

## DENSE ACTIVE SYSTEMS : activity and crowding

- Recall Lisa's confluent cell layers
- Show penguin movie

Today's Lecture : activity and exclude volume / steric effects

First → SP dynamics vs Brownian dynamics

- Overdamped Brownian particle ( $d=2$ )

$$\frac{d\vec{r}}{dt} = \vec{v} = \vec{\gamma}(+) \quad \langle \vec{\gamma}(+) \rangle = 0$$

$$\langle [\Delta \vec{r}(+)] \rangle = 4Dt \quad \langle 2\alpha^{(+)} 2\beta^{(+')} \rangle = 2D\delta_{\alpha\beta}\delta(t-t')$$

$$D = K_B T / 5$$

- SPP

- active colloids
- cells on substrate

• Flyy & MCM PRL 108 235702 (2012)

• Flyy, Henkes, MCM Soft Matter 10, 2132 (2014)

→ Palacci's low density movie + high density

Ajusman San 2005

$$\frac{d\vec{r}}{dt} = N_0 \hat{e} + \vec{\gamma}(+) \quad \hat{e} = (\cos\theta, \sin\theta)$$

$$\frac{d\theta}{dt} = \gamma_r(+) \quad \text{from different rates of H}_2\text{O}_2 \text{ consumption on two sides}$$

$$\langle 2\alpha(+) \rangle = 0$$

$$\langle 2\alpha(+) 2\beta^{(+')} \rangle = 2Dr \delta(t-t')$$

$$[D] = [l^2 t^{-1}]$$

equilibrium : noise  $\sim kT$

$$[Dr] = [t^{-1}]$$

$$D \sim a^2 Dr$$

HW : calculate MSD

$$\langle [\Delta \tilde{r}(t)]^2 \rangle = 4D_r t + \frac{2v_0}{D_r} \left[ t - \underbrace{\frac{1 - e^{-D_r t}}{D_r}}_{\sim v_0^2 t^2} \right]$$

$$t \ll D_r^{-1} \quad \sim v_0^2 t^2$$

$$t \gg D_r^{-1} \quad \sim \frac{v_0^2}{D_r} t$$

$$\boxed{t \gg D_r^{-1}}$$

$$\boxed{\langle [\Delta \tilde{r}(t)]^2 \rangle \approx 4 \left[ D_r + \frac{v_0^2}{2D_r} \right] t}$$

persistence length

$$l_p = v_0 / D_r$$

How does this compare to  
run-and-tumble ? (E.coli)

$$\frac{v_0^2}{2D_r} \sim l_p^2 D_r$$

continuous diffusion  
at rate  $D_r$

VS

discrete tumble events  
mean-time between tumbles  
exponentially distributed

$$D_{sp} \sim \frac{v_0^2}{d(d-1) D_r}$$

$$(d-1) D_r \rightarrow \infty$$

tumble rate  $\alpha$

$$D_{sp} \sim \frac{v_0^2}{d \alpha}$$

$$D_{sp} = \frac{v_0^2}{d[\alpha + (d-1) D_r]}$$

(some E.coli mutants  
do not tumble)

Differences disappear upon coarse graining.

Apparent only when there is a small-scale structure  
in the problem, e.g., traps of size  $\lambda$  <sup>large</sup> compared to  
run length: ABP trapped at walls.

{ Some numbers }

$$D = \frac{k_B T}{6\pi \eta a}$$

$$k_B T \approx 1.38 \times 10^{-23} \text{ J/K} \quad 300 \text{ K} \approx 5 \times 10^{-21} \text{ J}$$

$$\eta_{H_2O} \approx 10^{-3} \text{ Pa s}$$

$$D_r \approx 0.2 \times 10^{-12} \text{ m}^2/\text{s}$$

$$\approx 0.2 \mu\text{m}^2/\text{s}$$

$$a \approx \mu\text{m} \approx 10^{-6} \text{ m}$$

$$D_{sp} \approx N_0^2 / D_r$$

$$N_0 \approx 10 \mu\text{m/s}$$

$$D_r \approx 10^{-3} - 10^{-4} \text{ s}^{-1}$$

$$D_{sp} \approx 10^8 \mu\text{m}^2/\text{s}$$

$$\alpha \approx 1 \text{ s}^{-1}$$

{  $D_{sp} \gg D$  }

We can neglect translational noise

Both systems :

• particles do not exert torques on each other

nor on a surrounding solvent.

