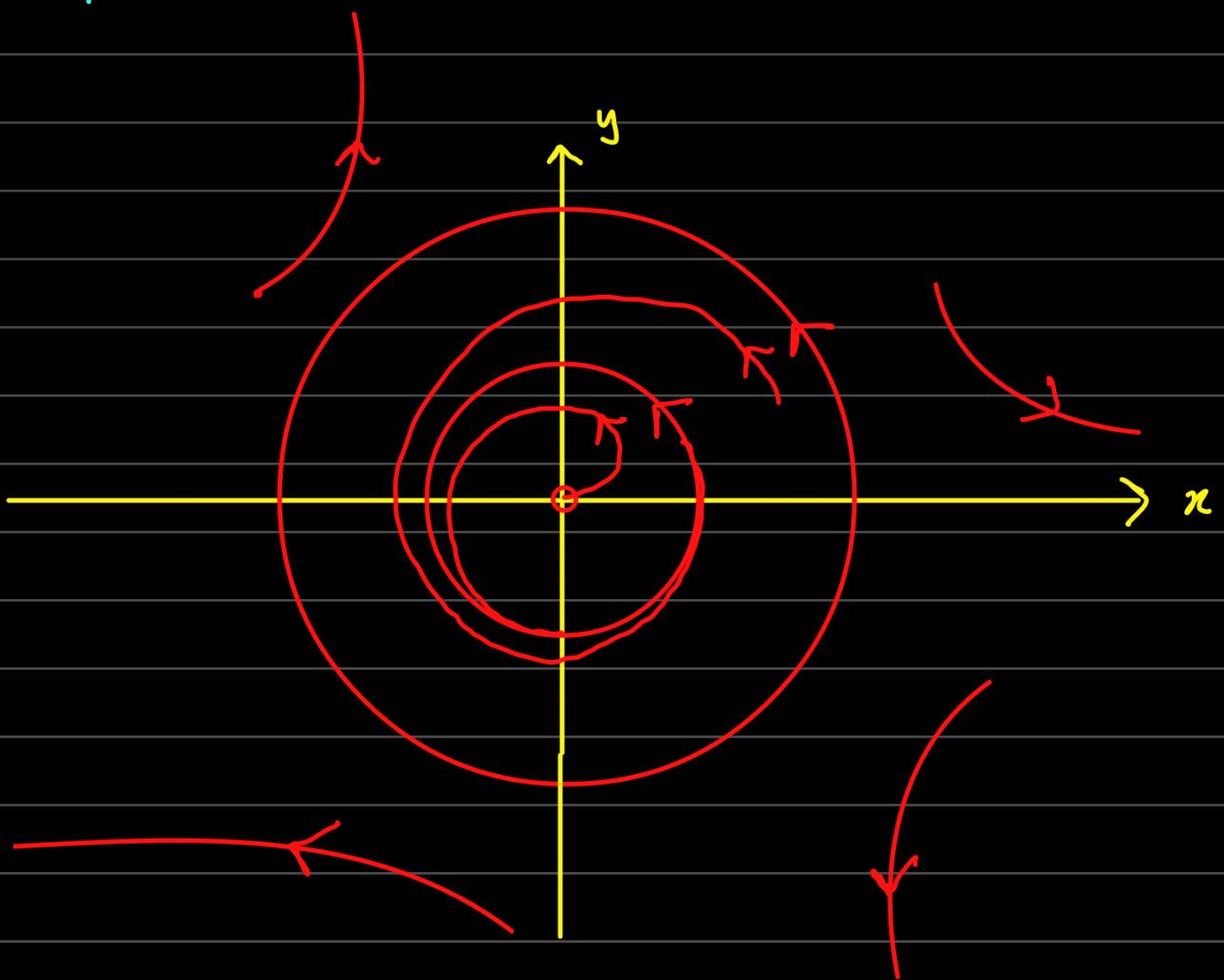
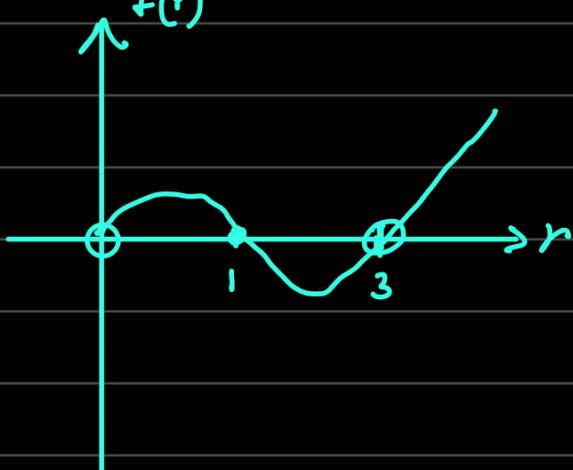


1. Sketch the phase portraits of the following systems:

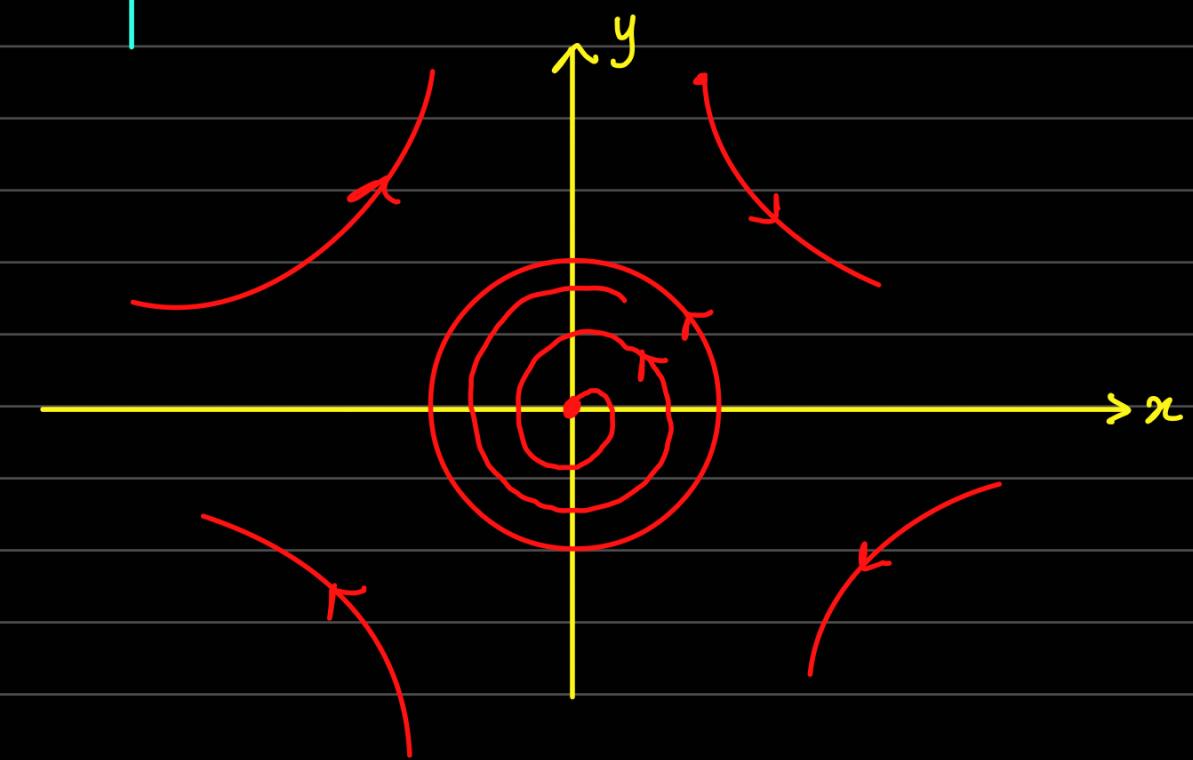
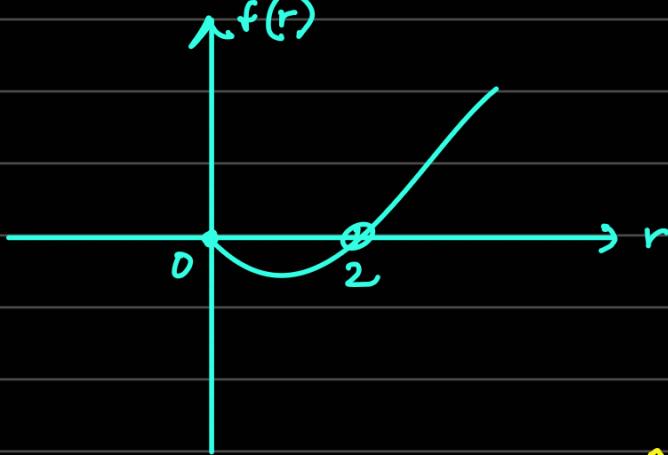
(a)  $\dot{r} = r(1 - r^2)(9 - r^2)$ ,  $\dot{\theta} = 1$

