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Online supporting information for

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Studying predator foraging mode and hunting success at the

3

individual level with an online videogame

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Supporting Information: Materials and methods

Principal component analysis

We computed a principal components analysis (PCA) using the packages ‘FactoMineR’ version 2.4 (Lê et al. 2008) and ‘factoextra’ version 1.0.7 (Kassambara and Mundt 2020 Apr 1) in the R software version 4.0.4 (R Core Team, 2021), under a Windows 10 Home computer OS (version 21H2, OS build 19044.1466). The ‘PCA()’ function in ‘FactoMineR’ uses singular value decomposition. Before running the PCA, we divided each variable (except travel speed) by the match duration to account for differences in game time length among matches. We applied a square-root transformation to all the variables. They were then standardized to mean and unit variance (Z scores) before running the PCA. We ranked variables based on their contribution (in %) to a given principal component axis. To do so, for each variable, we used the ratio between their \cos^2 multiplied by 100 and the \cos^2 of the principal component.

Parametrization of the bayesian multivariate mixed-model

We used a half-normal prior with mean of 0 and standard-deviation of 1 for all the variance parameters, and applied a weakly informative LKJ prior with a shape parameter (n) set to 2 for the random effects variance-covariance matrices. We applied a Gaussian prior with mean of 0 and standard deviation of 2 for the fixed effects (i.e. prey travel speed x_1 and rate of space covered x_2) of all the submodels (i.e. for each response variable). We ran four chains using 2500 iterations, sampled every 8 intervals (thinning), and used the first 500 iterations as warmups. We visually inspected the trace plots, effective sample sizes, and residuals to assess convergence and stability. We also evaluated the model’s prediction accuracy using posterior predictive checks. We computed a variance-covariance matrix (Ω_k) for each random effect (k). We extracted the among-environment, among-individual, and within-individual variance components and behavioral correlations using the function ‘as_draws_df()’ in the ‘brms’ package (for details, consult the code files on the GitHub repository : <https://github.com/quantitative-ecologist/predator-foraging-mode-videogames>). We could thus compute the mean of the variance and correlation sample values, and the HDP intervals to obtain their 95% credible intervals. The variance-covariance matrixes were parametrized as :

$$\begin{bmatrix} en_{0y1,g} \\ en_{0y2,g} \\ en_{0y3,g} \\ en_{0y4,g} \end{bmatrix} = MVN(0, \Omega_{en}) : \text{where } \Omega_{en} = \begin{bmatrix} V_{en_{0y1}} & & & \\ Cov_{en_{0y1}en_{0y2}} & V_{en_{0y2}} & & \\ Cov_{en_{0y1}en_{0y3}} & Cov_{en_{0y1}en_{0y4}} & V_{en_{0y3}} & \\ Cov_{en_{0y2}en_{0y3}} & Cov_{en_{0y2}en_{0y4}} & Cov_{en_{0y3}en_{0y4}} & V_{en_{0y4}} \end{bmatrix} \quad (S1)$$

$$\begin{bmatrix} av_{0y1,h} \\ av_{0y2,h} \\ av_{0y3,h} \\ av_{0y4,h} \end{bmatrix} = MVN(0, \Omega_{av}) : \text{where } \Omega_{av} = \begin{bmatrix} V_{av_{0y1}} & & & \\ Cov_{av_{0y1}av_{0y2}} & V_{av_{0y2}} & & \\ Cov_{av_{0y1}av_{0y3}} & Cov_{av_{0y1}av_{0y4}} & V_{av_{0y3}} & \\ Cov_{av_{0y2}av_{0y3}} & Cov_{av_{0y2}av_{0y4}} & Cov_{av_{0y3}av_{0y4}} & V_{av_{0y4}} \end{bmatrix} \quad (S2)$$

$$\begin{bmatrix} id_{0y1,i} \\ id_{0y2,i} \\ id_{0y3,i} \\ id_{0y4,i} \end{bmatrix} = MVN(0, \Omega_{id}) : \text{where } \Omega_{id} = \begin{bmatrix} V_{id_{0y1}} & & & \\ Cov_{id_{0y1}id_{0y2}} & V_{id_{0y2}} & & \\ Cov_{id_{0y1}id_{0y3}} & Cov_{id_{0y1}id_{0y4}} & V_{id_{0y3}} & \\ Cov_{id_{0y2}id_{0y3}} & Cov_{id_{0y2}id_{0y4}} & Cov_{id_{0y3}id_{0y4}} & V_{id_{0y4}} \end{bmatrix} \quad (S3)$$

