

Data

Category	Element	Description	Example
◆ Temporal structure	n_steps_input	Length of the sequence used as input (temporal history).	81 steps
	n_steps_output	Subsequent steps used as output (future prediction).	
	Sliding windows	Samples are generated by sliding through the temporal sequence with a 1-frame step.	If $N_t=10$, we obtain $81 - 10 + 1 = 72$ samples
	Sample form	Data Block ($n_{\{input\}}$, H, W, C).	81, 256, 256, 11

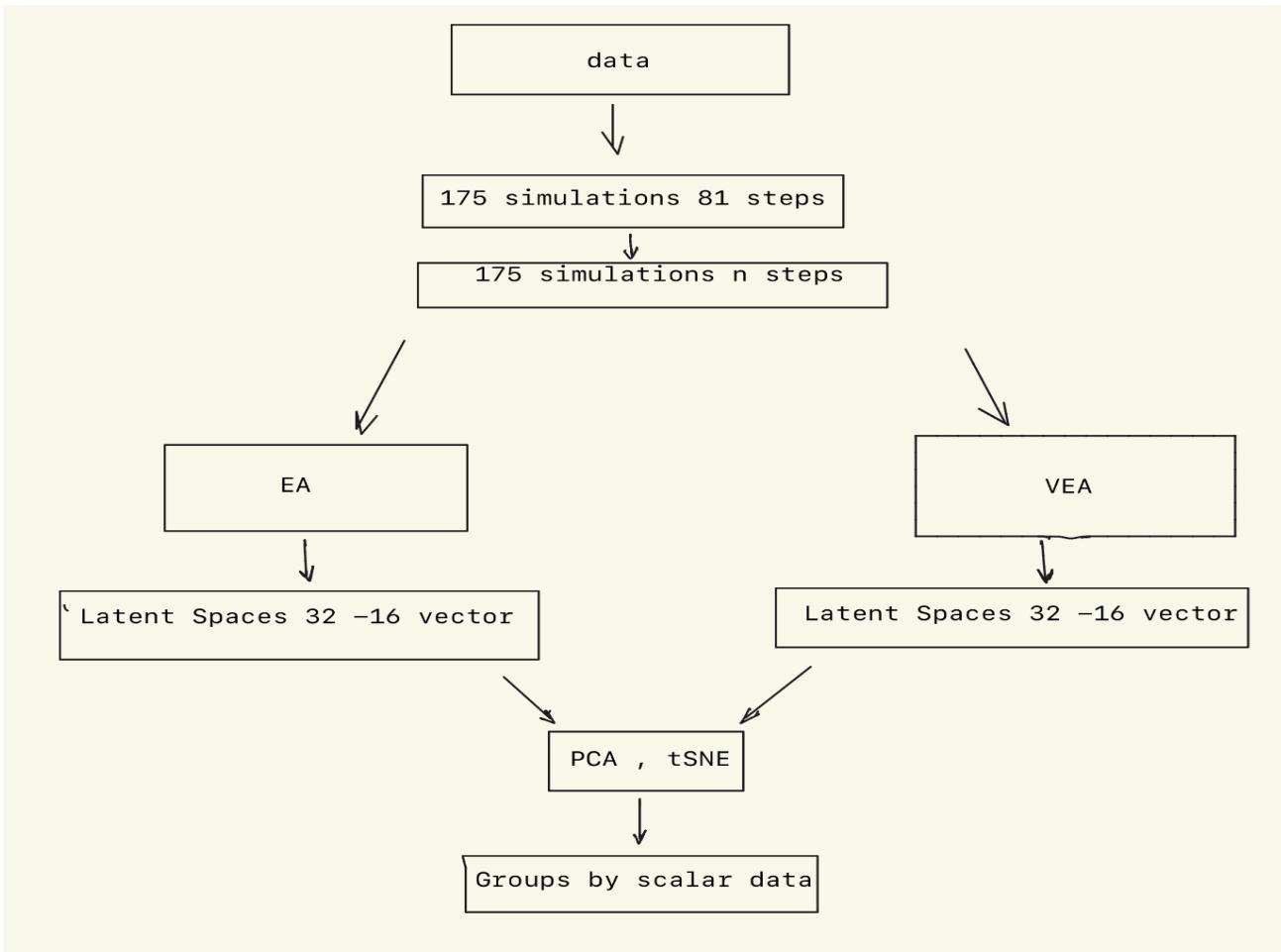
Category	Element	Description	Example
◆ Physical parameters	α (activity)	Intensidad de las fuerzas activas del sistema.	Negativo: pushers Positivo: pullers
		β (alineamiento)	Tendencia de las partículas a alinearse con su entorno.
	ζ (acoplamiento flujo-orientación)	Interacción entre el flujo y la orientación de las partículas.	ζ alto → vórtices grandes
◆ Simulated Data	Channels (11)	Magnitudes físicas calculadas en cada punto del campo.	