The angular dynamics of each particle is unaffected by that of the others or by interactions

{ Key simplification }

Peclet number

$$Pe = N_0 / a D_r = l_p / a$$

{Effective temperature}

tempting, but...

$$\begin{aligned} \frac{d\vec{r}}{dt} &= \dot{\epsilon}(t) v_0 \\ \frac{d\theta}{dt} &= \gamma_r(t) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad \begin{aligned} \frac{d\vec{r}}{dt} &= \vec{\xi}_{\text{eff}}(t) \end{aligned}$$

$$\langle \vec{\xi}_\alpha(t) \vec{\xi}_\beta(t') \rangle = v_0^2 e^{-Dr|t-t'|}$$

$$\rightarrow \frac{v_0^2}{Dr} \delta(t-t') \quad \cancel{\text{for } Dr \rightarrow 0}$$

Non-Markovian noise

$$k_B T_{\text{eff}} = \frac{v_0^2}{2\mu D_r}$$

$$\boxed{P_{\text{ideal}} = g k_B T_{\text{eff}}}$$

$$[D_r] = t^{-1}$$

$$[M] = [m^2 t^4]$$

skip

**PROB** Equilibrium : linear response  $R = \left( \frac{\partial \langle v \rangle}{\partial f} \right)_{f=0} = \mu = \frac{1}{5}$

$$\text{FD : } \frac{C}{R} = k_B T$$

$$\text{correlation function } C = D = \frac{1}{2} \int_0^\infty dt \langle \vec{v}(t) \cdot \vec{v}(0) \rangle$$

**Glassy systems** :  $\frac{C}{R} = k_B T_{\text{eff}}$  a useful concept sometimes  $T_{\text{eff}}(\omega)$

Here :

- Single active particle in an external force, e.g., ~~confined~~<sup>confining potential  $V_{\text{ext}}$</sup> ; equilibrium notion effective only if

$$DV_{\text{ext}} \ll F_{\text{sp}} = v_0 \sqrt{\frac{2}{5}}$$

or characteristic length set by balance of external and SP force  $\sim V_{\text{ext}} \sqrt{\frac{2}{v_0}} \gg l_p$

**Most striking phenomenon**  $\rightarrow$  MIPS = motility-reduced phase separation

many particles

$$\frac{1}{D_r} \ll T_{\text{coll}} \sim \frac{1}{2av_0g}$$

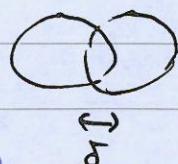
Interacting SPP : only repulsion

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_{\theta_i} + \mu \sum_j \vec{f}_{ij}$$

$$\frac{d\theta_i}{dt} = \gamma_{ri} (+)$$

Repulsive forces :

- soft  $\vec{f}_{ij} = -\delta K \vec{r}_{ij}$



- hard spheres
- WCA, LJ, ...

$$\boxed{2d + 3d}$$

Time scales

$$1/D_r$$

$$a/v_0$$

$$1/\mu K$$

$$\tau_c = 1/2av_0\rho$$

$v_0/a \gg \mu K$  pass through

$v_0/a\mu K \rightarrow 0$  athermal packing  
 $D_r \rightarrow \infty$  thermal

Phase separation with no attraction  $\rightarrow$  MIPS motility-induced

- $\Rightarrow$  movies : • our simulations  
• Palaecci clusters

phase separation if  $\tau_r > \tau_c$   
 $|Peg| \gg 1$

MIPS :

- mean speed of particles along propulsion direction decreases with increasing density ( $\neq$  equipartition)
- particles accumulate where they move slowly (not possible in equilibrium systems because speed distribution does not depend on position)

$$v_0 \rightarrow v(g) \approx v_0(1-\lambda g)$$

numerical fits to MSD

Schnitzer, PRE 48, 2553 (1993)