$$\begin{bmatrix} \varepsilon_{0y1,ghij} \\ \varepsilon_{0y2,ghij} \\ \varepsilon_{0y3,ghij} \\ \varepsilon_{0y4,ghij} \end{bmatrix} = MVN(0, \Omega_{\varepsilon}) : \text{where } \Omega_{\varepsilon} = \begin{bmatrix} V_{\varepsilon_{0y1}} & & & \\ Cov_{\varepsilon_{0y1}\varepsilon_{0y2}} & V_{\varepsilon_{0y2}} & & \\ Cov_{\varepsilon_{0y1}\varepsilon_{0y3}} & Cov_{\varepsilon_{0y1}\varepsilon_{0y4}} & V_{\varepsilon_{0y3}} & \\ Cov_{\varepsilon_{0y2}\varepsilon_{0y3}} & Cov_{\varepsilon_{0y2}\varepsilon_{0y4}} & Cov_{\varepsilon_{0y3}\varepsilon_{0y4}} & V_{\varepsilon_{0y4}} \end{bmatrix} \quad (S4)$$

30 where the diagonals represent the random effect (k) variance ($V_{k_{0y_n}}$) for each hunting trait (y_n), and the
31 lower off-diagonals the covariance between the random effect intercepts for each combination of hunting
32 traits (travel speed ($y1$), the rate of space covered ($y2$), the time spent guarding ($y3$), and the time before
33 first capture ($y4$)).

We ran three additional multivariate mixed-models:

1. Different structure: without prey behavior as fixed effects
2. Same structure: only on novice players
3. Same structure: only on experienced players

For the first model, we investigated how accounting for prey behavior in the predator behavioral variation (i.e. removing prey as a control) changed the behavioral correlations. With this, we could also consider whether it changed the environmental variance parameters. This would enable us to assess if prey responded to the game environment rather than the predator. We thus computed the same multivariate model, and excluded prey travel speed and rate of space covered as the linear fixed effects.

For the second and third models, we investigated if player experience changed the relationships between the predator behaviors (i.e. their correlations). To do so, we applied the same model procedure on two distinct datasets based on player experience by splitting the total experience of individual players from the main dataset in quartiles. This resulted in 75% of the players having played up to 31 matches, which represented ~5 hours of gameplay. Based on their cumulative number of matches, we then assigned novice players as those who played between 1 and 31 matches, and players with experience as those having above 31 cumulative matches played. Individuals who played above 31 matches could thus be assigned to both novice and experienced players. We split our data this way because if we separated players based on their total number of matches, we would have had matches for experienced players where they were still novice.

Parametrization of the Bayesian mixed-models for hunting success

We computed 4 different models to investigate the relationship between predator and prey behavior and predator hunting success. We used a half-normal prior for the variance parameters with a mean of 0 and a standard deviation of 1, and a Gaussian prior with a mean of 0 and a standard deviation of 2 for the fixed effects of all the models. We visually inspected trace plots, effective sample sizes, and residuals to assess convergence and stability. We also evaluated the models' prediction accuracies using posterior predictive checks. We calculated the ICC_k estimate for each random effect (k) using the function `as_draws_df()` in the 'brms' package by dividing each random effect variance sample value by the total variance. We used the mean of the posterior variance parameters to compute the ICC values of each random effect, and used the HDP intervals to obtain their corresponding 95% credible intervals.

62 For the first model, we aimed at investigating the relationship between hunting success and predator behavior
63 exclusively. For this model, we ran 4 chains using 2500 iterations and sampled every 8 intervals (thinning),
64 and used the first 500 iterations for warmup. The model was parametrized as :

$$\begin{aligned}
\text{logit}(P_{hij}) = & (\beta_0 + env_{0,h} + id_{0,i} + \varepsilon_{0,hij}) \\
& + \beta_{1,pred} speed_{hi} \\
& + \beta_{2,pred} space_{hi} \\
& + \beta_{3,pred} ambush\ time_{hi} \\
& + \beta_{4,pred} time\ I^{st} capture_{hi}
\end{aligned} \tag{S5}$$