a)  $f(r) = r(1 - r^2)(9 - r^2)$ ,  $r^* = 0, 1, 3 \rightarrow$  unstable, stable



$$(b) \dot{r} = r^3 - 4r, \dot{\theta} = 1.$$

b)  $f(r) = r(r^2 - 4)$   $r^* = 0, 2 \rightarrow$  unstable  
stable



2. Consider  $\ddot{x} + a\dot{x}(x^2 + \dot{x}^2 - 1) + x = 0$ , where  $a > 0$ .

(a) Find and classify all the fixed points.

$$\begin{aligned} a) \quad \dot{x} &= y &= f(x, y) \\ \dot{y} &= -ay(x^2 + y^2 - 1) - x &= g(x, y) \end{aligned}$$

For f.p.,  $y = 0, x = 0$

(b) Show that the system has a circular limit cycle, and find its amplitude and period.

b) Nullclines:  $y = 0$  and  $ay(x^2 + y^2 - 1) = -x$



So this hints at a circle as a choice for a trapping region, but  $(0,0)$  is a f.p.. We must show that this is a repeller.

$$J = \begin{pmatrix} 0 & 1 \\ -2ay - 1 & -a(x^2 + y^2 - 1) - 2ay^2 \end{pmatrix}$$

$$\text{At } (0,0), \quad J = \begin{pmatrix} 0 & 1 \\ -1 & a \end{pmatrix} \quad \tau = a > 0 \quad \Delta = a + 1 > 0$$

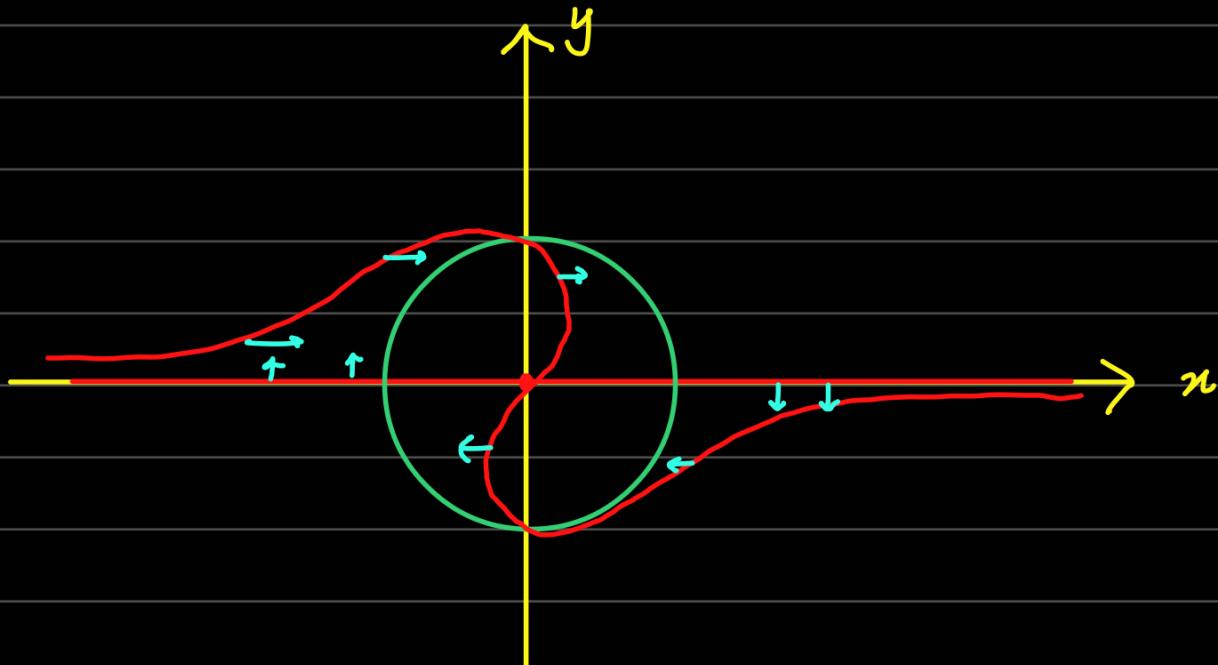
$\therefore (0,0)$  is a repeller.

let  $x = R\cos\theta$ ,  $y = R\sin\theta$  (fixed  $R$ )  
 Then we get,

$$-R\sin\theta \dot{\theta} = R\sin\theta \Rightarrow \dot{\theta} = -1$$

$$R\cos\theta \dot{\theta} = -aR\sin\theta (R^2 - 1) - R\cos\theta$$

$$\Rightarrow R = 1 \quad (\because \dot{\theta} = -1)$$



From judging the direction of arrows, we see that it is stable.

$$\text{Period} = \frac{2\pi}{|\dot{\theta}|} = \boxed{2\pi}, \text{ amplitude} = R = \boxed{1}$$

(c) Determine the stability of the limit cycle.

c) From the previous part, the direction of arrows shows that it is stable.  
 Alternatively,

$$x = (1+\varepsilon)\cos\theta \quad y = (1+\varepsilon)\sin\theta \quad |\varepsilon| \ll 1$$

$$\dot{x} = \dot{\varepsilon}\cos\theta - (1+\varepsilon)\sin\theta \dot{\theta} \quad \dot{y} = \dot{\varepsilon}\sin\theta + (1+\varepsilon)\cos\theta \dot{\theta}$$

Converting  $\dot{y}$ ,

$$\Rightarrow \dot{\varepsilon}\sin\theta + (1+\varepsilon)\cos\theta \dot{\theta} = -a(1+\varepsilon)\sin\theta ((1+\varepsilon)^2 - 1) - (1+\varepsilon)\cos\theta$$

$$\dot{\varepsilon} \sin \theta + (1+\varepsilon) \cos \theta \dot{\theta} = -a(1+\varepsilon) \sin \theta (2\varepsilon) - (1+\varepsilon) \cos \theta$$

$$\dot{\varepsilon} \sin \theta + (1+\varepsilon) \cos \theta (1+\dot{\theta}) = -2a\varepsilon \sin \theta$$

