qube 3 - DC Motor → Servo Workspace.
- **You have the Qube-Servo 3 User Manual.** It will be required to find relevant system information for some of the exercises. It should be located in the same folder as this document.
- You are familiar with the basics of Simulink. See the Simulink Onramp for more help with getting started with Simulink.