Chanel	Physical meaning
c	Density or local concentration
u_x, u_y	Velocity field components
D_xx, D_xy, D_yy	Deformation tensor components
Sxxxx, Sxxxy, Sxxyy, Sxyyy, Syyyy	Fourth-order moments (anisotropy and spatial correlations)

Project: Use autoencoders and variational autoencoders to learn low-dimensional latent representations that capture key features and phase transitions in active matter systems.

By analyzing the latent space with PCA and t-SNE, reveals transitions between dynamic regimes, meaningful clustering of physical phases, and interpretable organization related to the system's underlying parameters.

Identify low-dimensional latent structures revealing active-matter dynamic phases.



Algorithm 1 Resumen del pipeline cVAE para `active_matter`

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1: Input: Dataset  $\mathcal{D}$  (active_matter), parámetros  $(\alpha, \beta, \zeta)$ 
2: Output: Latentes  $Z_\mu$ , proyecciones PCA/t-SNE

3: function LOADDATASET
4:   Cargar  $\mathcal{D}$  con  $n\_steps\_input = 81$ , normalización z-score
5: end function
6: function SUBSAMPLE( $\mathcal{D}$ )
7:   Seleccionar frames  $\{0, step, 2step, \dots\}$  y condiciones  $(\alpha, \zeta)$ 
8:   Normalizar condiciones y asignar class_id
9: end function
10: function TRAINCVAE(dataset)
11:   for epoch = 1 to  $N$  do
12:     Calcular  $\beta$  (KL annealing)
13:      $(x, cond) \rightarrow (\hat{x}, \mu, \log \sigma^2, z)$ 
14:      $\mathcal{L} = MSE(x, \hat{x}) + \beta \cdot KL(\mu, \log \sigma^2)$ 
15:     Retropropagar y actualizar pesos
16:   end for
17: end function
18: function ANALYZELATENT(model)
19:   Obtener  $\mu$  para todas las muestras  $\rightarrow Z_\mu$ 
20:   Aplicar PCA y t-SNE, graficar por clase  $(\alpha, \zeta)$ 
21:   Guardar  $\{Z_\mu, Z_{PCA}, Z_{tSNE}\}$ 
22: end function

23:  $\mathcal{D} \leftarrow$  LOADDATASET
24:  $\text{wrap} \leftarrow$  SUBSAMPLE( $\mathcal{D}$ )
25: TRAINCVAE( $\text{wrap}$ )
26: ANALYZELATENT(model)
  
```

Architecture

Part	What it does	Shape / Size
Input	A short movie (sequence) of physical fields	(11 variables, 9 time steps, 256×256 pixels)
Encoder	Compresses the movie into a small numeric code	Becomes a 256-number feature vector
Condition	Adds the physical parameters (α, ζ)	2 numbers
Latent space	Final compact representation that summarizes the system	32 numbers (latent size = 32)
Decoder	Uses the 32 numbers and (α, ζ) to rebuild the movie	Output same size as input
Loss function	Compares input and output to learn good reconstructions	Uses error + regularization