Converting it,

$$\left\{ \begin{array}{l} \dot{\varepsilon} \cos \theta - (1+\varepsilon) \sin \theta \dot{\theta} = (1+\varepsilon) \sin \theta \\ \dot{\varepsilon} \cos \theta = (1+\varepsilon) \sin \theta (1+\dot{\theta}) \\ \Rightarrow 1+\dot{\theta} = \frac{\dot{\varepsilon} \cos \theta}{(1+\varepsilon) \sin \theta} \end{array} \right.$$

$$\Rightarrow \dot{\varepsilon} \sin \theta + \frac{\dot{\varepsilon} \cos^2 \theta}{\sin \theta} = -2a\varepsilon \sin \theta$$

$$\underline{\dot{\varepsilon} = (-2a \sin^2 \theta) \varepsilon} \quad \text{so the perturbation dies out, and } \underline{r=1 \text{ is stable}}$$

3. Show that  $\dot{x} = -x + 2y^3 - 2y^4$ ,  $\dot{y} = -x - y + xy$  has no periodic solutions.  
(Hint: Choose  $a, m$  and  $n$  such that  $V = x^m + ay^n$  is a Lyapunov function.)

$$\begin{aligned} (3) \quad \frac{dV}{dt} &= mx^{m-1} \dot{x} + any^{n-1} \dot{y} \\ &= mx^{m-1}(-x + 2y^3 - 2y^4) + any^{n-1}(-x - y + xy) \\ &= -mx^m + 2mx^{m-1}y^3 - 2mx^{m-1}y^4 - any^{n-1} - any^n \\ &\quad + any^n \\ &= -mx^m - any^n + 2mx^{m-1}y^3(1-y) - any^{n-1}(1-y) \end{aligned}$$

$$\frac{dV}{dt} = -mx^m - any^n + (1-y)(2mx^{m-1}y^3 - any^{n-1})$$

So to maintain  $\frac{dV}{dt} < 0 \quad \forall \bar{X} \neq \bar{X}^* = (0,0)$ ,

$$m=2, n=4, a=1$$

$$\text{So } V(x,y) = \boxed{x^2 + y^4} \quad \text{and } V(x,y) \geq 0 \quad \forall (x,y) \neq (0,0)$$

4. Consider  $\dot{x} = x - y - x(x^2 + 5y^2)$ ,  $\dot{y} = x + y - y(x^2 + y^2)$ .

(a) Classify the fixed point at the origin.

$$\text{a) } \frac{\partial f}{\partial x} = 1 - (x^2 + 5y^2) - 2x^2 \quad \frac{\partial f}{\partial y} = -1 - 10xy \\ = 1 - 3x^2 - 5y^2$$

$$\frac{\partial g}{\partial x} = 1 - 2xy \quad \frac{\partial g}{\partial y} = 1 - (x^2 + y^2) - 2y^2 \\ = 1 - x^2 - 3y^2$$

$$\therefore J = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \quad \tau = 2$$

$$\Delta = 2, \tau^2 - 4\Delta = -4 < 0$$

So it is an unstable spiral

(b) Rewrite the system in polar coordinates.

$$\text{b) } x = r\cos\theta, \quad y = r\sin\theta$$

$$\Rightarrow \dot{r}\cos\theta - r\sin\theta\dot{\theta} = r\cos\theta - r\sin\theta - r^3\cos\theta(1 + h\sin^2\theta) \quad -1 \\ \dot{r}\sin\theta + r\cos\theta\dot{\theta} = r\sin\theta + r\cos\theta - r^3\sin\theta \quad -2$$

$$\textcircled{1} \times \cos\theta + \textcircled{2} \times \sin\theta : \boxed{\dot{r} = r - r^3(1 + \sin^2 2\theta)}$$

$$\textcircled{1} \times \sin\theta - \textcircled{2} \times \cos\theta : \boxed{-r\dot{\theta} = -r - hr^3\cos\theta\sin^3\theta} \\ \Rightarrow \dot{\theta} = 1 + hr^2\cos\theta\sin^3\theta$$

(c) Determine the circle of maximum radius  $r_1$ , centered on the origin such that all trajectories have a radially outward component on it.

(d) Determine the circle of minimum radius  $r_2$ , centered on the origin such that all trajectories have a radially inward component on it.

$$\text{c) } \dot{r} > 0 \Rightarrow r - r^3(1 + \sin^2 2\theta) > 0 \Rightarrow \frac{1}{1 + \sin^2 2\theta} > r^2$$

For largest radius on which  $\dot{r} > 0$ , and observing that  $0 \leq \sin^2 2\theta \leq 1$ ,

we choose  $\theta = 0$ , such that  $r_1 = 1$

d)  $r < 0 \Rightarrow r - r^3(1 + \sin^2 2\theta) < 0 \Rightarrow \frac{1}{1 + \sin^2 2\theta} < r^2$

With logic similar to above, choose  $\theta = \frac{\pi}{4}$  to get a minimum radius on which  $r < 0$ , such that  $r_2 = \frac{1}{\sqrt{2}}$

- (e) Prove that the system has a limit cycle somewhere in the trapping region  $r_1 \leq r \leq r_2$ .

e) let's check for fixed points in this region.

$$\dot{r} = r - r^3(1 + \sin^2 2\theta) = 0 \Rightarrow r^{*2} = \frac{1}{1 + \sin^2 2\theta}$$

$$\dot{\theta} = 1 + h r^2 \cos \theta \sin^3 \theta = 0 \Rightarrow r^{*2} = -\frac{1}{h \cos \theta \sin^3 \theta}$$

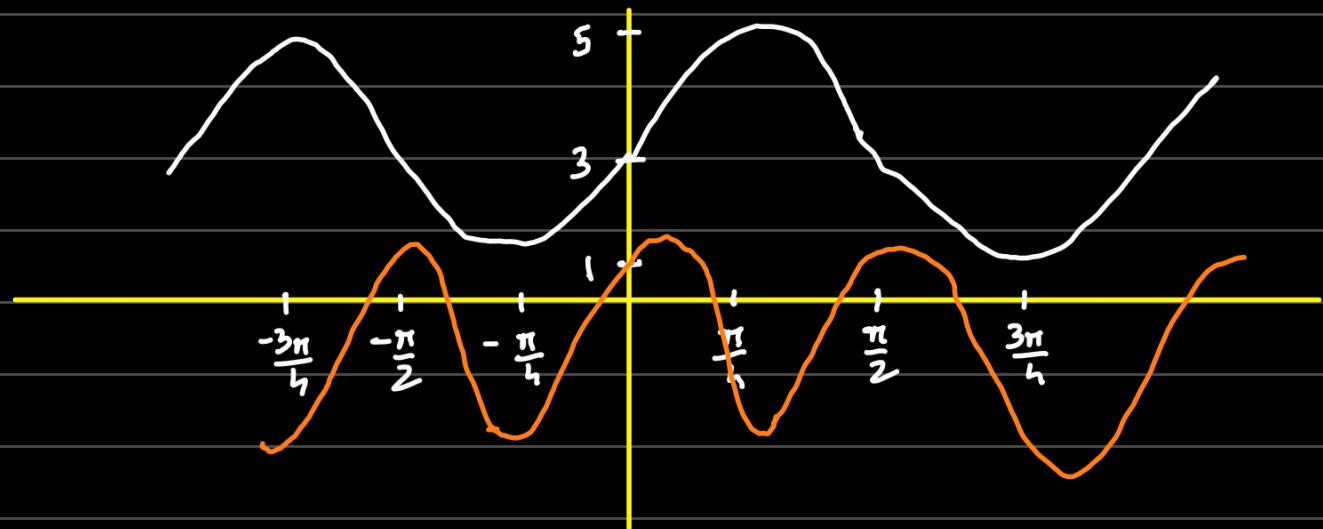
$$\Rightarrow \frac{1}{1 + \sin^2 2\theta} = -\frac{1}{h \cos \theta \sin^3 \theta}$$