65 We included prey behavior in the second model and kept the same structure as equation S5. Again, we ran
66 4 chains using 2500 iterations and sampled every 8 intervals (thinning), and used the first 500 iterations for
67 warmup. The model was parametrized as :

$$\begin{aligned}
\text{logit}(P_{hij}) = & (\beta_0 + env_{0h} + id_{0i} + \varepsilon_{0,hij}) \\
& + \beta_{1,pred} speed_{hi} \\
& + \beta_{2,pred} space_{hi} \\
& + \beta_{3,pred} ambush\ time_{hi} \\
& + \beta_{4,pred} time\ I^{st} capture_{hi} \\
& + \beta_{5,prey} speed'_{hi} \\
& + \beta_{6,prey} space'_{hi}
\end{aligned} \tag{S6}$$

68 In the third model, we were interested in investigating nonlinear relationships between hunting success and
69 predator behavior exclusively. We thus added quadratic effects for each hunting trait. We also investigated
70 how predator behaviors interact to affect hunting success. We used 4 chains and ran 2500 iterations by
71 sampling every 8 intervals, and used the first 500 iterations as warmups. This model was computed as :

$$\begin{aligned}
\text{logit}(P_{hij}) = & (\beta_0 + env_{0h} + id_{0i} + \varepsilon_{0,hij}) \\
& + \beta_{1,pred} speed_{hi} + \beta_{2,pred} space_{hi} \\
& + \beta_{3,pred} ambush\ time_{hi} + \beta_{4,pred} time\ I^{st}\ capture_{hi} \\
& + \frac{1}{2} \gamma_{1,pred} speed_{hi}^2 + \frac{1}{2} \gamma_{2,pred} space_{hi}^2 \\
& + \frac{1}{2} \gamma_{3,pred} ambush\ time_{hi}^2 + \frac{1}{2} \gamma_{4,pred} time\ I^{st}\ capture_{hi}^2 \\
& + \gamma_{1,pred} speed_{hi} \times space_{hi} \\
& + \gamma_{2,pred} speed_{hi} \times ambush\ time_{hi} \\
& + \gamma_{3,pred} speed_{hi} \times time\ I^{st}\ capture_{hi} \\
& + \gamma_{4,pred} space_{hi} \times ambush\ time_{hi} \\
& + \gamma_{5,pred} space_{hi} \times time\ I^{st}\ capture_{hi} \\
& + \gamma_{6,pred} ambush\ time_{hi} \times time\ I^{st}\ capture_{hi}
\end{aligned} \tag{S7}$$

72 The fourth and final model included prey behaviors with their quadratic effects as well as their interactions
 73 with predator behavior to investigate how they jointly affect hunting success. The model was run on 4
 74 chains with 2500 iterations where we set the sampling at every 8 intervals. We used the first 500 iterations
 75 for warmups. The model is described as :

$$\begin{aligned}
 \text{logit}(P_{hij}) = & (\beta_0 + env_{0h} + id_{0i} + \varepsilon_{0,hij}) \\
 & + \beta_{1,pred} speed_{hi} + \beta_{2,pred} space_{hi} \\
 & + \beta_{3,pred} ambush\ time_{hi} + \beta_{4,pred} time\ I^{st} capture_{hi} \\
 & + \beta_{5,prey} speed'_{hi} + \beta_{6,prey} space'_{hi} \\
 & + \frac{1}{2} \gamma_{1,pred} speed_{hi}^2 + \frac{1}{2} \gamma_{2,pred} space_{hi}^2 \\
 & + \frac{1}{2} \gamma_{3,pred} ambush\ time_{hi}^2 + \frac{1}{2} \gamma_{4,pred} time\ I^{st} capture_{hi}^2 \\
 & + \frac{1}{2} \gamma_{5,prey} speed'^2_{hi} + \frac{1}{2} \gamma_{6,prey} space'^2_{hi} \\
 & + \gamma_{1,pred} speed_{hi} \times space_{hi} \\
 & + \gamma_{2,pred} speed_{hi} \times ambush\ time_{hi} \\
 & + \gamma_{3,pred} speed_{hi} \times time\ I^{st} capture_{hi} \\
 & + \gamma_{4,pred} space_{hi} \times ambush\ time_{hi} \\
 & + \gamma_{5,pred} space_{hi} \times time\ I^{st} capture_{hi} \\
 & + \gamma_{6,pred} ambush\ time_{hi} \times time\ I^{st} capture_{hi} \\
 & + \gamma_{7,pred\ prey} speed_{hi} \times speed'_{hi} \\
 & + \gamma_{8,pred\ prey} speed_{hi} \times space'_{hi} \\
 & + \gamma_{9,pred\ prey} space_{hi} \times speed'_{hi} \\
 & + \gamma_{10,pred\ prey} space_{hi} \times space'_{hi} \\
 & + \gamma_{11,pred\ prey} ambush\ time_{hi} \times speed'_{hi} \\
 & + \gamma_{12,pred\ prey} ambush\ time_{hi} \times space'_{hi} \\
 & + \gamma_{13,pred\ prey} time\ I^{st} capture_{hi} \times speed'_{hi} \\
 & + \gamma_{14,pred\ prey} time\ I^{st} capture_{hi} \times space'_{hi}
 \end{aligned} \tag{S8}$$

