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Online	supporting	inform	ation	tor

- Analysing individual specialization and flexibility in predator
- hunting mode and its effect on hunting success using an online
- multiplayer videogame

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### S1. Materials and methods

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#### Behavioural traits measurements

We quantified the predator's average travel speed as the average number of meters per second traveled during a match. For the rate of space covered, grids with squares of 16 m<sup>2</sup> covering the entire playable surface area were drawn for all game environments. These grids are invisible to the 10 player, but are drawn by the videogame developer to calculate quantify this behaviour. Similar 11 to the open-field test for rodents (Montiglio et al. 2010), the number of times a predator entered 12 a square on the grid was recorded, however, it was not possible to know which specific square 13 was visited. Based on this data, we could divide the number of times a square was visited by the 14 match duration to obtain the rate of space covered. For the proportion of time spent ambushing 15 prey, circles of 9-meter radiuses were drawn around all sites (the circles' center) where the predator brought prey to be consumed. Predators in DBD wait for other prey to come save their conspecifics 17 to ambush them. For each event, the time (in seconds) a predator spent monitoring inside the area of a circle was recorded. We could then sum the amount of time spent ambushing during a match and divide it by the total amount of time a match lasted (in seconds) to have the proportion of time spent ambushing. Lastly, the time before the first capture was calculated as the amount 21 of seconds elapsed before a predator consumed his first prey, divided by the match duration. 22

## Principal component analysis

We computed the PCA using packages "FactoMineR" (Lê et al. 2008) and "factoextra" (Kassambara and Mundt 2020) in the R software version 4.0.4 (R Core Team, 2021), under a Windows 10
computer OS. The "PCA" function in "FactoMineR" uses singular value decomposition. Before
running the PCA, we divided each variable (except travel speed) by the match duration to account
for differences in duration among matches. All variables were standardized to mean and unit variance (Z scores) prior to running the PCA. We ranked variables based on their contribution (in %)
to a given principal component axis using the ratio of their specific cos2 multiplied by 100 with the
cos2 of the principal component. The PCA was computed on a sample of 70 831 matches from 2
171 players.

# Parametrization of the bayesian multivariate mixed-model

We used a weakly informative LKJ prior with a shape parameter (n) set to 2 for the random effects variance-covariance matrixes, and a gaussian prior with mean 0 and standard deviation of 5 for the 35 fixed effects of all the submodels (i.e. for each response variable). We ran four chains using 43 000 36 iterations by sampling every 40 intervals (thinning), and used the first 3000 iterations for warmup. 37 We visually inspected trace plots, effective sample sizes, and residuals to assess convergence and stability. We also evaluated the model's prediction accuracy using posterior predictive checks. 39 We computed among-individual, environment, avatar, and within-individual variance-covariance 40 matrixes. We extracted the among- (individual, avatar, environment) and within- individual be-41 havioural correlations using the function posterior samples() in the "brms" package. We could thus compute the mean and HDP intervals to obtain the correlation values. The variance-covariance 43 matrixes were parametrized as:

$$\begin{bmatrix} id_{0y1,i} \\ id_{0y2,i} \\ id_{0y3,i} \\ id_{0y3,i} \\ id_{0y4,i} \end{bmatrix} = MVN(0,\Omega_{id}): \text{ where } \Omega_{id} = \begin{bmatrix} V_{id_{0y1,i}} \\ Cov_{id_{0y1,i}id_{0y2,i}} & V_{id_{0y2,i}} \\ Cov_{id_{0y1,i}id_{0y3,i}} & Cov_{id_{0y1,i}id_{0y4,i}} & V_{id_{0y3,i}} \\ Cov_{id_{0y2,i}id_{0y3,i}} & Cov_{id_{0y2,i}id_{0y4,i}} & Cov_{id_{0y3,i}id_{0y4,i}} & V_{id_{0y4,i}} \end{bmatrix}$$

$$= MVN(0,\Omega_{en}): \text{ where } \Omega_{en} = \begin{bmatrix} V_{en_{0y1,i}} \\ Cov_{en_{0y1,i}en_{0y2,i}} & V_{en_{0y2,i}} \\ Cov_{en_{0y1,i}en_{0y3,i}} & Cov_{en_{0y1,i}en_{0y4,i}} & V_{en_{0y3,i}} \\ Cov_{en_{0y1,i}en_{0y3,i}} & Cov_{en_{0y1,i}en_{0y4,i}} & V_{en_{0y3,i}} \\ Cov_{en_{0y2,i}en_{0y3,i}} & Cov_{en_{0y2,i}en_{0y4,i}} & Cov_{en_{0y3,i}en_{0y4,i}} & V_{en_{0y4,i}} \end{bmatrix}$$

$$= MVN(0,\Omega_{av}): \text{ where } \Omega_{av} = \begin{bmatrix} V_{av_{0y1,i}} \\ V_{av_{0y1,i}} \\ V_{av_{0y1,i}} \\ V_{av_{0y1,i}} \\ V_{av_{0y2,i}} \\ V_{av_{0y2,i}} \\ V_{av_{0y2,i}} \\ V_{av_{0y2,i}} \\ V_{av_{0y3,i}} \\ V_{av$$