$$\Rightarrow 1 + \sin^2 2\theta = -2 \sin 2\theta \sin^2 \theta$$

$$1 + \sin^2 2\theta = \sin 2\theta (\cos 2\theta - 1)$$

$$3 - \cos 4\theta = \sin 4\theta - 2 \sin 2\theta$$

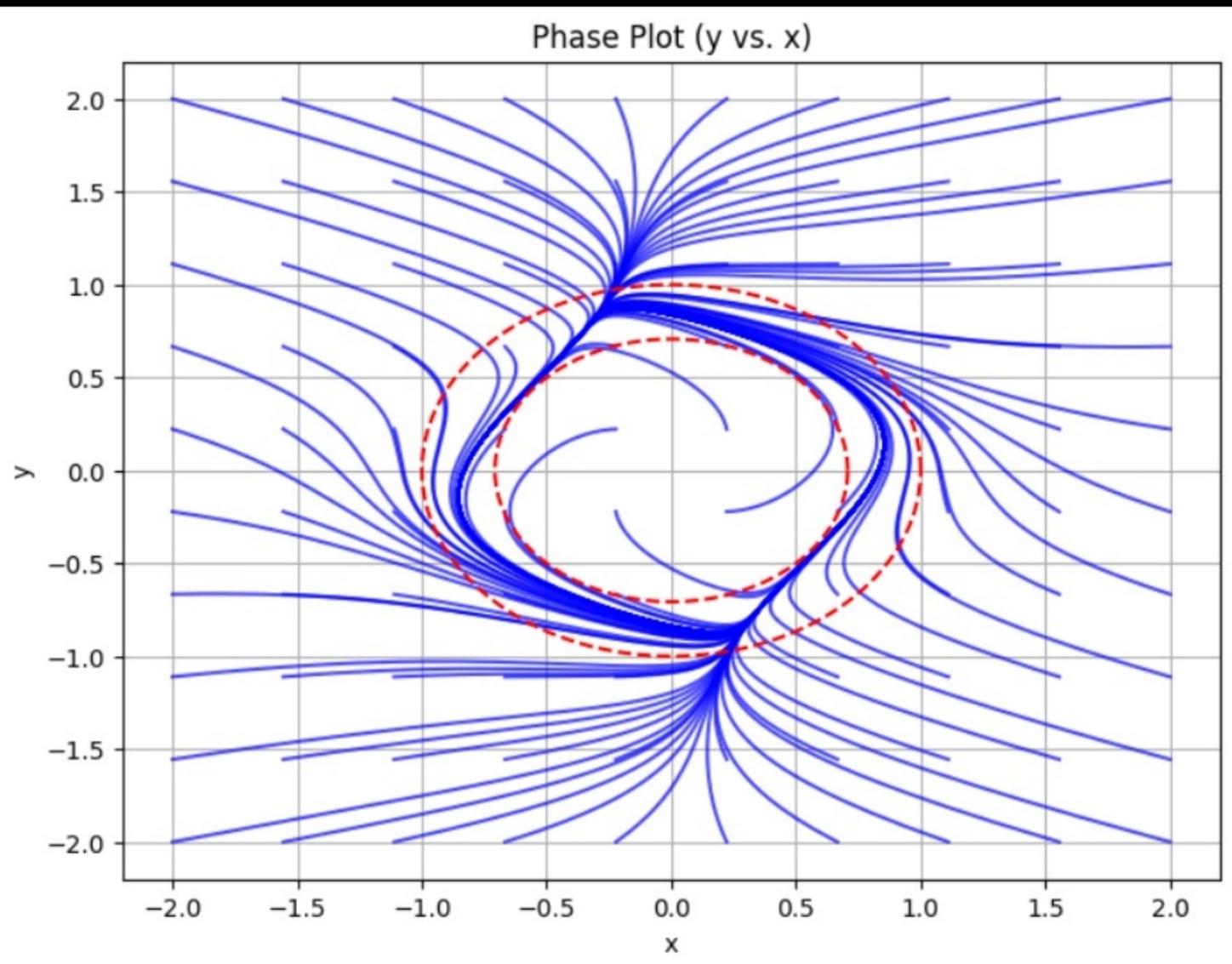
$$3 + 2 \sin 2\theta = \sin 4\theta + \cos 4\theta$$



Never cross, so no fixed points.

Since  $r \in [r_1, r_2]$  is a trapping region, all vector fields are continuous and there are no fixed points, we have a limit cycle in this region (Poincaré-Bendixson Theorem)

- (f) Using numerical integration, compute the limit cycle and verify that it lies in the trapping region constructed in the previous step.



5. Let  $\dot{x} = f(x, y)$ ,  $\dot{y} = g(x, y)$  be a smooth vector field defined on the phase plane.

(a) Show that this is a gradient system, then  $\partial f / \partial y = \partial g / \partial x$ .

a)  $\dot{x} = f = -\frac{\partial V}{\partial x} \Rightarrow \frac{\partial f}{\partial y} = -\frac{\partial V}{\partial y \partial x}$

$$\dot{y} = g = -\frac{\partial V}{\partial y} \Rightarrow \frac{\partial g}{\partial x} = -\frac{\partial V}{\partial x \partial y}$$

For smooth vector fields and smooth  $V$ ,

$$\boxed{\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}}$$

(b) Is the above condition also sufficient?

b) No, just because  $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}$ , it does not mean the system is a gradient system. You still need to satisfy  $\frac{\partial f}{\partial x} = -\frac{\partial^2 V}{\partial x^2}$ ,  $\frac{\partial g}{\partial y} = -\frac{\partial^2 V}{\partial y^2}$ .

(c) If  $f(x, y) = y + 2xy$ ,  $g(x, y) = x + x^2 - y^2$ , prove that closed orbits cannot exist.

(d) Find potential function  $V$ .

$$-\frac{\partial V}{\partial x} = y + 2xy \Rightarrow V = -xy - x^2y + \phi(y)$$

$$-\frac{\partial V}{\partial y} = x + x^2 - y^2 \Rightarrow V = -xy - x^2y + \frac{y^3}{3} + \psi(x)$$

Comparing, we get  $\phi(y) = \frac{y^3}{3}$ ,  $\psi(x) = 0$ .

$\therefore V(x, y) = -xy - x^2y + \frac{y^3}{3}$ , the system is a gradient system so closed orbits cannot exist.

(e) Sketch the phase portrait.