Supporting Information: Results

Principal component analysis

The first principal component (PC1) explained 20.9% of the total variation, and the second principal component (PC2) explained 19.6% of the total variation (figure S1). We found that the time before the first capture, the rate of space covered, and the time spent guarding had the highest contribution (36.71, 27.04, and 23.38 respectively) to the first principal component (table S1), while the travel speed had the highest contribution (33.29) to the second principal component (table S1).

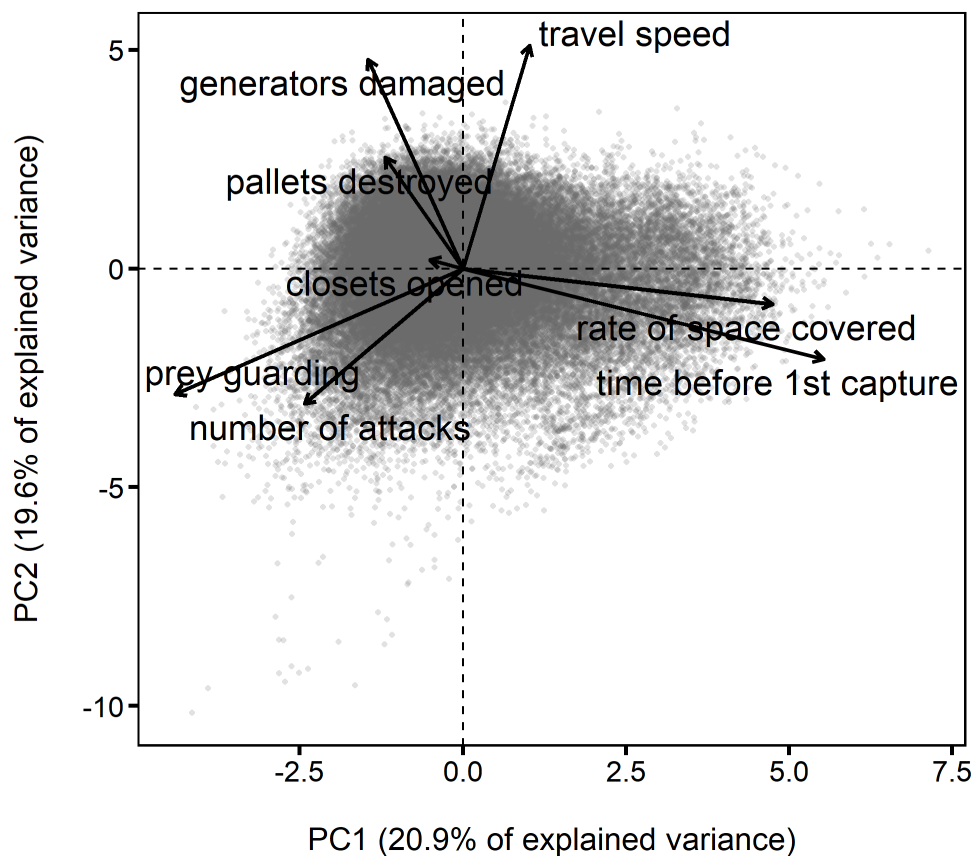


Figure S 1: Biplot of the principal component analysis on predator hunting behaviors. We extracted correlations and the percentages of explained variance on the first and second PC axes to select variables for the subsequent analyses.

Table S1: Principal component loadings for all the predator behavioral traits.

