Streaming Machine Learning (SML)

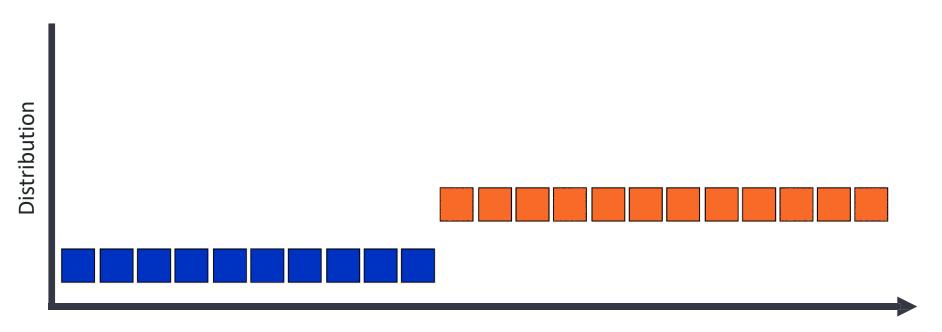
Alessio Bernardo & Emanuele Della Valle 14-03-2022

Part II

Concept Drift

Credits

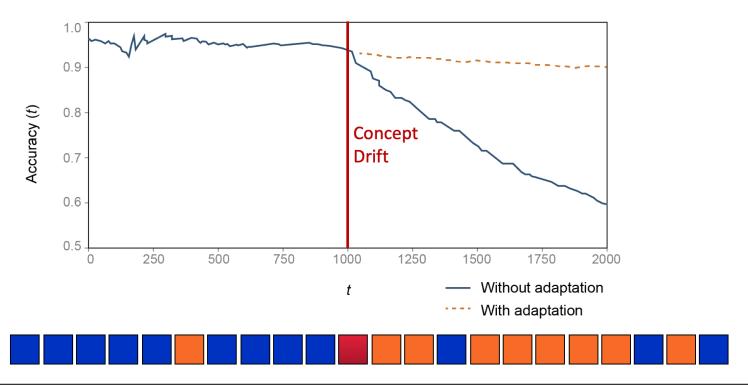
- Albert Bifet DATA STREAM MINING 2020-2021 course at Telecom Paris
- Alessio Bernardo & Emanuele Della Valle



Time

Source: A. Bifet, R. Gavaldà, G. Holmes, B. Pfahringer Machine Learning for Data Streams: with Practical Examples in MOA. The MIT Press (March 2, 2018)





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Problem

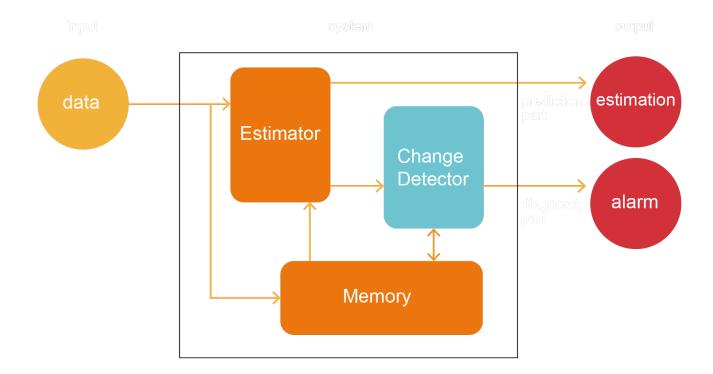
Given an input sequence $X_1, X_2, ..., X_t$ we want to output at instant t an alarm signal if there is a distribution change and also a prediction \hat{X}_{t+1} minimizing the prediction error:

$$\left|\widehat{X}_{t+1}-X_{t+1}\right|$$

Outputs

- an estimation of some important parameters of the input distribution, and
- a signal alarm indicating that distribution changes has recently occurred

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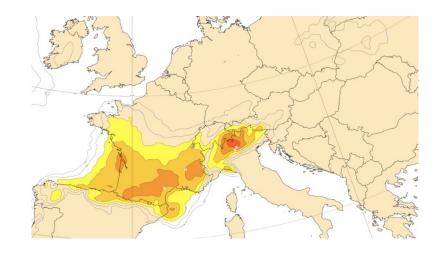


Bifet, A. and Gavaldá, R. Adaptive Learning from evolving data streams. In International Symposium on Intelligent Data Analysis (pp.249-260). Springer 2009, August.