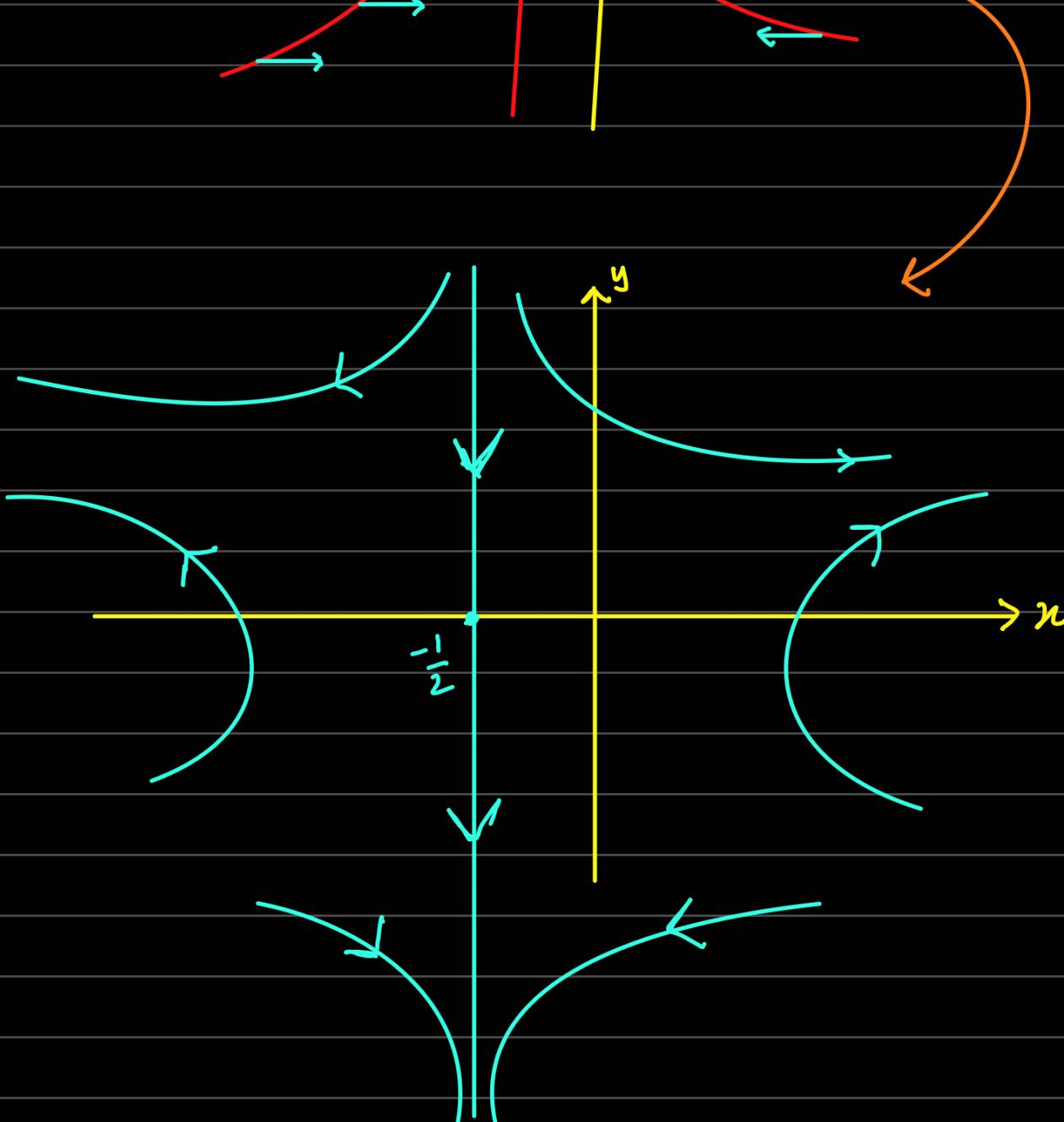
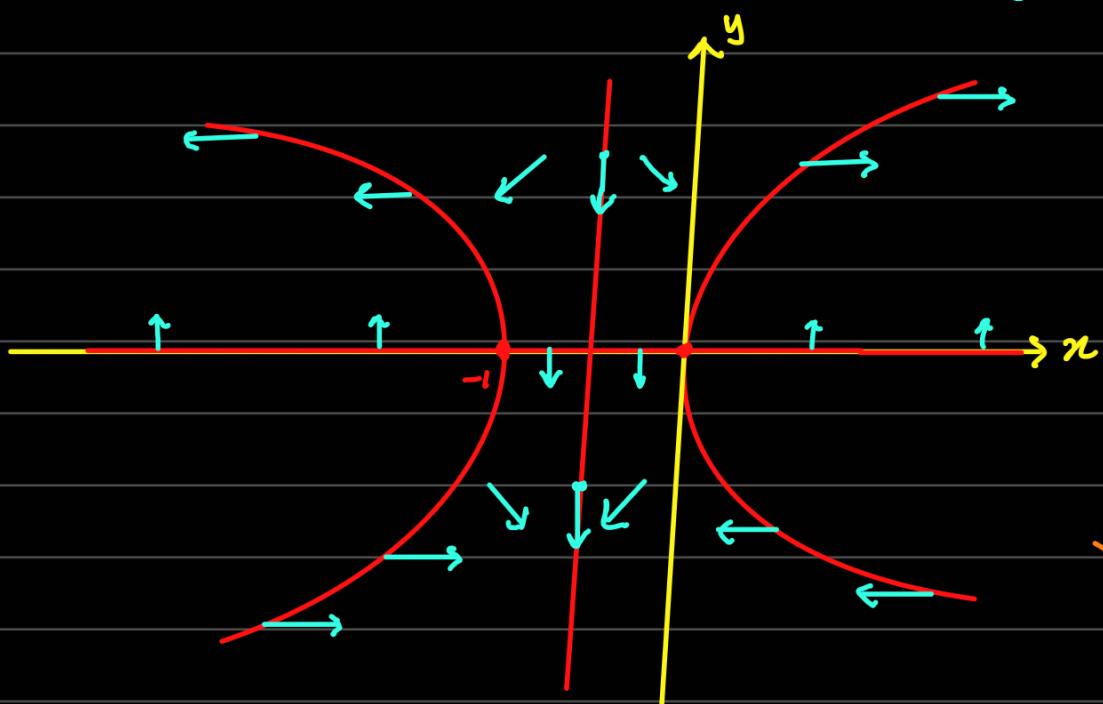
e)

$$\dot{x} = y + 2xy$$

$$\dot{y} = x + x^2 - y^2$$

$$\text{nullclines: } y(1+2x) = 0$$

$$x + x^2 - y^2 = 0$$



6. Consider the two-dimensional system  $\dot{\mathbf{x}} = \mathbf{A}\mathbf{x} - r^2\mathbf{x}$ , where  $r = \|\mathbf{x}\|$  and  $\mathbf{A}$  is a  $2 \times 2$  constant real matrix with complex eigenvalues  $\alpha \pm i\omega$ . Prove that there exists at least one limit cycle for  $\alpha > 0$  and that there are none for  $\alpha < 0$ .

$$(6) \quad r^2 = \|\mathbf{x}\|^2 \Rightarrow r\dot{r} = \dot{\mathbf{x}} \cdot \mathbf{x}$$

$$r\dot{r} = (\mathbf{A}\mathbf{x} - r^2\mathbf{x}) \cdot \mathbf{x}$$

$$r\dot{r} = \mathbf{A}\mathbf{x} \cdot \mathbf{x} - r^4$$

$$\text{Now } \|\mathbf{A}\mathbf{x} \cdot \mathbf{x}\| \leq \|\mathbf{A}\| r^2,$$

$$\text{So } \frac{dr}{dt} \leq \|\mathbf{A}\| r - r^3 = r(\|\mathbf{A}\| - r^2)$$

$$\text{For } r > \sqrt{\|\mathbf{A}\|}, \quad \frac{dr}{dt} < 0$$

Now, for  $\alpha > 0$ , origin has an unstable spiral, so  $r \in (0, \sqrt{\|\mathbf{A}\|})$  is a trapping region.

Then by the Poincaré-Bendixson Theorem, there is a limit cycle  
(for  $\alpha > 0$ )

Now consider  $\alpha < 0$ .

$$\nabla \cdot \dot{\mathbf{x}} = \nabla \cdot (\mathbf{A}\mathbf{x} - r^2\mathbf{x}) = \text{tr}(\mathbf{A}) - r^4 = 2\alpha - r^4 < 0$$

As per Dulai's criterion, with  $g=1$ ,  $\nabla \cdot (g\dot{\mathbf{x}})$  maintains the same sign so there exists no limit cycle for  $\alpha < 0$ .