	PC1 (% variance = 21.0)		PC2 (% variance = 15.3)	
	Correlation	% variance	Correlation	% variance
ambush time	-0.66	23.19	-0.03	0.05
travel speed	0.75	29.38	0.15	1.73
rate of space covered	0.00	0.00	0.82	48.12
closets opened	-0.06	0.21	-0.09	0.56
pallets destroyed	0.21	2.42	-0.08	0.43
generators damaged	0.46	11.17	-0.37	9.79
normal attacks	-0.61	19.89	-0.13	1.31
special attacks	0.48	12.02	0.18	2.47
time before 1st capture	-0.18	1.72	0.70	35.55

Intra-class correlation coefficients of the predator behaviors for the three additional multivariate mixed-models

After removing prey behavior as linear fixed effects (model 2), the percentage of explained variance by the game environments remained almost the same compared to the first model for predator travel speed, the time spent guarding, and the time required to capture the first prey (table S2). Thus, variation in these three behaviors was not explained by differences among game environments. However, there was an increase in the variation among game environments for the rate of space covered (table S2). The ICCs remained mostly similar for all the random effects when comparing novice and experimented players, but among-individual differences tended to be lower for experimented players.

Table S2: Posterior means of the ICC estimates for the three additional multivariate mixed-models.

Behavior	Random effect	ICC (95% CI) - No prey	ICC (95% CI) - Novices	ICC (95% CI) - Experienced
travel speed	player ID	0.28 (0.26, 0.30)	0.35 (0.32, 0.38)	0.19 (0.16, 0.22)
	game environment	0.00 (0.00, 0.00)	0.00 (0.00, 0.00)	0.00 (0.00, 0.00)
	avatar	0.09 (0.04, 0.14)	0.09 (0.04, 0.15)	0.10 (0.05, 0.17)
	residuals	0.63 (0.59, 0.67)	0.56 (0.51, 0.59)	0.71 (0.65, 0.76)
space covered	player ID	0.08 (0.06, 0.09)	0.06 (0.05, 0.07)	0.06 (0.05, 0.07)
	game environment	0.19 (0.12, 0.29)	0.04 (0.02, 0.06)	0.19 (0.12, 0.28)
	avatar	0.01 (0.01, 0.03)	0.02 (0.01, 0.03)	0.02 (0.01, 0.03)
	residuals	0.72 (0.64, 0.79)	0.88 (0.86, 0.91)	0.73 (0.65, 0.80)
guard time	player ID	0.31 (0.28, 0.33)	0.23 (0.21, 0.25)	0.15 (0.13, 0.18)
	game environment	0.00 (0.00, 0.00)	0.02 (0.01, 0.02)	0.00 (0.00, 0.00)
	avatar	0.03 (0.01, 0.05)	0.02 (0.01, 0.04)	0.04 (0.01, 0.07)
	residuals	0.67 (0.64, 0.69)	0.73 (0.71, 0.75)	0.81 (0.77, 0.84)
time 1st capture	player ID	0.26 (0.24, 0.28)	0.21 (0.20, 0.23)	0.15 (0.13, 0.17)
	game environment	0.01 (0.00, 0.01)	0.03 (0.02, 0.04)	0.01 (0.00, 0.01)
	avatar	0.03 (0.01, 0.05)	0.02 (0.01, 0.04)	0.03 (0.01, 0.06)
	residuals	0.70 (0.68, 0.73)	0.74 (0.71, 0.76)	0.81 (0.78, 0.84)

Table S3: Among-individual and within-individual behavioral correlations for the three additional multi-variate mixed-models.

	speed	space	prey guarding	time 1st cap.
Model: without prey				
speed	-	0.21 (0.21, 0.22)	-0.05 (-0.05,-0.06)	-0.07 (-0.06,-0.07)
space	-0.03 (-0.09, 0.04)	-	-0.25 (-0.24,-0.26)	0.09 (0.08, 0.10)
prey guarding	0.06 (0.00, 0.13)	-0.48 (-0.42,-0.54)	-	-0.43 (-0.43,-0.44)
time 1st cap.	-0.41 (-0.35,-0.46)	0.59 (0.53, 0.64)	-0.73 (-0.70,-0.76)	-
Model: novice players				
speed	-	0.22 (0.21, 0.23)	-0.13 (-0.12,-0.14)	-0.02 (-0.01,-0.03)
space	0.50 (0.44, 0.57)	-	-0.19 (-0.18,-0.21)	0.07 (0.05, 0.08)
prey guarding	0.08 (0.02, 0.14)	0.05 (-0.04, 0.14)	-	-0.45 (-0.44,-0.46)
time 1st cap.	-0.49 (-0.45,-0.55)	-0.21 (-0.13,-0.29)	-0.62 (-0.58,-0.66)	-
Model: experienced players				
speed	-	0.22 (0.21, 0.23)	-0.13 (-0.12,-0.14)	-0.02 (-0.01,-0.03)
space	0.50 (0.44, 0.57)	-	-0.19 (-0.18,-0.21)	0.07 (0.05, 0.08)
prey guarding	0.08 (0.02, 0.14)	0.05 (-0.04, 0.14)	-	-0.45 (-0.44,-0.46)
time 1st cap.	-0.49 (-0.45,-0.55)	-0.21 (-0.13,-0.29)	-0.62 (-0.58,-0.66)	-