Example

Weather forecast

- The chaotic nature of the atmosphere leads to continuous and sudden weather changes (concept drifts)
- Weather forecast models must detect these changes and adapt to them, without be retrained from scratch



https://www.meteosvizzera.admin.ch/home/attualita/meteosvizzera-blog.subpage.html/it/data/blogs/2021/8/efi---extreme-forecast-index.html

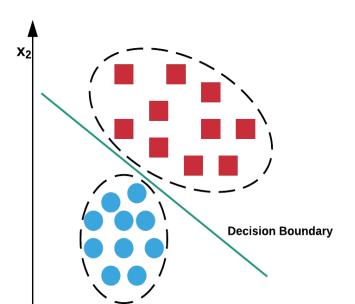
Given an input sequence $X_1, X_2, ..., X_t$ to classify X_t we need to know the prior probability of observing each class, p(y), and the conditional probability of observing X_t given each class, $p(X_t|y)$. Using the Bayes' theorem:

$$p(y|X_t) = \frac{p(y) * p(X_t|y)}{p(X_t)}$$

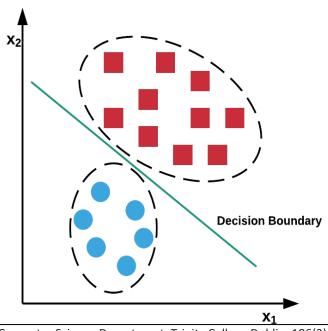
it is possible to compute the probability that X_t is an instance of class y, where $p(X_t)$ is the probability of observing X_t . Since the latter is constant for all the classes y, it can be ignored.

 X_1

Original distribution

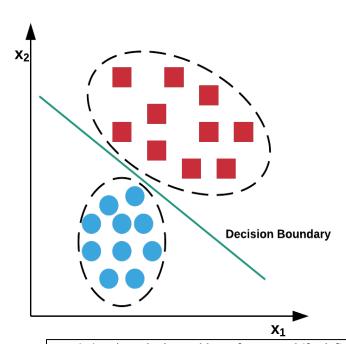


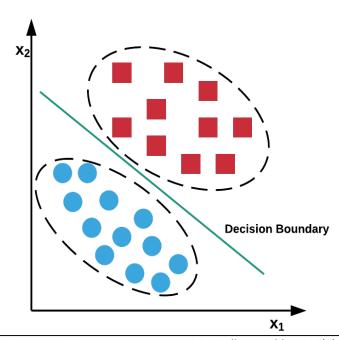
p(y) changes



Original distribution

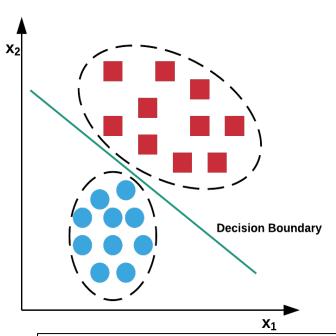


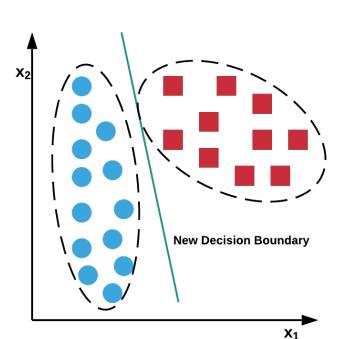




Original distribution



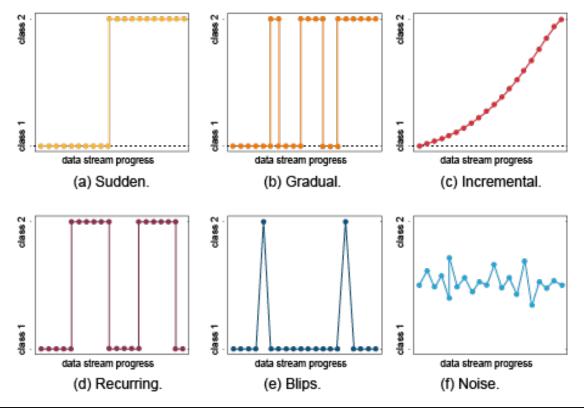




Example

 Consider the case of predicting extreme weather phenomena occurrences based on atmospheric pressure and temperature. Usually, extreme weather phenomena occur in the case of low atmospheric pressure and high temperature.