7. Consider the system  $\dot{r} = r(1 - r^2) + \mu r \cos \theta$ ,  $\dot{\theta} = 1$ . Using the Poincaré-Bendixson theorem, show that a closed orbit exists for all  $\mu < 1$ , and it lies somewhere in the annulus  $0.999\sqrt{1-\mu} < r < 1.001\sqrt{1+\mu}$ . (This was shown in the class). Now using the computer, plot the phase portrait for various values of  $\mu > 0$ . Is there a critical value  $\mu_c$  at which the closed orbits ceases to exist? If so, estimate it. If not, prove that a closed orbit exists for all  $\mu > 0$ .

7

Let's search for a circle on which flow is outward.

$$\text{Then } r > 0, \quad r(1-r^2) + \mu r \cos \theta > 0$$

For an extremal radius, LHS must be +ve even when  $\cos \theta$  is -ve enough. So for  $\cos \theta = -1$ ,

$$r(1-r^2) - \mu r = 0$$

$$1-r^2-\mu=0 \Rightarrow r = \sqrt{1-\mu}$$

This must be the min. radius (as flow is outward).

For inward flow,  $r < 0$

$$r(1-r^2) + \mu r \cos \theta < 0$$

For an extremal radius, LHS must be -ve even when  $\cos \theta$  is +ve enough. So for  $\cos \theta = +1$ ,

$$r(1-r^2) + \mu r = 0$$

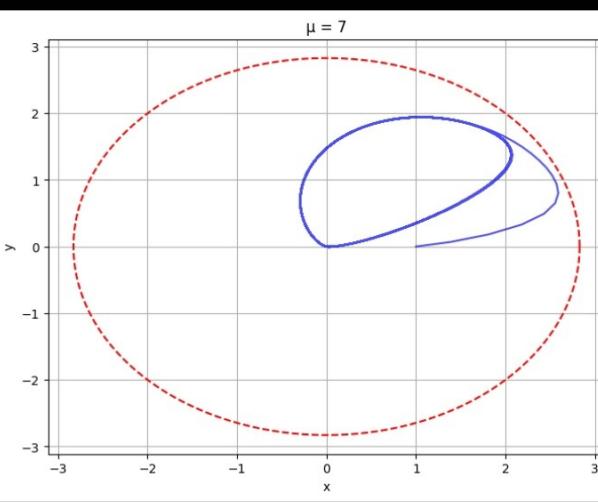
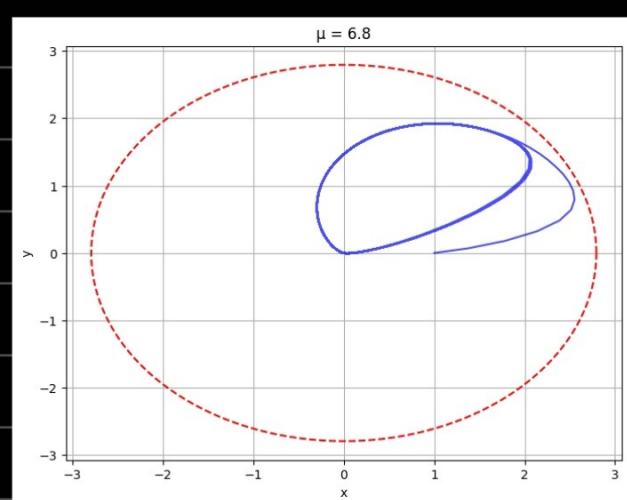
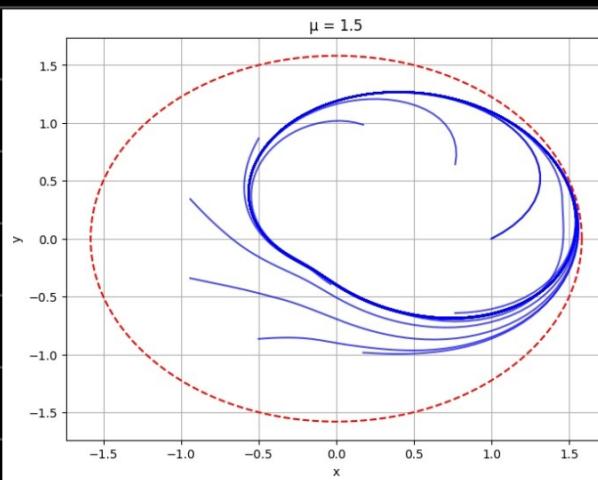
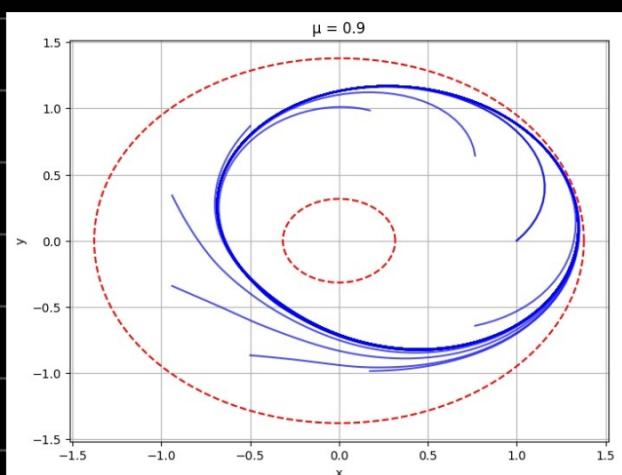
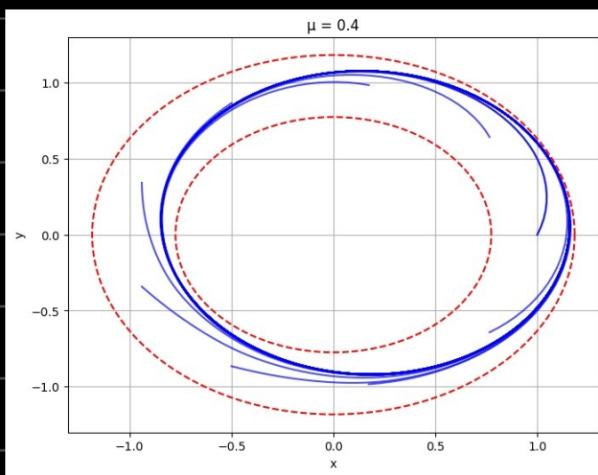
$$\Rightarrow r = \sqrt{1+\mu}$$

This must be the max. radius (as flow is inward).