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$$\begin{bmatrix} \varepsilon_{0y1,i} \\ \varepsilon_{0y2,i} \\ \varepsilon_{0y3,i} \\ \varepsilon_{0y4,i} \end{bmatrix} = MVN(0,\Omega_{\varepsilon}) : \text{where } \Omega_{\varepsilon} = \begin{bmatrix} V_{\varepsilon_{0y1,i}} \\ Cov_{\varepsilon_{0y1,i}\varepsilon_{0y2,i}} & V_{\varepsilon_{0y2,i}} \\ Cov_{\varepsilon_{0y1,i}\varepsilon_{0y3,i}} & Cov_{\varepsilon_{0y1,i}\varepsilon_{0y4,i}} & V_{\varepsilon_{0y3,i}} \\ Cov_{\varepsilon_{0y2,i}\varepsilon_{0y3,i}} & Cov_{\varepsilon_{0y2,i}\varepsilon_{0y4,i}} & Cov_{\varepsilon_{0y3,i}\varepsilon_{0y4,i}} & V_{\varepsilon_{0y4,i}} \end{bmatrix}$$

$$(S4)$$

where the diagonals represent the random effect variances for each hunting trait, and the lower off-diagonals the covariance between the random effect intercepts for each combination of hunting traits (travel speed, the rate of space covered, the proportion of time spent ambushing, and the time before first capture).

# Parametrization of the bayesian mixed-models of hunting success

We used a gaussian prior with mean 0 and standard deviation of 5 for the fixed effects of all models.

We visually inspected trace plots, effective sample sizes, and residuals to assess convergence and stability. We also evaluated the model's prediction accuracy using posterior predictive checks. We computed random intercepts for the individual player ID and the game environment. We also included an observation-level random effect to account for overdispersion. We calculated the ICC estimates using the function posterior\_samples() in the "brms" package, by dividing each random effect variances by the total variance. We could thus compute the mean and HDP intervals to obtain the ICC values.

For the first model, we aimed at investigating the relationship between hunting success and predator behaviour exclusively. For this model, we ran four chains using 103 000 iterations by sampling every 100 intervals (thinning), and used the first 3000 iterations for warmup. The model was parametrized as:

$$logit(P_{ij}) = (\beta_0 + id_{0i} + env_{0i} + \varepsilon_{0,ij})$$

$$+ \beta_{1,pred} speed_i$$

$$+ \beta_{2,pred} space_i$$

$$+ \beta_{3,pred} time in ambush_i$$

$$+ \beta_{4,pred} time 1^{st} capture_i$$
(S5)

We included prey behaviour in the second model and kept the same structure as equation S5. For this model, we ran four chains using 153 000 iterations by sampling every 100 intervals (thinning), and used the first 3000 iterations for warmup. The model was parametrized as:

$$logit(P_{ij}) = (\beta_0 + id_{0i} + env_{0i} + \varepsilon_{0,ij})$$

$$+ \beta_{1,pred} speed_i$$

$$+ \beta_{2,pred} space_i$$

$$+ \beta_{3,pred} time \ in \ ambush_i$$

$$+ \beta_{4,pred} time \ 1^{st} capture_i$$

$$+ \beta_{5,prey} speed'_i$$

$$+ \beta_{6,prey} space'_i$$

$$(S6)$$

In the third model, we were interested in investigating nonlinear relationships between hunting success and predator behaviour exhusively. We thus added quadratic effects for each hunting trait.

We also investigated how predator behaviours interact to affect huntin success. The model was run for 103 000 iterations by sampling every 100 intervals and using the first 3000 iterations as warmups. This model was computed as:

$$\begin{split} logit(P_{ij}) &= (\beta_0 + id_{0i} + env_{0i} + \varepsilon_{0,ij}) \\ &+ \beta_{1,pred} speed_i + \beta_{2,pred} space_i + \beta_{3,pred} time \ in \ ambush_i + \beta_{4,pred} time \ 1^{st} \ capture_i \\ &+ \frac{1}{2} \gamma_{1,pred} speed_i^2 + \frac{1}{2} \gamma_{2,pred} space_i^2 + \frac{1}{2} \gamma_{3,pred} time \ in \ ambush_i^2 + \frac{1}{2} \gamma_{4,pred} time \ 1^{st} \ capture_i^2 \\ &+ \gamma_{1,pred} speed_i \times space_i + \gamma_{2,pred} speed_i \times time \ in \ ambush_i \\ &+ \gamma_{3,pred} speed_i \times time \ 1^{st} \ capture_i + \gamma_{4,pred} space_i \times time \ in \ ambush_i \\ &+ \gamma_{5,pred} space_i \times time \ 1^{st} \ capture_i + \gamma_{6,pred} time \ in \ ambush_i \times time \ 1^{st} \ capture_i \end{split}$$

The fourth and final model included prey behaviours with their quadratic effects. We also included interactions between predator and prey behaviours to investigate how they jointly affect hunting success. The model was run for 103 000 iterations by sampling every 100 intervals and using the