1d run-and-tumble w/ spatially varying speed

$v(x)$  speed of run

$\alpha$  tumble rate

$R(x)/L(x) = \text{density of right/left moving particles}$

$$\begin{cases} \dot{R} = -\partial_x(vR) - \frac{\alpha}{2}R + \frac{\alpha}{2}L \\ \dot{L} = \partial_x(vR) + \frac{\alpha}{2}R - \frac{\alpha}{2}L \end{cases}$$

factor of  $\frac{1}{2}$  because

$\frac{1}{2}$  of tumbles are

$R \rightarrow R$  or  $L \rightarrow L$

direction switches at

rate  $\alpha/2$

$\rho = R+L = \text{density}$

$\sigma = R-L = \text{polarization}$

$J = v\sigma = \text{current}$

$$\partial_t \rho = -\partial_x J \quad \text{conserved}$$

$$\partial_t \sigma = -\partial_x(v\rho) - \alpha\sigma \quad \text{relaxational}$$

$$\text{time } \gg \frac{1}{\alpha} \quad \sigma \approx -\frac{1}{\alpha} \partial_x(v\rho) \quad \text{"adiabatic" approximation}$$

$$\partial_t \rho = -\partial_x \left[ -\frac{v}{\alpha} \partial_x v\rho \right]$$

$$\partial_t \rho = -\partial_x \left[ \underbrace{-\frac{v^2}{\alpha} \partial_x \rho + \frac{vv'}{\alpha} \rho}_{\text{cf convection-diffusion}} \right]$$

cf convection-diffusion current

$$J = v\rho - D\partial_x \rho$$

$$\partial_x \rho / \partial_x(D(\rho) \partial_x \rho) \approx \partial_x D(\rho) \partial_x \rho$$

$$D(x) = v^2(x)/\alpha$$

$$V(x) = - \frac{v(x)v'(x)}{\alpha}$$

shift towards regions  
of smaller  $v$  (- signs)

- $v(x) = \text{constant}$

$$\partial_t p = D \partial_x^2 p$$

only stationary solution is  $p = p_*$

- $v(x) \neq \text{constant}$

$\begin{array}{c} T \\ \downarrow \\ S_1 \end{array}$	$\begin{array}{c} T \\ \downarrow \\ S_2 \end{array}$	<u>steady state</u> $J(x) \equiv \text{const} = 0 \quad \text{no flux}$
$\boxed{S_1 v_1 \quad   \quad S_2 v_2}$	$S_1 v_{th} = S_2 v_{th}$	$\frac{1}{p} \partial_x p = - \frac{1}{v} \partial_x v$
$\boxed{S_1 v_1 \quad   \quad S_2 v_2}$	$S_1 v_1 = S_2 v_2$	$\left\{ p(x) = p_0 \frac{v(0)}{v(x)} \right\}$

This result depends critically on having an upper bound for speed, as opposed to a speed distribution (e.g. M-B) that allows (even if with small probability) arbitrarily large speeds.

Many interacting particles

$$v \rightarrow v(p)$$

$$p \sim \frac{1}{v(p)}$$

feedback yields  
phase separation

## Continuum Model

$\rho$  conserved

$\vec{p}$  no phase transition

Non interacting particles

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_i + \vec{\gamma}_i(t)$$

$$\frac{d\vec{p}_i}{dt} = \vec{\gamma}_{Ri}(t)$$

$$\partial_t \psi(r, \theta, t) = -\vec{\nabla} [v_0 \hat{e}_4 - D \vec{\nabla} \psi] + D_r \partial_\theta^2 \psi$$

$$\partial_t \rho = -\vec{\nabla} \cdot [v_0 \rho \vec{p} - D \vec{\nabla} \rho]$$

$$\partial_t \vec{p} = -D_r \vec{p} - \frac{v_0}{2} \vec{\nabla} \rho + \kappa (D \vec{\nabla} \rho)$$

interactions here are repulsive steric effect.

do not yield alignment, but reduce motility

$$v_0 \rightarrow v(\rho) = v_0(1 - \lambda\rho)$$

$\lambda$  depends on pair correlation function

higher probability of finding particles ahead of you than behind

Clustering of inelastic systems arise from combining the dynamics of a conserved field (density) with non-conserving noise. This gives  $S(k) \sim 1/k^2$ , like GNF in ordered state

$$\partial_t \tilde{g} = -\vec{\nabla} \cdot [v(\phi) g \vec{p}] + D \nabla^2 g$$

$$\partial_t \tilde{p} = -D_r \tilde{p} - \frac{1}{2} \vec{\nabla} [\tilde{p} v(\phi)] + O(D^2)$$