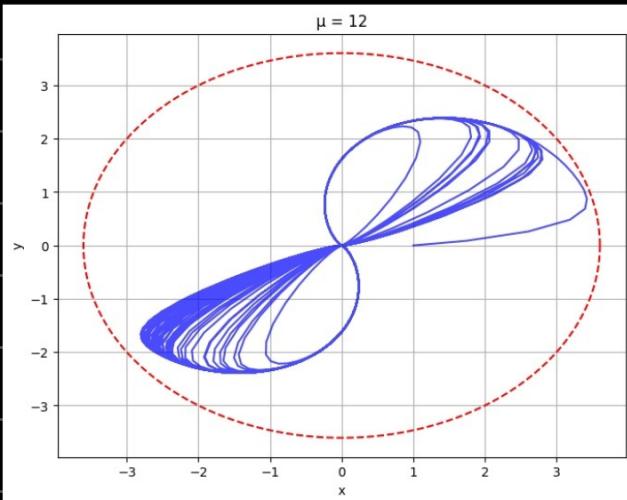
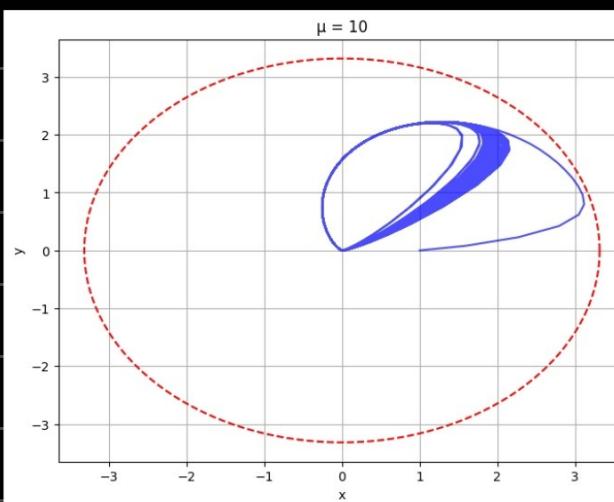
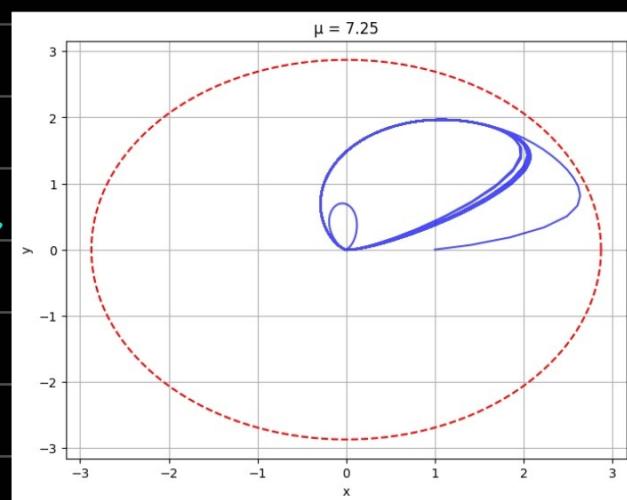
So we have constructed a trapping region  $\sqrt{1-\mu} < r < \sqrt{1+\mu}$ .

there are no fixed points in this region and all fields are smooth enough.

$\therefore$  As per the Poincaré-Bendixson Theorem, there exists a limit cycle in this region for  $\mu < 1$ .



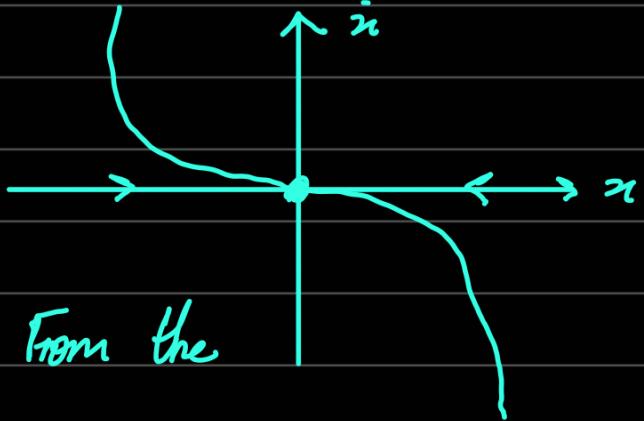
So  $\mu_c \approx 7$   
after which  
precessions are  
observed.



8. There is a theorem which states that: Let  $\bar{v}$  be an equilibrium of  $\dot{v} = f(v)$ . If the real part of each eigenvalue of  $Df(\bar{v})$  is strictly negative, then  $\bar{v}$  is asymptotically stable. If the real part of at least one eigenvalue is strictly positive, then  $\bar{v}$  is unstable.

Now the one dimensional system  $\dot{x} = -x^3$  has an equilibrium at  $x = 0$ . Decide whether  $x = 0$  is an asymptotically stable. Does this equation have unique solutions? Find all solutions that satisfy  $x(0) = 1$ .

(8)  $f(x) = -x^3$ , with  $x^* = 0$   
 $\frac{df}{dx} \Big|_{x=0} = -3x^2 \Big|_{x=0} = 0$



So the theorem does not really apply here. From the graph, we see it is asymptotically stable.

$$\frac{dx}{dt} = -x^3 \Rightarrow \frac{dx}{x^3} = -dt$$

$$\frac{x^{-2}}{-2} \Big|_{x_0}^x = -t$$

$$\Rightarrow \frac{1}{x^2} - \frac{1}{x_0^2} = 2t$$

$$\Rightarrow \frac{1}{x^2} = \frac{1}{x_0^2} + 2t$$

$$\frac{1}{x^2} = 1 + 2t \Rightarrow$$

$$x = \frac{1}{\sqrt{1+2t}}$$

So solutions are unique.

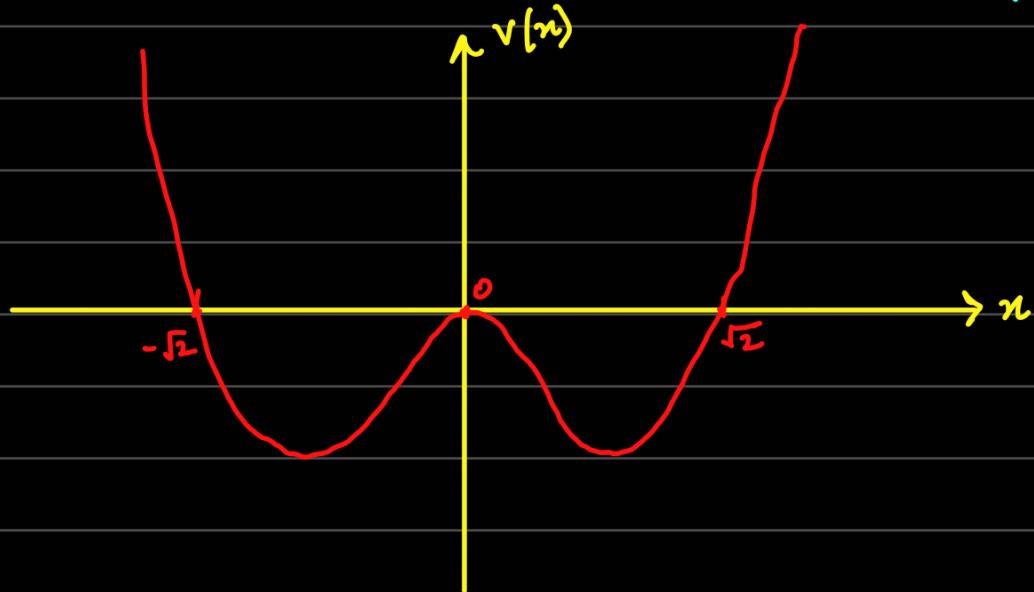
- 9) Consider the forced damped Duffing oscillator given by  $\ddot{x} + 0.1\dot{x} - x + x^3 = 2 \sin t$ . Show that the corresponding undamped unforced system has a double well potential. Plot the potential function.

Write a computer program to plot numerical solutions of the forced damped double-well in the  $(x - \dot{x})$ -plane. In particular, locate and plot the attracting periodic orbit of period  $2\pi$  and the two attracting periodic orbits of period  $6\pi$  that lie in the region  $-5 \leq x, \dot{x} \leq 5$ .