* The among-individual correlations are on the lower off-diagonal and the residual within-individual correlations on the upper off-diagonal

The model with the lowest expected log predictive density was chosen as the best model for our interpretations of the relationship between behavior and hunting success.

Table S4: Summary table comparing the hunting success models based on approximate leave-one-out cross-validation

model	elpd difference	sd difference	elpd loo value	elpd loo standard error
quadratic model pred-prey	0.00	0.00	-96 276.18	239.14
linear model pred-prey	-2 356.80	94.08	-98 632.99	239.65
quadratic model pred	-7 243.63	138.56	-103 519.82	250.09
linear model pred	-8 905.85	156.73	-105 182.03	248.13

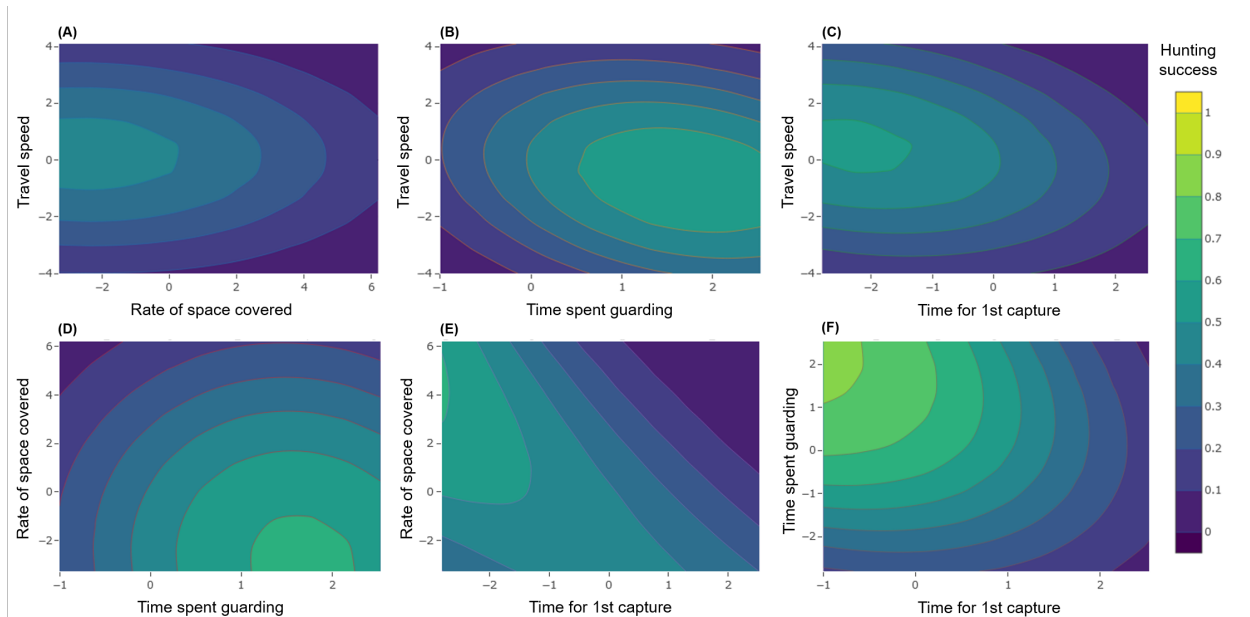


Figure S 2: Interacting effects of the predator behaviors on hunting success. Hunting success is represented by the color gradient. We computed the plots by predicting the mean probability of capturing four prey based on the best quadratic approximation of the predator behavior interaction terms. (A) Travel speed and the rate of space covered. (B) Travel speed and the time spent guarding prey. (C) Time before the first capture and travel speed. (D) The rate of space covered and the time spent guarding. (E) The rate of space covered and the time before the first capture. (F) The time spent guarding prey and the time before the first capture.

Literature Cited

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