- **p(y) concept drift:** in the XX century, the distribution of atmospheric pressure and temperature did not change, but the extreme weather phenomena were more frequent.
- p(X|y) concept drift: in the first two decades of XXI century, the atmospheric pressure and air temperature conditions, in which these phenomena occur, also started to change, but not so drastically to move the decision boundary we use for predicting them.
- **p(y|X) concept drift:** due to the on going climate change, these phenomena start occurring more frequently with higher atmospheric pressure and lower temperature. As a consequence, we have to update the decision boundary to keep an high predictive performance.



Concept Drift vs Anomaly Detection

Concept Drift question: "Is yesterday's model capable of explaining today's data?"

Anomaly detection question: "Do these samples conform the normal ones?"

Monitoring the input distribution

Pro:

Does not require supervised samples

Cons:

 Difficult to design sequential detection tool, i.e., change detection tests when streams are multivariate and distribution unknown

Monitoring the input distribution - CUmulative SUM Test (CUSUM)

- It gives an alarm when the mean of the input data is significantly different from zero.
- It is memoryless, and its accuracy depends on the choice of parameters v and h.
- It is a one sided test: it assumes that changes can happen only in one direction of the statistics, detecting only increases.

$$g_0 = 0$$

$$g_t = \max(0, g_{t-1} + (x_t - \hat{x}) - v)$$

$$if \ g_t > h \text{ then Alarm}$$

Lee, S., Ha, J., Na, O., & Na, S. (2003). The cusum test for parameter change in time series models. Scandinavian Journal of Statistics, 30(4), 781-796.

Monitoring the input distribution - Page Hinkley Test

- It is designed to detect a change in the average of a Gaussian signal and monitors the difference between g_t and G_t .
- Its accuracy depends on the choice of parameters v and h.

$$g_0 = 0$$

 $g_t = g_{t-1} + (x_t - \hat{x}) - v$
 $G_t = \min(g_t, G_{t-1}) *$
 $if \ g_t - G_t > h \text{ then Alarm } *$

* When the signal is decreasing, we should use:

$$G_t = \max(g_t, G_{t-1})$$

if $G_t - g_t > h$ then Alarm

Mouss, H., et al. Test of page-hinckley, an approach for fault detection in an agro-alimentary production system. IEEE Asian Control Conference 2004

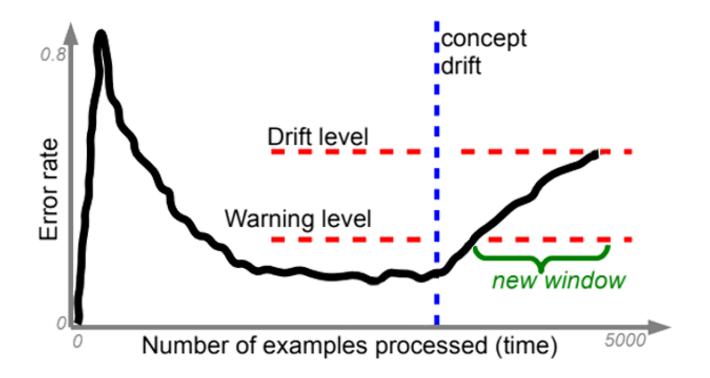
Monitoring the classification error

Pro:

- the most straightforward figure of merit to monitor
- changes in p_t prompt adaptation only when performances are affected

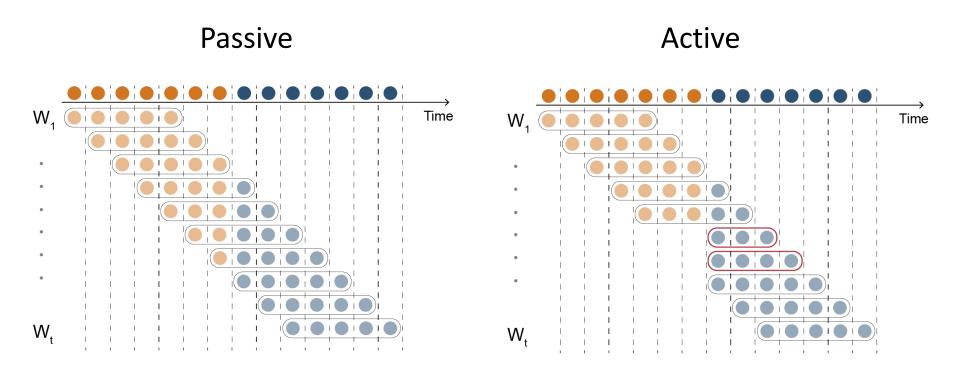
Cons:

Concept drift detection from supervised samples only



Gama, et. al, Learning with Drift Detection, SBIA 2004, Springer.

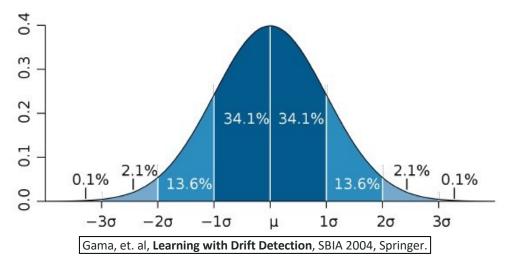
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Gama, João, et al. A survey on concept drift adaptation. ACM computing surveys (CSUR) 46.4 (2014): 1-37.

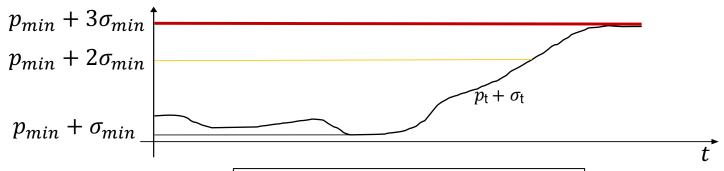
Monitoring the classification error – Drift Detection Method (DDM)

- Detect concept drift as an outlier in the classification error.
- In stationary conditions error decreases, so look for outliers in the tails.



Monitoring the classification error – Drift Detection Method (DDM)

- 1. Compute the classification error mean p_t and $\sigma_t = \sqrt{\frac{p_t(1-p_t)}{t}}$
- 2. Let p_{\min} and σ_{\min} the minimum p_t and σ_t values seen until now
- 3. Raise a warning when $p_{\rm t}+\sigma_{\rm t}>p_{\rm min}+2*\sigma_{\rm min}$
- 4. Raise a **change** when $p_t + \sigma_t > p_{\min t} + 3 * \sigma_{\min t}$



Gama, et. al, Learning with Drift Detection, SBIA 2004, Springer.

Monitoring the classification error – Early Drift Detection Method (EDDM)

- It considers the distance between two errors classification instead of considering only the number of errors.
- While the learning method is learning, it will improve the predictions and the distance between two errors will increase.
- When a drift occurs, the distance between two errors will decrease.
- Compute the average distance between 2 errors and its std, and look for outliers in the tails.

Monitoring the classification error – ADaptive data stream sliding WINdow (ADWIN)

- An adaptive sliding window whose size is recomputed online according to the rate of change observed.
- It does not need parameters

Monitoring the classification error – ADaptive data stream sliding WINdow (ADWIN)

$$W = 101010110111111$$
 $W_0 = 1 W_1 = 01010110111111$

$$W_0 = \boxed{10} W_1 = \boxed{1010110111111}$$

$$W_0 = \boxed{101} W_1 = \boxed{010110111111}$$

••••••

$$W_0 = 101010110 W_1 = 1111111$$

$$|\hat{\mu}_{W_0} - \hat{\mu}_{W_1}| \geq \epsilon_c$$
: CHANGE DETECTED!

A. Bifet, R Gavalda: **Learning from Time-Changing Data with Adaptive Windowing**. SDM 2007

QUIZ

- 1. What is concept drifts?
 - a. Sometimes few samples are different from the others
 - b. A change in the model performances
 - c. A change of the new data underlying statistics
- 2. Why is so important detect concept drift occurrences?
 - a. Because the model risks being trained on data no longer representative and must be adapted
 - b. To be able to raise an alarm, so the user can decide to take some actions or not
 - c. It is not important. A SML model is always able to adapt to concept drifts without any detectors

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EXERCISE 2: Concept Drift LAB 2: Concept Drift Detectors