9

$$\ddot{x} - x + x^3 = 0$$

Comparing with  $\ddot{x} + \frac{dV}{dx} = 0$ ,  $V(x) = -\frac{x^2}{2} + \frac{x^4}{4}$

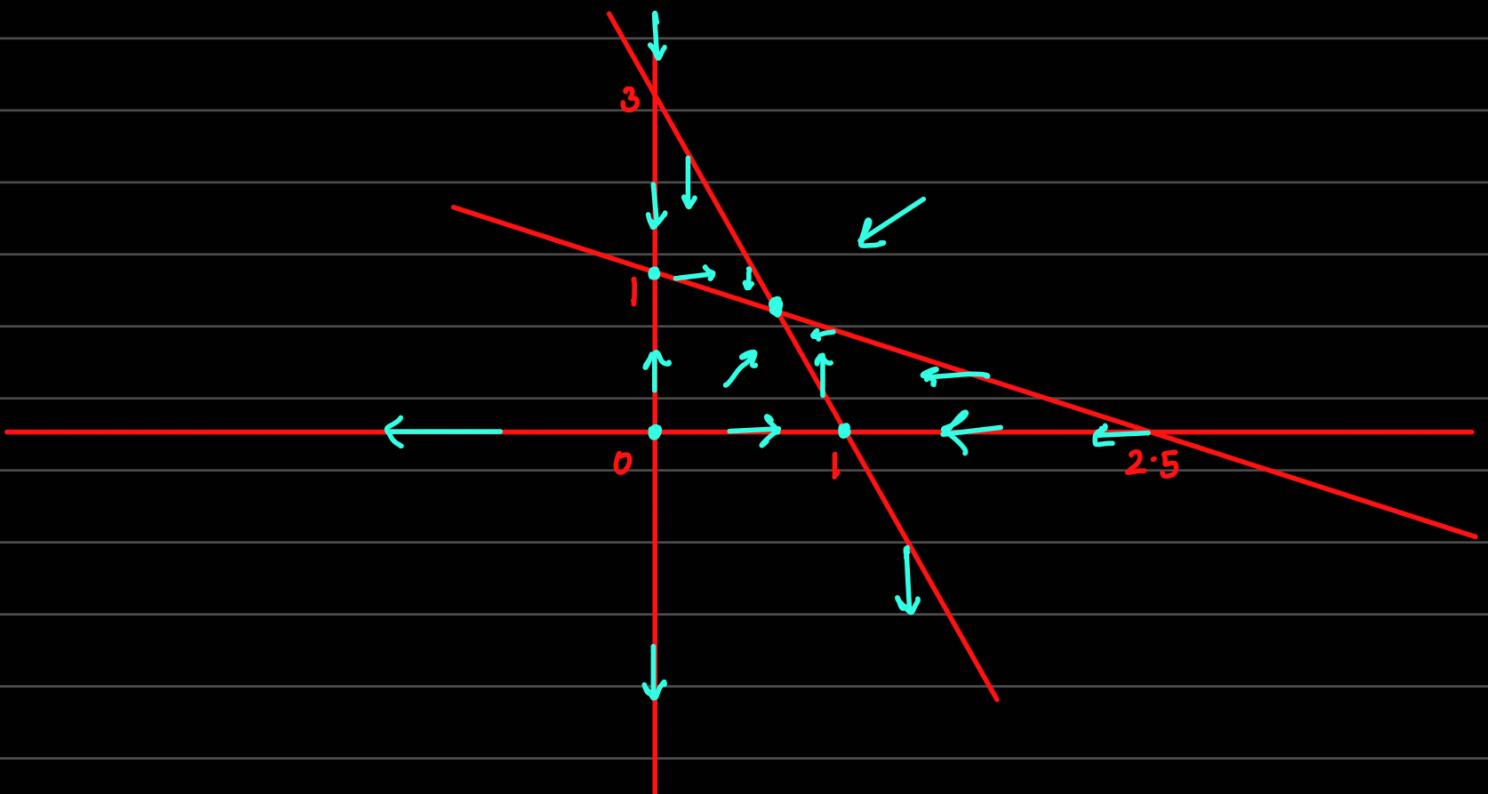


10. Use the method of nullclines to determine the global behaviour of solutions for the following system

$$\begin{aligned}\dot{x} &= 3x(1-x) - xy \\ \dot{y} &= 5y(1-y) - 2xy.\end{aligned}$$

Describe sets of initial conditions that evolve to distinct final states.

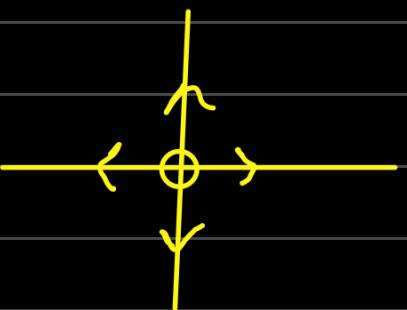
(10) Nullclines :  $x(3-3x-y) = 0 \Rightarrow x=0, 3x+y=3$   
 $y(5-5y-2x) = 0 \Rightarrow y=0, 2x+5y=5$



$$J = \begin{pmatrix} 3-6x-y & -x \\ -2x & 5-10y-2x \end{pmatrix}$$

At  $(0,0)$ ,  $J = \begin{pmatrix} 3 & 0 \\ 0 & 5 \end{pmatrix}$   $\tau = 8 \quad \Delta = 15$   
 $\tau^2 - h\Delta > 0 \Rightarrow$  unstable node

Has eigenvectors along  $x-y$  axes



$$\text{At } (1,0) : \quad J = \begin{pmatrix} -3 & -1 \\ -2 & 3 \end{pmatrix} \quad \tau = 0, \Delta = -11$$

$$\begin{pmatrix} -3 & -1 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} \sqrt{11}a \\ \sqrt{11}b \end{pmatrix}$$

$\lambda = \pm \sqrt{11}$

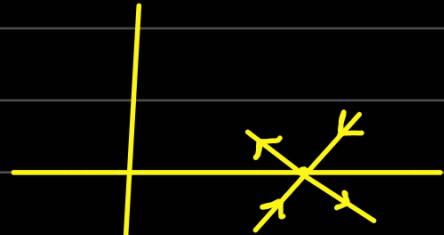
$$\Rightarrow -3a - b = \sqrt{11}a$$

$$-2a + 3b = \sqrt{11}b$$

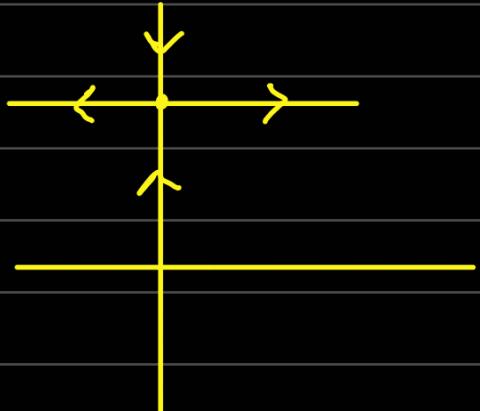
$$\Rightarrow \frac{a}{b} = \frac{3 - \sqrt{11}}{2}$$

$\lambda = \sqrt{11}, \begin{pmatrix} \frac{3-\sqrt{11}}{2} \\ 1 \end{pmatrix}$

$\lambda = -\sqrt{11}, \begin{pmatrix} \frac{3+\sqrt{11}}{2} \\ 1 \end{pmatrix}$



$$\text{At } (0,1) : \quad J = \begin{pmatrix} 2 & 0 \\ 0 & -5 \end{pmatrix}$$



$$\text{At } \left(\frac{10}{13}, \frac{9}{13}\right) : \quad J = \begin{pmatrix} 3 - \frac{60}{13} & -\frac{9}{13} \\ -\frac{20}{13} & 5 - \frac{90}{13} - \frac{20}{13} \end{pmatrix}$$

$$= \begin{pmatrix} -30/13 & -10/13 \\ -20/13 & -45/13 \end{pmatrix} \quad \tau = -75/13$$

$$\Delta = \frac{30 \cdot 45 - 200}{169} = 70$$