<sup>76</sup> first 3000 iterations as warmups. The model is described as:

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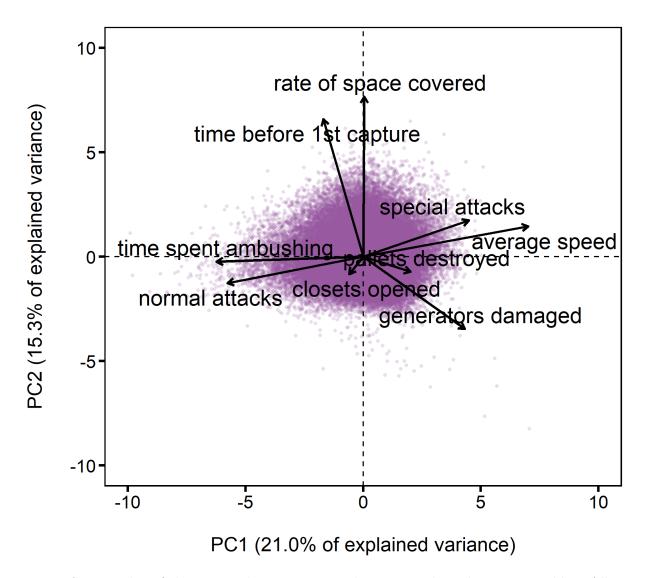
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$$\begin{split} logit(P_{ij}) &= (\beta_0 + id_{0i} + env_{0i} + \varepsilon_{0,ij}) \\ &+ \beta_{1,pred} speed_i + \beta_{2,pred} space_i + \beta_{3,pred} time \ in \ ambush_i + \beta_{4,pred} time \ 1^{st} \ capture_i \\ &+ \frac{1}{2} \gamma_{1,pred} speed_i^2 + \frac{1}{2} \gamma_{2,pred} space_i^2 + \frac{1}{2} \gamma_{3,pred} time \ in \ ambush_i^2 + \frac{1}{2} \gamma_{4,pred} time \ 1^{st} \ capture_i^2 \\ &+ \gamma_{1,pred} speed_i \times space_i + \gamma_{2,pred} speed_i \times time \ in \ ambush_i \\ &+ \gamma_{3,pred} speed_i \times time \ 1^{st} \ capture_i + \gamma_{4,pred} space_i \times time \ in \ ambush_i \\ &+ \gamma_{5,pred} space_i \times time \ 1^{st} \ capture_i + \gamma_{6,pred} time \ in \ ambush_i \times time \ 1^{st} \ capture_i \\ &+ \beta_{5,prey} speed_i' + \beta_{6,prey} space_i' \\ &+ \frac{1}{2} \gamma_{5,prey} speed_i'^2 + \frac{1}{2} \gamma_{6,prey} space_i'^2 \\ &+ \gamma_{7,pred} \ prey speed_i \times speed_i' + \gamma_{8,pred} \ prey speed_i \times space_i' + \gamma_{9,pred} \ prey space_i \times speed_i' \\ &+ \gamma_{10,pred} \ prey space_i \times space_i' + \gamma_{11,pred} \ prey time \ in \ ambush_i \times speed_i' \\ &+ \gamma_{12,pred} \ prey time \ in \ ambush_i \times space_i' + \gamma_{13,pred} \ prey time \ 1^{st} \ capture_i \times speed_i' \\ &+ \gamma_{14,pred} \ prey time \ 1^{st} \ capture_i \times space_i' \end{aligned}$$

S2. Results

Principal component analysis

The first principal component (PC1) explained 20% of the total variation, and the second principal component (PC2) explained 15.3% of the total variation (Fig. S1). We found that travel speed and time spent ambushing had the highest contribution to the first principal component (23.19% and 29.38% respectively) (Table SI), while the rate of space covered and the time before first capture had the second highest contribution (48.12% and 35.55%) to the second principal component (Table SI). Time spent ambushing is negatively correlated with travel speed (Fig. S1), which may indicate the presence of structured tactics where individuals that are fast do not ambush, and individuals who ambush prey are slower travelers.



**Figure S 1:** Biplot of the principal component analysis on predator hunting variables. All variables were standardized to 0 mean and unit variance (Z scores) prior to analysis. We extracted correlations and the percentages of explained variance on the first and second PC axes to select variables for the subsequent analyses.

Table SI: Principal component loadings for all the predator behavioural traits.

	PC1 (% variance = 21.0)		PC2 (% variance = 15.3)	
	Correlation	% variance	Correlation	% variance
time spent ambushing	-0.66	23.19	-0.03	0.05
average speed	0.75	29.38	0.15	1.73
rate of space covered	0.00	0.00	0.82	48.12
closets opened	-0.06	0.21	-0.09	0.56
pallets destroyed	0.21	2.42	-0.08	0.43
generators damaged	0.46	11.17	-0.37	9.79
normal attacks	-0.61	19.89	-0.13	1.31
special attacks	0.48	12.02	0.18	2.47
time before 1st capture	-0.18	1.72	0.70	35.55

Literature Cited

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