$\left\{ t \gg 1/D_r \right\}$

$$\tilde{p} \approx -\frac{1}{2D_r} \vec{\nabla} [\tilde{p} v(\phi)]$$

quasi-thermal limit

$$\partial_t g = \vec{\nabla} \cdot Q(g) \vec{\nabla} g$$

$$Q(g) = D + \frac{v'(g)}{2D_r} + \frac{v g N'}{2D_r}$$

$$N(g) = N_0(1-\lambda g)$$

$$Q_{eff} = D + \frac{v_0^2}{2D_r} (1-\lambda g)(1-2\lambda g)$$

minimum Pe  
required for  
phase separation

$Q_{eff} < 0$  spinodal phase separation

$\left\{ \text{Kinetic estimate of } \lambda \right\}$

$$\tau_c \sim (2a N_0 g)^{-1} \quad \text{mean free time}$$

$$v(g) \sim v_0 (1 - \tau/\tau_c) \quad \tau \sim \text{mean delay caused by collisions}$$

- $\tau_1 \sim a/v_0$  escape by traveling a while maintaining orientation

- $\tau_2 \sim 1/D_r$  must rotate to escape

$$\frac{1}{\tau} = \frac{1}{\tau_1} + \frac{1}{\tau_2} \quad \text{faster mechanisms wins (back)}$$

finite  $D_r$ : retain dynamics of  $\vec{p}$  and examine stability of homogeneous state  $p = p_0, \vec{p} = 0$   
by letting  $p = p_0 + \delta p$

$$\vec{p} = \delta \vec{p}$$

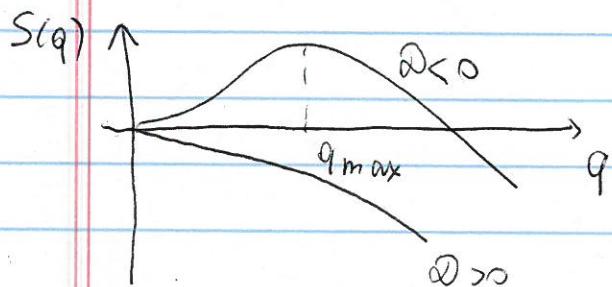
$$\delta g(\vec{r}, t), \delta \vec{p}(\vec{r}, t) \sim e^{s \cancel{at} + i \vec{q} \cdot \vec{r}}$$

$$(\partial_t + D q^2) \delta g_q + i v(g_0) \vec{q} \cdot \vec{p} = 0$$

$$(\partial_t + D_r \sqrt{+kq^2}) \delta \vec{p} + \frac{1}{2} (v' + g_0 v') i \vec{q} \delta p = 0$$

small  $q$ : mode

$$S(q) = -q^2 D(p_0) + q^4 B$$



$$q_{\max} \sim \sqrt{-\frac{D}{2kD}}$$

This result can also be interpreted in the context of a Landau-type HFT (ignoring gradient terms, i.e.,  $v(g(r))$  is local).

In fact one can map a SPP with  $v(g)$  onto a Landau-like HFT of a system of attractive particles undergoing liquid-gas phase separation.

Pressure

- force/area on walls of container
- thermodynamics :  $p = -\left(\frac{\partial F}{\partial V}\right)_N \Rightarrow$  eqn. of state
- hydrodynamics :  $p = gkT + \frac{1}{6V} \left\langle \sum_{i \neq j} \vec{r}_{ij} \cdot \vec{F}_{ij} \right\rangle$   
or virial

Ideal gas of SP particles :

$$\vec{r}_i = \underbrace{\sum v_0 \hat{e}_i}$$

$$\dot{\vec{r}}_i = \gamma_i(t) \quad \rightarrow \text{SP force } \vec{f}_i^{\text{SP}}$$

$$\text{or } \frac{1}{3V} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i \right\rangle$$

virial

$$P_{\text{act/swim}} = \frac{1}{2A} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i^{\text{SP}} \right\rangle$$

$$= \frac{1}{2A} \int_{-\infty}^t dt' \left\langle \sum v_0 \hat{e}_i(t') \cdot \sum v_0 \hat{e}_i(t) \right\rangle$$

$$P_{\text{act/swim}} = \frac{\rho v_0^2}{2\mu D_r} (1 - e^{-D_r t}) \xrightarrow[t \rightarrow \infty]{} \frac{\rho v_0^2}{2\mu D_r} = \rho k T_{\text{eff}}$$

in a container

$$t \sim L/v_0$$

$$P_{\text{swim}}(t \sim L/v_0) \sim \begin{cases} \rho k T_{\text{eff}} & \text{if } L \gg \ell_p \\ \frac{\rho v_0 L}{2\mu} & L \ll \ell_p \end{cases}$$

Detailed calculations have shown

$$P_{\text{sink}} = \frac{\rho v_0 n(g)}{2 \mu D_r}$$